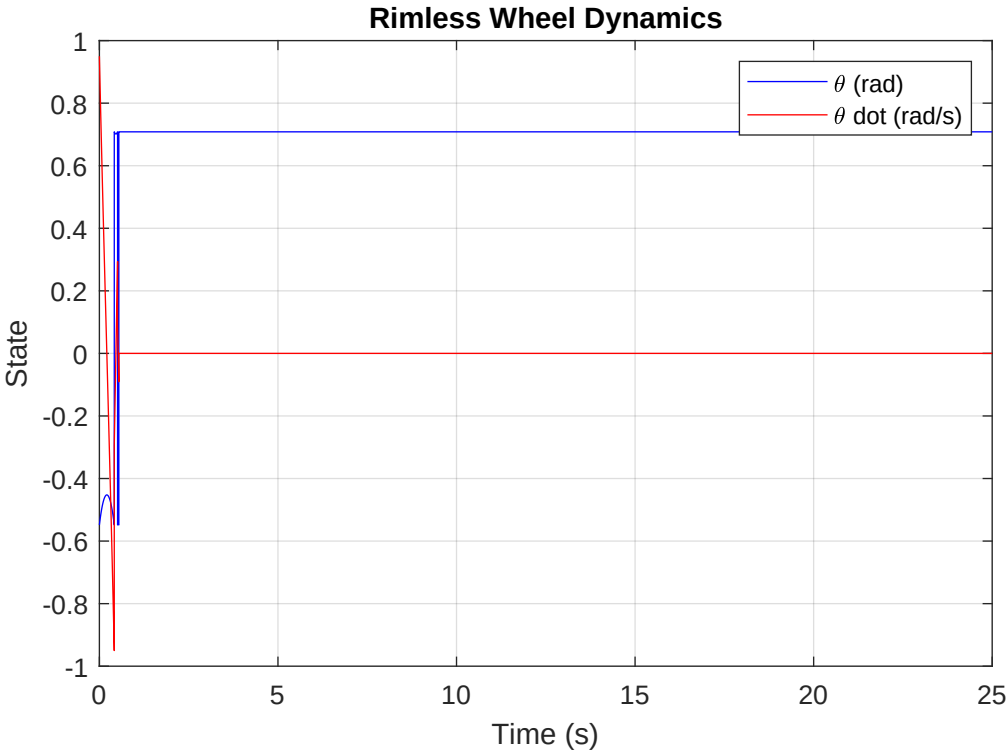
Rimless Wheel Dynamics
θ (rad)
θ dot (rad/s)
State
Time (s)
1
0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-0.8
-1
0
5
10
15
20
25