

1- Using list data structure

Pseudo code:

```
function convex_hull(polygon)
    leftmost = find leftmost vertex of polygon
    hull = [leftmost]
    current = leftmost
    while True
        next_vertex = None
        for vertex in polygon
            if vertex is current
                continue
            else if next_vertex is None
                next_vertex = vertex
            else
                cross_product = calculate cross product of (vertex -
current) and (next_vertex - current)
                if cross_product > 0
                    next_vertex = vertex
                else if cross_product == 0
                    dist1 = calculate distance between vertex and current
                    dist2 = calculate distance between next_vertex and
current
                    if dist1 > dist2
                        next_vertex = vertex
                add next_vertex to hull
                current = next_vertex
                if current is leftmost
                    break
    return hull

function read_txt_file(file_path)
    lines = read contents of file into list of strings
    data = []
    for line in lines
        columns = split line into columns and convert to appropriate data
type
        data.append(columns)
    return data

points = read_txt_file('ban5000w-0.01-adjlist.txt')
```

```

before = get current time in milliseconds
convex_hull(points)
after = get current time in milliseconds
print "Time Used = ", after - before, " MilleSeconds"

```

2- Using queue data structure

Pseudo Code:

```

IMPORT math

FUNCTION convex_hull(polygon):
    # Find the leftmost vertex of the polygon
    leftmost = minimum value in polygon with key as the first element of
the vertex

    # Create a list to store the convex hull vertices
    hull = [leftmost]

    # Start at the leftmost vertex and iterate clockwise
    current = leftmost
    WHILE True:
        next_vertex = None
        FOR vertex in polygon:
            IF vertex == current:
                continue
            ELIF next_vertex is None:
                next_vertex = vertex
            ELSE:
                # Compare the angle between the current vertex and the
next candidate vertex
                # with the angle between the current vertex and the
next_vertex
                cross_product = (vertex[0] - current[0]) * (next_vertex[1]
- current[1]) - (vertex[1] - current[1]) * (next_vertex[0] - current[0])
                IF cross_product > 0:
                    next_vertex = vertex
                ELIF cross_product == 0:
                    # If the cross product is 0, choose the vertex that is
farther away

```

```

        dist1 = square root of (vertex[0] - current[0])^2 +
(vertex[1] - current[1])^2
        dist2 = square root of (next_vertex[0] - current[0])^2
+ (next_vertex[1] - current[1])^2
        IF dist1 > dist2:
            next_vertex = vertex

    # Add the next vertex to the convex hull
    add next_vertex to hull

    # Update the current vertex
    current = next_vertex

    # If we have completed a loop and returned to the leftmost vertex,
exit the loop
    IF current == leftmost:
        break
    RETURN hull

FUNCTION read_txt_file(file_path):
    # Read the contents of the file into a list of strings
    open file with file_path in read mode and assign to file
    lines = read all lines of file

    # Create an empty list to store the data
    data = []

    # Iterate through the lines and split them into columns
    FOR line in lines:
        columns = split line by space and remove the third element
        columns[0] = convert first element of columns to integer
        columns[1] = convert second element of columns to integer
        add columns to data
    RETURN data

points = read_txt_file('./ban5000w-0.01-adjlist.txt')

IMPORT time

before = current time in milliseconds
convex_hull(points)
after = current time in milliseconds
print("Time Used = ", (after - before), " MilleSeconds")

```

3- Using stack data structure

Code

```
function convex_hull(points):
    xmin = ymin = float('inf')
    xmax = ymax = float('-inf')
    for x, y in points:
        if x < xmin:
            xmin = x
        if y < ymin:
            ymin = y
        if x > xmax:
            xmax = x
        if y > ymax:
            ymax = y
    points = [p for p in points if not (p[0] == xmin or p[0] == xmax or
p[1] == ymin or p[1] == ymax)]
    sort points by x-coordinate
    hull = []
    for p in points:
        while len(hull) > 1 and cross(hull[-2], hull[-1], p) <= 0:
            remove last element from hull
        add p to hull
    return hull

function cross(p1, p2, p3):
    return (p2[0] - p1[0]) * (p3[1] - p1[1]) - (p2[1] - p1[1]) * (p3[0] -
p1[0])

FUNCTION read_txt_file(file_path):
    # Read the contents of the file into a list of strings
    open file with file_path in read mode and assign to file
    lines = read all lines of file

    # Create an empty list to store the data
    data = []

    # Iterate through the lines and split them into columns
```

```

FOR line in lines:
    columns = split line by space and remove the third element
    columns[0] = convert first element of columns to integer
    columns[1] = convert second element of columns to integer
    add columns to data
RETURN data

points = read_txt_file('./ban5000w-0.01-adjlist.txt')

IMPORT time

before = current time in milliseconds
convex_hull(points)
after = current time in milliseconds
print("Time Used = ", (after - before), " MilleSeconds")

```

4- Using priority queue data structure

Pseudo Code

```

import math

function convex_hull(points)
    xmin, ymin, xmax, ymax = infinity, infinity, negative infinity,
negative infinity
    for (x, y) in points:
        if x < xmin then xmin = x
        if y < ymin then ymin = y
        if x > xmax then xmax = x
        if y > ymax then ymax = y
    points = [p for p in points if p[0] ≠ xmin and p[0] ≠ xmax and p[1] ≠
ymin and p[1] ≠ ymax]
    p0 = min(points, key=lambda p: (p[1], p[0]))
    sort(points, key=lambda p: (angle(p0, p), distance(p0, p)))
    hull = []
    for p in points[:3]:
        while length(hull) > 1 and cross(hull[-2], hull[-1], p) <= 0:
            hull.pop()
        hull.append(p)

```

```

    for p in points[3:]:
        while length(hull) > 1 and cross(hull[-2], hull[-1], p) <= 0:
            hull.pop()
        hull.append(p)
    return hull

function angle(p1, p2)
    return atan2(p2[1] - p1[1], p2[0] - p1[0])

function distance(p1, p2)
    return sqrt((p2[1] - p1[1])^2 + (p2[0] - p1[0])^2)

function cross(p1, p2, p3)
    return (p2[0] - p1[0]) * (p3[1] - p1[1]) - (p2[1] - p1[1]) * (p3[0] - p1[0])

function read_txt_file(file_path)
    open file_path for reading and store the file in file
    lines = read the lines of file
    data = []
    for line in lines:
        columns = split line by white spaces and remove the 3rd column
        convert the first and second columns to integers
        append columns to data
    return data

points = read_txt_file('ban5000w-0.01-adjlist.txt')

import time
before = current time in milliseconds
convex_hull(points)
after = current time in milliseconds
print("Time Used = ", after - before, " MilleSeconds")

```