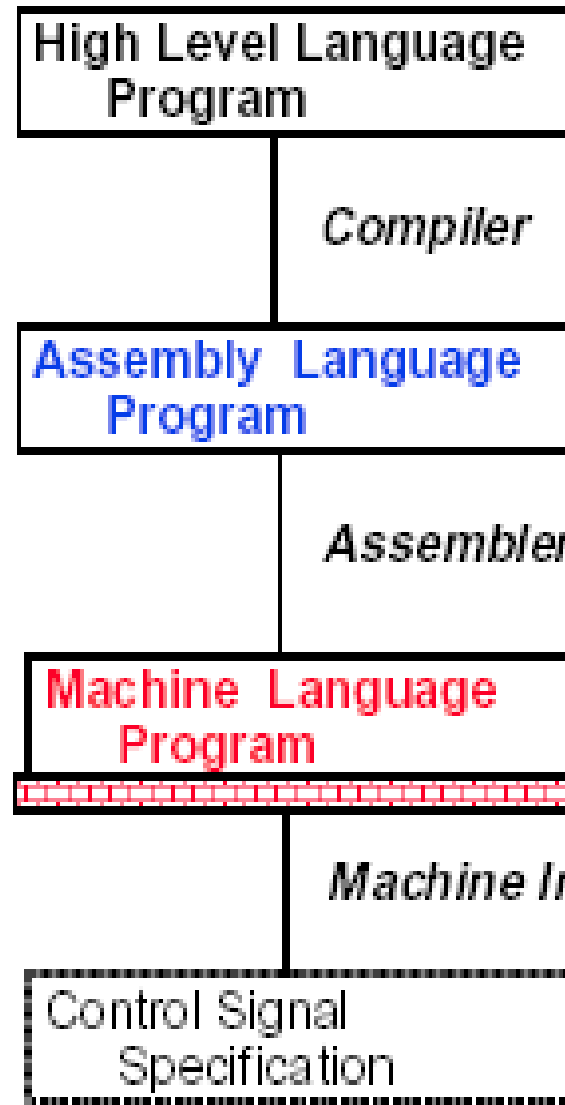# COMPUTER HARDWARE

Instruction Set Architecture

Overview

- Computer architecture
- Operand addressing
  - Addressing architecture
  - Addressing modes
- Elementary instructions
  - Data transfer instructions
  - Data manipulation instructions
    - Floating point computations
  - Program control instructions
    - Program interrupt and exceptions

Overview

High Level Language Program

Compiler

Assembly Language Program

Assembler

Machine Language Program

Machine Interpretation

Control Signal Specification

temp = v[k];

v[k] = v[k+1];

v[k+1] = temp;

lw $15, 0($2)
lw $16, 4($2)
sw $16, 0($2)
sw $15, 4($2)

```
0000 1001 1100 0110 1010 1111 0101 1000
1010 1111 0101 1000 0000 1001 1100 0110
1100 0110 1010 1111 0101 1000 0000 1001
0101 1000 0000 1001 1100 0110 1010 1111
```

ALUOP[0:3] <= InstReg[9:11] & MASK

Computer Architecture

- Instruction set architecture
  - A set of hardware-implemented instructions, the symbolic name and the binary code format of each instruction
- Organization
  - Structures such as datapath, control units, memories, and the busses that interconnect them
- Hardware
  - The logic, the electronic technology employed, the various physical design aspects of the computer
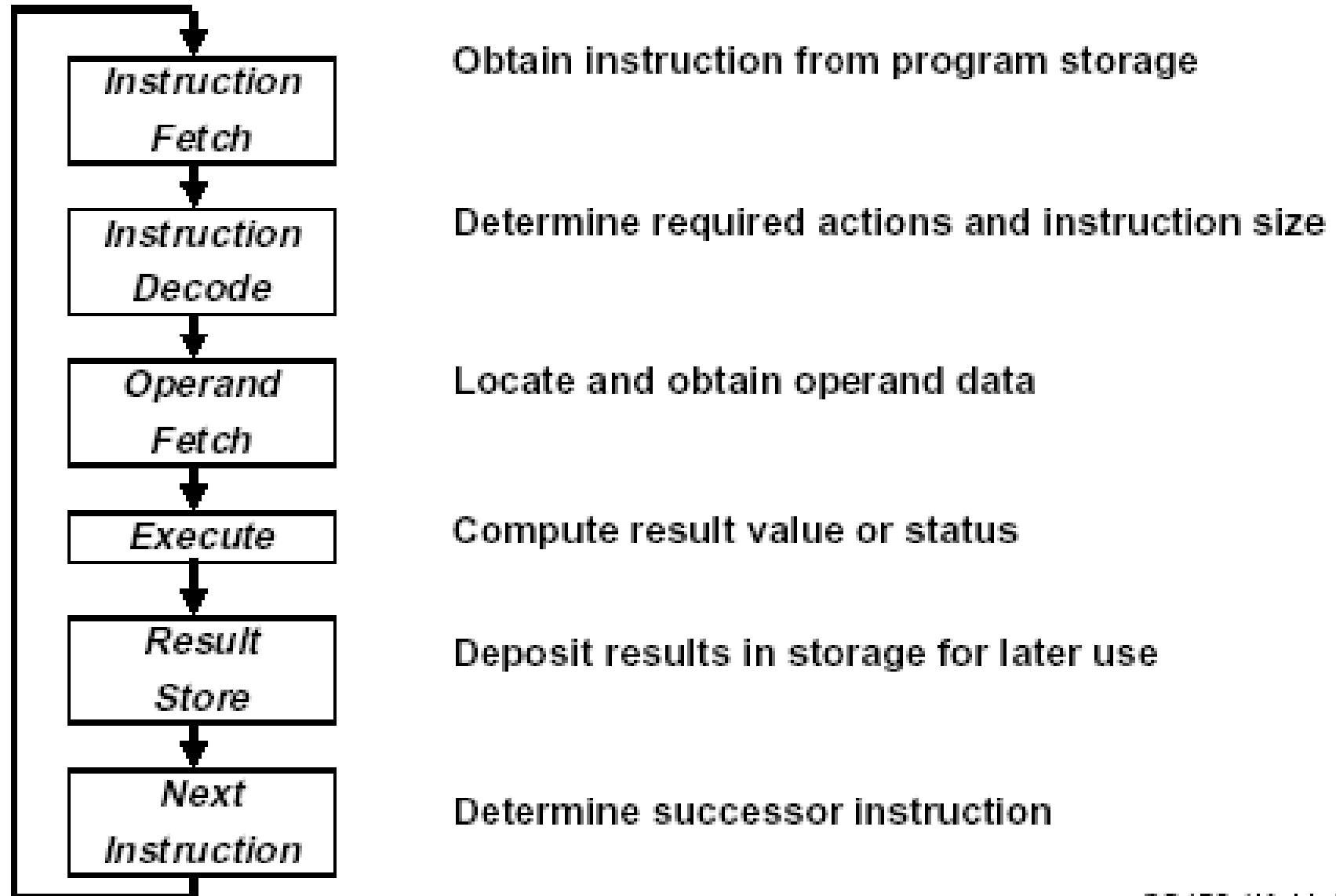
Example ISAs (Instruction Set Architectures)

- RISC (Reduced Instruction Set Computer)
  – Digital Alpha
  – Sun Sparc
  – MIPS RX000
  – IBM PowerPC
  – HP PA/RISC

- CISC (Complex Instruction Set Computer)
  – Intel x86
  – Motorola 68000
  – DEC VAX

- VLIW (Very Large Instruction Word)
  – Intel Itanium

Instruction Set Architecture

- A processor is specified completely by its *instruction set architecture (ISA)*

- Each ISA will have a variety of instructions and instruction formats, which will be interpreted by the processor's control unit and executed in the processor's datapath

- An instruction represents the smallest indivisible unit of computation. It is a string of bits grouped into different numbers and size of *substrings* (*field*s)

  - *Operation code (opcode): the operation to be performed*
  - *Address field: where we can find the operands needed for that operation*
  - *Mode field:* how to derive the data's effective address from the information given in the address field
  - *Other fields: constant immediate operand or shift*

Computer Operation Cycle

Instruction Fetch	Obtain instruction from program storage
Instruction Decode	Determine required actions and instruction size
Operand Fetch	Locate and obtain operand data
Execute	Compute result value or status
Result Store	Deposit results in storage for later use
Next Instruction	Determine successor instruction

CS152 (Kubiat

Register Set

- Programmer accessible registers (R0 to R7 in previous multi-cycle computer)

- Other registers

  - Registers in the register file accessible only to microprograms (R8 to R15)

  - Instruction registers (IR)

  - Program counter (PC)

  - Pipeline registers

  - Processor status register (PSR: CVNZ state)

  - Stack pointer (SP)

Operand Addressing

- Operand: register value, memory content, or immediate
- **_Explicit address_**: address field in the instruction
- **_Implied address_**: the location of operand is specified by the opcode or other operand address

Three Address Instructions

- Example: X=(A+B)(C+D)

- Operands are in memory address symbolized by the letters A,B,C,D, result stored memory address of X

ADD T1, A, B	M[T1] ← M[A] + M[B]
ADD T2, C, D	M[T2] ← M[C] + M[D]
MUX X, T1, T2	M[X] ← M[T1] X M[T2]
OR	
ADD R1, A, B	R1 ← M[A] + M[B]
ADD R2, C, D	R2 ← M[C] + M[D]
MUX X, R1, R2	M[X]← R1 X R2

- +: Short program, 3 instructions

- -: Binary coded instruction require more bits to specify three addresses

Two Address Instructions

- The first operand address also serves as the implied address for the result

MOVE T1, A	M[T1] ← M[A]
ADD T1, B	M[T1] ← M[T1] + M[B]
MOVE X, C	M[X] ← M[C]
ADD X, D	M[X] ← M[X] + M[D]
MUX X, T1	M[X] ← M[X] X M[T1]

- 5 instructions

One Address Instructions

● Implied address: a register called *an accumulator ACC* for one operand and the result, *single-accumulator architecture*

LD	A	ACC ← M[A]
ADD	B	ACC ← ACC + M[B]
ST	X	M[X] ← ACC
LD	C	ACC ← M[C]
ADD	D	ACC ← ACC + M[D]
MUX	X	ACC ← ACC X M[X]
ST	X	M[X] ← ACC

7 instructions

● All operations are between the ACC register and a memory operand

Zero Address Instructions

- ## Use stack (FILO):

  - ADD $TOS \leftarrow TOS + TOS_{-1}$
  - PUSH X $TOS \leftarrow M[X]$
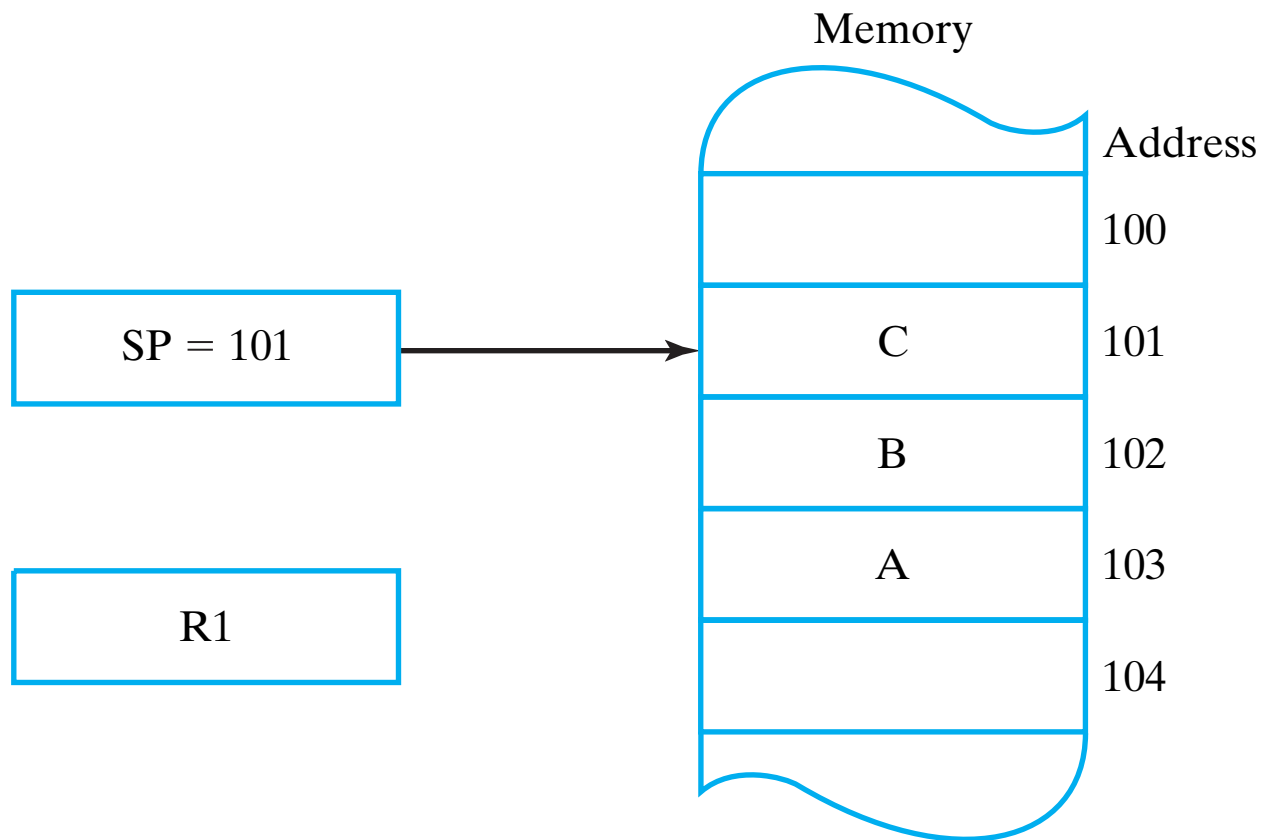 - POP X $M[X] \leftarrow TOS$

PUSH A	$TOS \leftarrow M[A]$	
PUSH B	$TOS \leftarrow M[B]$	
ADD	$TOS \leftarrow TOS + TOS_{-1}$	
PUSH C	$TOS \leftarrow M[C]$	8 instructions
PUSH D	$TOS \leftarrow M[D]$	
ADD	$TOS \leftarrow TOS + TOS_{-1}$	
MUX	$TOS \leftarrow TOS \times TOS_{-1}$	
POP X	$M[X] \leftarrow TOS$	

- ## Data manipulation operations: between the stack elements
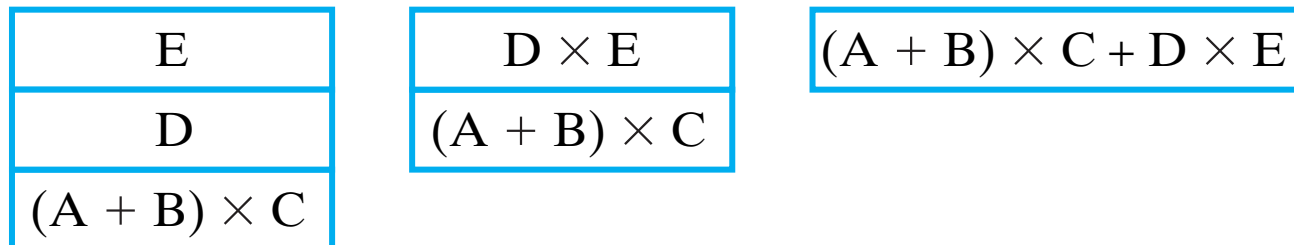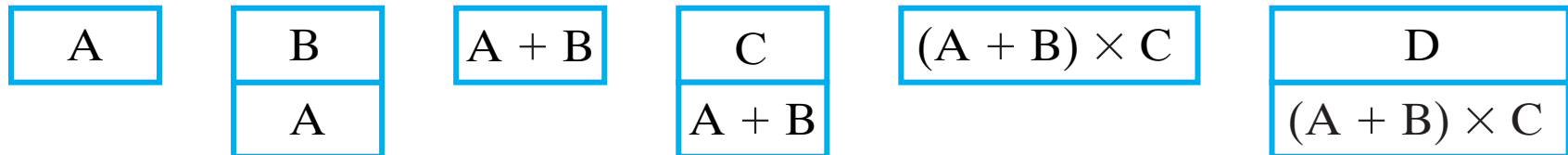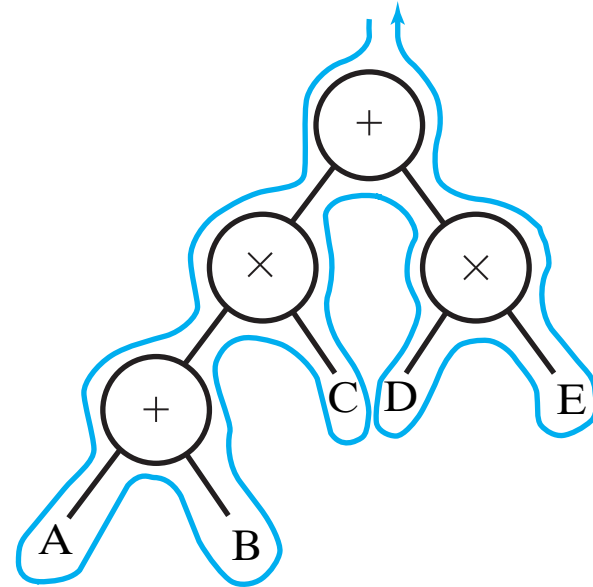
- ## Transfer operations: between the stack and the memory

Stack Instructions

- Push: SP←SP-1; TOS←R1
- Pop: R1←TOS; SP←SP +1

Memory

Address

	100
C	101
B	102
A	103
	104

SP = 101

R1

Stack Architecture

- The infix architecture
  (A + B) x C + (D x E)
- Reverse Polish Notation (RPN)
  A B + C x D E x +

A

B
A

A + B

C
A + B

$(A + B) \times C$

D
$(A + B) \times C$

E
D
$(A + B) \times C$

$D \times E$
$(A + B) \times C$

$(A + B) \times C + D \times E$

Addressing Architecture

- Defines:
  - Restriction on the number of memory addresses in instructions
  - Number of operands

- Two kinds of addressing architecture:
  - Memory-to-memory architecture
    - Only one register - PC
    - All operands from memory, and results to memory
    - Many memory accesses
  - Register-to-register (load/store) architecture
    - Restrict only one memory address to load/store types, all other operations are between registers

LD R1, A	R1 ← M[A]
LD R2, B	R2 ← M[B]
ADD R3, R1, R2	R3 ← R1 + R2
LD R1, C	R1 ← M[C]
LD R2, D	R2 ← M[D]
ADD R1, R1, R2	R1 ← R1 + R2
MUL R1, R1, R3	R1 ← R1 X R3
ST X, R1	M[X] ← R1

Addressing Modes

- **Address field:** contains the information needed to determine the location of the operands and the result of an operation

- **Addressing mode:** specifies how to interpret the information within this address field, how to compute the **actual** or **effective** address of the data needed.

- Availability of a variety of addressing modes lets programmers write more efficient code
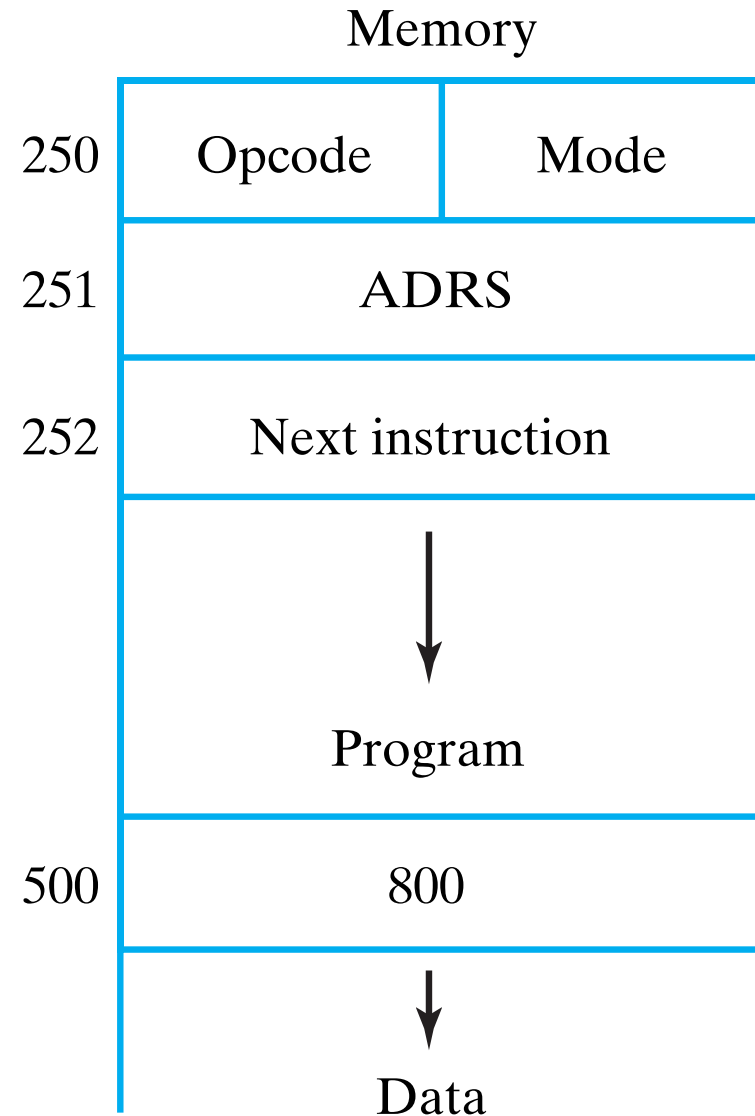
Addressing Modes

- **Implied** mode - implied in the opcode, such as stack, accumulator
- **Immediate** mode (operand) - a = 0x0801234
- **Register** mode - a=R[b]
- **Register-indirect** mode – a =M[R[b]]
- **Direct** addressing mode - a = M[0x0013df8]
- **Indirect** Addressing mode - a= M[M[0x0013df8]]
- **PC-relative** addressing – branch etc. (offset + PC)
- **Indexed** addressing - a=b[1]

Demonstrating Direct Addressing

PC = 250

ACC

Opcode: Load ACC
Mode: Direct address
ADRS: 500
Operation: ACC ← 800

Memory

250	Opcode	Mode
251	ADRS	
252	Next instruction	

Program

| 500 | 800 |

Data

Example

Opcode: Load to ACC,   ADRS or NBR=500

Memory

250	Opcode	Mode
251	ADRS or NBR = 500	
252	Next instruction	
400	700	
500	800	
752	600	
800	300	
900	200	

PC = 250   R1 = 400   ACC

Refers to Figure 10-6

Addressing Mode	Symbolic Convention	Register Transfer	Effective Address	Contents of *ACC*
Direct	LDA ADRS	$ACC \leftarrow M[ADRS]$	500	800
Immediate	LDA #NBR	$ACC \leftarrow NBR$	251	500
Indirect	LDA [ADRS]	$ACC \leftarrow M[M[ADRS]]$	800	300
Relative	LDA $ADRS	$ACC \leftarrow M[ADRS + PC]$	752	600
Index	LDA ADRS (R1)	$ACC \leftarrow M[ADRS + R1]$	900	200
Register	LDA R1	$ACC \leftarrow R1$	—	400
Register-indirect	LDA (R1)	$ACC \leftarrow M[R1]$	400	700

Instruction Set Architecture

	RISC (reduced instruction set computers)	CISC (complex instruction set computers)
Memory access	restricted to load/store instructions, and data manipulation instructions are register-to-register	is directly available to most types of instructions
Addressing mode	limited in number	substantial in number
Instruction formats	all of the same length	of different lengths
Instructions	perform elementary operations	perform both elementary and complex operations
Control unit	Hardwired, high throughput and fast execution	Microprogrammed, facilitate compact programs and conserve memory,

Data Transfer Instructions

- Data transfer: memory← →registers, processor registers ← → input/output registers, among the processor registers
- Data transfer instructions

Name	Mnemonic
Load	LD
Store	ST
Move	MOVE
Exchange	XCH
Push	PUSH
Pop	POP
Input	IN
Output	OUT
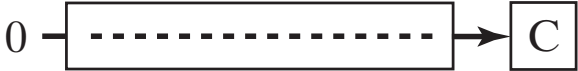
I/O

- Input and output (I/O) instructions transfer data between processor registers and I/O devices
  - Ports

- Independent I/O system: address range assigned to memory and I/O ports are independent from each other

- Memory-mapped I/O system: assign a subrange of the memory addresses for addressing I/O ports

Data Manipulation Instructions

Arithmetic		Logical and bit manipulation		Shift instructions	
Name	**Mnemonic**	**Name**	**Mnemonic**	**Name**	**Mnemonic**
Increment	INC	Clear	CLR	Logical shift right	SHR
Decrement	DEC	Set	SET	Logical shift left	SHL
Add	ADD	Complement	NOT	Arithmetic shift right	SHRA
Subtract	SUB	AND	AND	Arithmetic shift left	SHRL
Multiply	MUL	OR	OR	Rotate right	ROR
Divide	DIV	Exclusive-OR	XOR	Rotate left	ROL
Add with carry	ADDC	Clear carry	CLRC	Rotate right with carry	RORC
Subtract with borrow	SUBB	Set Carry	SETC	Rotate left with carry	ROLC
Subtract reverse	SUBR	Complement carry	COMC		
Negate	NEG				

Typical Shift Instructions

Name	Mnemonic	Diagram
Logical shift right	SHR	$0 \rightarrow \boxed{\text{- - - - - - - -}} \rightarrow \boxed{C}$
Logical shift left	SHL	$\boxed{C} \leftarrow \boxed{\text{- - - - - - - -}} \leftarrow 0$
Arithmetic shift right	SHRA	$\boxed{\text{- - - - - - - -}} \rightarrow \boxed{C}$
Arithmetic shift left	SHLA	$\boxed{C} \leftarrow \boxed{\text{- - - - - - - -}} \leftarrow 0$
Rotate right	ROR	$\boxed{\text{- - - - - - - -}} \rightarrow \boxed{C}$
Rotate left	ROL	$\boxed{C} \leftarrow \boxed{\text{- - - - - - - -}}$
Rotate right with carry	RORC	$\boxed{\text{- - - - - - - -}} \rightarrow \boxed{C}$
Rotate left with carry	ROLC	$\boxed{C} \leftarrow \boxed{\text{- - - - - - - -}}$

Program Control Instructions

- Control over the flow of program execution and a capability of branching to different program segments

- One-address instruction:
  - Jump: direct addressing
  - Branch: relative addressing

Name	Mnemonic
Branch	BR
Jump	JMP
Call procedure	CALL
Return from procedure	RET
Compare (by subtraction)	CMP
Test (by ANDing)	TEST

Conditional Branching Instructions

- May or may not cause a transfer of control, depending on the value of stored bits in the *PSR (processor state register)*

Branch Condition	Mnemonic	Test Condition
Branch if zero	BZ	$Z = 1$
Branch if not zero	BNZ	$Z = 0$
Branch if carry	BC	$C = 1$
Branch if no carry	BNC	$C = 0$
Branch if minus	BN	$N = 1$
Branch if plus	BNN	$N = 0$
Branch if overflow	BV	$V = 1$
Branch if no overflow	BNV	$V = 0$

Conditional Branching Instructions

● for Unsigned Numbers

Branch Condition	Mnemonic	Condition	Status Bits*
Branch if above	BA	$A > B$	$C + Z = 0$
Branch if above or equal	BAE	$A \geq B$	$C = 0$
Branch if below	BB	$A < B$	$C = 1$
Branch if below or equal	BBE	$A \leq B$	$C + Z = 1$
Branch if equal	BE	$A = B$	$Z = 1$
Branch if not equal	BNE	$A \neq B$	$Z = 0$

*Note that C here is a borrow bit.

● for Signed Numbers

Branch condition	Mnemonic	Condition	Status Bits
Branch if greater	BG	$A > B$	$(N \oplus V) + Z = 0$
Branch if greater or equal	BGE	$A \geq B$	$N \oplus V = 0$
Branch if less	BL	$A < B$	$N \oplus V = 1$
Branch if less or equal	BLE	$A \leq B$	$(N \oplus V) + Z = 1$
Branch if equal	BE	$A = B$	$Z = 1$
Branch if not equal	BNE	$A \neq B$	$Z = 0$

Datapath for Branch instruction
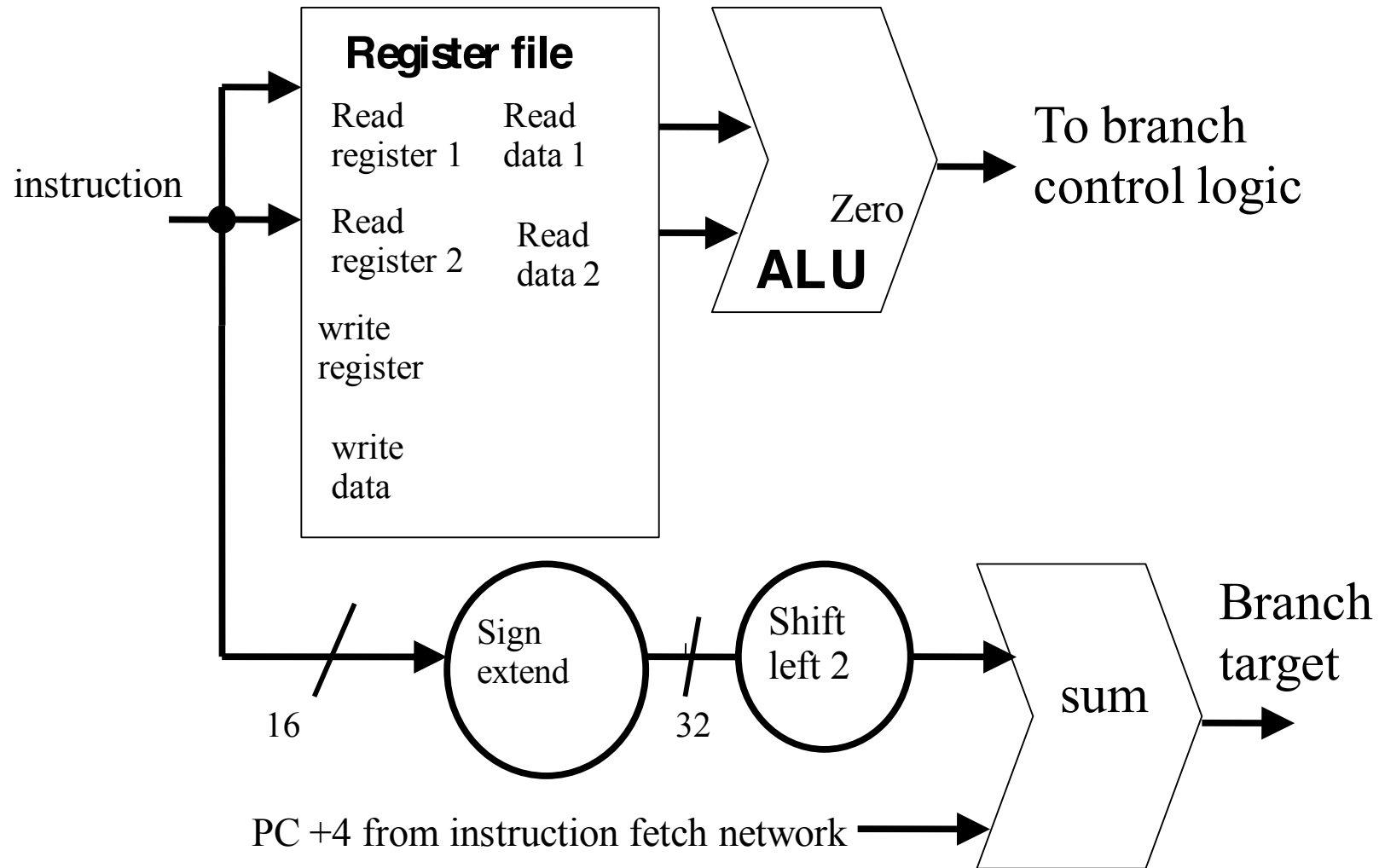
Procedure Call and Return Instructions

- Procedure: self-contained sequence of instructions that performs a given computational task

- Call procedure instruction: one-address field

  - Stores the value of the PC (return address) in a temporary location

  - The address in the call procedure instruction is loaded into the PC

- Final instruction in every procedure: return instruction

  - Take the return address and load into the PC

- Temporary Location: fixed memory location, processor register or memory stack

  - E.g. stack

    - Procedurecall: SP←SP-1;M[SP] ←PC+4;PC←Effectiveaddress
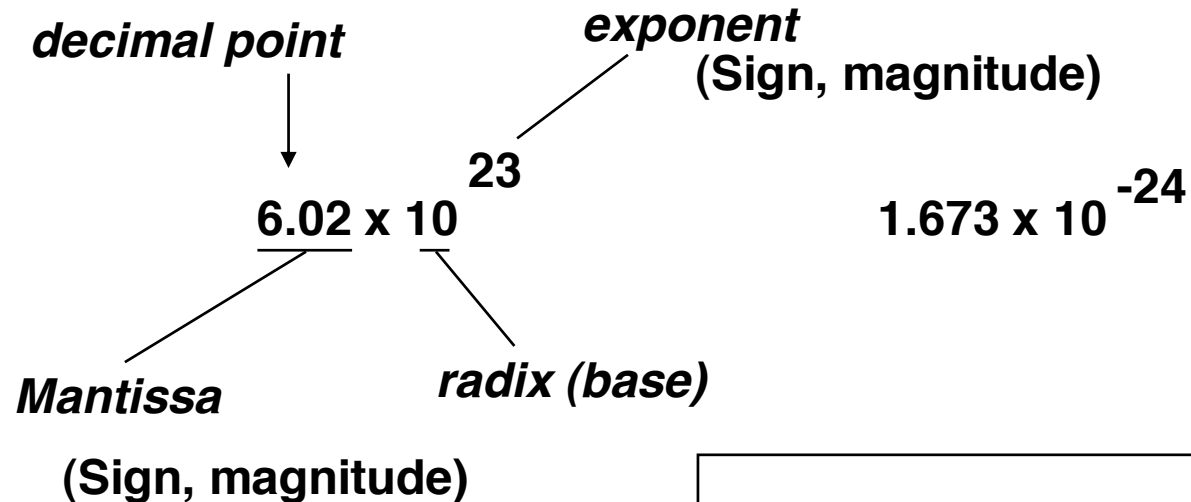   - Return: PC ←M[SP]; SP ←SP+1

Interrupts

- Types of Interrupts
  1. **External:** Hard Drive, Mouse, Keyboard, Modem, Printer

  2. **Internal :** Overflow; Divide by zero; Invalid opcode; Memory stack overflow; Protection violation

  3. **Software:** A software interrupt provides a way to call the interrupt routines normally associated with external or internal interrupts by inserting an instruction into the code.

Floating-Point Computation

- What can be represented in N bits?

Unsigned	0	to	2^N-1
2s Complement	-2^{N-1}	to	$2^{N-1} - 1$
1s Complement	$-2^{N-1}+1$	to	$2^{N-1}-1$
BCD	0	to	$10^{N/4} - 1$

- But, what about?
  - very large numbers?
    9,349,398,989,787,762,244,859,087,678
  - very small number? 0.00000000000000000000045691
  - rationals   2/3
  - irrationals $\sqrt{2}$
  - transcendentals   e

Recall Scientific Notation

decimal point

exponent
(Sign, magnitude)

$$6.02 \times 10^{23}$$

$$1.673 \times 10^{-24}$$

Mantissa
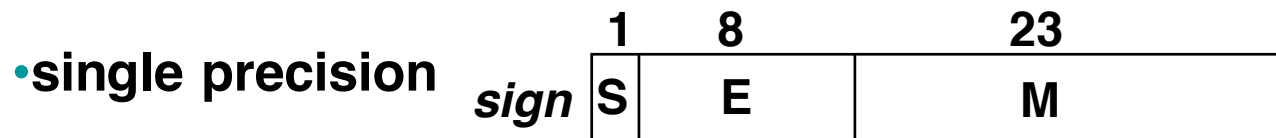
radix (base)

(Sign, magnitude)

■ Issues:

- Representation, Normal form
- Range and Precision
- Arithmetic (+, -, *, /)
- Rounding
- Exceptions (e.g., divide by zero, overflow, underflow)
- Errors
- Properties (negation, inversion, if A $\neq$ B then A - B $\neq$ 0)

$$\text{IEEE F.P.} \quad \pm 1.M \times 2^{e-127}$$

Floating-Point Numbers

- **Representation of floating point numbers in IEEE 754 standard:**

  - **single precision**

1	8	23
S	E	M

    sign

    exponent: binary integer

    mantissa: sign + magnitude, normalized binary significand w/ hidden integer bit: 1.M

    Biased exponent: actual exponent is $e = E - 127$ $(0 < E < 255)$

    $$N = (-1)^S \, 2^{E-127} \, (1.M)$$

    $0 = 0 \; 00000000 \; 0 \ldots 0$ $-1.5 = 1 \; 01111111 \; 10 \ldots 0$

- **Exponent field (E):**
  E=0 reserved for **zero** (with fraction **M=0**), and denormalized #s (**M ≠ 0**)
  E=255 reserved for $\pm\infty$ (with fraction **M=0**), and **NaN** (**M ≠ 0**)
- **Magnitude of numbers that can be represented is in the range: (with E in [1, 254]):**

  2^{-126} (1.8×10^{-38}) ~ $2^{127} (2 - 2^{-23})$ (3.4×10^{38})

Basic Addition Algorithm

- **Steps for addition (or subtraction):**

(1) compute Ye - Xe *(getting ready to align binary point). Ye>Xe*
(2) right shift Xm that many positions to form Xm • 2^{Xe-Ye}
(3) compute Xm • 2^{Xe-Ye} + Ym

Example: $.5372400 \times 10^2$ ⟹ $.5372400 \times 10^2$

       $^-.1580000 \times 10^{-1}$ $- .0001580 \times 10^2$
       _____   _____
                                                    $.5370820 \times 10^2$

if result demands normalization, then normalization step follows:
(4) left shift result, decrement result exponent (e.g., 0.001xx…)
       right shift result, increment result exponent (e.g., 101.1xx…)
       continue until MSB of data is 1   (NOTE: Hidden bit in IEEE
       Standard)
(5) if result is 0 mantissa, may need to zero exponent by special
       step

Example

- Adding operation on two IEEE single precision floating point numbers (X and Y)

X = 0100 0000 1010 0000 0000 0000 0000 0000

Y = 1100 0000 0011 0000 0000 0000 0000 0000

1	8	23
S	E	M

$$N = (-1)^S 2^{E-127} (1.M)$$

$X = (-1)^0 2^{129-127} (1.01) = 2^2 * 1.01$

$Y = (-1)^1 2^{128-127} (1.011) = -2*1.011$

Xe>Ye

$Y = -2^2*(1.011 * 2^{-1}) = -2^2*(0.1011)$

$X+Y = 2^2*(1.01 - 0.1011) = 2^2*(0.1001) = 2*1.001$

$\quad = 0100\ 0000\ 0001\ 0000\ 0000\ 0000\ 0000\ 0000$