

Wire - pinswap_via_swap, pinswap_via_pins, SFRReader_reader

Example Code

```
// Wire pinswapping via Wire.pins()
// Copy of Wire Master Reader
// except for the Wire.pins() call.
// This is mostly here to make sure it gets tested by CI.

#include <Wire.h>

void setup() {
  Wire.swap(2);          // Choose pin swapping level 2 (PC2/PC3 master/slave)
  Wire.begin();          // join i2c bus (address optional for master)
  Serial.begin(9600);    // start serial for output
}

void loop() {
  Wire.requestFrom(8, 6); // request 6 bytes from slave device #8

  while (Wire.available()) { // slave may send less than requested
    char c = Wire.read(); // receive a byte as character
    Serial.print(c);      // print the character
  }

  delay(500);
}
```

```
// Wire pinswapping via Wire.pins()
// Copy of Wire Master Reader
// except for the Wire.pins() call.
// This is mostly here to make sure it gets tested by CI.

#include <Wire.h>

void setup() {
  Wire.pins(PIN_PC2, PIN_PC3); // Choose the PC2/PC3 pinset for the TWI interface
  Wire.begin();                // join i2c bus (address optional for master)
  Serial.begin(9600);          // start serial for output
}

void loop() {
  Wire.requestFrom(8, 6); // request 6 bytes from slave device #8
```

```
while (Wire.available()) { // slave may send less than requested
  char c = Wire.read(); // receive a byte as character
  Serial.print(c);        // print the character
}

delay(500);
}
```

```
// I2C SRF10 or SRF08 Devantech Ultrasonic Ranger Finder
// by Nicholas Zambetti <http://www.zambetti.com>
// and James Tichenor <http://www.jamestichenor.net>

// Demonstrates use of the Wire library reading data from the
// Devantech Ultrasonic Rangers SFR08 and SFR10

// Created 29 April 2006

// This example code is in the public domain.

#include <Wire.h>

void setup() {
  Wire.begin();                // join i2c bus (address optional for master)
  Serial.begin(9600);          // start serial communication at 9600bps
}

int reading = 0;

void loop() {
  // step 1: instruct sensor to read echoes
  Wire.beginTransmission(112); // transmit to device #112 (0x70)
  // the address specified in the datasheet is 224 (0xE0)
  // but i2c addressing uses the high 7 bits so it's 112
  Wire.write(byte(0x00));      // sets register pointer to the command register
  // (0x00)
  Wire.write(byte(0x50));      // command sensor to measure in "inches" (0x50)
  // use 0x51 for centimeters
  // use 0x52 for ping microseconds
  Wire.endTransmission();      // stop transmitting

  // step 2: wait for readings to happen
  delay(70);                   // datasheet suggests at least 65 milliseconds

  // step 3: instruct sensor to return a particular echo reading
  Wire.beginTransmission(112); // transmit to device #112
  Wire.write(byte(0x02));      // sets register pointer to echo #1 register (0x02)
  Wire.endTransmission();      // stop transmitting
```

```
// step 4: request reading from sensor
Wire.requestFrom(112, 2);    // request 2 bytes from slave device #112

// step 5: receive reading from sensor
if (2 <= Wire.available()) { // if two bytes were received
  reading = Wire.read();    // receive high byte (overwrites previous reading)
  reading = reading << 8;   // shift high byte to be high 8 bits
  reading |= Wire.read();   // receive low byte as lower 8 bits
  Serial.println(reading);  // print the reading
}

delay(250);                // wait a bit since people have to read the output
:)
}

/*

// The following code changes the address of a Devantech Ultrasonic Range Finder
(SRF10 or SRF08)
// usage: changeAddress(0x70, 0xE6);

void changeAddress(byte oldAddress, byte newAddress) {
  Wire.beginTransmission(oldAddress);
  Wire.write(byte(0x00));
  Wire.write(byte(0xA0));
  Wire.endTransmission();

  Wire.beginTransmission(oldAddress);
  Wire.write(byte(0x00));
  Wire.write(byte(0xAA));
  Wire.endTransmission();

  Wire.beginTransmission(oldAddress);
  Wire.write(byte(0x00));
  Wire.write(byte(0xA5));
  Wire.endTransmission();

  Wire.beginTransmission(oldAddress);
  Wire.write(byte(0x00));
  Wire.write(newAddress);
  Wire.endTransmission();
}

*/
```

Result

Examples compiled and uploaded successfully to the board.

Messages

Sketch uses 3734 bytes (2%) of program storage space. Maximum is 131072 bytes. Global variables use 494 bytes (3%) of dynamic memory, leaving 15890 bytes for local variables. Maximum is 16384 bytes.

avrdude: Version 6.3-20201216
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Copyright (c) 2007-2014 Joerg Wunsch

System wide configuration file is
"C:\Users\ivanFernandez\AppData\Local\Arduino15\packages\Microchip\hardware\megaavr\1.0.0/avrdude.conf"

Using Port : usb
Using Programmer : curiosity_updi
avrdude: Found CMSIS-DAP compliant device, using EDBG protocol
AVR Part : AVR128DA48
Chip Erase delay : 0 us
PAGEL : P00
BS2 : P00
RESET disposition : dedicated
RETRY pulse : SCK
serial program mode : yes
parallel program mode : yes
Timeout : 0
StabDelay : 0
CmdexeDelay : 0
SyncLoops : 0
ByteDelay : 0
PollIndex : 0
PollValue : 0x00
Memory Detail :

		Block Poll						Page					
Polled		Memory	Type	Mode	Delay	Size	Indx	Paged	Size	Size	#Pages	MinW	MaxW
ReadBack		-----											

0x00 0x00		signature		0	0	0	0	no	3	0	0	0	0
0x00 0x00		prodsig		0	0	0	0	no	125	125	0	0	0
0x00 0x00		fuses		0	0	0	0	no	9	16	0	0	0
0x00 0x00		fuse0		0	0	0	0	no	1	0	0	0	0
0x00 0x00		fuse1		0	0	0	0	no	1	0	0	0	0
0x00 0x00		fuse2		0	0	0	0	no	1	0	0	0	0
0x00 0x00		fuse4		0	0	0	0	no	1	0	0	0	0

0x00 0x00	fuse5	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse6	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse7	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse8	0	0	0	0	no	1	0	0	0	0
0x00 0x00	lock	0	0	0	0	no	4	1	0	0	0
0x00 0x00	data	0	0	0	0	no	0	0	0	0	0
0x00 0x00	flash	0	0	0	0	no	131072	512	0	0	0
0x00 0x00	eeeprom	0	0	0	0	no	512	32	0	0	0

```

Programmer Type : JTAGICE3_UPDI
Description      : Microchip Curiosity in UPDI mode
ICE hardware version: 0
ICE firmware version: 1.17 (rel. 514)
Serial number    : MCHP3280031800001901
Vtarget          : 3.31 V
JTAG clock megaAVR/program: 0 kHz
JTAG clock megaAVR/debug: 0 kHz
JTAG clock Xmega: 0 kHz
PDI clock Xmega : 100 kHz

```

```

avrdude: Partial Family_ID returned: "    "
avrdude: AVR device initialized and ready to accept instructions

```

```

Reading | ##### | 100% 0.01s

```

```

avrdude: Device signature = 0x1e9708 (probably avr128da48)
avrdude: NOTE: "flash" memory has been specified, an erase cycle will be performed
        To disable this feature, specify the -D option.
avrdude: erasing chip
avrdude: reading input file "0b11001001"
avrdude: writing fuse5 (1 bytes):

```

```

Writing | ##### | 100% 0.02s

```

```

avrdude: 1 bytes of fuse5 written
avrdude: verifying fuse5 memory against 0b11001001:
avrdude: load data fuse5 data from input file 0b11001001:
avrdude: input file 0b11001001 contains 1 bytes
avrdude: reading on-chip fuse5 data:

```

```

Reading | ##### | 100% 0.00s

```

```

avrdude: verifying ...
avrdude: 1 bytes of fuse5 verified
avrdude: reading input file "0x00"
avrdude: writing fuse7 (1 bytes):

```

Writing | ##### | 100% 0.02s

avrdude: 1 bytes of fuse7 written
avrdude: verifying fuse7 memory against 0x00:
avrdude: load data fuse7 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse7 data:

Reading | ##### | 100% 0.00s

avrdude: verifying ...
avrdude: 1 bytes of fuse7 verified
avrdude: reading input file "0x00"
avrdude: writing fuse8 (1 bytes):

Writing | ##### | 100% 0.02s

avrdude: 1 bytes of fuse8 written
avrdude: verifying fuse8 memory against 0x00:
avrdude: load data fuse8 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse8 data:

Reading | ##### | 100% 0.00s

avrdude: verifying ...
avrdude: 1 bytes of fuse8 verified
avrdude: reading input file
"C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_627681/pinswap_via_pins.ino.hex"
avrdude: writing flash (3734 bytes):

Writing | ##### | 100% 1.26s

avrdude: 3734 bytes of flash written
avrdude: verifying flash memory against
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_627681/pinswap_via_pins.ino.hex
:
avrdude: load data flash data from input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_627681/pinswap_via_pins.ino.hex
:
avrdude: input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_627681/pinswap_via_pins.ino.hex
contains 3734 bytes
avrdude: reading on-chip flash data:

Reading | ##### | 100% 0.69s

avrdude: verifying ...
avrdude: 3734 bytes of flash verified

avrdude done. Thank you.

Sketch uses 3734 bytes (2%) of program storage space. Maximum is 131072 bytes. Global variables use 494 bytes (3%) of dynamic memory, leaving 15890 bytes for local variables. Maximum is 16384 bytes.

avrdude: Version 6.3-20201216

Copyright (c) 2000-2005 Brian Dean, <http://www.bdmicro.com/>

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System wide configuration file is

"C:\Users\ivanFernandez\AppData\Local\Arduino15\packages\Microchip\hardware\megaavr\1.0.0/avrdude.conf"

Using Port : usb

Using Programmer : curiosity_updi

avrdude: Found CMSIS-DAP compliant device, using EDBG protocol

AVR Part : AVR128DA48

Chip Erase delay : 0 us

PAGEL : P00

BS2 : P00

RESET disposition : dedicated

RETRY pulse : SCK

serial program mode : yes

parallel program mode : yes

Timeout : 0

StabDelay : 0

CmdexeDelay : 0

SyncLoops : 0

ByteDelay : 0

PollIndex : 0

PollValue : 0x00

Memory Detail :

Polled	Block Poll						Page					
	Memory	Type	Mode	Delay	Size	Indx	Paged	Size	Size	#Pages	MinW	MaxW
ReadBack	-----											
-----	signature		0	0	0	0	no	3	0	0	0	0
0x00 0x00	prodsig		0	0	0	0	no	125	125	0	0	0
0x00 0x00	fuses		0	0	0	0	no	9	16	0	0	0
0x00 0x00	fuse0		0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse1		0	0	0	0	no	1	0	0	0	0
0x00 0x00												

0x00 0x00	fuse2	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse4	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse5	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse6	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse7	0	0	0	0	no	1	0	0	0	0
0x00 0x00	fuse8	0	0	0	0	no	1	0	0	0	0
0x00 0x00	lock	0	0	0	0	no	4	1	0	0	0
0x00 0x00	data	0	0	0	0	no	0	0	0	0	0
0x00 0x00	flash	0	0	0	0	no	131072	512	0	0	0
0x00 0x00	eprom	0	0	0	0	no	512	32	0	0	0

```

Programmer Type : JTAGICE3_UPDI
Description      : Microchip Curiosity in UPDI mode
ICE hardware version: 0
ICE firmware version: 1.17 (rel. 514)
Serial number    : MCHP3280031800001901
Vtarget         : 3.31 V
JTAG clock megaAVR/program: 0 kHz
JTAG clock megaAVR/debug: 0 kHz
JTAG clock Xmega: 0 kHz
PDI clock Xmega : 100 kHz

```

```

avrdude: Partial Family_ID returned: "    "
avrdude: AVR device initialized and ready to accept instructions

```

```

Reading | ##### | 100% 0.01s

```

```

avrdude: Device signature = 0x1e9708 (probably avr128da48)
avrdude: NOTE: "flash" memory has been specified, an erase cycle will be performed
        To disable this feature, specify the -D option.
avrdude: erasing chip
avrdude: reading input file "0b11001001"
avrdude: writing fuse5 (1 bytes):

```

```

Writing | ##### | 100% 0.02s

```

```

avrdude: 1 bytes of fuse5 written
avrdude: verifying fuse5 memory against 0b11001001:
avrdude: load data fuse5 data from input file 0b11001001:
avrdude: input file 0b11001001 contains 1 bytes
avrdude: reading on-chip fuse5 data:

```

```

Reading | ##### | 100% 0.00s

```



```
avrdude: verifying ...
avrdude: 1 bytes of fuse5 verified
avrdude: reading input file "0x00"
avrdude: writing fuse7 (1 bytes):

Writing | ##### | 100% 0.02s

avrdude: 1 bytes of fuse7 written
avrdude: verifying fuse7 memory against 0x00:
avrdude: load data fuse7 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse7 data:

Reading | ##### | 100% 0.00s

avrdude: verifying ...
avrdude: 1 bytes of fuse7 verified
avrdude: reading input file "0x00"
avrdude: writing fuse8 (1 bytes):

Writing | ##### | 100% 0.02s

avrdude: 1 bytes of fuse8 written
avrdude: verifying fuse8 memory against 0x00:
avrdude: load data fuse8 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse8 data:

Reading | ##### | 100% 0.00s

avrdude: verifying ...
avrdude: 1 bytes of fuse8 verified
avrdude: reading input file
"C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_733041/pinswap_via_swap.ino.he
x"
avrdude: writing flash (3734 bytes):

Writing | ##### | 100% 1.26s

avrdude: 3734 bytes of flash written
avrdude: verifying flash memory against
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_733041/pinswap_via_swap.ino.hex
:
avrdude: load data flash data from input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_733041/pinswap_via_swap.ino.hex
:
avrdude: input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_733041/pinswap_via_swap.ino.hex
contains 3734 bytes
avrdude: reading on-chip flash data:

Reading | ##### | 100% 0.69s

avrdude: verifying ...
```

```
avrdude: 3734 bytes of flash verified
```

```
avrdude done. Thank you.
```

```
Sketch uses 4150 bytes (3%) of program storage space. Maximum is 131072 bytes.
Global variables use 629 bytes (3%) of dynamic memory, leaving 15755 bytes for
local variables. Maximum is 16384 bytes.
```

```
avrdude: Version 6.3-20201216
```

```
Copyright (c) 2000-2005 Brian Dean, http://www.bdmicro.com/
```

```
Copyright (c) 2007-2014 Joerg Wunsch
```

```
System wide configuration file is
```

```
"C:\Users\ivanFernandez\AppData\Local\Arduino15\packages\Microchip\hardware\megaavr\1.0.0/avrdude.conf"
```

```
Using Port : usb
```

```
Using Programmer : curiosity_updi
```

```
avrdude: Found CMSIS-DAP compliant device, using EDBG protocol
```

```
AVR Part : AVR128DA48
```

```
Chip Erase delay : 0 us
```

```
PAGEL : P00
```

```
BS2 : P00
```

```
RESET disposition : dedicated
```

```
RETRY pulse : SCK
```

```
serial program mode : yes
```

```
parallel program mode : yes
```

```
Timeout : 0
```

```
StabDelay : 0
```

```
CmdexeDelay : 0
```

```
SyncLoops : 0
```

```
ByteDelay : 0
```

```
PollIndex : 0
```

```
PollValue : 0x00
```

```
Memory Detail :
```

		Block Poll				Page							
Polled		Memory	Type	Mode	Delay	Size	Indx	Paged	Size	Size	#Pages	MinW	MaxW
ReadBack		-----											
	signature			0	0	0	0	no	3	0	0	0	0
0x00 0x00	prodsig			0	0	0	0	no	125	125	0	0	0
0x00 0x00	fuses			0	0	0	0	no	9	16	0	0	0

```

0x00 0x00
fuse0      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse1      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse2      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse4      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse5      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse6      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse7      0      0      0      0 no      1      0      0      0      0
0x00 0x00
fuse8      0      0      0      0 no      1      0      0      0      0
0x00 0x00
lock       0      0      0      0 no      4      1      0      0      0
0x00 0x00
data       0      0      0      0 no      0      0      0      0      0
0x00 0x00
flash      0      0      0      0 no    131072  512      0      0      0
0x00 0x00
eeprom     0      0      0      0 no      512    32      0      0      0
0x00 0x00

```

```

Programmer Type : JTAGICE3_UPDI
Description      : Microchip Curiosity in UPDI mode
ICE hardware version: 0
ICE firmware version: 1.17 (rel. 514)
Serial number    : MCHP3280031800001901
Vtarget         : 3.31 V
JTAG clock megaAVR/program: 0 kHz
JTAG clock megaAVR/debug:  0 kHz
JTAG clock Xmega: 0 kHz
PDI clock Xmega : 100 kHz

```

```

avrdude: Partial Family_ID returned: "    "
avrdude: AVR device initialized and ready to accept instructions

```

```

Reading | ##### | 100% 0.01s

```

```

avrdude: Device signature = 0x1e9708 (probably avr128da48)
avrdude: NOTE: "flash" memory has been specified, an erase cycle will be performed
        To disable this feature, specify the -D option.
avrdude: erasing chip
avrdude: reading input file "0b11001001"
avrdude: writing fuse5 (1 bytes):

```

```

Writing | ##### | 100% 0.02s

```

```

avrdude: 1 bytes of fuse5 written
avrdude: verifying fuse5 memory against 0b11001001:
avrdude: load data fuse5 data from input file 0b11001001:

```

```
avrdude: input file 0b11001001 contains 1 bytes
avrdude: reading on-chip fuse5 data:
```

```
Reading | ##### | 100% 0.00s
```

```
avrdude: verifying ...
avrdude: 1 bytes of fuse5 verified
avrdude: reading input file "0x00"
avrdude: writing fuse7 (1 bytes):
```

```
Writing | ##### | 100% 0.02s
```

```
avrdude: 1 bytes of fuse7 written
avrdude: verifying fuse7 memory against 0x00:
avrdude: load data fuse7 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse7 data:
```

```
Reading | ##### | 100% 0.00s
```

```
avrdude: verifying ...
avrdude: 1 bytes of fuse7 verified
avrdude: reading input file "0x00"
avrdude: writing fuse8 (1 bytes):
```

```
Writing | ##### | 100% 0.02s
```

```
avrdude: 1 bytes of fuse8 written
avrdude: verifying fuse8 memory against 0x00:
avrdude: load data fuse8 data from input file 0x00:
avrdude: input file 0x00 contains 1 bytes
avrdude: reading on-chip fuse8 data:
```

```
Reading | ##### | 100% 0.01s
```

```
avrdude: verifying ...
avrdude: 1 bytes of fuse8 verified
avrdude: reading input file
"C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_874061/SFRRanger_reader.ino.hex"
avrdude: writing flash (4150 bytes):
```

```
Writing | ##### | 100% 1.41s
```

```
avrdude: 4150 bytes of flash written
avrdude: verifying flash memory against
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_874061/SFRRanger_reader.ino.hex
:
avrdude: load data flash data from input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_874061/SFRRanger_reader.ino.hex
:
avrdude: input file
C:\Users\IVANFE~1\AppData\Local\Temp\arduino_build_874061/SFRRanger_reader.ino.hex
contains 4150 bytes
```

```
avrdude: reading on-chip flash data:  
  
Reading | ##### | 100% 0.78s  
  
avrdude: verifying ...  
avrdude: 4150 bytes of flash verified  
  
avrdude done. Thank you.
```

Notes

1. Each of the sketches compiled and uploaded successfully to the AVR128DA48 board. This concludes testing of the Wire2 examples within the Team 25 core.