Recorded at time: 1734719988.6863112 map Broadcaster: default_authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $1\overline{0.789}$ Buffer length: 3.8 Buffer length: 0.0 Most recent transform: 49.4 Most recent transform: 0.0 Oldest transform: 45.6 Oldest transform: 0.0 fra2mo/odom aruco pose tf Broadcaster: default authority Average rate: $5\overline{0.481}$ Buffer length: 2.496 Most recent transform: 49.22 Oldest transform: 46.724 base footprint Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: 10.278 Average rate: 10.278 Average rate: $10\overline{0}00.0$ Average rate: 10000.0 Buffer length: 0.0 Buffer length: 3.6 Buffer length: 3.6 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 49.184 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 49.184 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 45.584 Oldest transform: 45.584 $right_wheel_link$ d435_link camera link lidar link left_wheel_link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 laser_frame Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 fra2mo/base footprint/laser frame

view frames Result