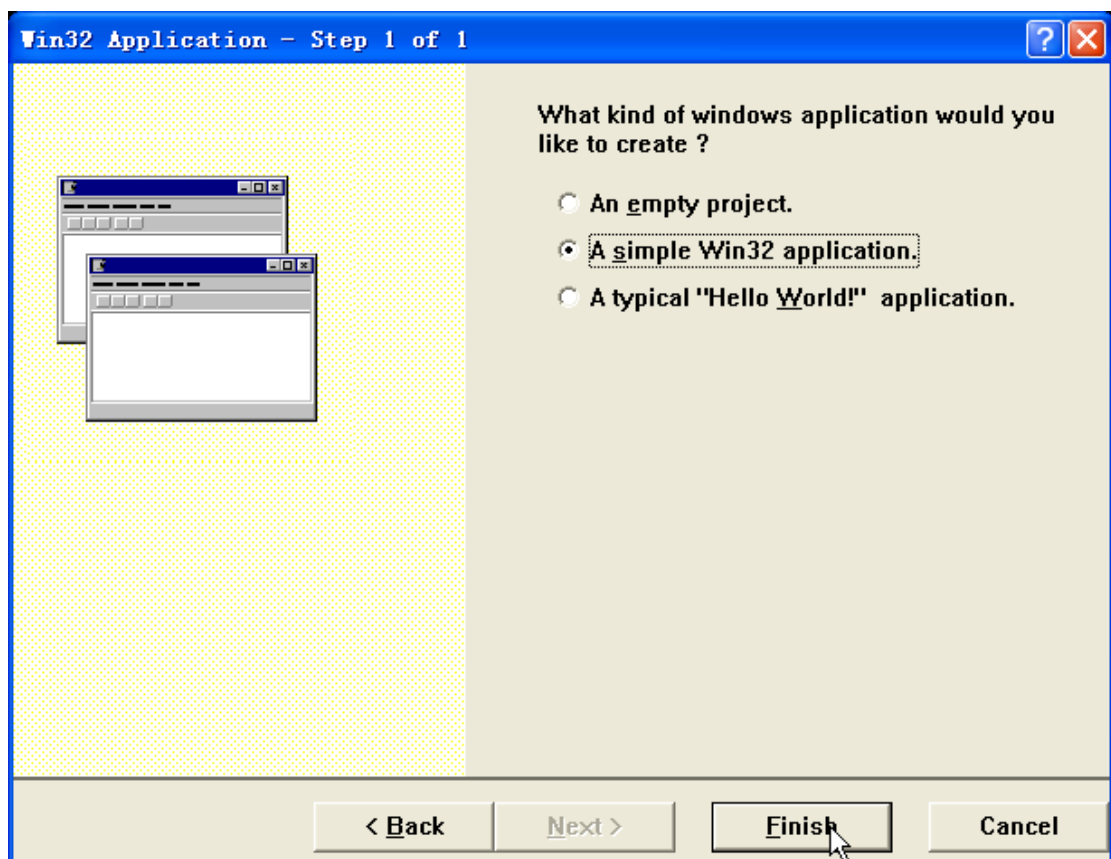
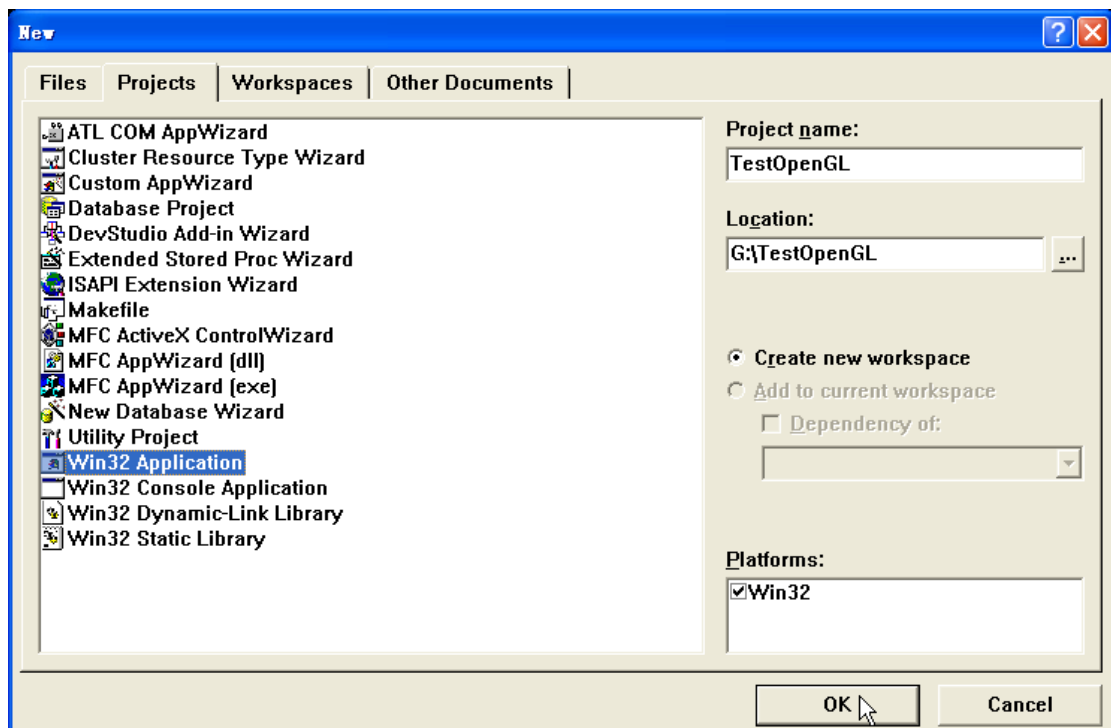
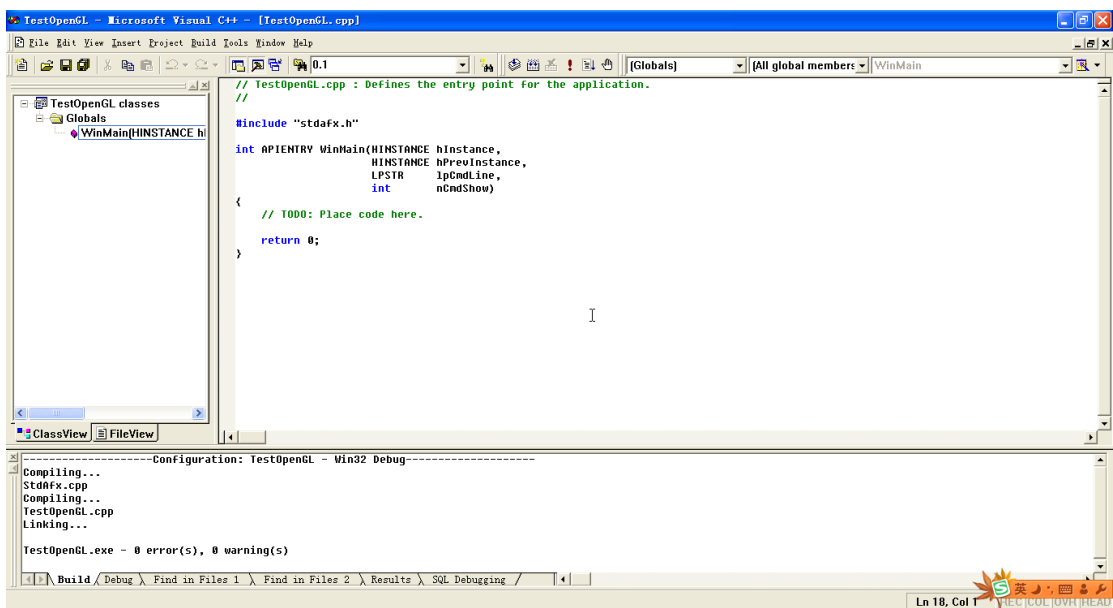
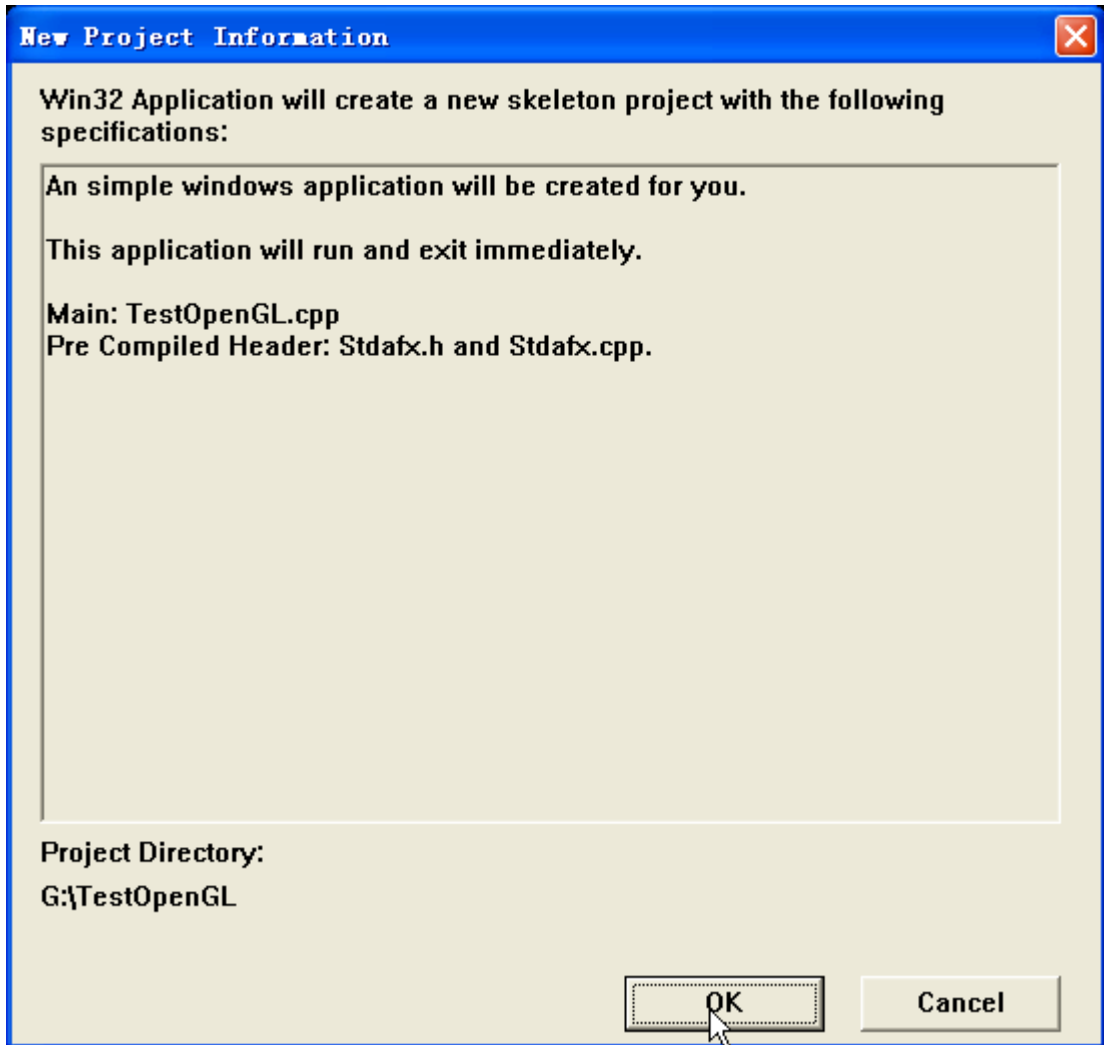
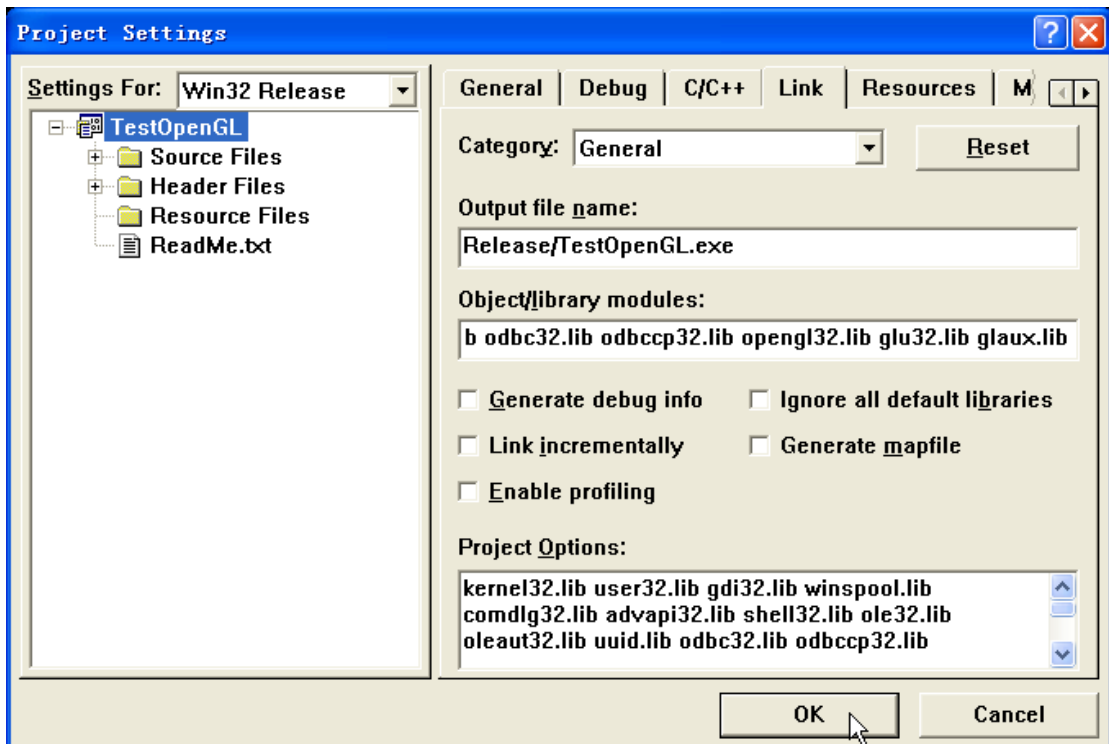


一. 建立一个 Win32 应用程序





二. 设置工程，使其可以进行 OpenGL 编程



三. 包含头文件

```
#include "stdafx.h"
#include <gl\gl.h>           // 核心库
#include <gl\glu.h>          // 实用库
#include <gl\glaux.h>        // 辅助库
```

四. 阅读 Nehe 的教程，编写程序框架，可以实现全屏显示或窗口显示

```
return true; // 一切OK

GLvoid KillGLWindow(GLvoid) // 正常销毁窗口
{
    if (fullscreen) // 是否全屏模式?
    {
        ChangeDisplaySettings(NULL, 0); // 切换回桌面
        ShowCursor(true); // 显示鼠标指针
    }

    if (hRC) // 有着色描述表吗?
    {
        if (!wglMakeCurrent(NULL, NULL)) // 我们能否释放DC和RC描述表?
        {
            MessageBox(NULL, "Release of DC And RC Failed.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        }

        if (!wglDeleteContext(hRC)) // 能否删除RC?
        {
            MessageBox(NULL, "Release Rendering Context Failed.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        }
        hRC=NULL; // Set RC To NULL
    }

    if (hDC && !ReleaseDC(hWnd, hDC)) // 能否释放DC?
    {
        MessageBox(NULL, "Release Device Context Failed.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        hDC=NULL; // Set DC To NULL
    }

    if (hWnd && !DestroyWindow(hWnd)) // 能否销毁窗口?
    {
        MessageBox(NULL, "Could Not Release hWnd.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        hWnd=NULL; // Set hWnd To NULL
    }
}
```

```

        MessageBox(NULL, "Could Not Release hWnd.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        hWnd=NULL; // Set hWnd To NULL
    }

    if (!UnregisterClass("OpenGL", hInstance)) // 能否注销类?
    {
        MessageBox(NULL, "Could Not Unregister Class.", "SHUTDOWN ERROR", MB_OK | MB_ICONINFORMATION);
        hInstance=NULL; // Set hInstance To NULL
    }
}

/* This Code Creates Our OpenGL Window. Parameters Are:
 * title - Title To Appear At The Top Of The Window
 * width - Width Of The GL Window Or Fullscreen Mode
 * height - Height Of The GL Window Or Fullscreen Mode
 * bits - Number Of Bits To Use For Color (8/16/24/32)
 * fullscreenflag - Use Fullscreen Mode (true) Or Windowed Mode (false) */

bool CreateGLWindow(char* title, int width, int height, int bits, bool fullscreenflag)
{
    GLuint PixelFormat; // 保存查找匹配的结果
    WNDCLASS wc; // 窗口类结构
    DWORD dwExStyle; // 扩展窗口风格
    DWORD dwStyle; // 窗口风格
    RECT WindowRect; // 取得矩形的左上角和右下角的坐标值
    WindowRect.left=(long)0; // Set Left Value To 0
    WindowRect.right=(long)width; // Set Right Value To Requested Width
    WindowRect.top=(long)0; // Set Top Value To 0
    WindowRect.bottom=(long)height; // Set Bottom Value To Requested Height

    fullscreen=fullscreenflag; // 设置全局全屏标记

    hInstance = GetModuleHandle(NULL); // 取得窗口的实例
    wc.style = CS_HREDRAW | CS_VREDRAW | CS_OVNDNC; // 移动时重画, 并为窗口取得DC.
    wc.hCursor = LoadCursor(NULL, IDC_ARROW); // 装入鼠标指针
    wc.hbrBackground = NULL; // GL不需要背景
    wc.lpszMenuName = NULL; // 不需要菜单
    wc.lpszClassName = "OpenGL"; // 设定类名字

    if (!RegisterClass(&wc)) // 尝试注册窗口类
    {
        MessageBox(NULL, "Failed To Register The Window Class.", "ERROR", MB_OK | MB_ICONEXCLAMATION);
        return false;
    }

    if (fullscreen) // 尝试全屏模式?
    {
        DEVMODE dmScreenSettings; // 设备模式
        memset(&dmScreenSettings, 0, sizeof(dmScreenSettings)); // 确保内存分配
        dmScreenSettings.dmSize=sizeof(dmScreenSettings); // Size Of The Devmode Structure
        dmScreenSettings.dmPelsWidth = width; // Selected Screen Width
        dmScreenSettings.dmPelsHeight = height; // Selected Screen Height
        dmScreenSettings.dmBitsPerPel = bits; // Selected Bits Per Pixel
        dmScreenSettings.dmFields=DM_BITSPERPEL | DM_PELSWIDTH | DM_PELSHEIGHT;

        // 尝试设置显示模式并返回结果。注: CDS_FULLSCREEN 移去了状态条。
        if (ChangeDisplaySettings(&dmScreenSettings, CDS_FULLSCREEN)!=DISP_CHANGE_SUCCESSFUL)
        {
            // 若模式失败, 提供两个选项, 退出或在窗口内运行
            if (MessageBox(NULL, "The Requested Fullscreen Mode Is Not Supported By\nYour Video Card. Use Windowed Mode Instead?", "NeH
            {
                fullscreen=false; // 选择窗口模式
            }
            else
            {
                // 如果用户选择退出, 弹出消息窗口告知用户程序将结束。
                MessageBox(NULL, "Program Will Now Close.", "ERROR", MB_OK | MB_ICONSTOP);
                return false; // Return false
            }
        }
        return false; // Return false
    }

    if (fullscreen) // 仍处于全屏模式?
    {
        dwExStyle=WS_EX_APPWINDOW; // 扩展窗体风格
        dwStyle=WS_POPUP; // 窗体风格
        ShowCursor(false); // 隐藏鼠标指针
    }
    else
    {
        dwExStyle=WS_EX_APPWINDOW | WS_EX_WINDOWEDGE; // 扩展窗体风格
        dwStyle=WS_OVERLAPPEDWINDOW; // 窗体风格
    }

    AdjustWindowRectEx(&WindowRect, dwStyle, false, dwExStyle); // Adjust Window To True Requested Size

    // Create The Window
    if (!hWnd=CreateWindowEx( dwExStyle, // Extended Style For The Window
        "OpenGL", // Class Name
        title, // Window Title
        dwStyle | // Defined Window Style
        WS_CLIPSIBLINGS | // Required Window Style
        WS_CLIPCHILDREN, // Required Window Style
        0, 0, // Window Position
        WindowRect.right-WindowRect.left, // Calculate Window Width
        WindowRect.bottom-WindowRect.top, // Calculate Window Height
        NULL, // No Parent Window
        NULL, // No Menu
        hInstance, // Instance
        NULL))) // Dont Pass Anything To WM_CREATE
    {
        return false; // Report The Problem
    }
}

```

```

        return false; // Return False
    }

    static PIXELFORMATDESCRIPTOR pfd= // pfd Tells Windows How We Want Things To Be
    {
        sizeof(PIXELFORMATDESCRIPTOR), // Size Of This Pixel Format Descriptor
        1, // Version Number
        PFD_DRAW_TO_WINDOW | // Format Must Support Window
        PFD_SUPPORT_OPENGL | // Format Must Support OpenGL
        PFD_DOUBLEBUFFER, // Must Support Double Buffering
        PFD_TYPE_RGBA, // Request An RGBA Format
        bits, // Select Our Color Depth
        0, 0, 0, 0, 0, 0, // Color Bits Ignored
        0, // No Alpha Buffer
        0, // Shift Bit Ignored
        0, // No Accumulation Buffer
        0, 0, 0, 0, // Accumulation Bits Ignored
        16, // 16Bit Z-Buffer (Depth Buffer)
        0, // No Stencil Buffer
        0, // No Auxiliary Buffer
        PFD_MAIN_PLANE, // Main Drawing Layer
        0, // Reserved
        0, 0, 0 // Layer Masks Ignored
    };

    if (!hDC=GetDC(hWnd)) I // 取得设备描述表了么?
    {
        KillGLWindow(); // Reset The Display
        MessageBox(NULL, "Can't Create A GL Device Context.", "ERROR", MB_OK|MB_ICONEXCLAMATION);
        return false; // Return False
    }

    if (!PixelFormat=ChoosePixelFormat(hDC, &pfd)) // Did Windows Find A Matching Pixel Format?
    {
        KillGLWindow(); // Reset The Display
    }

    if (!hRC=wglCreateContext(hDC)) // Are We Able To Get A Rendering Context?
    {
        KillGLWindow(); // Reset The Display
        MessageBox(NULL, "Can't Create A GL Rendering Context.", "ERROR", MB_OK|MB_ICONEXCLAMATION);
        return false; // Return False
    }

    if (!wglMakeCurrent(hDC, hRC)) // Try To Activate The Rendering Context
    {
        KillGLWindow(); // Reset The Display
        MessageBox(NULL, "Can't Activate The GL Rendering Context.", "ERROR", MB_OK|MB_ICONEXCLAMATION);
        return false; // Return False
    }

    ShowWindow(hWnd, SW_SHOW); // 显示窗口
    SetForegroundWindow(hWnd); // Slightly Higher Priority
    SetFocus(hWnd); // 设置键盘的焦点至窗口
    ResizeGLScene(width, height); // 设置透视GL屏幕

    if (!InitGL()) // Initialize Our Newly Created GL Window
    {
        KillGLWindow(); // Reset The Display
        MessageBox(NULL, "Initialization Failed.", "ERROR", MB_OK|MB_ICONEXCLAMATION);
        return false; // Return False
    } I

    return true; // Success
}

LRESULT CALLBACK WndProc( HWND hWnd, // Handle For This Window
                          UINT uMsg, // Message For This Window
                          WPARAM wParam, // Additional Message Information
                          LPARAM lParam) // Additional Message Information
{
    return false; // Return False
}

return true; // Success
}

LRESULT CALLBACK WndProc( HWND hWnd, // Handle For This Window
                          UINT uMsg, // Message For This Window
                          WPARAM wParam, // Additional Message Information
                          LPARAM lParam) // Additional Message Information
{
    switch (uMsg) // Check For Windows Messages
    {
        case WM_ACTIVATE: // Watch For Window Activate Message
        {
            if (!HIWORD(wParam)) // Check Minimization State
            {
                active=true; // Program Is Active
            }
            else
            {
                active=false; // Program Is No Longer Active
            }

            return 0; // Return To The Message Loop
        }

        case WM_SYSCOMMAND: I // Intercept System Commands
        {
            switch (wParam) // Check System Calls
            {
                case SC_SCREENSAVE: // Screensaver Trying To Start?
                case SC_MONITORPOWER: // Monitor Trying To Enter Powersave?
                return 0; // Prevent From Happening
            }
        }
    }
}

```

```

        {
            case SC_SCREENSAVE: // Screensaver Trying To Start?
            case SC_MONITORPOWER: // Monitor Trying To Enter Powersave?
                return 0; // Prevent From Happening
            break; // Exit
        }

    case WM_CLOSE: // Did We Receive A Close Message?
    {
        PostQuitMessage(0); // Send A Quit Message
        return 0; // Jump Back
    }

    case WM_KEYDOWN: // Is A Key Being Held Down?
    {
        keys[wParam] = true; // If So, Mark It As true
        return 0; // Jump Back
    }

    case WM_KEYUP: // Has A Key Been Released?
    {
        keys[wParam] = false; // If So, Mark It As false
        return 0; // Jump Back
    }

    case WM_SIZE: // Resize The OpenGL Window
    {
        ResizeGLScene(LOWORD(lParam), HIWORD(lParam)); // LoWord=Width, HiWord=Height
        return 0; // Jump Back
    }
}

// Pass All Unhandled Messages To DefWindowProc
return DefWindowProc(hWnd, uMsg, wParam, lParam);
}

// Pass All Unhandled Messages To DefWindowProc
return DefWindowProc(hWnd, uMsg, wParam, lParam);
}

int WINAPI WinMain( HINSTANCE hInstance, // 实例
                   HINSTANCE hPrevInstance, // 前一个实例
                   LPSTR lpCmdLine, // 命令行参数
                   int nCmdShow) // 窗口显示状态
{
    MSG msg; // Windows Message Structure
    bool done=false; // Bool Variable To Exit Loop

    nFullWidth = GetSystemMetrics(SM_CXSCREEN);
    nFullHeight = GetSystemMetrics(SM_CYSCREEN);

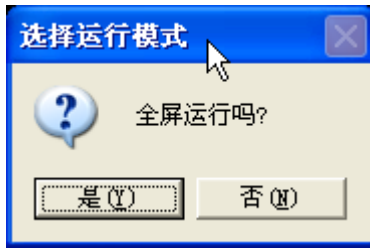
    // Ask The User Which Screen Mode They Prefer
    if (MessageBox(NULL, "全屏运行吗?", "选择运行模式", MB_YESNO|MB_ICONQUESTION)==IDNO)
    {
        fullscreen=false; // 窗口模式
    }

    // Create Our OpenGL Window
    if (!CreateGLWindow("机器人", nFullWidth, nFullHeight, 32, fullscreen))
    {
        return 0; // Quit If Window Was Not Created
    }
    Reset();

    while(!done)
    {
        if (PeekMessage(&msg, NULL, 0, 0, PM_REMOVE)) // Is There A Message Waiting?
        {
            return 0; // Quit If Window Was Not Created
        }
        Reset();

        while(!done)
        {
            if (PeekMessage(&msg, NULL, 0, 0, PM_REMOVE)) // Is There A Message Waiting?
            {
                if (msg.message==WM_QUIT) // Have We Received A Quit Message?
                {
                    glClearColor(0.0f, 0.0f, 0.0f, 0.0f);
                    glClearDepth(1.0);
                    glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
                    done=true; // If So done=true
                }
                else // If Not, Deal With Window Messages
                {
                    TranslateMessage(&msg); // Translate The Message
                    DispatchMessage(&msg); // Dispatch The Message
                }
            }
            else // If There Are No Messages
            {
                // Draw The Scene. Watch For ESC Key And Quit Messages From DrawGLScene()
                if (active) // Program Active?
                {
                    if (keys[VK_ESCAPE]) // Was ESC Pressed?
                    {
                        glClearColor(0.0f, 0.0f, 0.0f, 0.0f);
                        glClearDepth(1.0);
                        glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
                        done=true; // ESC Signalled A Quit
                    }
                    else // Not Time To Quit, Update Screen

```



五. 在绘图函数中添加代码, 通过计算坐标, 绘制出一个漂亮的机器人形体

```

        return true; // 初始化 OK
    }

    //绘图函数
    int DrawGLScene(GLvoid)
    {
        //设置清除屏幕的颜色, 并清除屏幕和深度缓冲
        glClearColor(0.0f, 0.0f, 0.0f, 0.0f);
        glClearDepth(1.0);
        glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
        G_vLitPosition[0] = 5.0f + G_fLightx;

        //设置光照
        glMatrixMode(GL_MODELVIEW);
        glLoadIdentity();
        glLightfv(GL_LIGHT0, GL_AMBIENT, G_vLitAmbient);
        glLightfv(GL_LIGHT0, GL_DIFFUSE, G_vLitDiffuse);
        glLightfv(GL_LIGHT0, GL_SPECULAR, G_vLitSpecular);
        glLightf(GL_LIGHT0, GL_SPOT_EXPONENT, 3.0f);
        glLightfv(GL_LIGHT0, GL_POSITION, G_vLitPosition);
        glLightModel(GL_LIGHT_MODEL_TWO_SIDE, 1.0);

        glColorMaterial(GL_FRONT, GL_DIFFUSE);
        glEnable(GL_COLOR_MATERIAL);
        //打开光照
        glEnable(GL_LIGHTING);
        glEnable(GL_LIGHT0);

        //变换并绘制物体
        glMatrixMode(GL_MODELVIEW);
        glLoadIdentity();

        //坐标中心向z轴平移-G_fDistance (使坐标中心位于摄像机前方)
        //变换并绘制物体
        glMatrixMode(GL_MODELVIEW);
        glLoadIdentity();

        //坐标中心向z轴平移-G_fDistance (使坐标中心位于摄像机前方)
        glTranslatef(G_fDistance_horizon, G_fDistance_vertical, -G_fDistance);
        // glTranslatef(G_fDistance_horizon, 0.0, 0.0);
        // glTranslatef(0.0, G_fDistance_vertical, 0.0);
        glRotatef(G_fAngle_horizon, 0.0f, 1.0f, 0.0f);
        glRotatef(G_fAngle_vertical, 1.0f, 0.0f, 0.0f);

        //脑袋
        glPushMatrix();
        glTranslatef(0, 1, 0);
        glRotatef(G_fHead_Ang, 0, 1, 0);
        glColor3f(MYCOLOR);
        if(wire)
            auxWireSphere(0.5);
        else
            auxSolidSphere(0.5);

        //鼻子
        glPushMatrix();
        glTranslatef(0, -0.1f, 0.5f);
        glColor3f(0.973f, 0.973f, 1.0f);
        if(wire)
            auxWireBox(0.05, 0.15, 0.05);
        else
            auxSolidBox(0.05, 0.15, 0.05);

        //嘴巴
        glTranslatef(0, -0.2f, -0.4f);
    }

```

```

//嘴巴
glTranslatef(0, -0.2f, -0.1f);
glColor3f(1.0f, 0.753f, 0.796f);
if(wire)
    auxWireBox(0.1f, 0.02f, 0.05f);
else
    auxSolidBox(0.1f, 0.02f, 0.05f);

//眼睛
glPushMatrix();
glColor3f(0.118f, 0.565f, 1.0f);
glTranslatef(-0.15f, 0.4f, 0.07f);
if(wire)
    auxWireSphere(0.05);
else
    auxSolidSphere(0.05);
glTranslatef(0.3f, 0.0f, 0.0f);
if(wire)
    auxWireSphere(0.05);
else
    auxSolidSphere(0.05);
glPopMatrix();
glPopMatrix();
glPopMatrix();

glPushMatrix();
//身体
glTranslatef(0.0f, 0.0f, -0.2f);
glRotatef(90, 0, 1, 0);
glColor3f(MV_COLOR);
if(wire)
    auxWireIcosahedron(0.75);
else
    auxSolidIcosahedron(0.75);

glPopMatrix();
glPushMatrix();

//右手
glTranslatef(0.65f, 0.0f, 0);
glColor3f(MV_COLOR);
if(wire)
    auxWireSphere(0.1);
else
    auxSolidSphere(0.1);
glRotatef(G_FRArm_Ang, 1, 0, 0);
glRotatef(G_FRArm_Ang + 180, 0, 0, -1);
glTranslatef(0, -0.5, 0);
glColor3f(MV_COLOR);

if(wire)
    auxWireCylinder(0.1, 0.5);
else
    auxSolidCylinder(0.1, 0.5);
glTranslatef(0.0, 1.0, 0.0);
glColor3f(MV_COLOR);

if(wire)
    auxWireSphere(0.1);
else
    auxSolidSphere(0.1);

glRotatef(-G_FRArm_Ang + G_FRDArm_Ang, 0, 0, -1); //侧抬降右下臂
glTranslatef(0, -0.5, 0);
glColor3f(MV_COLOR);

if(wire)
    auxWireCylinder(0.1, 0.5);
else
    auxSolidCylinder(0.1, 0.5);
glTranslatef(0, 1, 0);
glColor3f(MV_COLOR);

if(wire)
{
    auxWireSphere(0.1);
    auxWireOctahedron(0.135);
}
else
{
    auxSolidSphere(0.1);
    auxSolidOctahedron(0.135);
}

glPopMatrix();
glPushMatrix();

//左手
glColor3f(MV_COLOR);
glTranslatef(-0.65f, 0.0f, 0);
if(wire)
    auxWireSphere(0.1);
else
    auxSolidSphere(0.1);
glRotatef(G_FLArm_Ang, 1, 0, 0); //前后抬手臂
glRotatef(G_FLArm_Ang - 180, 0, 0, -1); //侧抬降左上臂
glTranslatef(0, -0.5, 0);
glColor3f(MV_COLOR);
if(wire)
    auxWireCylinder(0.1, 0.5);
else
    auxSolidCylinder(0.1, 0.5);
glTranslatef(0, 1, 0);
glColor3f(MV_COLOR);

```



```

        if(wire)
            auxWireSphere(0.1);
        else
            auxSolidSphere(0.1);
        glRotatef(-G_FLArm_Ang + G_FLDArm_Ang, 0, 0, -1); //侧抬降左下臂
        glTranslatef(0, -0.5, 0);
        glColor3f(MYCOLOR);
        if(wire)
            auxWireCylinder(0.1, 0.5);
        else
            auxSolidCylinder(0.1, 0.5);
        glTranslatef(0, 1, 0);
        glColor3f(MYCOLOR);
        if(wire)
        {
            auxWireSphere(0.1);
            auxWireOctahedron(0.135);
        }
        else
        {
            auxSolidSphere(0.1);
            auxSolidOctahedron(0.135);
        }
    }
    glPopMatrix();

    glPushMatrix();
    ////////////////////////////////////////
    //右腿
    glTranslatef(0.25f, -0.6f, 0.0f);
    glRotatef(G_FRLeg_Horizon, 0, 0, -1);
    glRotatef(180 + G_FRLeg_Ang, 1.0f, 0.0f, 0.0f); //抬右大腿
    glColor3f(MYCOLOR);
    if(wire)
        auxWireSphere(0.15);
    else
        auxSolidSphere(0.15);

    //右腿
    glTranslatef(0.25f, -0.6f, 0.0f);
    glRotatef(G_FRLeg_Horizon, 0, 0, -1);
    glRotatef(180 + G_FRLeg_Ang, 1.0f, 0.0f, 0.0f); //抬右大腿
    glColor3f(MYCOLOR);
    if(wire)
        auxWireSphere(0.15);
    else
        auxSolidSphere(0.15);
    glTranslatef(0, -0.18f, 0);
    glColor3f(MYCOLOR);

    if(wire)
        auxWireCylinder(0.15, 0.8);
    else
        auxSolidCylinder(0.15, 0.8);
    glTranslatef(0, 1, 0);
    glColor3f(MYCOLOR);
    if(wire)
        auxWireSphere(0.15);
    else
        auxSolidSphere(0.15);
    glRotatef(-G_FRLeg_Ang + G_FRCalf_Ang, 1.0, 0.0, 0.0); //抬右小腿
    glTranslatef(0, -0.5, 0);
    glColor3f(MYCOLOR);
    if(wire)
        auxWireCylinder(0.15, 0.5);
    else
        auxSolidCylinder(0.15, 0.5);
    glTranslatef(0, 1, 0);
    glColor3f(MYCOLOR);
    if(wire)
    {
        auxWireSphere(0.15);
        auxWireOctahedron(0.202);
    }
    else
    {
        auxSolidSphere(0.15);
        auxSolidOctahedron(0.202);
    }
    glRotatef(180, 0, 1, 0);

    if(wire)
    {
        auxWireCone(0.15, 0.15);
        auxWireTetrahedron(0.3);
    }
    else
    {
        auxSolidCone(0.15, 0.15);
        auxSolidTetrahedron(0.3);
    }
}
glPopMatrix();

glPushMatrix();
//////////////////////////////////////
//左腿
glTranslatef(-0.25f, -0.6f, 0.0f);
glRotatef(G_FLLeg_Horizon, 0, 0, -1);
glRotatef(180 + G_FLLeg_Ang, 1.0f, 0.0f, 0.0f); //抬左大腿
glColor3f(MYCOLOR);
if(wire)
    auxWireSphere(0.15);
else
    auxSolidSphere(0.15);

```

```

//左腿
glTranslatef(-0.25f, -0.6f, 0.0f);
glRotatef(G_FLLeg_Horizon, 0, 0, -1);
glRotatef(180 + G_FLLeg_Ang, 1.0f, 0.0f, 0.0f); //抬左大腿
glColor3f(MVCOLOR);
if(wire)
    auxWireSphere(0.15);
else
    auxSolidSphere(0.15);
glTranslatef(0, -0.18f, 0);
glColor3f(MVCOLOR);

if(wire)
    auxWireCylinder(0.15, 0.8);
else
    auxSolidCylinder(0.15, 0.8);
glTranslatef(0, 1, 0);
glColor3f(MVCOLOR);
if(wire)
    auxWireSphere(0.15);
else
    auxSolidSphere(0.15);
glRotatef(-G_FLLeg_Ang + G_FL calf_Ang, 1.0, 0.0, 0.0); //抬右小腿
glTranslatef(0, -0.5, 0);
glColor3f(MVCOLOR);
if(wire)
    auxWireCylinder(0.15, 0.5);
else
    auxSolidCylinder(0.15, 0.5);
glTranslatef(0, 1, 0);
glColor3f(MVCOLOR);
if(wire)
{
    auxWireSphere(0.15);
    auxWireOctahedron(0.202);
}
else
{
    auxSolidCylinder(0.15, 0.5);
    glTranslatef(0, 1, 0);
    glColor3f(MVCOLOR);
    if(wire)
    {
        auxWireSphere(0.15);
        auxWireOctahedron(0.202);
    }
    else
    {
        auxSolidSphere(0.15);
        auxSolidOctahedron(0.202);
    }
}
glRotatef(90, 0, 1, 0);

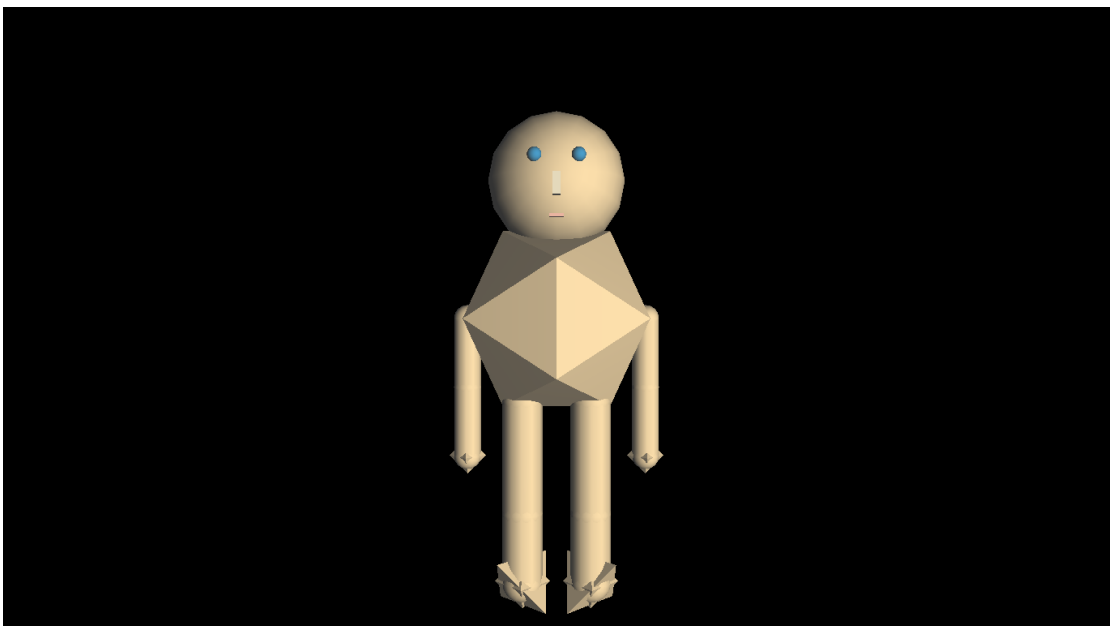
if(wire)
{
    auxWireCone(0.15, 0.15);
    auxWireTetrahedron(0.3);
}
else
{
    auxSolidCone(0.15, 0.15);
    auxSolidTetrahedron(0.3);
}
glPopMatrix();

auxSwapBuffers();

return true; // 一切OK
}

GLvoid KillGLWindow(GLvoid) // 正常销毁窗口
{

```



六. 添加函数，修改绘制机器人过程中的各个角度参数，并响应键盘消息，实现对机器人形状的控制

```
int nFullWidth;
int nFullHeight;

////////////////////////////////////
//远近距离
float G_fDistance;

//水平移动距离
float G_fDistance_horizon;

//垂直移动距离
float G_fDistance_vertical;

//水平旋转角度
float G_fAngle_horizon;

//垂直旋转角度
float G_fAngle_vertical;

//右上臂旋转角度
float G_fRArm_Ang;

//左上臂旋转角度
float G_fLArm_Ang;

//右大腿旋转角度
float G_fRLeg_Ang;

//左大腿旋转角度
float G_fLLeg_Ang;

//右小腿旋转角度
float G_fRCalf_Ang;

//左小腿旋转角度

//右上臂旋转角度
float G_fRArm_Ang;

//左上臂旋转角度
float G_fLArm_Ang;

//右大腿旋转角度
float G_fRLeg_Ang;

//左大腿旋转角度
float G_fLLeg_Ang;

//右小腿旋转角度
float G_fRCalf_Ang;

//左小腿旋转角度
float G_fLCalf_Ang;

//右下臂旋转角度
float G_fRDarm_Ang;

//左下臂旋转角度
float G_fLDarm_Ang;

//右上臂旋转角度
float G_fRArmF_Ang;

//左下臂旋转角度
float G_fLDarmF_Ang;

//右大腿旋转角度
float G_fRLeg_Ang;

//左大腿旋转角度
float G_fLLeg_Ang;

//光照角度
float G_fLightx;

//光照参数
float G_uLitAmbient[4] = { 0.8F, 0.8F, 0.8F, 1.0F };

float G_uLitDiffuse[4] = { 0.8F, 0.75F, 0.6F, 1.0F };

float G_uLitSpecular[4] = { 0.5F, 0.5F, 0.5F, 1.0F };

float G_uLitPosition[4] = { 5.0F, 0.0F, 5.0F, 1.0F };

float G_uMaterialSpecu[4] = { 0.0F, 0.0F, 0.0F, 1.0F };

////////////////////////////////////
//函数声明
LRESULT CALLBACK WndProc(HWND, UINT, WPARAM, LPARAM);

//主函数
```

```

        // Shutdown
        KillGLWindow();
        return (msg.wParam);
    }

    //移近
    void inline MoveNear(void)
    {
        G_fDistance -= 0.1f;
    }

    //移远
    void inline MoveFar(void)
    {
        G_fDistance += 0.1f;
    }

    //左移
    void inline MoveLeft(void)
    {
        G_fDistancece_horizon -= 0.02f;
    }

    //右移
    void inline MoveRight(void)
    {
        G_fDistancece_horizon += 0.02f;
    }

    //上移
    void inline MoveUp(void)
    {
        G_fDistancece_vertical += 0.05f;
    }

    //下移
    void inline MoveDown(void)
    {
        G_fDistancece_vertical -= 0.05f;
    }

    //左转
    void inline LeftRotate(void)
    {
        G_fAngle_horizon -= 5;
    }

    //右转
    void inline RightRotate(void)
    {
        G_fAngle_horizon += 5;
    }

    //向上转动
    void inline UpRotate(void)
    {
        G_fAngle_vertical -= 5;
    }

    //向下转动
    void inline DownRotate(void)
    {
        G_fAngle_vertical += 5;
    }

    //向左转动
    void inline LeftRotate(void)
    {
        G_fAngle_vertical -= 5;
    }

    //向右转动
    void inline RightRotate(void)
    {
        G_fAngle_vertical += 5;
    }

    //左上臂向下转动
    void inline RotateLeftArmDown(void)
    {
        if (G_fLArm_Ang > 0)
        {
            G_fLArm_Ang -= 3;
        }
        if (G_fLArm_Ang < G_fLDArm_Ang)
        {
            G_fLDArm_Ang = G_fLArm_Ang;
        }
    }

    //左上臂向上转动
    void inline RotateLeftArmUp(void)
    {
        if (G_fLArm_Ang < 135)
        {
            G_fLArm_Ang += 3;
        }
        if (G_fLArm_Ang - 135 > G_fLDArm_Ang)
        {
            G_fLDArm_Ang = G_fLArm_Ang - 135;
        }
    }

```

```

}

//右上臂向下转动
void inline RotateRightArmDown(void)
{
    if (G_FRArm_Ang < 0)
    {
        G_FRArm_Ang += 3;
    }
    if (G_FRArm_Ang > G_FRDArm_Ang)
    {
        G_FRDArm_Ang = G_FRArm_Ang;
    }
}

//右上臂向上转动
void inline RotateRightArmUp(void)
{
    if (G_FRArm_Ang > -135)
    {
        G_FRArm_Ang -= 3;
    }
    if (G_FRArm_Ang + 135 < G_FRDArm_Ang)
    {
        G_FRDArm_Ang = G_FRArm_Ang + 135;
    }
}

//左大腿向下旋转
void inline RotateLeftLegDown(void)
{
    if (G_FLLeg_Ang < 90)
    {
        G_FLLeg_Ang += 3;
    }
    if (G_FLLeg_Ang > G_FLCalf_Ang)
    {
        G_FLCalf_Ang = G_FLLeg_Ang;
    }
}

```

```

//左大腿向下旋转
void inline RotateLeftLegDown(void)
{
    if (G_FLLeg_Ang < 90)
    {
        G_FLLeg_Ang += 3;
    }
    if (G_FLLeg_Ang > G_FLCalf_Ang)
    {
        G_FLCalf_Ang = G_FLLeg_Ang;
    }
}

//左大腿向上旋转
void inline RotateLeftLegUp(void)
{
    if (G_FLLeg_Ang > -135)
    {
        G_FLLeg_Ang -= 3;
    }
    if (G_FLCalf_Ang > G_FLLeg_Ang + 135)
    {
        G_FLCalf_Ang = G_FLLeg_Ang + 135;
    }
}

//右大腿向下旋转
void inline RotateRightLegDown(void)
{
    if (G_FRLeg_Ang < 90)
    {
        G_FRLeg_Ang += 3;
    }
    if (G_FRLeg_Ang > G_FRCalf_Ang)
    {
        G_FRCalf_Ang = G_FRLeg_Ang;
    }
}

//右大腿向上旋转
void inline RotateRightLegUp(void)
{
    if (G_FRLeg_Ang > -135)
    {
        G_FRLeg_Ang -= 3;
    }
    if (G_FRCalf_Ang > G_FRLeg_Ang + 135)
    {
        G_FRCalf_Ang = G_FRLeg_Ang + 135;
    }
}

```

```

//右大腿向上旋转
void inline RotateRightLegUp(void)
{
    if (G_FRLeg_Ang > -135)
    {
        G_FRLeg_Ang -= 3;
    }
    if (G_FRCalf_Ang > G_FRLeg_Ang + 135)
    {
        G_FRCalf_Ang = G_FRLeg_Ang + 135;
    }
}

//右小腿向下旋转
void inline RotateRightCalfDown(void)
{
    if (G_FRCalf_Ang < G_FRLeg_Ang + 135)
    {
        G_FRCalf_Ang += 3;
    }
}

//右小腿向上旋转
void inline RotateRightCalfUp(void)
{
    if (G_FRCalf_Ang > G_FRLeg_Ang)
    {
        G_FRCalf_Ang -= 3;
    }
}

//左小腿向下旋转
void inline RotateLeftCalfDown(void)
{
    if (G_FLCalf_Ang < G_FLLeg_Ang + 135)
    {
        G_FLCalf_Ang += 3;
    }
}

//左小腿向上旋转
void inline RotateLeftCalfUp(void)
{
    if (G_FLCalf_Ang > G_FLLeg_Ang)
    {
        G_FLCalf_Ang -= 3;
    }
}

```

```

{
    if (G_FLCalF_Ang > G_FLLeg_Ang)
        G_FLCalF_Ang -= 3;
}

//重置机器人的状态为初始状态
void inline Reset(void)
{
    G_FDistance = 5.5f;
    G_FDistancece_horizon = 0.0f;
    G_FDistancece_vertical = 0.0f;
    G_FAngle_horizon = 0.0f;
    G_FAngle_vertical = 0.0f;
    G_FRArm_Ang = 0.0f;
    G_FLArm_Ang = 0.0f;
    G_FRLeg_Ang = 0.0f;
    G_FLLeg_Ang = 0.0f;
    G_FRCaIF_Ang = 0.0f;
    G_FLCaIF_Ang = 0.0f;
    G_FLDArm_Ang = 0.0f;
    G_FRDArm_Ang = 0.0f;
    G_FLArmF_Ang = 0.0f;
    G_FRArmF_Ang = 0.0f;
    G_FHead_Ang = 0.0f;
    G_FRLeg_Horizon = 0.0f;
    G_FLLeg_Horizon = 0.0f;
    G_FLLightx = 0.0f;
}

//左下臂向下旋转
void inline RotateLeftDArmDown(void)
{
    if (G_FLArm_Ang - G_FLDArm_Ang < 135)
        G_FLDArm_Ang -= 3;
}

//左下臂向下旋转
void inline RotateLeftDArmDown(void)
{
    if (G_FLArm_Ang - G_FLDArm_Ang < 135)
        G_FLDArm_Ang -= 3;
}

//左下臂向上旋转
void inline RotateLeftDArmUp(void) {
    if (G_FLArm_Ang > G_FLDArm_Ang)
        G_FLDArm_Ang += 3;
}

//右下臂向下旋转
void inline RotateRightDArmDown(void)
{
    if (G_FRDArm_Ang - G_FRArm_Ang < 135)
        G_FRDArm_Ang += 3;
}

//右下臂向上旋转
void inline RotateRightDArmUp(void)
{
    if (G_FRArm_Ang < G_FRDArm_Ang)
        G_FRDArm_Ang -= 3;
}

//光照左移
void inline LightMoveLeft(void)
{
    if (G_FLLightx > -120)
        G_FLLightx -= 3;
}

void inline LightMoveLeft(void)
{
    if (G_FLLightx > -120)
        G_FLLightx -= 3;
}

//光照右移
void inline LightMoveRight(void)
{
    if (G_FLLightx < 120)
        G_FLLightx += 3;
}

//左臂向前旋转
void inline RotateLeftArmForward(void)
{
    if (G_FLArmF_Ang > -180)
        G_FLArmF_Ang -= 3;
}

//左臂向后旋转
void inline RotateLeftArmBack(void)
{
    if (G_FLArmF_Ang < 45)
        G_FLArmF_Ang += 3;
}

//右臂向前旋转
void inline RotateRightArmForward(void)
{
    if (G_FRArmF_Ang > -180)
        G_FRArmF_Ang -= 3;
}

//右臂向后旋转

```

```

        G_FLArmF_Ang += 3;
    }

    //右臂向前旋转
    void inline RotateRightArmForward(void)
    {
        if (G_FRArmF_Ang > -180)
            G_FRArmF_Ang -= 3;
    }

    //右臂向后旋转
    void inline RotateRightArmBack(void)
    {
        if (G_FRArmF_Ang < 45)
            G_FRArmF_Ang += 3;
    }

    //脑袋左转
    void inline RotateHeadLeft(void)
    {
        if (G_fHead_Ang < 90)
            G_fHead_Ang += 3;
    }

    //脑袋右转
    void inline RotateHeadRight(void)
    {
        if (G_fHead_Ang > -90)
            G_fHead_Ang -= 3;
    }

```

```

        DrawGLScene();                // Draw The Scene
        SwapBuffers(hdc);              // Swap Buffers (Double Buffering)
    }

    if (keys[VK_F1])                  // Is F1 Being Pressed?
    {
        keys[VK_F1]=false;           // If So Make Key False
        KillGLWindow();              // Kill Our Current Window
        fullscreen=!fullscreen;       // Toggle Fullscreen / Windowed Mode
        // Recreate Our OpenGL Window
        if (!CreateGLWindow("机器人",nFullWidth,nFullHeight,32,fullscreen))
        {
            return 0;                // Quit If Window Was Not Created
        }
    }

    if (keys[VK_F2])
    {
        keys[VK_F2] = false;
        wire = !wire;
    }

    if (keys[VK_SPACE])
    {
        keys[VK_SPACE] = false;
        Reset();
    }

    if(keys[VK_ADD])
    {
        keys[VK_ADD] = false;
        MoveNear();
    }

    {
        keys[VK_SUBTRACT] = false;
        MoveFar();
    }

    int kg = 0;
    if(keys[VK_INSERT])
        kg += 1;
    if(keys[VK_HOME])
        kg += 2;
    if(keys[VK_DELETE])
        kg += 5;
    if(keys[VK_END])
        kg += 11;
    if(keys[VK_CONTROL])
        kg += 23;
    if(keys[VK_SHIFT])
        kg += 43;
    if(keys[VK_PRIOR])
        kg += 87;
    if(keys[VK_NEXT])
        kg += 173;

    if (keys[VK_LEFT])
    {
        keys[VK_LEFT] = false;
        switch(kg)
        {
            case 0 : LeftRotate(); break;
            case 1 : RotateLeftDArmUp(); break;
            case 2 : RotateRightDArmDown(); break;
            case 5 : RotateLeftCalfDown(); break;
            case 11 : RotateRightCalfDown(); break;
            case 23 : MoveLeft(); break;
            case 43 : LightModelLeft(); break;

```

```

        case 2 : RotateRightDArmDown(); break;
        case 5 : RotateLeftCalfDown(); break;
        case 11 : RotateRightCalfDown(); break;
        case 23 : MoveLeft(); break;
        case 43 : LightMoveLeft(); break;
        case 87 : RotateLeftArmForward(); break;
        case 173 : RotateLeftArmBack(); break;
        default : break;
    }
}

if (keys[VK_RIGHT])
{
    keys[VK_RIGHT] = false;
    switch(kg)
    {
        case 0 : RightRotate(); break;
        case 1 : RotateLeftDArmDown(); break;
        case 2 : RotateRightDArmUp(); break;
        case 5 : RotateLeftCalfUp(); break;
        case 11 : RotateRightCalfUp(); break;
        case 23 : MoveRight(); break;
        case 43 : LightMoveRight(); break;
        case 87 : RotateRightArmForward(); break;
        case 173 : RotateRightArmBack(); break;
        default : break;
    }
}

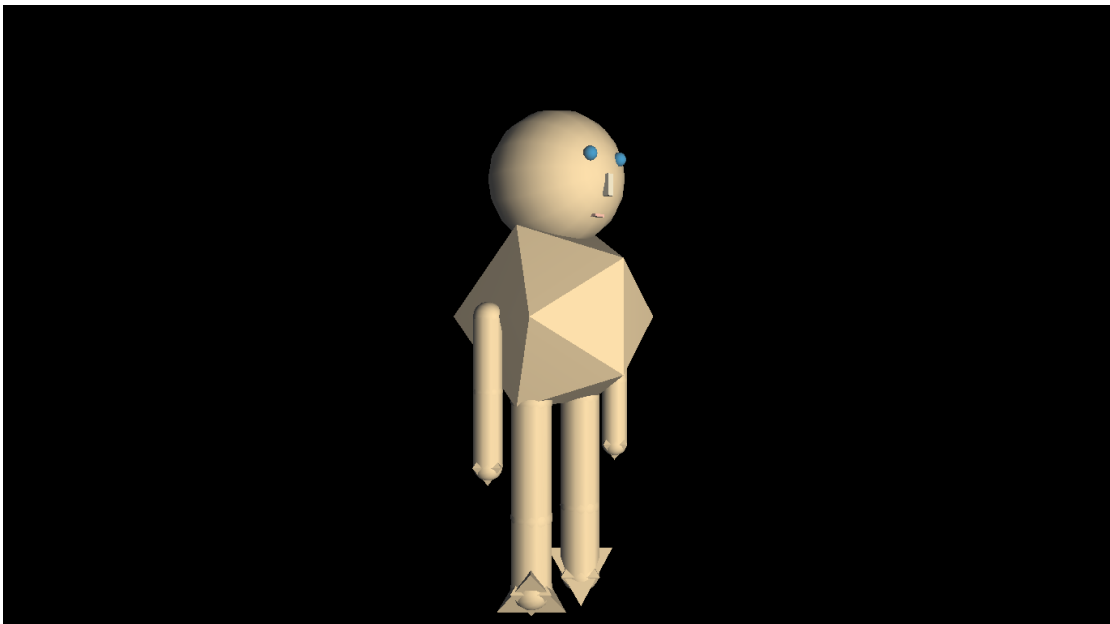
if (keys[VK_UP])
{
    keys[VK_UP] = false;
    switch(kg)
    {
        case 0 : UpRotate(); break;
        case 1 : RotateLeftArmUp(); break;
        case 2 : RotateRightArmUp(); break;
        case 5 : RotateLeftLegUp(); break;
        case 11 : RotateRightLegUp(); break;
        case 23 : MoveUp(); break;
        default : break;
    }
}

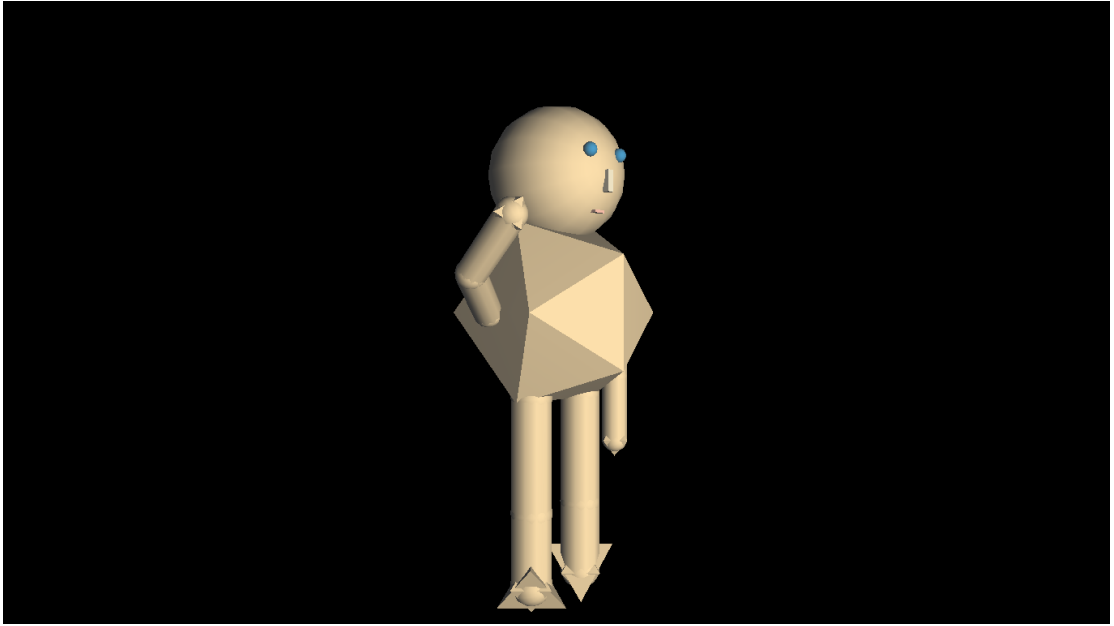
if (keys[VK_DOWN])
{
    keys[VK_DOWN] = false;
    switch(kg)
    {
        case 0 : DownRotate(); break;
        case 1 : RotateLeftArmDown(); break;
        case 2 : RotateRightArmDown(); break;
        case 5 : RotateLeftLegDown(); break;
        case 11 : RotateRightLegDown(); break;
        case 23 : MoveDown(); break;
        default : break;
    }
}
}
}

// Shutdown
KillGLWindow(); // Kill The Window
return (msg.wParam); // Exit The Program
}

//移近
void inline MoveMove(void)

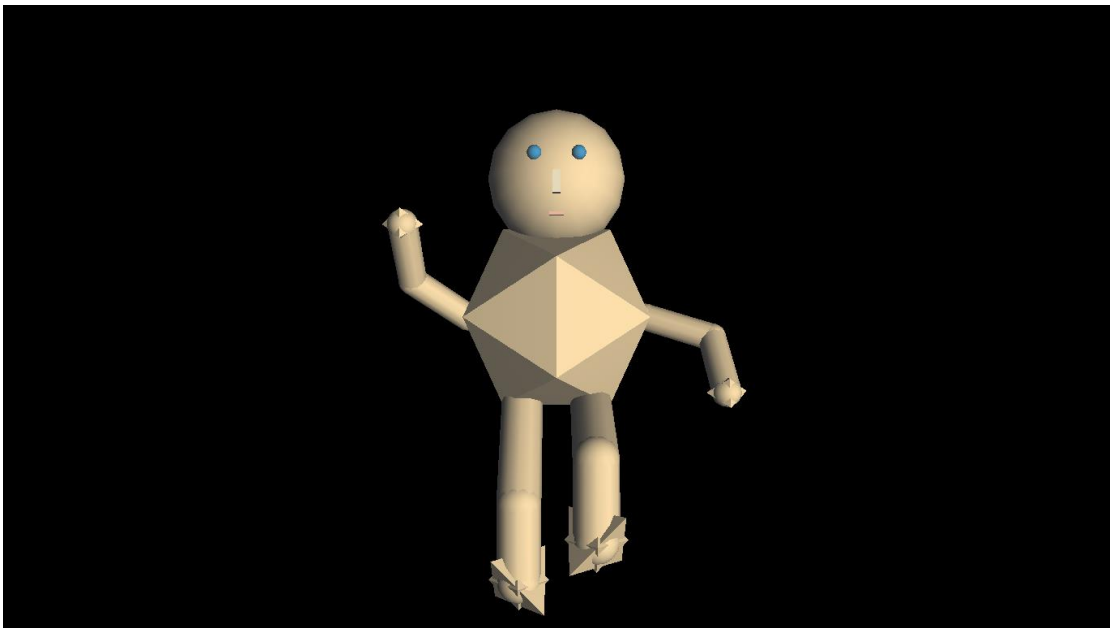
```

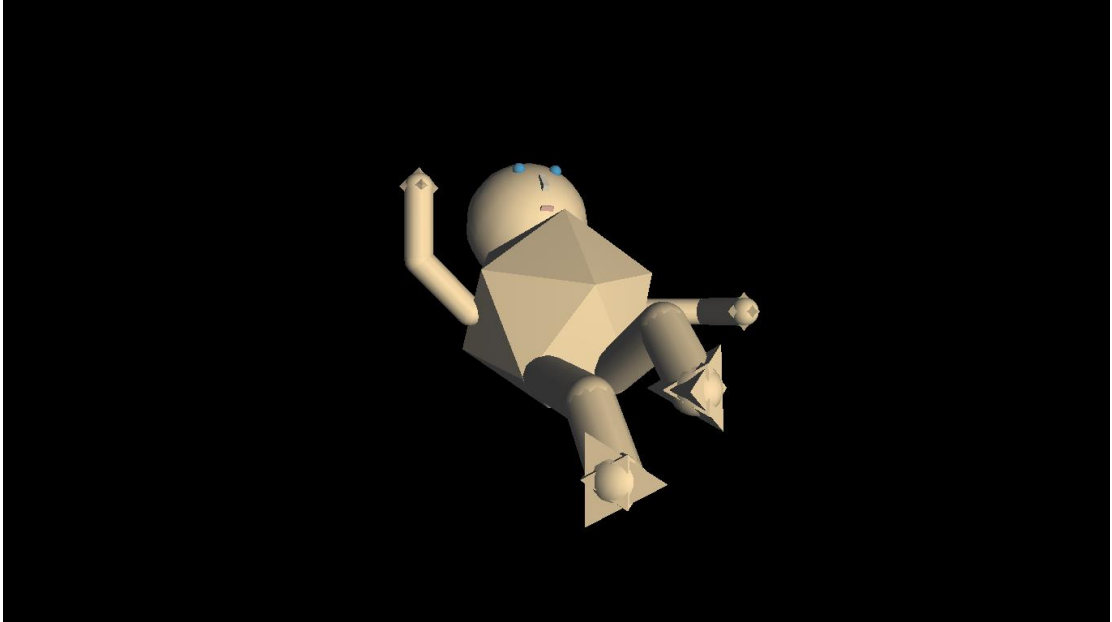
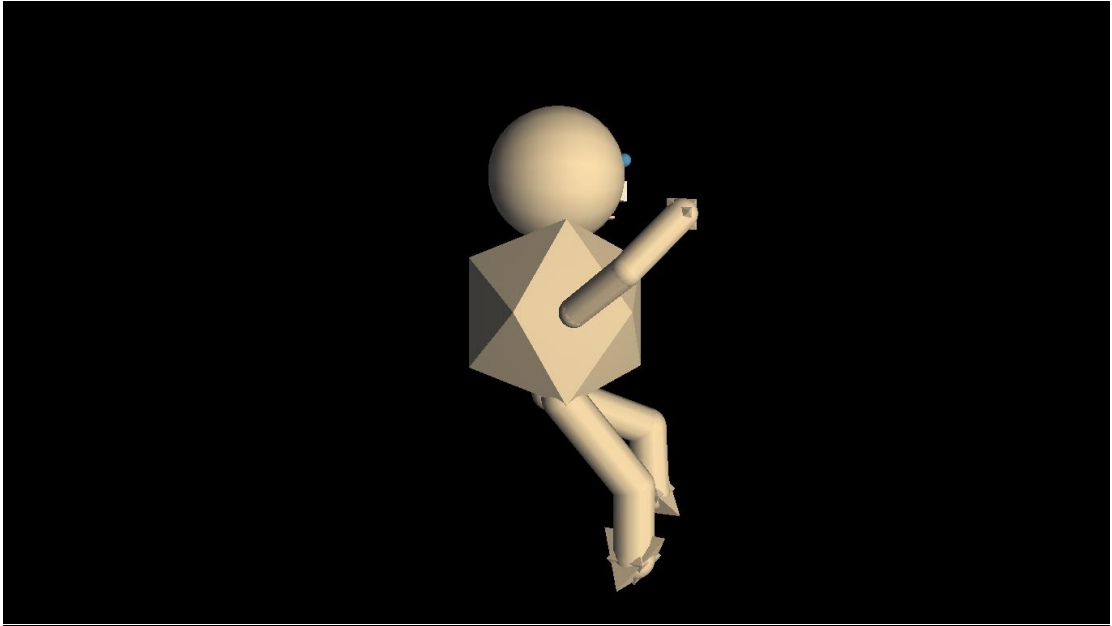


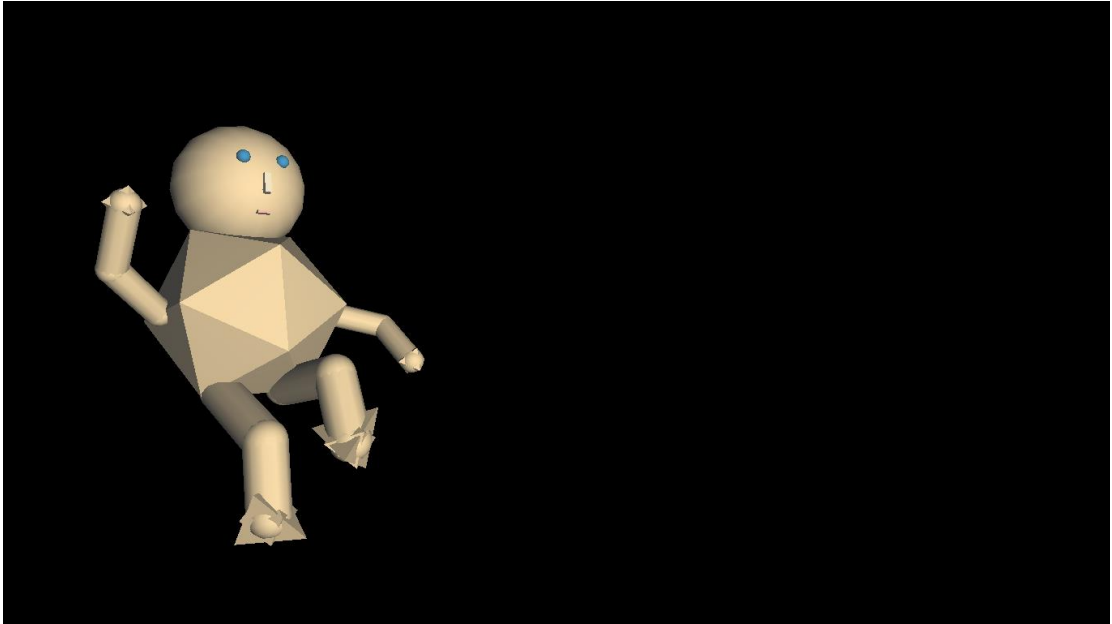


实验结果：

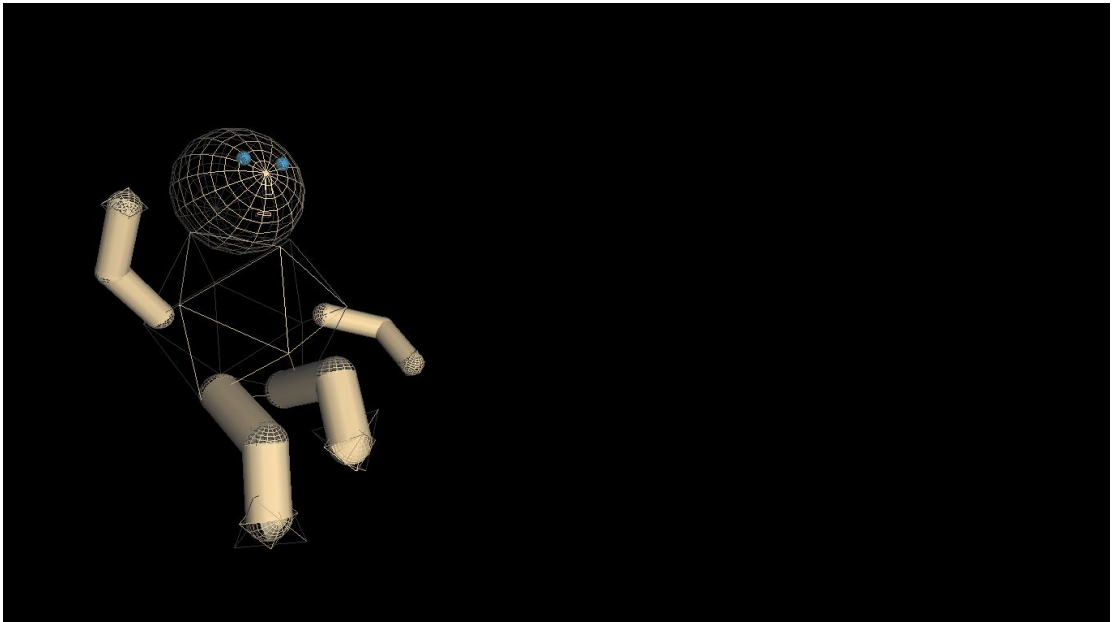
可以灵活转动，并带光照效果的机器人

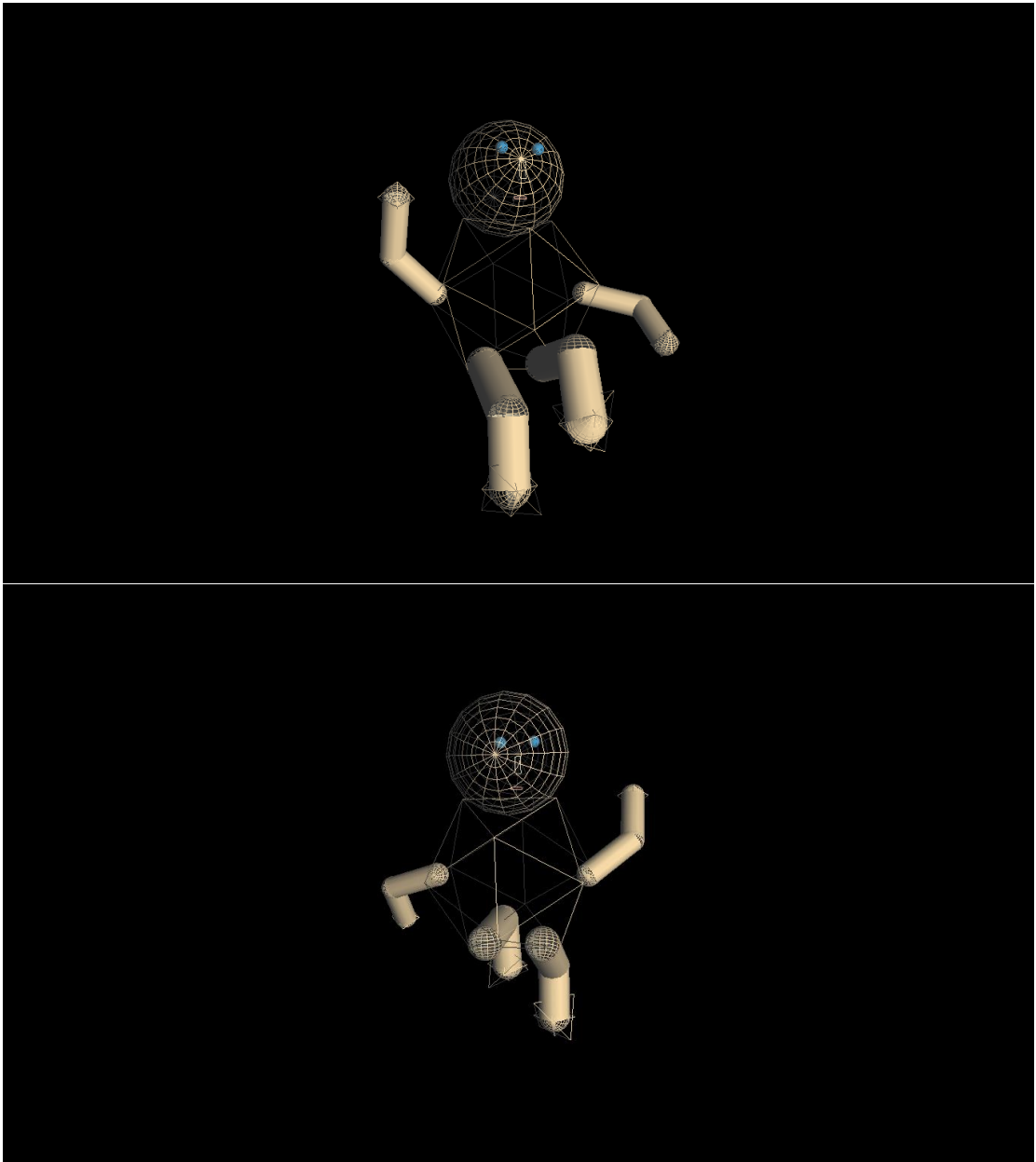




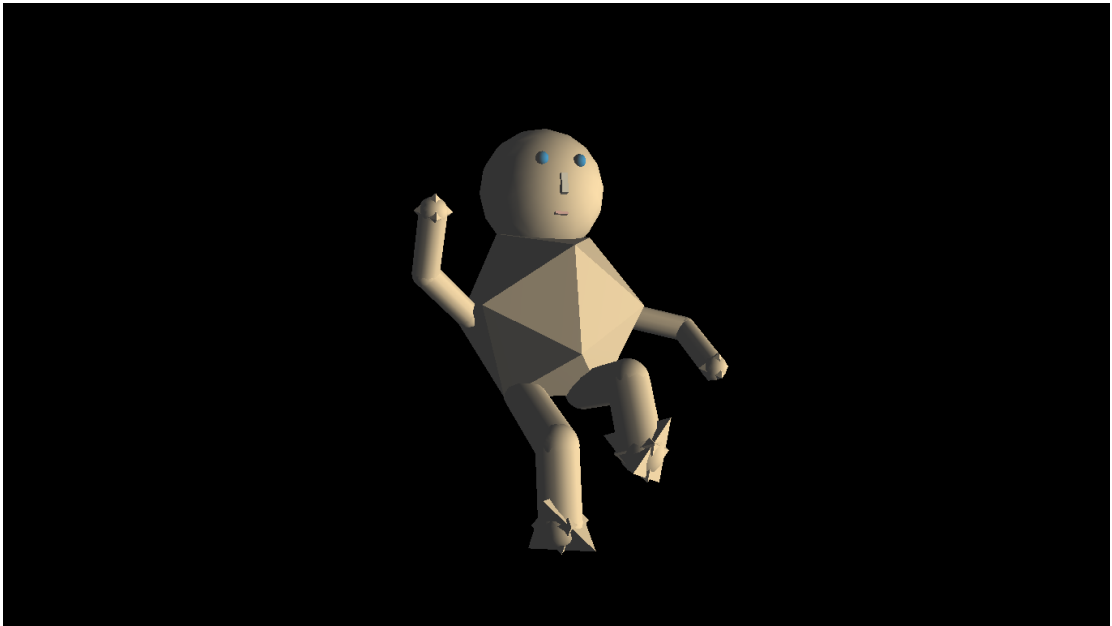


可以切换面片为线框

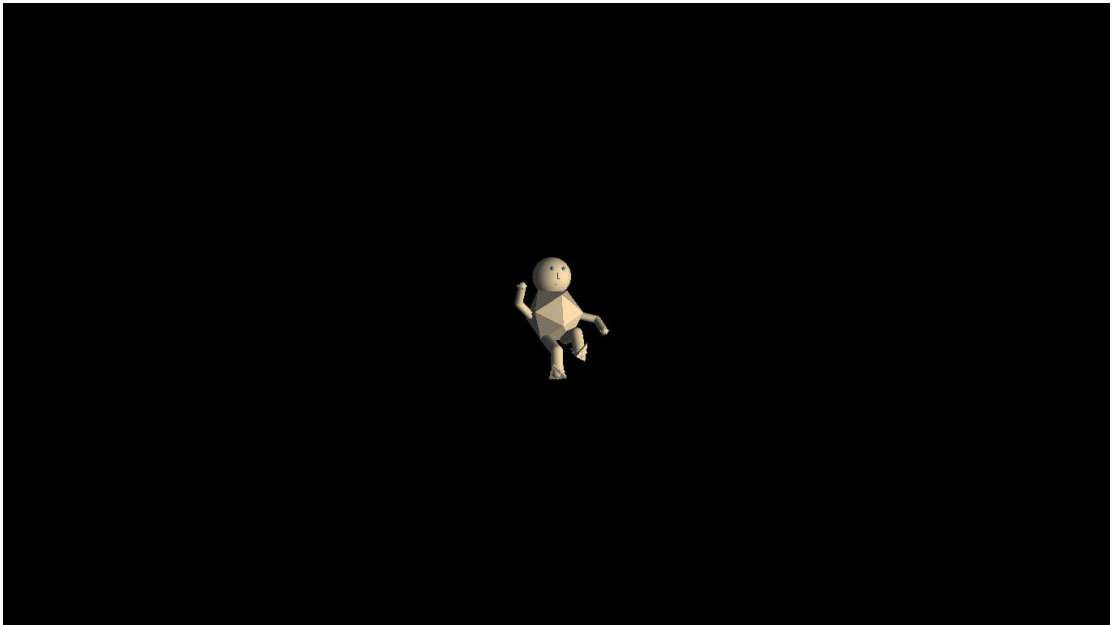


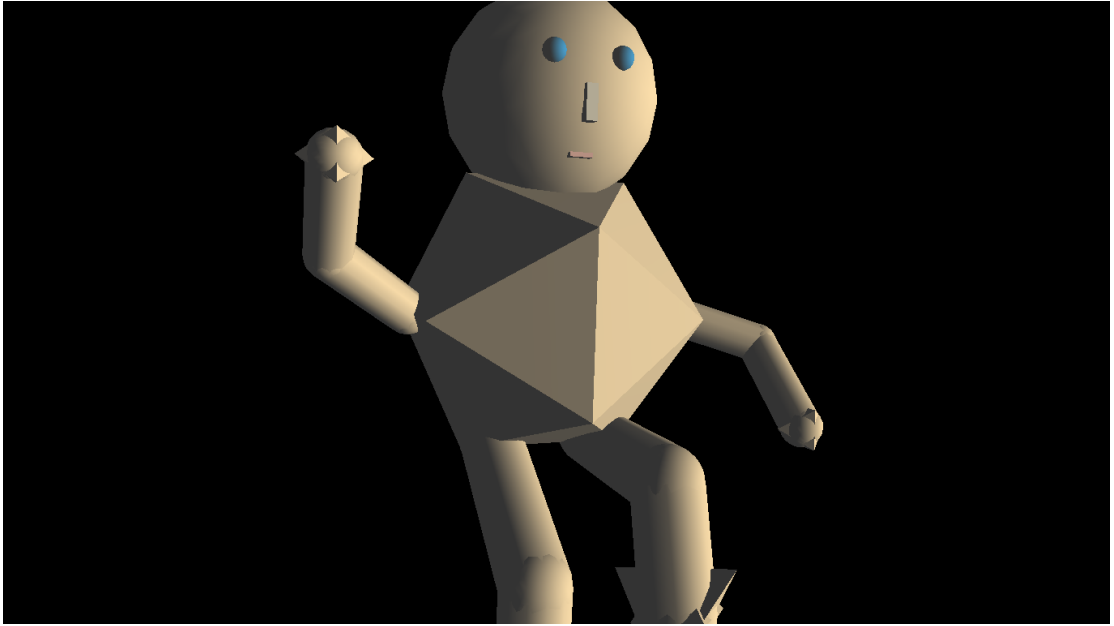


可以改变光照方向

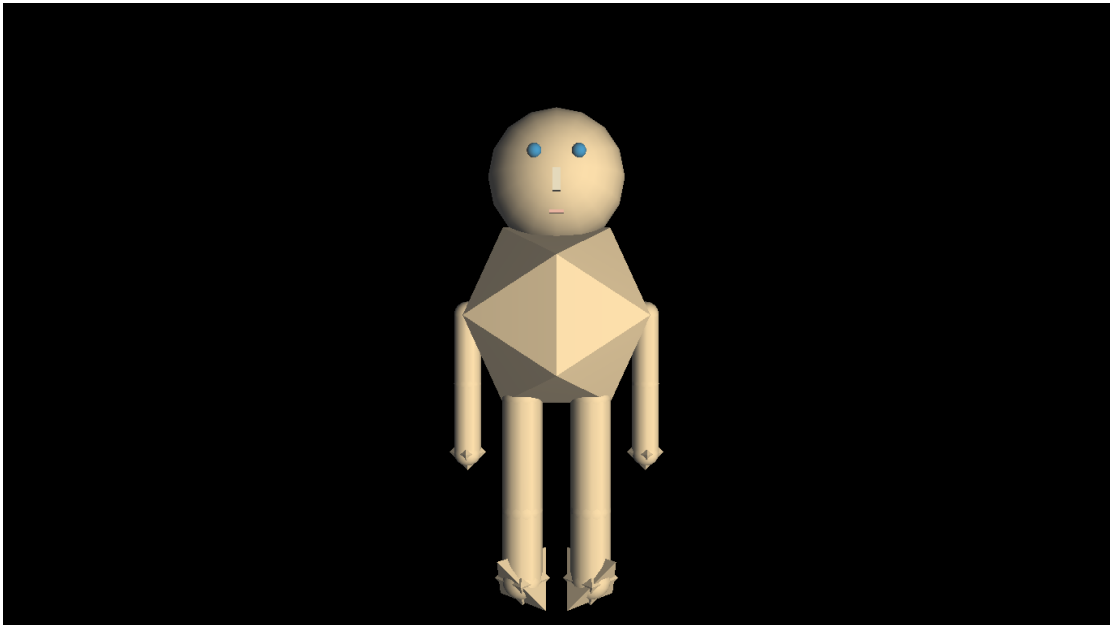


可以拉近拉远

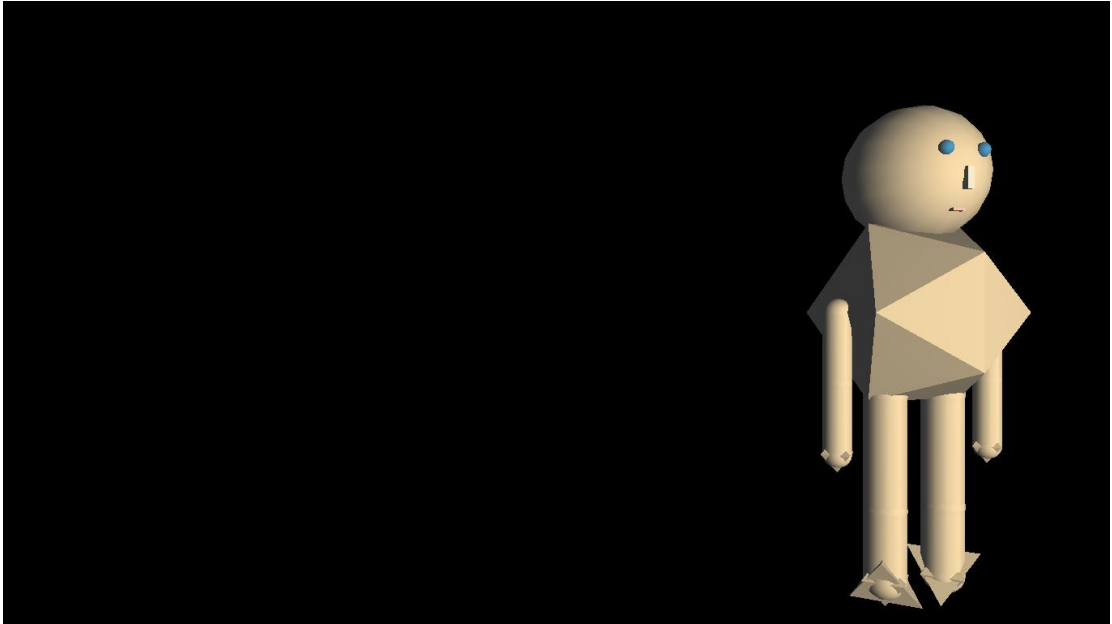




按空格恢复到初始状态



可以上下左右移动



可以旋转



按键说明：

上下左右方向键 旋转
 Ctrl+上下左右方向键 移动
 Shift + 左右方向键 移动光源
 Home + 上下左右方向键 移动右臂
 End + 上下左右方向键 移动右腿
 Insert + 上下左右方向键 移动左臂
 Delete + 上下左右方向键 移动左腿
 PageUp + 左右方向键 向前移动手臂
 PageDown + 左右方向键 向后移动手臂
 空格键 重置机器人状态

F1 键 切换全屏与窗口模式

F2 键 切换面片与线框模式

.....