```
library(lpSolve)
1
2
3
   cvec=c(6,7,9,5,8,9);
4
5
   b=c(120,140,100,60,80);
   condir=rep(">=",5)
6
7
   A=rbind(c(rep(1,3),rep(0,3)),
8
               c(rep(0,3), rep(1,3)),
9
               rep(c(1,0,0),2),
10
               rep(c(0,1,0),2),
               rep(c(0,0,1),2));
11
12
   o=lp(direction = "min",objective.in = cvec,const.mat = A,const.dir = condir,const.rhs = b)
13
   o$solution
14
   o$objval
 > o=lp(direction = "min",objection
 > o$solution
                         60 120
            0 60
                                         0
                                              20
 > o$objval
  [1] 1740
 16
     #2
     cvec=c(3,12,8,10,5,6,6,7,10);
 17
    b=c(90,30,100,70,110,80);
condir=c(rep("=",3),rep("<=",3));
 18
    A=rbind(c(1,1,1,0,0,0,0,0,0,0),
 20
 21
             c(0,0,0,1,1,1,0,0,0),
 22
             c(0,0,0,0,0,0,1,1,1),
 23
             c(1,0,0,1,0,0,1,0,0),
 24
             c(0,1,0,0,1,0,0,1,0),
     c(0,0,1,0,0,1,0,0,1));
o=lp(direction = "min",objective.in = cvec,const.mat = A,const.dir = condir,const.rhs = b)
 25
 26
 27
     o$solution
 28 o$objval
 o=1p(a)rection = min, objective.in = cv
> o$solution
[1]
       70
                   20
                           0
                               10
                                     20
                                             0 100
                                                         0
               0
> o$objval
[1] 1240
< I
```