

Preliminary Data Sheet: <http://ww1.microchip.com/downloads/en/DeviceDoc/40002183A.pdf>

Connecting pins to the board: <https://onlinedocs.microchip.com/pr/GUID-71FEFD75-E46F-4322-9BEB-8C68686D4A50-en-US-2/index.html?GUID-82573161-4180-468B-B0B3-864D6575B47F>

Servo Motor Basics: <https://docs.arduino.cc/learn/electronics/servo-motors>

Using Servo motors with Arduino @ 14:13 <https://www.youtube.com/watch?v=kUHmYKWwuWs>

Servo Libraries - Arduino Open Source <https://github.com/arduino-libraries/Servo>

"Examples Knob: control the shaft of a servo motor by turning a potentiometer Sweep: sweeps the shaft of a servo motor back and forth

Methods `attach()` `write()` `writeMicroseconds()` `read()` `attached()` `detach()`"

1. Connect header pins to board
2. Connect Servo power cord to VBUS output pin on Arduino board
- 3.