

Tensor Decomposition Approaches for fMRI Classification

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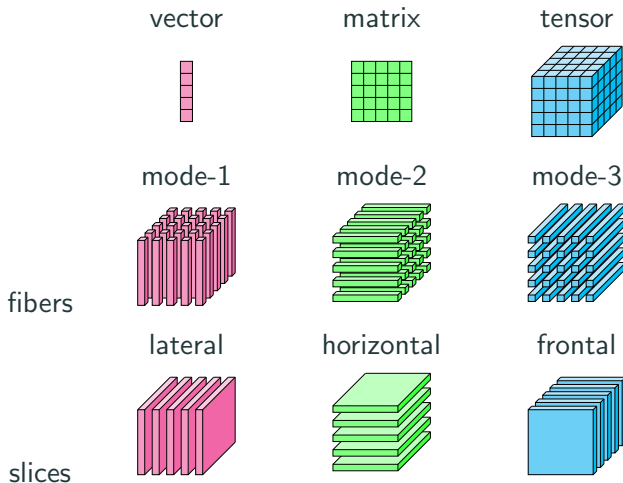
Tensor

A multidimensional array of numbers, representing fMRI 3D brain images in response to stimuli over time.

- Exploit correlations of pixels in space and time,
- Use low rank approximations
- Better representation



Notation



Mode- k Product ($\mathcal{A} \times_k \mathbf{M}$):

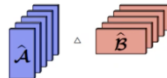
The mode- k product of a tensor \mathcal{A} with a matrix \mathbf{M} results in a tensor whose mode- k unfolding is \mathbf{M} times the mode- k unfolding of \mathcal{A} . In other words, $\mathcal{A} \times_k \mathbf{M} = \text{fold}(\mathbf{M} \mathcal{A}_{(k)})$

Facewise Product ($\hat{\mathcal{A}} \triangle \hat{\mathcal{B}}$):

The facewise product multiplies each of the $n_1 \times n_2$ and $n_2 \times \ell$ frontal slices of two tensors in the transform domain in parallel to create a set of $n_1 \times \ell$ new slices.



$\mathbf{M} \times$



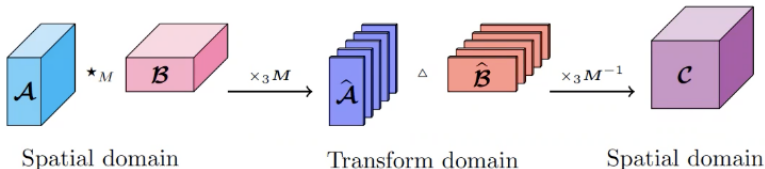
A Family of Tensor-Tensor Products

\star_M -product:

Given the $n_1 \times n_2 \times n_3$ tensor \mathcal{A} , and the $n_2 \times \ell \times n_3$ tensor \mathcal{B} , with an invertible $n_3 \times n_3$ matrix M :

$$\mathcal{C} = \mathcal{A} \star_M \mathcal{B} = (\hat{\mathcal{A}} \triangle \hat{\mathcal{B}}) \times_3 M^{-1}$$

such that \mathcal{C} is an $n_1 \times \ell \times n_3$ tensor.



Data

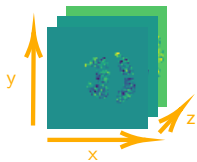
- StarPlus fMRI images of a subject's brain over time
- Multiple trials correspond to each subject
- Each trial corresponds to the subject either reading a sentence or seeing a picture

Questions

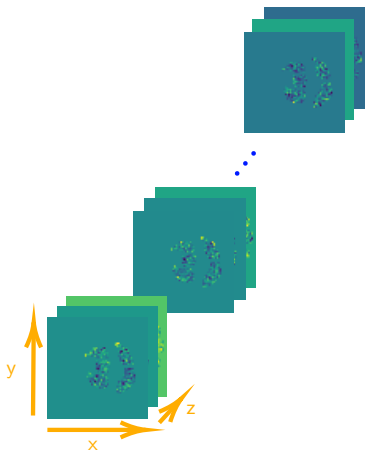
- Are tensor approaches better than matrix approaches to classifying fMRI data (i.e. picture or sentence)?
- If so, what tensor approach is best?



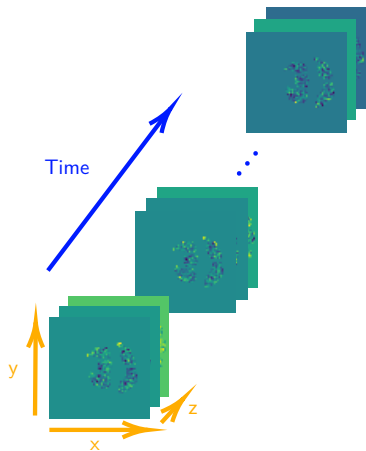
fMRI Data



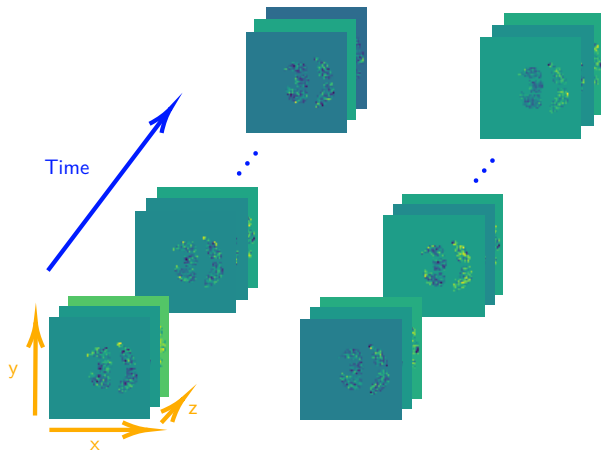
fMRI Data



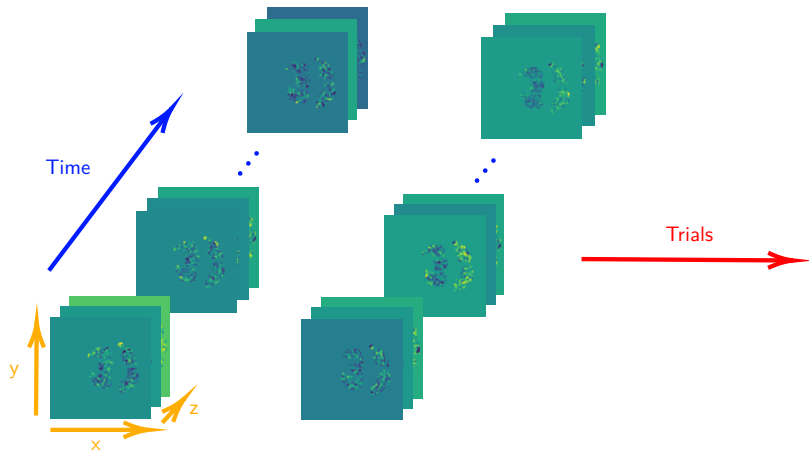
fMRI Data

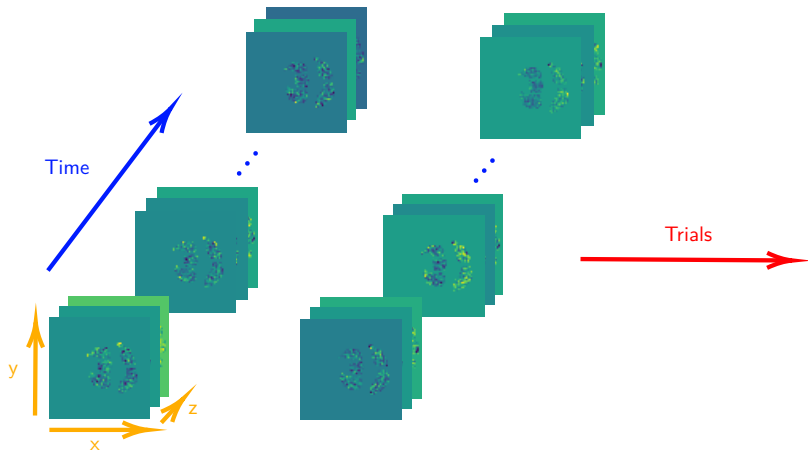


fMRI Data



fMRI Data





5-dimensional representation of data: (**trials**, x , y , z , **time**)

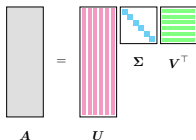


Review of Singular Value Decomposition

- SVD factorizes any matrix \mathbf{A} :

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$$

- Properties
 - Columns of \mathbf{U} can be used as a basis for \mathbf{A}
 - \mathbf{U} and \mathbf{V} are orthogonal
- Highly useful in compression or extracting dominant features

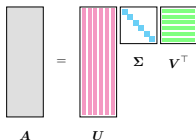


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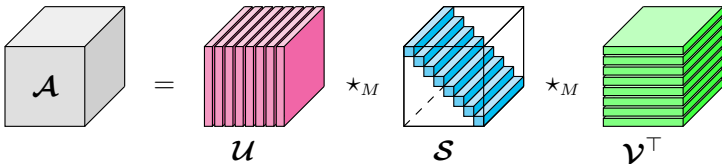
How can this be extended to higher dimensions (tensors)?

t-SVDM (third order)

Given $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ and an invertible $\mathbf{M} \in \mathbb{R}^{n_3 \times n_3}$, the t-SVDM of \mathcal{A} is given by

$$\mathcal{A} = \mathcal{U} \star_M \mathcal{S} \star_M \mathcal{V}^T$$

where $\mathcal{U} \in \mathbb{R}^{n_1 \times n_1 \times n_3}$, $\mathcal{S} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$, $\mathcal{V} \in \mathbb{R}^{n_2 \times n_2 \times n_3}$.



Local t-SVDM Algorithm

- Pre-processing

1. Separate the training dataset \mathcal{A} into distinct classes

$$\mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_{\# \text{ of classes}}$$

2. For each class i , compute a truncated local t-SVDM and store the first k basis elements

$$\mathcal{A}_i = \mathcal{U}_i \star_M \mathcal{S}_i \star_M \mathcal{V}_i^\top \qquad \mathcal{U}_{i,k} = \mathcal{U}_i(:, 1:k, :)$$

The Frobenius norm for third-order tensors is $\|\mathcal{B}\|_F = \sqrt{\sum_{i,j,k} b_{ijk}^2}$.

Newman, Kilmer, and Horesh, *Image classification using local tensor singular value decompositions*

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- For each test image \mathcal{T}

1. For each basis, project a test image onto the space spanned by the class basis

$$\mathcal{P}_i = \mathbf{U}_{i,k} \star_M \mathbf{U}_{i,k}^\top \star_M \mathcal{T}$$

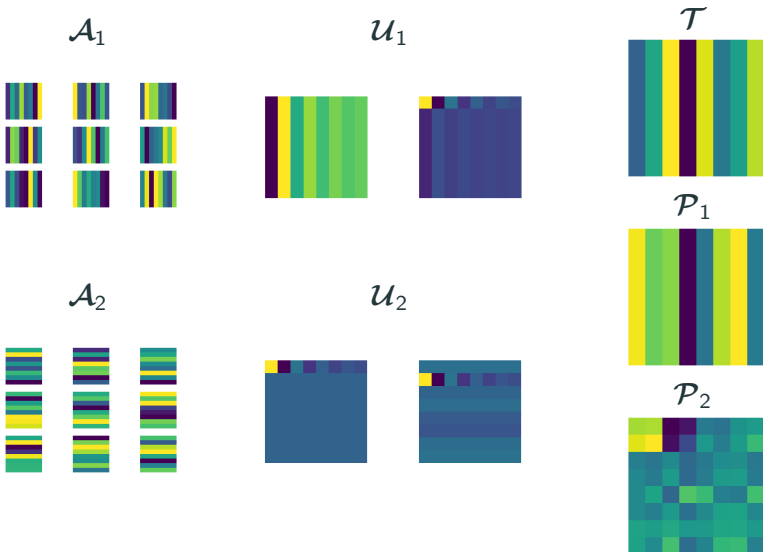
2. Categorize the test image as the class whose projection was "closest" to the original image

$$i^* = \arg \min_i \|\mathcal{T} - \mathcal{P}_i\|_F$$

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Intuition - Stripe Data Example



Choice of M

To use t-SVDM, following M s are selected and implemented:

| Matrix Type | Advantage | Orthogonal |
|-------------------|------------------------|------------|
| Banded | Time Series | No |
| Haar | Capture Data Structure | Yes |
| Random Orthogonal | Base Line | Yes |
| Data-Dependent | Data Matching | Yes |

Special choices of M give us the following products:

| Method Type | Abbreviation | Transformation |
|---------------|--------------|---------------------------|
| Tensor-tensor | t | Fast Fourier Transform |
| Cosine | c | Discrete Cosine Transform |
| Facewise | f | No Transform |

Malik et al., *Tensor Graph Convolutional Networks for Prediction on Dynamic Graphs*

Kernfeld, Kilmer, and Aeron, "Tensor-tensor products with invertible linear transforms"

Preliminary Results

| Attributes | Matrix Approach | Tensor Approach |
|-------------------|---------------------------------------------------|---------------------------------------------|
| Dimensions | ($x \cdot y \cdot z \cdot \text{time}$, trials) | (x , trials, y , z , time) |
| Shape | (524288,26) | (64,26,64,8,16) |
| Computation | Expensive | Parallelizable |
| Transformation | N/A | M can be varied |
| Best Accuracy | 78.6% | 100% |
| (With Parameters) | $k = 4$ | $M = \text{'ddm'}$, $k = 4/5$ |

- Accuracy = number of correct classification in one class/all data points in one class

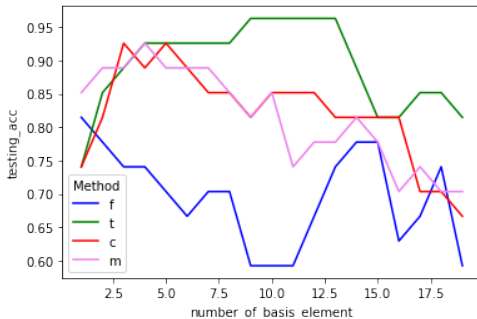


Hyperparameter Tuning

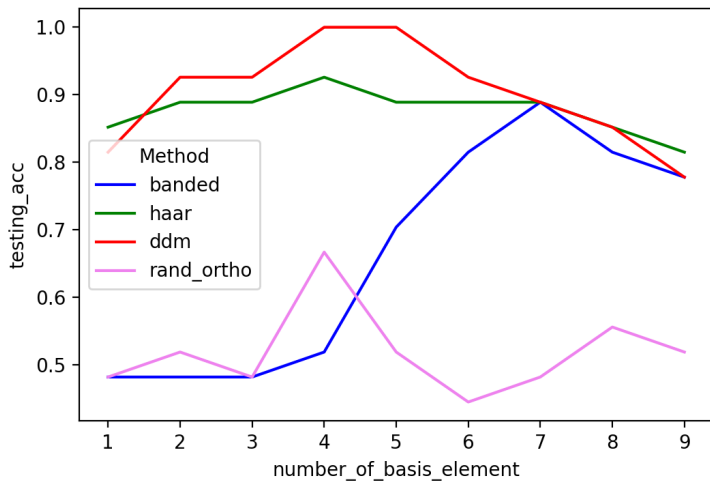
Number of basis elements: Choose the k largest singular values and their corresponding tensors to be our basis element.

Punchline:

low representation power \longleftrightarrow high representation power
small k \longleftrightarrow large k



Choice of M



Conclusion: Tensor approach outperforms matrix approach

Future Work: Experiment with various parameters:

- Transformations (M)
- Bases (k)
- Distance metrics



Thank you!

References



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Choice of M

- Banded Matrix

- Lower triangular and banded matrix. Entries in M on the diagonal and a specific number of subdiagonals are set to 1, while all others are 0. Finally normalization along the row.

- Example (4×4 , bandwidth = 1):
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0.5 & 0.5 & 0 & 0 \\ 0 & 0.5 & 0.5 & 0 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}$$

- Normalized Haar Matrix

- Random Orthogonal Matrix

- Data-Dependent Matrix

- Unfold the tensor to a matrix along an axis (whose dimension later becomes the dimension of M)
- Conduct SVD on the matrix, and U is the M we need here.

