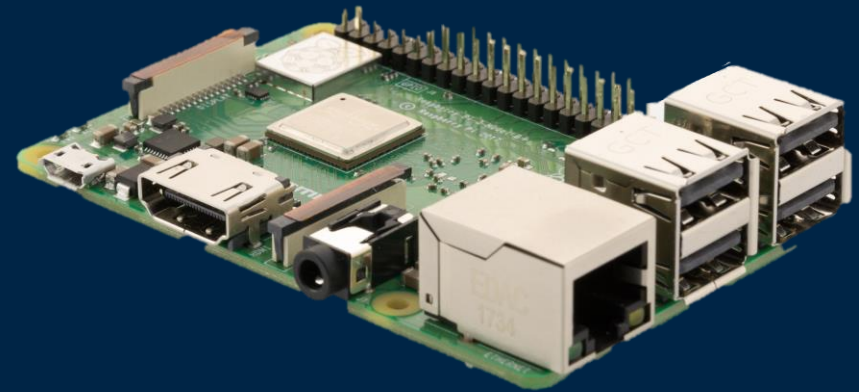
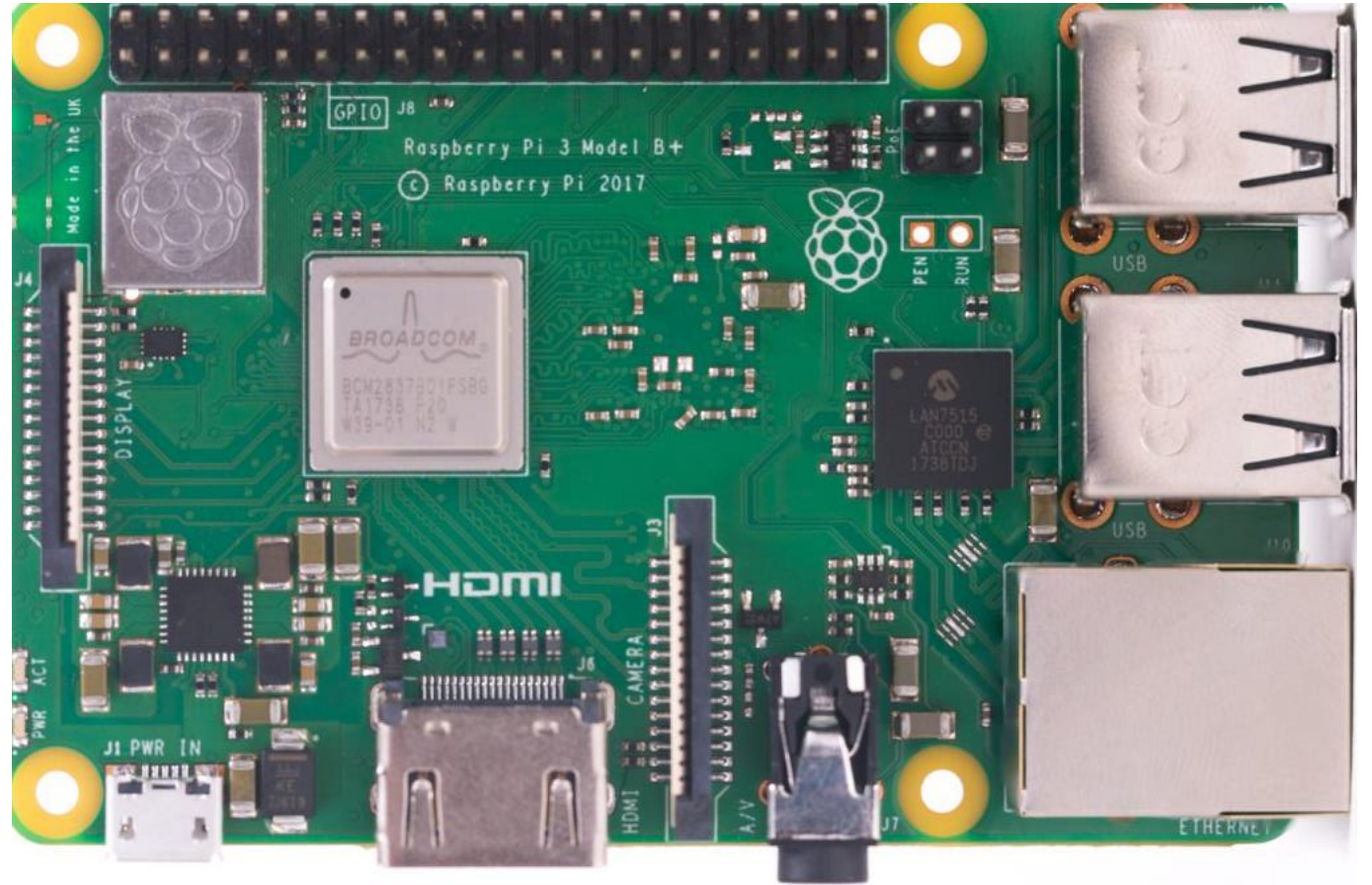


Raspberry PI Intro



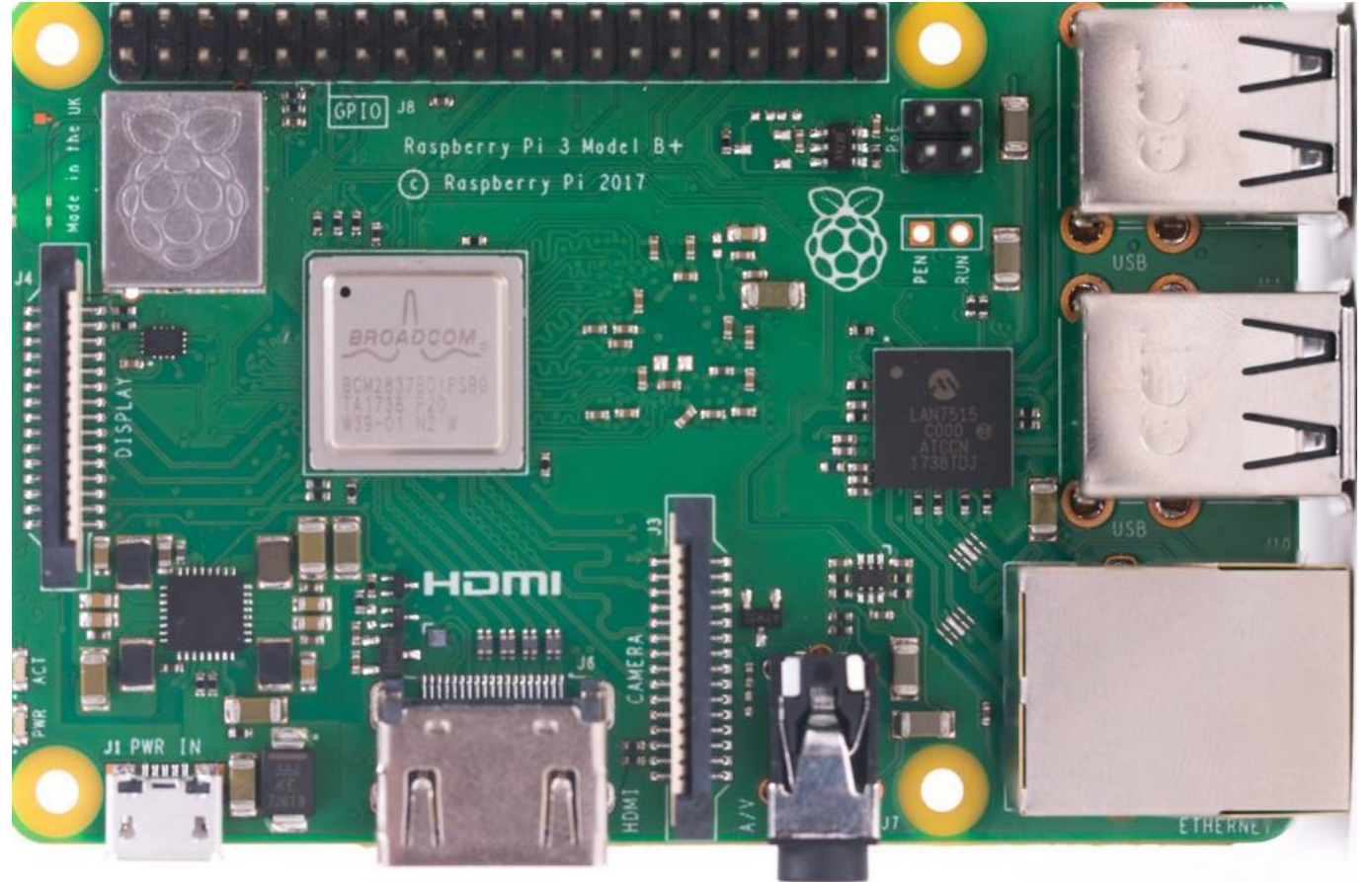
Raspberry Pi 3 model B+

- I. Single-board computer



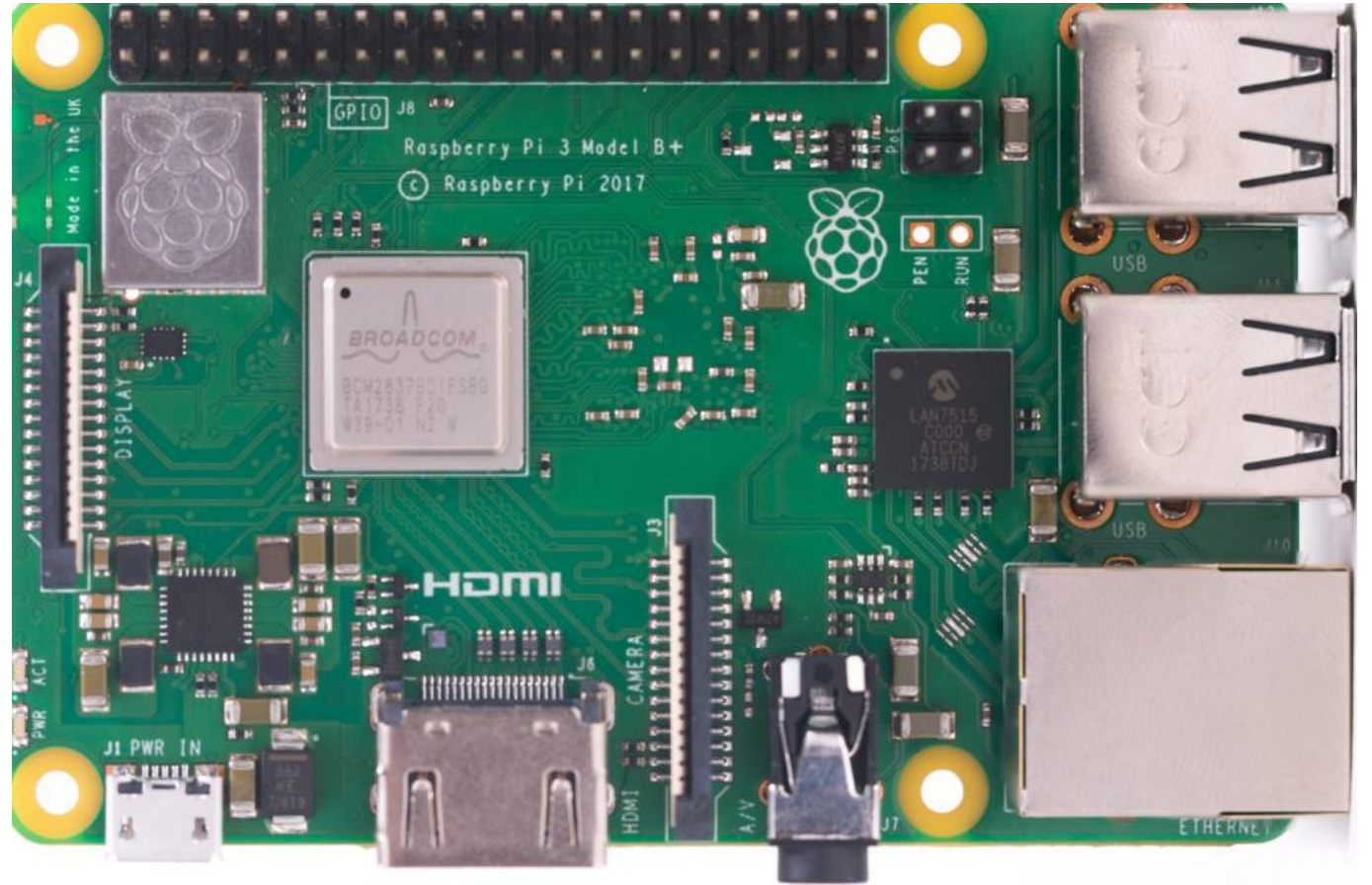
Raspberry Pi 3 model B+

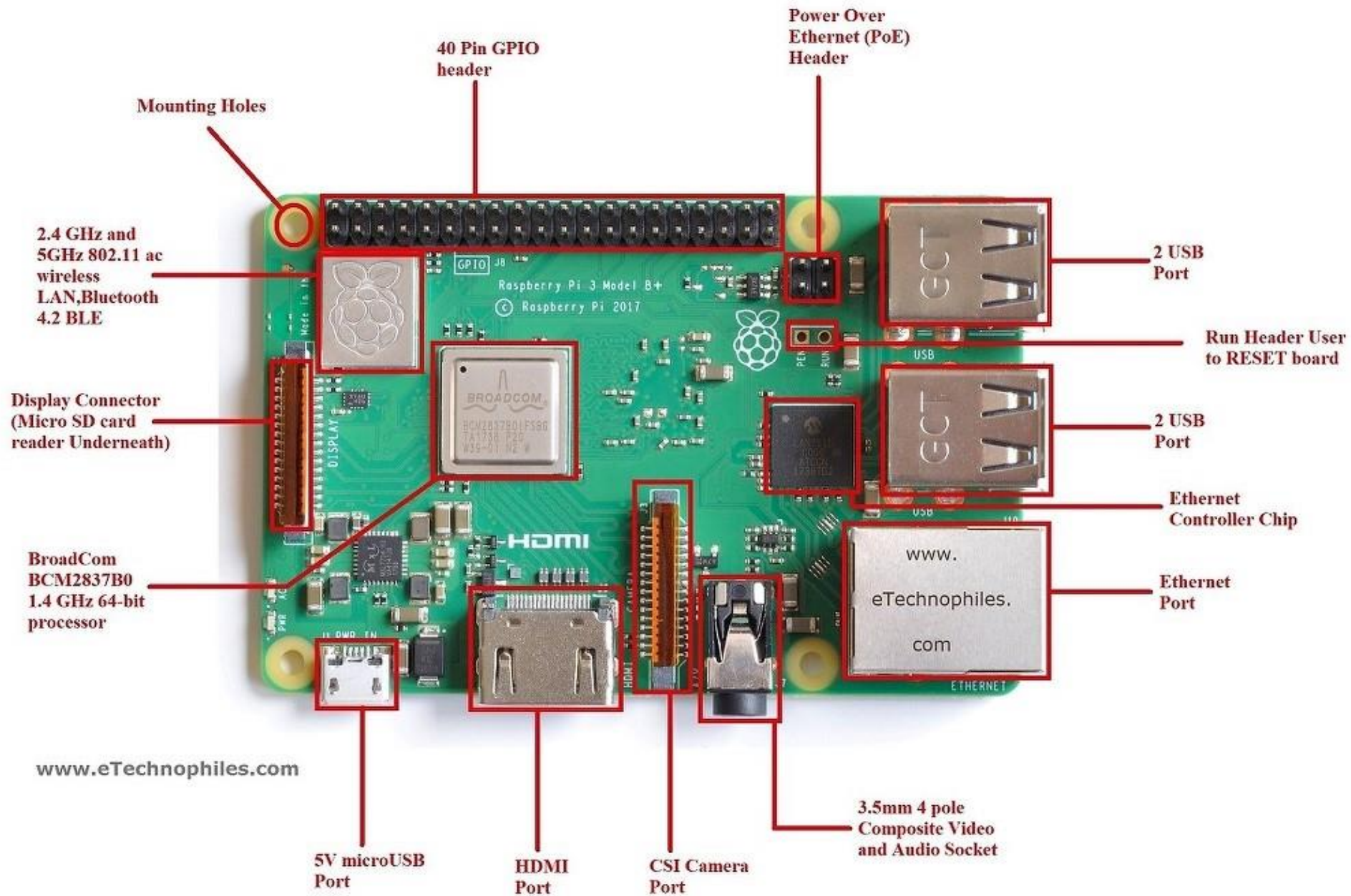
- I. Single-board computer
- II. A set of useful ports
 - a. USBs
 - b. Ethernet
 - c. Hdmi
 - d. MicroUsb
 - e. CSI camera



Raspberry Pi 3 model B+

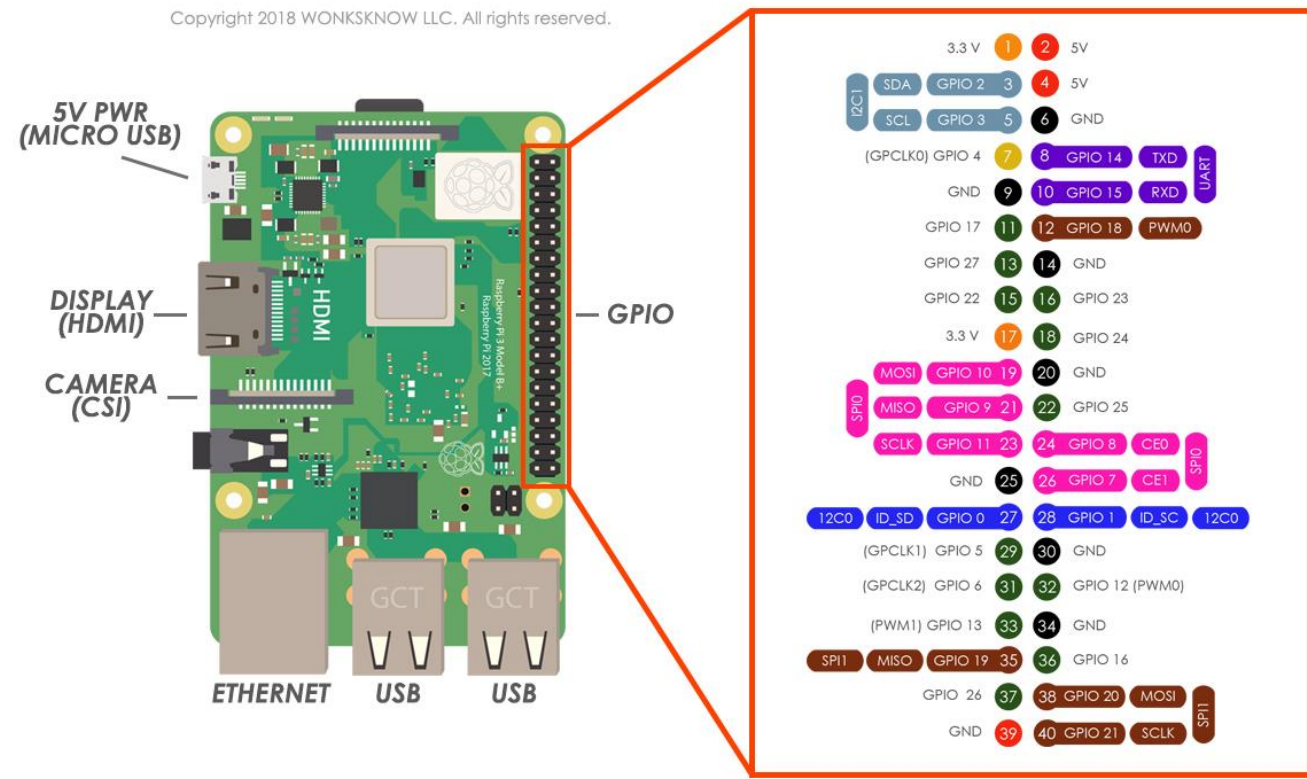
- I. Single-board computer
- II. A set of useful ports
 - a. USBs
 - b. Ethernet
 - c. Hdmi
 - d. MicroUsb
 - e. CSI camera
- III. 40 Pin GPIO





Raspberry Pi 3 model B+ cntd

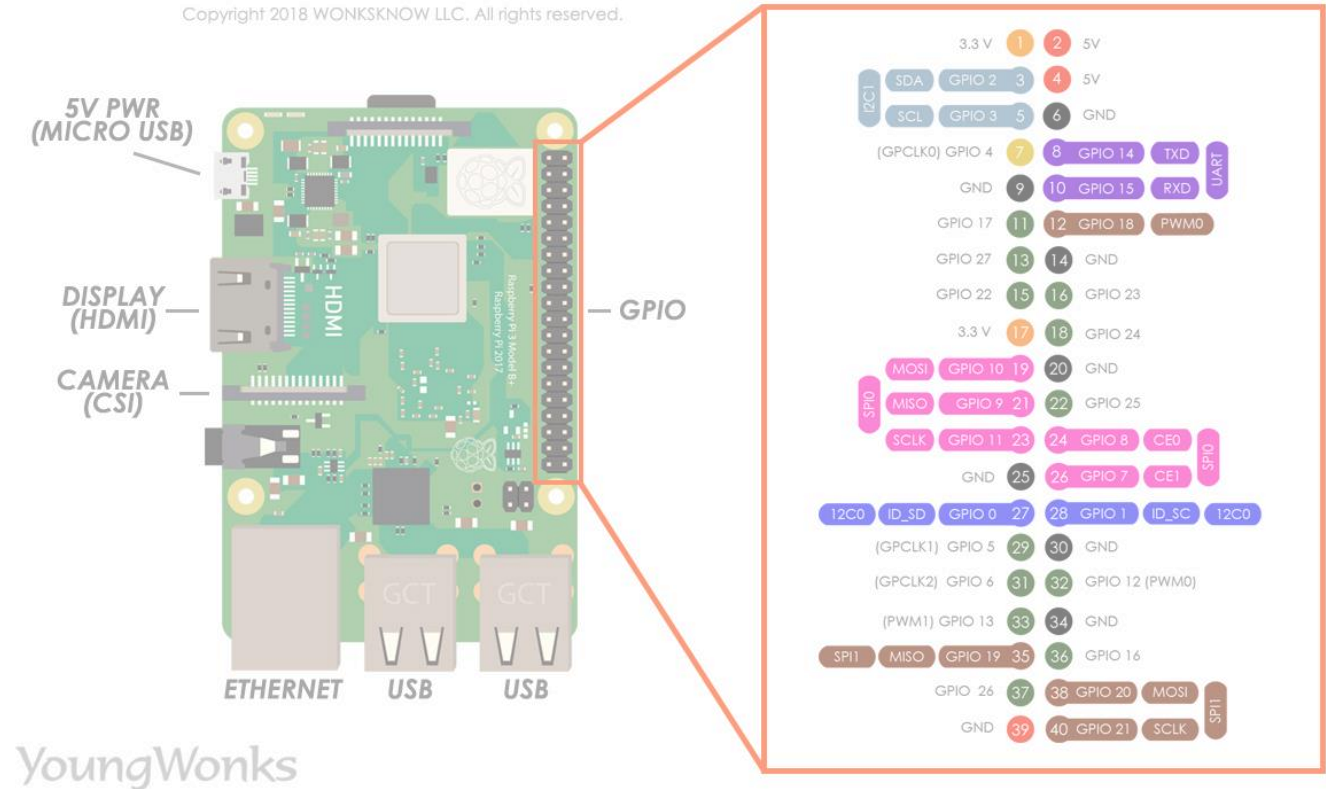
I. Pin Layout



Raspberry Pi 3 model B+ cntd

I. Pin Layout

II. Already connected on the turtlebot!



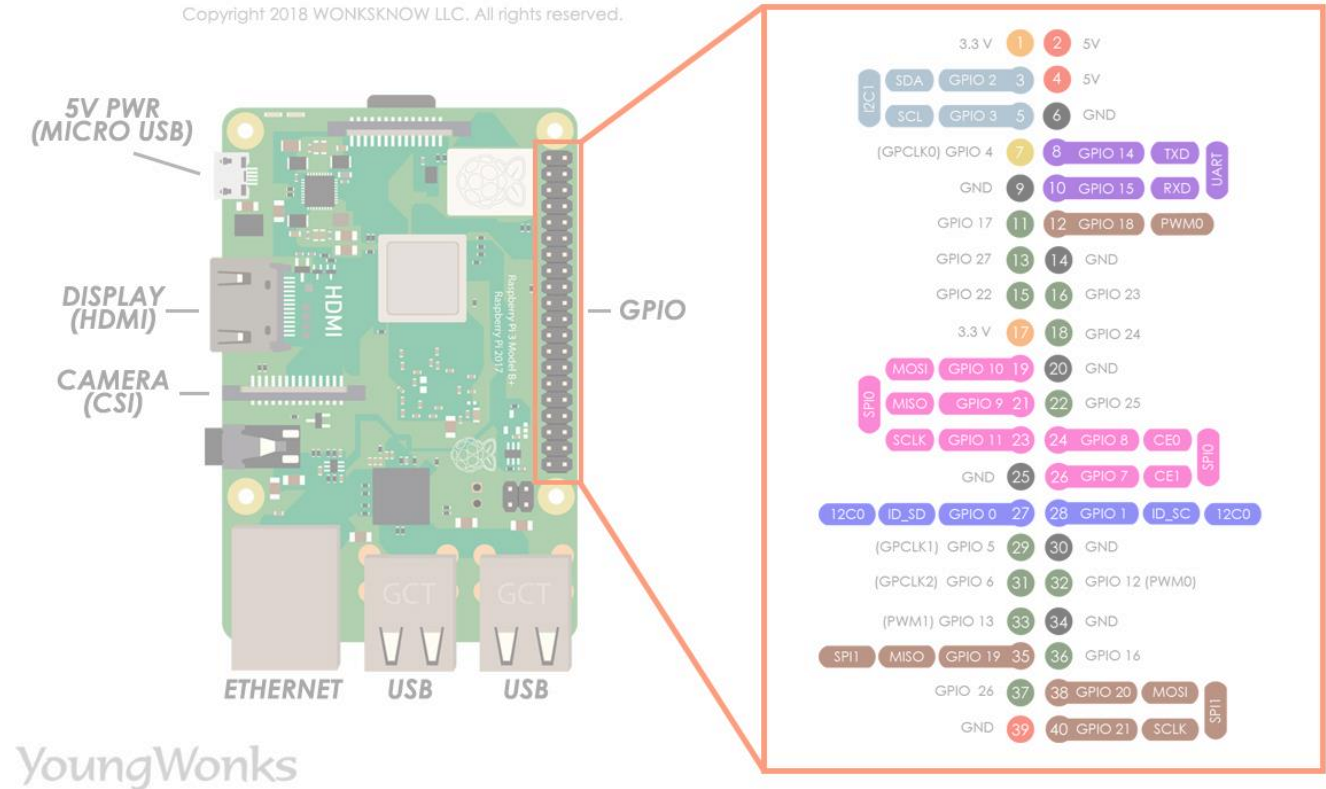
Raspberry Pi 3 model B+ cntd

I. Pin Layout

II. Already connected on the turtlebot!

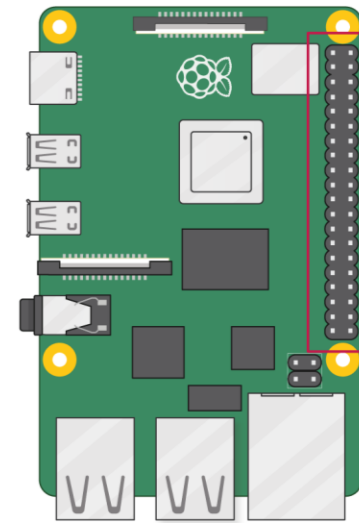
III. Your job today:

a. Communicate with the PI



Raspberry PI 4 ***

- I. 5 robots have a Raspberry 4 instead
 - a. Check the label on top of the lidar
 - b. Usb-c instead of hdmi
 - c. Check for pinout when connecting the sensors



3V3 power	1	2	5V power
GPIO 2 (SDA)	3	4	5V power
GPIO 3 (SCL)	5	6	Ground
GPIO 4 (GPCLK0)	7	8	GPIO 14 (TXD)
Ground	9	10	GPIO 15 (RXD)
GPIO 17	11	12	GPIO 18 (PCM_CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3V3 power	17	18	GPIO 24
GPIO 10 (MOSI)	19	20	Ground
GPIO 9 (MISO)	21	22	GPIO 25
GPIO 11 (SCLK)	23	24	GPIO 8 (CE0)
Ground	25	26	GPIO 7 (CE1)
GPIO 0 (ID_SD)	27	28	GPIO 1 (ID_SC)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
GPIO 13 (PWM1)	33	34	Ground
GPIO 19 (PCM_FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM_DIN)
Ground	39	40	GPIO 21 (PCM_DOUT)

Materials

- I. Checkout: **THE OFFICIAL RASPBERRY PI BEGINNER'S GUIDE**
 - a. **Chapters 1-2: get to know your PI**

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