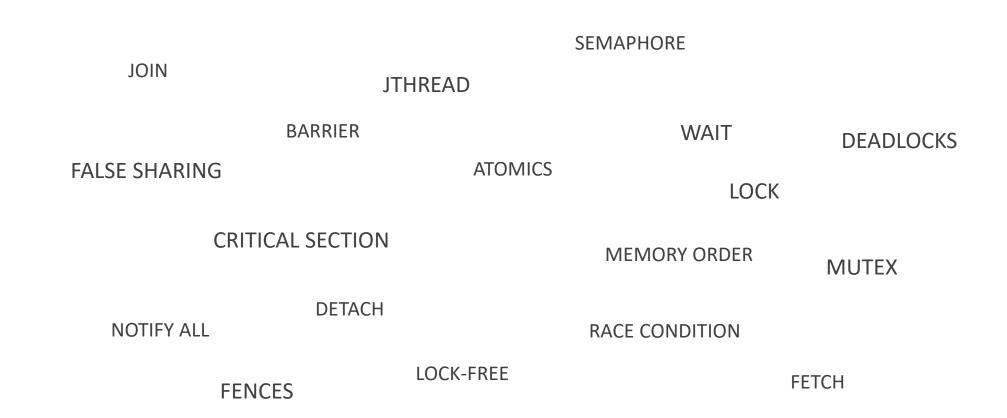
# Stories from a parallel universe

Jana Machutová

## Do you feel sudden tension in your brain?



## We have a painkiller for you!

			SEMAPHORE			
JOIN	JTHREAD					DEADLOCKS
	BARRIER		ATOMICS		WAIT	
FALSE SHARING						
CRITICAL SECTION	STANDARD LIBRARY					
		PARALLEL ALGORITHMS			LOCK	
					MEMORY ORD	ER MUTEX
NOTIFY ALL						
		DETACH		RACE CONDITION		ETCH
	FENCES	LOCK-FREE				

#### Standard library parallel algorithm

- Provides parallel version of most of standard library algorithms
- Introduced execution policy parameter all the rest is same as before
- Easy switch between sequential and few types of parallel executions
- Well optimized solution to common problems
- No need to reinvent parallel wheels
- In standard since version 17 (with some changes in 20 and another on their way for future versions)
- Several new algorithms appeared
- Several old don't have any parallel version
- Not available for ranges so far

#### Create new worlds

No need to take care of any threads at all – it's handled automatically Underlying thread management saves price of creating/destructing threads, split the load equally and don't create crazy amount of threads

#### Create new worlds

});

```
Thread #0 species [0]

Thread #1 SPECIES [1]

RESO ALABLE

UNAVAILABLE

UNAVAILABLE

Thread #999 999 species [999 999]
```

```
Thread #0 species [0-9999]

for_each(execution::par_unseq, species.begin(), species.end(), Thread #1 species [10000-19999]

[](const auto name){
    swim deep(name);
```

Thread #100 species [90 000 – 99 999]

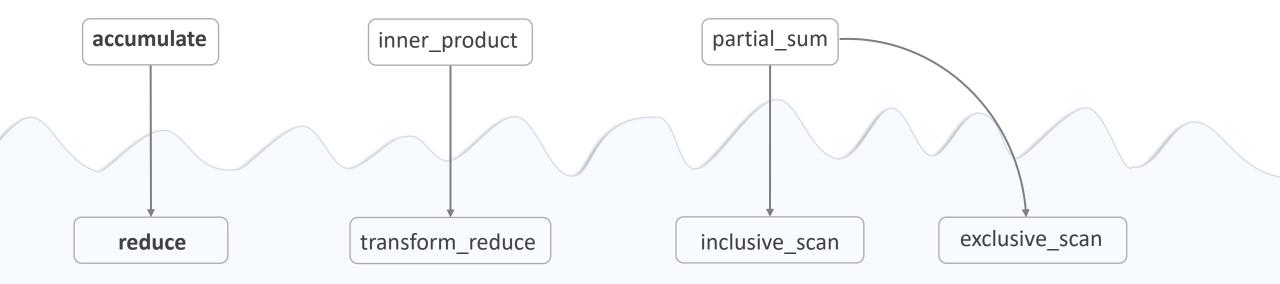
#### Why do you want to use parallel algorithms

- No need for direct manipulation with threads
- No need to care about threads lifetime
- Clever thread management is already part of the package
- Widely tested and optimized solution
- Easy to switch between different execution policies
- Improved readability
- Less error prone
- If you can use sequential version, you will be able to use parallel without any additional studies

Do not reinvent a wheel – use standard library as much as you can

#### New algorithms introduced

All of them are here as an alternative to existing sequential only solution



Second sight try to modify operation to some custom

```
vector<int> species_count{68, 15, 4, 45, 18, 3, 2, 11};
accumulate(species_count.begin(), species_count.end(), 0, plus{});
```

output: **166** 

```
reduce(execution::par, species_count.begin(), species_count.end(), 0 , plus{});
```

output: **166** 

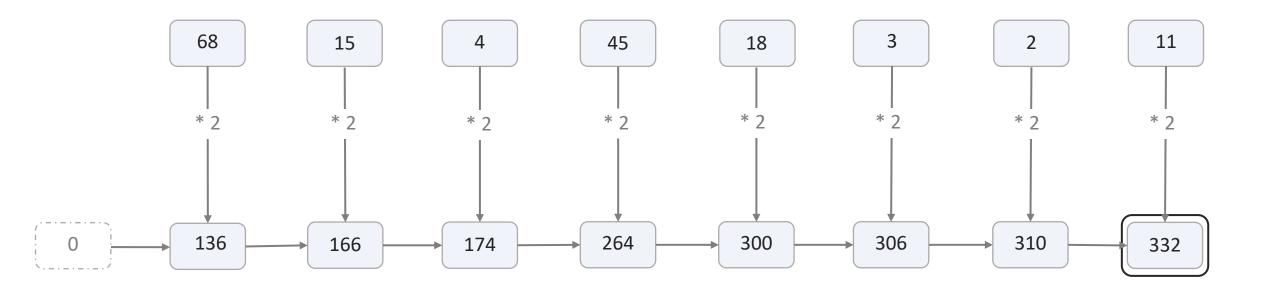
#### accumulate vs reduce

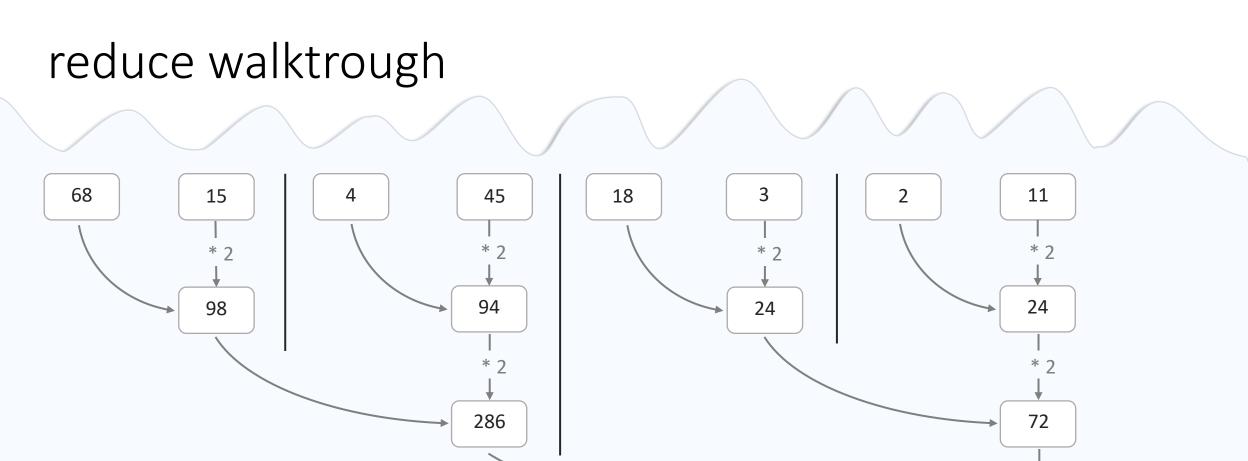
```
How many animals will be there in next generation with growth_factor 2
```

Non-associative reduction function makes mess

Have a look what's going on in both cases on next slides

## accumulate walktrough





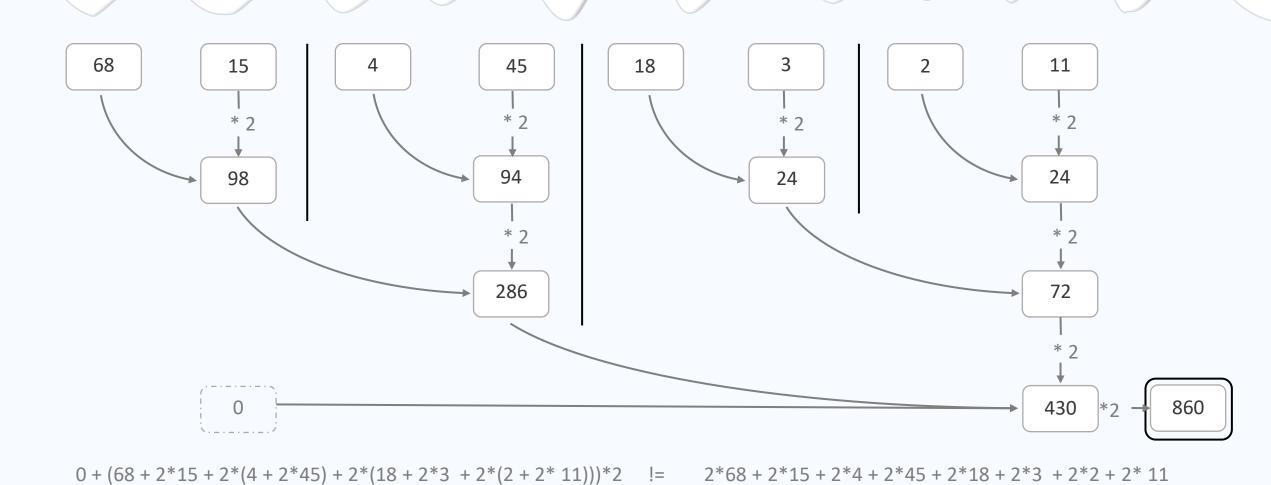
 $0 + (68 + 2*15 + 2*(4 + 2*45) + 2*(18 + 2*3 + 2*(2 + 2*11)))*2 \quad != \quad 2*68 + 2*15 + 2*4 + 2*45 + 2*18 + 2*3 + 2*2 + 2*11$ 

#### accumulate vs reduce

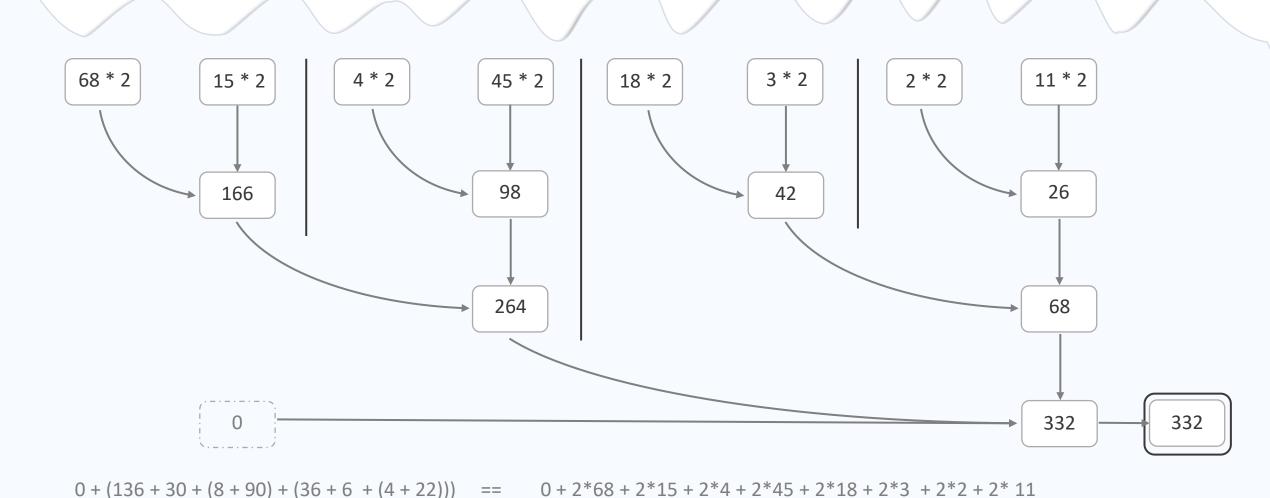
#### accumulate vs reduce - fixed

output: 332

## reduce walktrough



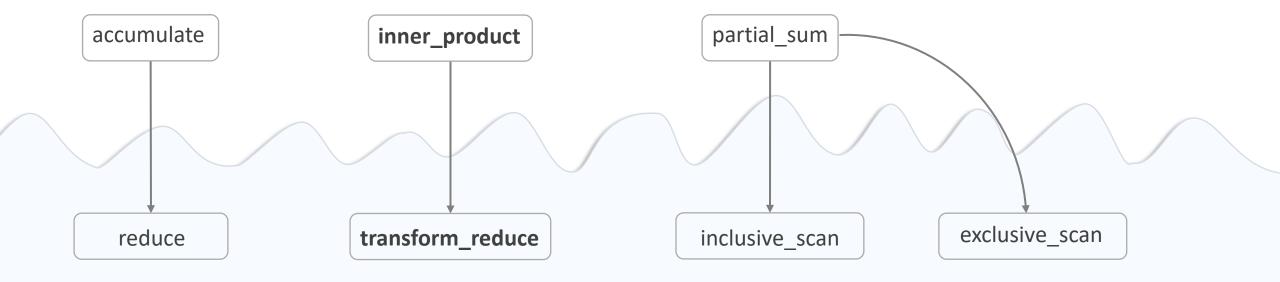
transform\_reduce walktrough



one honey bee hive contains 60,000 to 80,000 bees

### New algorithms introduced

All of them are here as an alternative to existing sequential only solution



#### inner\_product vs transform\_reduce

```
vector<int> weights{1e-6f, 2.1e-5f, 3.f, 43.3f, 5.1e3f, 6.5e4f, 7.7e6f, 1.5e8f};
vector<int> species_count{68, 15, 4, 45, 18, 3, 2, 11};
inner_product(species_count.begin(), species_count.end(), weights.begin(), 0);
0+1e-6f*68+2.1e-5f*15+3.f*4+43.3f*45+5.1e3f*18+6.5e4f*3+7.7e6f*2+1.5e8f*11
```

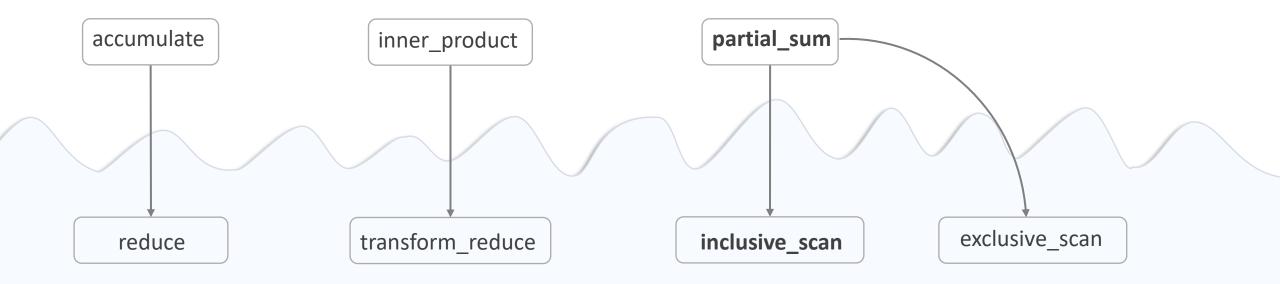
output: 1 665 688 704 g output with double: 1 665 688 761 g

```
transform\_reduce(execution::par, species\_count.begin(), species\_count.end(), weights.begin(), 0); \\ 0 + (1e-6f*68 + 2.1e-5f*15 + (3.f*4 + 43.3f*45) + (5.1e3f*18 + 6.5e4f*3 + (7.7e6f*2 + 1.5e8f*11)))
```

output: 1 665 688 832 g output with double: 1 665 688 761 g

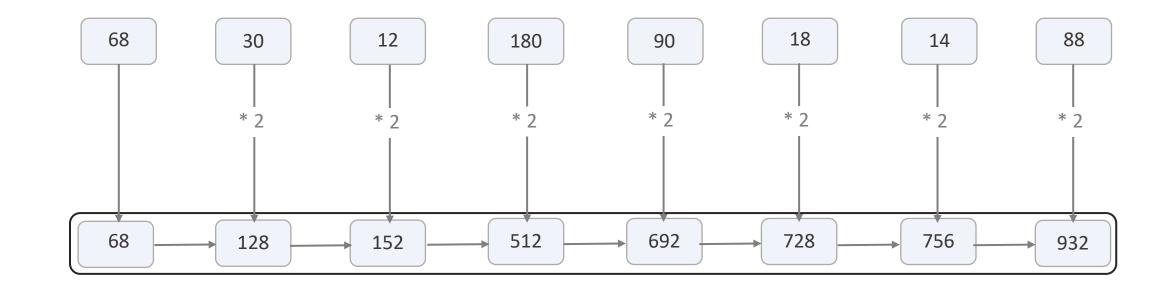
### New algorithms introduced

All of them are here as an alternative to existing sequential only solution

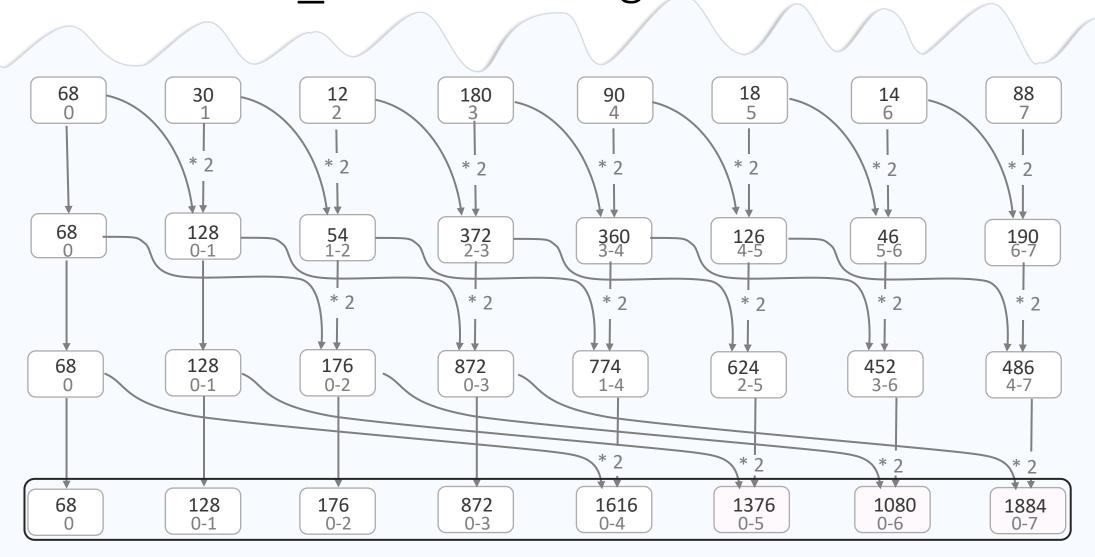


#### partial\_sum vs inclusive\_scan

## partial\_sum walktrough

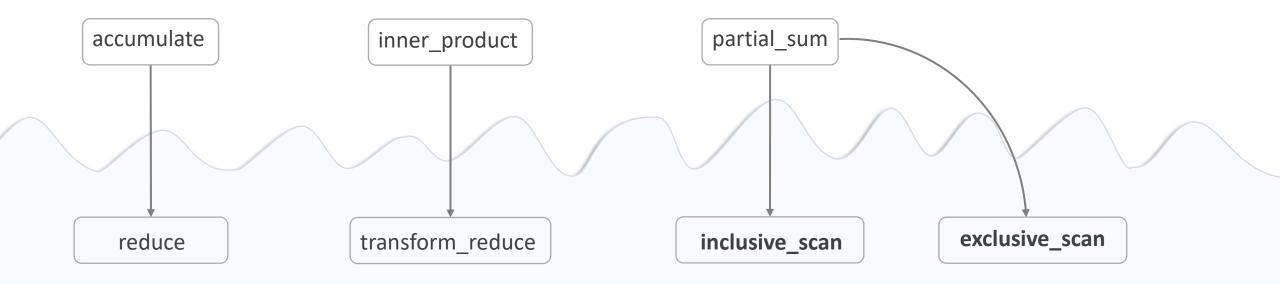


naïve inclusive\_scan walktrough



### New algorithms introduced

All of them are here as an alternative to existing sequential only solution



#### inclusive scan vs exclusive scan

```
vector<int> species_mass{136, 60, 24, 360, 180, 36, 28, 176};
array<int, 8> edible_mass;
inclusive_scan(species_mass.begin(), species_mass.end(), edible_mass.begin());
```

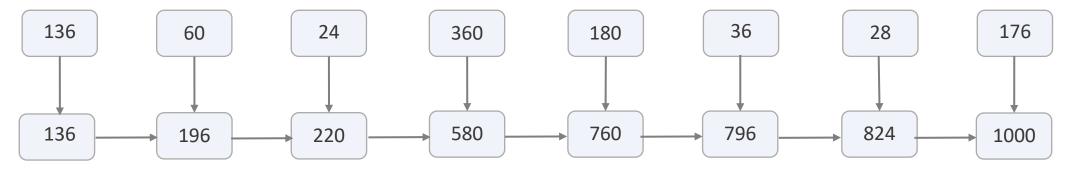
output: **136, 196, 220, 580, 760, 796, 824, 1000** 

```
exclusive_scan(species_mass.begin(), species_mass.end(), edible_mass.begin(), 0);
```

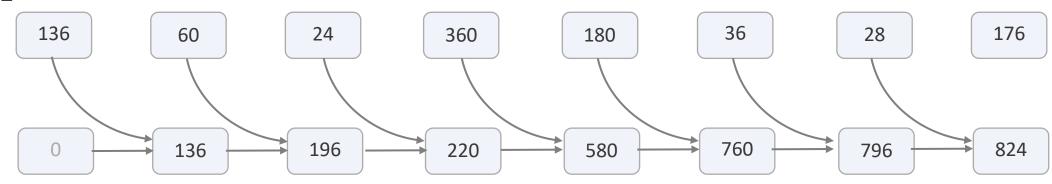
output: **0, 136, 196, 220, 580, 760, 796, 824** 

### inclusive\_scan vs exclusive\_scan

#### inclusive\_scan:



#### exclusive\_scan:



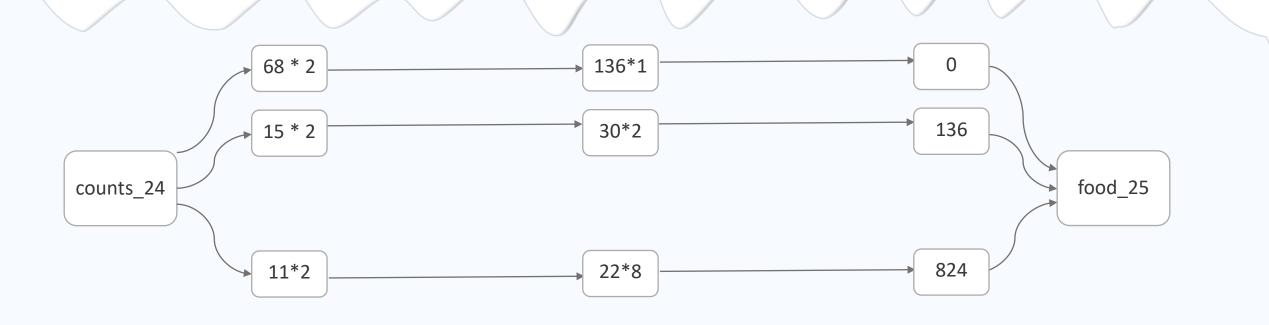
#### Unwanted synchronization points

```
array<int, 8> counts_24{68, 15, 4, 45, 18, 3, 2, 11}; array<int, 8> weights{1, 2, 3, 4, 5, 6, 7, 8};
```

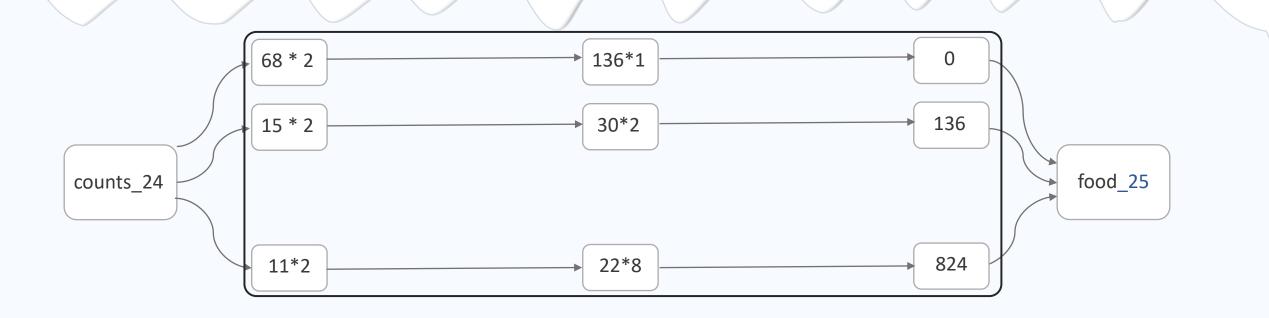
transform(par\_unseq, counts\_24.begin(), counts\_24.end(), counts\_25.begin(), [](auto i){return i \* 2;});
transform(par\_unseq, counts\_25.begin(), counts\_25.end(), weights.begin(), weight\_25.begin(), multiplies{});
exclusive\_scan(par\_unseq, weight\_25.begin(), weight\_25.end(), food\_25.begin(), 0);



#### Unwanted synchronization points

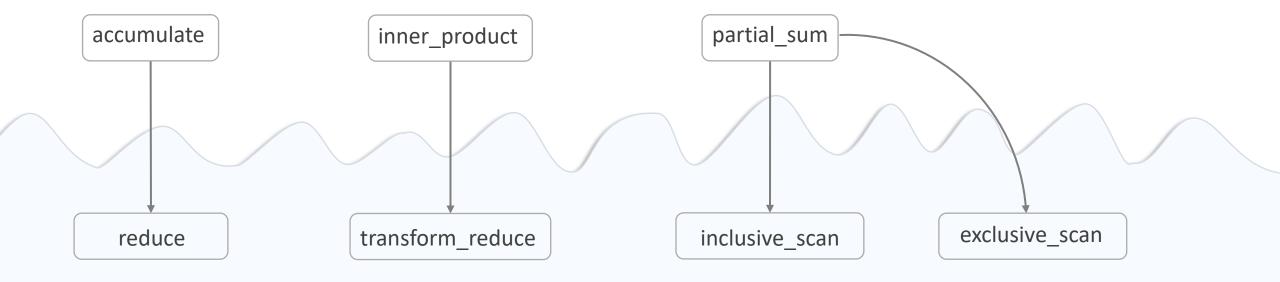


#### Unwanted synchronization points



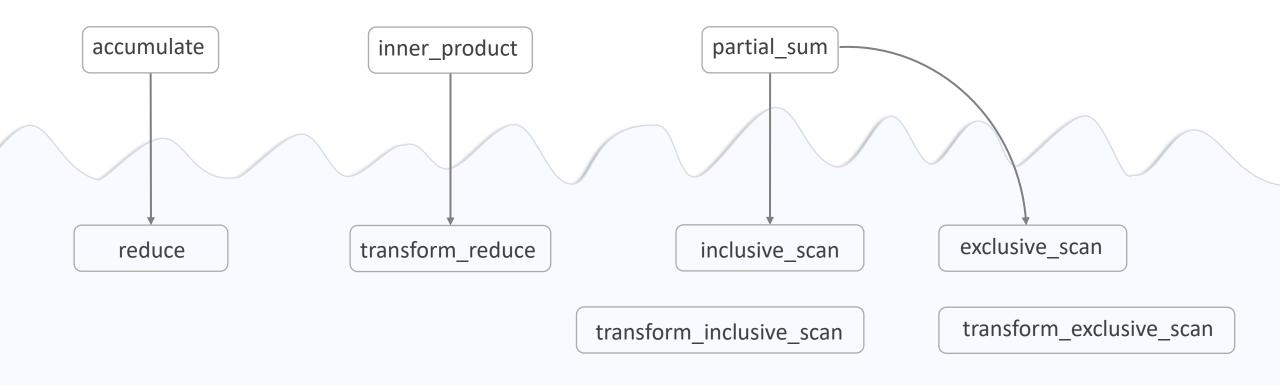
### New algorithms introduced

All of them are here as an alternative to existing sequential only solution



## New algorithms introduced

All of them are here as an alternative to existing sequential only solution



#### Execution policy

- First param of each parallel algorithm
- Defines how much is it possible to parallelize code inside algorithm body
- For the best results go for the strongest policy you can
- The stronger policy you get, the more limited you are inside the algorithm body
- If you are unable to use strongest one, maybe you won't gain from parallelization
- Always measure performance before and after parallelization
- execution::seq
- execution::par
- execution::unseq
- execution::par\_unseq

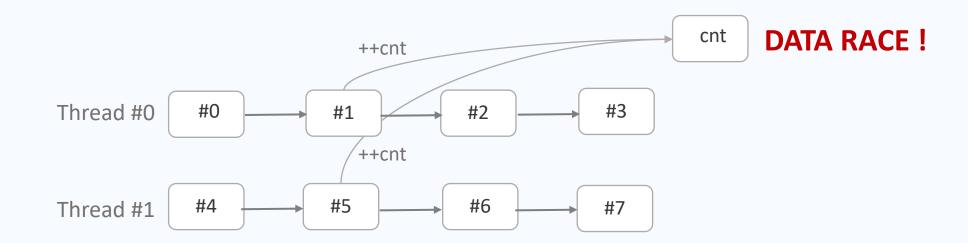
#### execution::seq

- Code is executed sequentially
- All computations are executed on single thread one by one
- No parallelization at all
- If there is no policy defined it runs in execution::seq



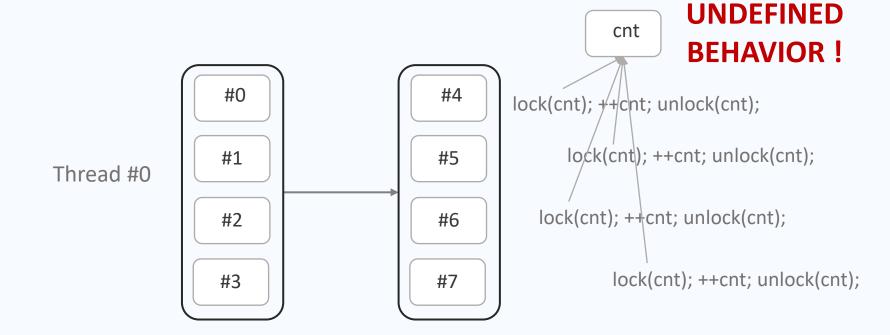
#### execution::par

- Code is executed on multiple threads
- Order in which are elements processed is not predictable
- Shared data needs to be protected as they may be accessed by different threads concurrently
- If blocking protection is needed it may not perform better than sequential approach don't forget to measure it



#### execution::unseq

- Code is executed in single thread
- Whole vector of data is executed together their instruction are in unpredictable order
- No synchronization is allowed
- No, not even atomics



#### execution::par\_unseq

- Data are vectorized and executed on multiple threads
- Strongest possible version of parallelization
- Keeps the same limitation as unseq no synchronization is allowed
- If your code may run on unseq it may run on par\_unseq there is no difference in rules
- You should try to target this policy





## Plenty of fish in the sea

```
struct Fish{ int pos; int velocity;};
vector<Fish> fishes{{32, 10}, {54, 15}, {55, 5}, {123, 20}, {124, 18}, {124, 18}, {320, 2}, {323, 5}, {480, 16}};
const auto time_interval = 1;

for_each(fishes.begin(), fishes.end(), [&](auto& fish)
{
    fish.pos += time_interval * fish.velocity;
});
```

# Plenty of fish in the sea

```
struct Fish{ int pos; int velocity;};
vector<Fish> fishes{{32, 10}, {54, 15}, {55, 5}, {123, 20}, {124, 18}, {124, 18}, {320, 2}, {323, 5}, {480, 16}};
const auto time_interval = 1;

for_each(execution::par_unseq, fishes.begin(), fishes.end(), [&](auto& fish)
{
    fish.pos += time_interval * fish.velocity;
});
```

#### Beware of shark

#### Beware of shark

Atomic shark allows us to go par, but it's synchronization so it's not allowed to go par\_unseq. We can reason that this very specific scenario would be safe, but it's still not allowed by standard.

But you don't loose much. It will be impossible to vectorize atomic operations anyway, so we would end up with par anyway

## Look for a hideout

Fish is looking for safety.
Each hideout has just limited capacity.
Check only those with free slots.
Choose the closest on left and right
Go for the closest
Swimming takes some time
Try to get inside and hope nobody was faster

```
struct Hideout{ int pos; int slots; };
vector<Hideout> hideouts{{30, 1}, {54, 1}, {123, 1}, {145, 1}, {345, 1}, {423, 1}, {700, 1}};
for_each(execution::par_unseq, fishes.begin(), fishes.end(), [&](auto& fish)
    auto safety = filter view(hideouts, [](auto& hideout){ return hideout.slots > 0;});
    auto closest = adjacent_find(safety.begin(), safety.end(), [&](auto& first, auto& second) {
         return (first.pos < fish.pos && second.pos >= fish.pos)});
    auto& selected = choose_closer_neighbor(closest);
    swim for(std::abs(selected->pos - fish.pos) * fish.velocity);
    if(selected_hideout->take_slot())
         stay hidden();
    else
         try mimicry();
});
```

## Look for a hideout

```
struct Hideout{ int pos; int slots_cnt(); bool take_slot(); private: int slots; mutex slot_mutex; };
vector<Hideout> hideouts{{30, 1}, {54, 1}, {123, 1}, {145, 1}, {345, 1}, {423, 1}, {700, 1}};
for_each(execution::par, fishes.begin(), fishes.end(), [&](auto& fish)
    auto safety = filter_view(hideouts, [](auto& hideout){ return hideout.slots cnt());
    auto closest = adjacent find(safety.begin(), safety.end(), [&](auto& first, auto& second) {
         return (first.pos < fish.pos && second.pos >= fish.pos)});
    auto& selected = choose closer neighbor(closest);
    swim for(std::abs(selected->pos - fish.pos) * fish.velocity);
    if(selected hideout->take slot())
         stay hidden();
    else
         try mimicry();
});
```

```
bool has_leader = false;
mutex leaders_mutex;
vector<Fish> fishes;
for_each(execution::par_unseq, fishes.begin(), fishes.end(), [&](auto& fish)
    unique_lock lock(leaders_mutex);
    while(has_leader){
        lock.unlock(); swim_around(); lock.lock();
    has_leader = true;
    lock.unlock();
    live_leaders_life();
    lock.lock();
    has_leader = false;
});
```

```
bool has_leader = false;
mutex leaders_mutex;
vector<Fish> fishes;
for_each(execution::par_unseq, fishes.begin(), fishes.end(), [&](auto& fish)
                                                                             unique_lock lock(lentex_mutex);
    unique_lock lock(leaders_mutex);
                                                                             unique_lock NOK(leaders mutex);
    while(has_leader){
                                                                             unique_lock lock(letters_mutex);
        lock.unlock(); swim around(); lock.lock();
                                                                             unique_lockBlock(leaders_mutex);
    has_leader = true;
    lock.unlock();
    live_leaders_life();
    lock.lock();
    has_leader = false;
});
```

```
atomic<bool> has_leader = false;
vector<Fish> fishes;

for_each(execution::par_unseq, fishes.begin(), fishes.end(), [&](auto& fish)
{
    while(has_leader.exchange(true))
        swim_around();

    live_leaders_life();

    has_leader = false;
});
```

First fish will take a leadership and lives it's priviledge life.
Second fish will attemp to take the leadership before the first loose it.
Pitty they live in the same thread
Second one will wait forever as the loosing of leadership is sequenced after
Deadlock my friends

Nope

```
atomic<bool> has_leader = false;
vector<Fish> fishes;
for each(execution::par unseq, fishes.begin(), fishes.end(), [&](auto& fish)
    while(has_leader.exchange(true))
                                                                             while(has leader.exchange(true))
         swim around();
                                                                                  swim around();
    live leaders life();
                                                                             live leaders life();
                                                                             while(has_leader.exchange(true))
    has leader = false;
});
```

# Summary

Use standard library algorithms – your life will be easier

Use the strongest possible policy

Try to avoid data dependencies – synchronization impact is huge

Always measure your performance

Beware of non-associative operations

Avoid synchronization points by utilizing views

# Deeper insight

Think Parallel (by Bryce Adelstein Lelbach)

The C++ Execution Model (by Bryce Adelstein Lelbach)

Portable floating-point calculations (by Guy Davidson)

Parallel STL <a href="https://github.com/llvm/llvm-project/tree/main/pstl">https://github.com/llvm/llvm-project/tree/main/pstl</a>

Thrust <a href="https://github.com/NVIDIA/cccl/tree/main/thrust">https://github.com/NVIDIA/cccl/tree/main/thrust</a>

# Sources

All examples and naive algorithms as presented

https://github.com/EmptySquareBubble/Stories\_from\_a\_parallel\_universe

Thank you!

