Introduction

Numerical Methods for Deep Learning

Learning From Data: The Core of Science - 1

Given inputs and outputs, how to choose f?

Option 1 (Fundamental(?) understanding): For example, Galileo's law of motion

$$x(t)=\frac{1}{2}gt^2,$$

with unknown parameter g.

Learning From Data: The Core of Science - 1

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Option 1 (Fundamental(?) understanding): For example, Galileo's law of motion

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with unknown parameter g.

To estimate g observe falling object

t	X
0	0
1	4.9
2	20.1
3	44.1

Goal: Derive model from theory, calibrate it using data.

Learning From Data: The Core of Science - 2

Given inputs and outputs, how to choose f?

Option 2 (Phenomenological models): For example, Archie's law - what is the electrical resistivity of a rock and how it relates to its porosity, ϕ and saturation, S_w ?

$$\rho(\phi, S_w) = a\phi^{n/2}S_w^p$$

a, n, p unknown parameters

Obtaining parameters from observed data and lab experiments on rocks.

Goal: Find model that consistent with fundamental theory, without directly deriving it from theory.

Phenomenological vs. Fundamental

Fundamental laws come from understanding(?) the underlying process. They are **assumed invariant** and can therefore be predictive(?).

Phenomenological models are data-driven. They "work" on some given data. Hard to know what their limitations are.

But ...

- models based on understanding can do poorly weather, economics ...
- models based on data can sometimes do better
- how do we quantify understanding?

Deep Neural Networks: History

- ▶ Neural Networks with a particular (deep) architecture
- Exist for a long time (70's and even earlier) [11, 12, 9]
- Recent revolution computational power and lots of data [1, 10, 8]
- Can perform very well when trained with lots of data
- Applications
 - ► Image recognition [5, 7, 8], segmentation, natural language processing [2, 3, 6]

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- ► A few recent news articles:
 - ► Apple Is Bringing the Al Revolution to Your iPhone, WIRED 2016
 - Why Deep Learning Is Suddenly Changing Your Life, FORTUNE 2016
 - Data Scientist: Sexiest Job of the 21st Century, Harvard Business Rev '17

Learning Objective: Demystify Deep Learning

Artificial Intelligence / Machine Learning

The Dark Secret at the Heart of Al

No one really knows how the most advanced algorithms do what they do. That could be a problem.

by **Will Knight** Apr 11, 2017

Learning objectives of this minicourse:

- look under the hood of some deep learning examples
- describe deep learning mathematically (see also [4])
- expose numerical challenges / approaches to improve DL

DNN - A Quick Overview - 1

Neural networks are data interpolator/classifier when the underlying model is unknown.

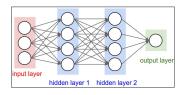
A generic way to write it is

$$\mathbf{c} = f(\mathbf{y}, \boldsymbol{\theta}).$$

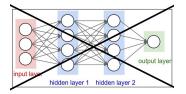
- ▶ the function *f* is the computational model
- $\mathbf{y} \in \mathbb{R}^{n_f}$ is the input data (e.g., an image)
- $\mathbf{c} \in \mathbb{R}^{n_c}$ is the output (e.g. class of the image)
- $m{ heta} \in \mathbb{R}^{n_p}$ are parameters of the model f

In supervised learning we have examples $\{(\mathbf{y}_j,\mathbf{c}_j):j=1,\ldots,n\}$ and the goal is to estimate or "learn" the parameters $\boldsymbol{\theta}$.

DNN - A Quick Overview - 2



DNN - A Quick Overview - 2



$$\begin{cases} \mathbf{y}_{l+1} &= \sigma(\mathbf{K}_l \mathbf{y}_l + \mathbf{b}_l) \\ \mathbf{y}_{l+1} &= \mathbf{y}_l + \sigma(\mathbf{K}_l \mathbf{y}_l + \mathbf{b}_l) \\ \mathbf{y}_{l+1} &= \mathbf{y}_l + \sigma(\mathbf{L}_l \sigma(\mathbf{K}_l \mathbf{y}_l + \mathbf{b}_l)) \\ \vdots \end{cases}$$

Here:

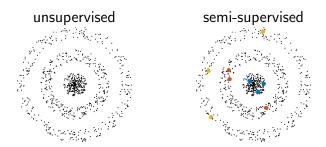
- ▶ I = 0, 1, 2, ..., N is the layer
- $ightharpoonup \sigma: \mathbb{R}
 ightharpoonup \mathbb{R}$ is the activation function
- $lackbr{>} lackbr{y}_0 = lackbr{y} \in \mathbb{R}^{n_f}$ is the input data (e.g., an image)
- ▶ $\mathbf{c} \in \mathbb{R}^{n_c}$ is the output (e.g. class of the image)
- ightharpoonup L_I, K_I, b_I are parameters of the model f

Machine learning (ML) is the scientific study of algorithms and statistical models that computer systems use to perform a specific task without using explicit instructions, relying on patterns and inference instead. (wiki)

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Two common tasks in machine learning:

- given data, cluster it and detect patterns in it (unsupervised learning)
- given data and labels, find a functional relation between them (supervised learning)



Unsupervised learning - given the data set $\mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_n]$ cluster the data into "similar" groups (labels).

- helps find hidden patterns
- often explorative and open-ended

Semisupervised - label the data based on a few examples



trained model



Supervised learning - given the data set $\mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathcal{Y}$ and their labels $\mathbf{C} = [\mathbf{c}_1, \dots, \mathbf{c}_n] \in \mathcal{C}$, find the relation $f: \mathcal{Y} \to \mathcal{C}$

- models range in complexity
- older models based on support vector machines (SVM) and kernel methods
- recently, deep neural networks (DNNs) dominate

Suppose that we have examples $\{\mathbf{y}_j, \mathbf{c}_j\}$, $j=1,\ldots,n$, a model $f(\mathbf{y}, \boldsymbol{\theta})$ and some optimal parameter $\boldsymbol{\theta}^*$. Let $\{(\mathbf{y}_j^t, \mathbf{c}_j^t): j=1,\ldots,s\}$ be some test set, that was not used to compute $\boldsymbol{\theta}^*$.

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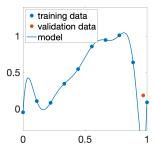
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then the model is predictive - it generalizes well

For phenomenological models, there is no reason why the model should generalize, but in practice it often does.

Why would a model generalize poorly?

$$1 \ll \|f(\mathbf{y}_j^t, \boldsymbol{\theta}^*) - \mathbf{c}_j^t\|_p$$

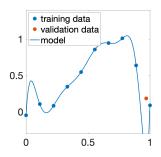


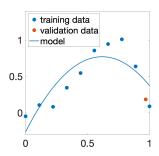
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- 1. Our "optimal" θ^* was optimal for the training but is less so for other data
- 2. The chosen computational model *f* is poor (e.g. quadratic model for a nonlinear function).

Example: Classification of Hand-written Digits

- ▶ Let $\mathbf{y}_i \in \mathbb{R}^{n_f}$ and let $\mathbf{c}_i \in \mathbb{R}^{n_c}$.
- ▶ The vector **c** is the probability of **y** belonging to a certain class. Clearly, $0 \le \mathbf{c}_j \le 1$ and $\sum_{j=1}^{n_c} \mathbf{c}_j = 1$.

Examples (MNIST):



$$\boldsymbol{c}_1 = [0, 0, 0, 0, 1, 0, 0, 0, 0, 0]^\top \quad \boldsymbol{c}_2 = [0, 0.3, 0, 0, 0, 0, 0, 0.7, 0, 0]^\top$$

Example: Classification of Natural Images

Image classification of natural images

Examples (CIFAR-10):

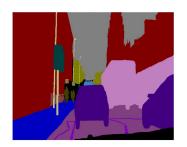


- ▶ let $\mathbf{y}_j \in \mathbb{R}^n$ be an RGB or grey valued image.
- ▶ let the pixels in $\mathbf{c}_i \in \{1, 2, 3, ...\}^k$ denote the labels.

y, input image



c, segmentation (labeled image)



Goal: Find map $\mathbf{c} = f(\mathbf{y}, \boldsymbol{\theta})$

Problem: Given image \mathbf{y} and label \mathbf{c} , find a map $f(\cdot, \boldsymbol{\theta})$ such that $\mathbf{c} \approx f(\mathbf{y}, \boldsymbol{\theta})$

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First step: Reduce the dimensionality of problem.

- extract features from the image
- classify in the feature space

Reduce the problem of learning from the image to feature detection and classification

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Simpler setup

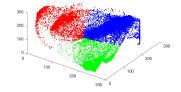
▶ input: **y** is the RGB value of the pixel (and its neighbors?)

▶ output: **c** is a labeled pixel

> goal: map $\mathbf{c} = f(\mathbf{y}, \boldsymbol{\theta})$







input image and segmentation

3D representation of RGB values

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