## **Ipopt Options: .ipopt**

## $\textbf{See Ipopt Documentation:} \ \underline{\textbf{https://coin-or.github.io/Ipopt/OPTIONS.html}}$

| List of available options  Id        | Туре                | Default           | Description  |
|--------------------------------------|---------------------|-------------------|--|
| accept_after_max_steps               | OT_INT              | -1                | Accept a trial point after maximal this number of steps. (see IPOPT documentation)                                   |
| accept_every_trial_step              | OT_STRING           | no                | Always accept the first trial step. (see IPOPT documentation)  |
| acceptable_compl_inf_tol             | OT_DOUBLE           | 0.010             | Acceptance threshold for the complementarity conditions. (see IPOPT documentation)                                   |
| acceptable_constr_viol_tol           | OT_DOUBLE           | 0.010             | Acceptance threshold for the constraint violation. (see IPOPT documentation)   |
| acceptable_dual_inf_tol              | OT_DOUBLE           | 1.000e+10         | Acceptance threshold for the dual infeasibility. (see IPOPT documentation)   |
| acceptable_iter                      | OT_INT              | 15                | Number of acceptable iterates before triggering termination. (see IPOPT documentation)                               |
| acceptable_obj_change_tol            | OT_DOUBLE           | 1.000e+20         | Acceptance stopping criterion based on objective function change. (see IPOPT documentation)                          |
| acceptable_tol                       | OT_DOUBLE           | 0.000             | Acceptable convergence tolerance (relative). (see IPOPT documentation)   |
| adaptive_mu_globalization            | OT_STRING           | obj-constr-filter | Globalization strategy for the adaptive mu selection mode. (see IPOPT documentation)                                 |
| adaptive_mu_kkt_norm_type            | OT_STRING           | 2-norm-squared    | Norm used for the KKT error in the adaptive mu globalization strategies. (see IPOPT documentation)                   |
| adaptive_mu_kkterror_red_fact        | OT_DOUBLE           | 1.000             | Sufficient decrease factor for kkt-error globalization strategy. (see IPOPT documentation)                           |
| adaptive_mu_kkterror_red_iters       | OT_INT              | 4                 | Maximum number of iterations requiring sufficient progress. (see IPOPT documentation)                                |
| adaptive_mu_monotone_init_factor     | OT_DOUBLE           | 0.800             | Determines the initial value of the barrier parameter when switching to the monotone mode. (see IPOPT documentation) |
| adaptive_mu_restore_previous_iterate | OT_STRING           | no                | Indicates if the previous iterate should be restored if the  |
| adaptive_mu_safeguard_factor         | OT_DOUBLE           | 0                 | monotone mode is entered. (see IPOPT documentation) (see IPOPT documentation)  |
| alpha_for_y                          | OT_STRING           | primal            | Method to determine the step size for constraint multipliers. (see IPOPT documentation)                              |
| alpha_for_y_tol                      | OT_DOUBLE           | 10                | Tolerance for switching to full equality multiplier steps. (see IPOPT documentation)                                 |
| alpha_min_frac                       | OT_DOUBLE           | 0.050             | Safety factor for the minimal step size (before switching to restoration phase). (see IPOPT documentation)           |
| alpha_red_factor                     | OT_DOUBLE           | 0.500             | Fractional reduction of the trial step size in the backtracking line search. (see IPOPT documentation)               |
| barrier_tol_factor                   | OT_DOUBLE           | 10                | Factor for mu in barrier stop test. (see IPOPT documentation)  |
| bound_frac                           | OT_DOUBLE           | 0.010             | Desired minimum relative distance from the initial point to bound. (see IPOPT documentation)                         |
| bound_mult_init_method               | OT_STRING           | constant          | Initialization method for bound multipliers (see IPOPT documentation)  |
| bound_mult_init_val                  | OT_DOUBLE           | 1                 | Initial value for the bound multipliers. (see IPOPT documentation)   |
| bound_mult_reset_threshold           | OT_DOUBLE           | 1000              | Threshold for resetting bound multipliers after the restoration phase. (see IPOPT documentation)                     |
| bound_push                           | OT_DOUBLE           | 0.010             | Desired minimum absolute distance from the initial point to bound. (see IPOPT documentation)                         |
| bound_relax_factor                   | OT_DOUBLE           | 0.000             | Factor for initial relaxation of the bounds. (see IPOPT documentation)   |
| check_derivatives_for_naninf         | OT_STRING           | no                | Indicates whether it is desired to check for Nan/Inf in derivative matrices (see IPOPT documentation)                |
| chi_cup                              | OT_DOUBLE           | 1.500             | LIFENG WRITES THIS. (see IPOPT documentation)  |
| chi_hat<br>chi_tilde                 | OT_DOUBLE OT_DOUBLE | 2<br>5            | LIFENG WRITES THIS. (see IPOPT documentation) LIFENG WRITES THIS. (see IPOPT documentation)                          |
| compl_inf_tol                        | OT_DOUBLE           | 0.000             | Desired threshold for the complementarity conditions. (see IPOPT documentation)                                      |
| con_integer_md                       | OT_DICT             | None              | Integer metadata (a dictionary with lists of integers) about constraints to be passed to IPOPT                       |
| con_numeric_md                       | OT_DICT             | None              | Numeric metadata (a dictionary with lists of reals) about constraints to be passed to IPOPT                          |
| con_string_md                        | OT_DICT             | None              | String metadata (a dictionary with lists of strings) about constraints to be passed to IPOPT                         |
| constr_mult_init_max                 | OT_DOUBLE           | 1000              | Maximum allowed least-square guess of constraint multipliers. (see IPOPT documentation)                              |
| constr_mult_reset_threshold          | OT_DOUBLE           | 0                 | Threshold for resetting equality and inequality multipliers after restoration phase. (see IPOPT documentation)       |
| constr_viol_tol                      | OT_DOUBLE           | 0.000             | Desired threshold for the constraint violation. (see IPOPT documentation)  |
| constraint_violation_norm_type       | OT_STRING           | 1-norm            | Norm to be used for the constraint violation in the line search. (see IPOPT documentation)                           |
| corrector_compl_avrg_red_fact        | OT_DOUBLE           | 1                 | Complementarity tolerance factor for accepting corrector step (unsupported!). (see IPOPT documentation)              |

| corrector_type                   | OT_STRING           | none                | The type of corrector steps that should be taken (unsupported!). (see IPOPT documentation)   |
|----------------------------------|---------------------|---------------------|--|
| delta                            | OT_DOUBLE           | 1                   | Multiplier for constraint violation in the switching rule. (see IPOPT documentation)   |
| delta_y_max                      | OT_DOUBLE           | 1.000e+12           | a parameter used to check if the fast direction can be<br>used asthe line search direction (for Chen-Goldfarb line<br>search). (see IPOPT documentation) |
| dependency_detection_with_rhs    | OT_STRING           | no                  | Indicates if the right hand sides of the constraints should be considered during dependency detection (see IPOPT documentation)                          |
| dependency_detector              | OT_STRING           | none                | Indicates which linear solver should be used to detect linearly dependent equality constraints. (see IPOPT documentation)                                |
| derivative_test                  | OT_STRING           | none                | Enable derivative checker (see IPOPT documentation)  |
| derivative_test_first_index      | OT_INT              | -2                  | Index of first quantity to be checked by derivative checker (see IPOPT documentation)  |
| derivative_test_perturbation     | OT_DOUBLE           | 0.000               | Size of the finite difference perturbation in derivative test. (see IPOPT documentation)   |
| derivative_test_print_all        | OT_STRING           | no                  | Indicates whether information for all estimated derivatives should be printed. (see IPOPT documentation)   |
| derivative_test_tol              | OT_DOUBLE           | 0.000               | Threshold for indicating wrong derivative. (see IPOPT documentation)   |
| diverging_iterates_tol           | OT_DOUBLE           | 1.000e+20           | Threshold for maximal value of primal iterates. (see IPOPT documentation)  |
| dual_inf_tol                     | OT_DOUBLE           | 1                   | Desired threshold for the dual infeasibility. (see IPOPT documentation)  |
| epsilon_c<br>eta_min             | OT_DOUBLE OT_DOUBLE | 0.010<br>10         | LIFENG WRITES THIS. (see IPOPT documentation) LIFENG WRITES THIS. (see IPOPT documentation)  |
| eta_penalty                      | OT_DOUBLE           | 0.000               | Relaxation factor in the Armijo condition for the penalty  |
| eta_phi                          | OT_DOUBLE           | 0.000               | function. (see IPOPT documentation)<br>Relaxation factor in the Armijo condition. (see IPOPT   |
| evaluate_orig_obj_at_resto_trial | OT_STRING           | yes                 | documentation)  Determines if the original objective function should be evaluated at restoration phase trial points. (see IPOPT                          |
| expect_infeasible_problem        | OT_STRING           | no                  | documentation) Enable heuristics to quickly detect an infeasible   |
| expect_infeasible_problem_ctol   | OT_DOUBLE           | 0.001               | problem. (see IPOPT documentation) Threshold for disabling expect_infeasible_p roblem  |
| expect_infeasible_problem_ytol   | OT_DOUBLE           | 10000000            | option. (see IPOPT documentation)  Multiplier threshold for activating exp ect_infeasible_ problem option. (see IPOPT documentation)                     |
| fast_des_fact                    | OT_DOUBLE           | 0.100               | a parameter used to check if the fast direction can be<br>used asthe line search direction (for Chen-Goldfarb line                                       |
|                                  |                     |                     | search). (see IPOPT documentation)<br>Indicates if the linear system should be solved quickly.   |
| fast_step_computation            | OT_STRING           | no                  | (see IPOPT documentation)  Verbosity level for output file. (see IPOPT   |
| file_print_level                 | OT_INT              | 5                   | documentation) Factor determining width of margin for obj-constr- filter   |
| filter_margin_fact               | OT_DOUBLE           | 0.000               | adaptive globalization strategy. (see IPOPT documentation)   |
| filter_max_margin                | OT_DOUBLE           | 1                   | Maximum width of margin in obj-constr- filter adaptive globalization strategy. (see IPOPT documentation)   |
| filter_reset_trigger             | OT_INT              | 5                   | Number of iterations that trigger the filter reset. (see IPOPT documentation)  |
| findiff_perturbation             | OT_DOUBLE           | 0.000               | Size of the finite difference perturbation for derivative approximation. (see IPOPT documentation)   |
| first_hessian_perturbation       | OT_DOUBLE           | 0.000               | Size of first x-s perturbation tried. (see IPOPT documentation)  |
| fixed_mu_oracle                  | OT_STRING           | average_compl       | Oracle for the barrier parameter when switching to fixed mode. (see IPOPT documentation)   |
| fixed_variable_treatment         | OT_STRING           | make_parameter      | Determines how fixed variables should be handled. (see IPOPT documentation)  |
| gamma_hat                        | OT_DOUBLE           | 0.040               | LIFENG WRITES THIS. (see IPOPT documentation)  |
| gamma_phi                        | OT_DOUBLE           | 0.000               | Relaxation factor in the filter margin for the barrier function. (see IPOPT documentation)   |
| gamma_theta                      | OT_DOUBLE           | 0.000               | Relaxation factor in the filter margin for the constraint violation. (see IPOPT documentation)   |
| gamma_tilde                      | OT_DOUBLE           | 4                   | LIFENG WRITES THIS. (see IPOPT documentation)  |
| hessian_approximation            | OT_STRING           | exact               | Indicates what Hessian information is to be used. (see IPOPT documentation)  |
| hessian_approximation_space      | OT_STRING           | nonlinear-variables | Indicates in which subspace the Hessian information is to be approximated. (see IPOPT documentation)   |
| hessian_constant                 | OT_STRING           | no                  | Indicates whether the problem is a quadratic problem (see IPOPT documentation)   |
| honor_original_bounds            | OT_STRING           | yes                 | Indicates whether final points should be projected into original bounds. (see IPOPT documentation)   |
| inf_pr_output                    | OT_STRING           | original            | Determines what value is printed in the inf_pr output column. (see IPOPT documentation)  |
| jac_c_constant                   | OT_STRING           | no                  | Indicates whether all equality constraints are linear (see IPOPT documentation)  |
| jac_d_constant                   | OT_STRING           | no                  | Indicates whether all inequality constraints are linear (see IPOPT documentation)  |
| jacobian_approximation           | OT_STRING           | exact               | Specifies technique to compute constraint Jacobian (see IPOPT documentation)   |
| jacobian_regularization_exponent | OT_DOUBLE           | 0.250               | Exponent for mu in the regularization for rank- deficient constraint Jacobians. (see IPOPT documentation)  |

| jacobian_regularization_value    | OT_DOUBLE | 0.000            | Size of the regularization for rank- deficient constraint Jacobians. (see IPOPT documentation)  |
|----------------------------------|-----------|------------------|---|
| kappa_d                          | OT_DOUBLE | 0.000            | Weight for linear damping term (to handle one-sided bounds). (see IPOPT documentation)  |
| kappa_sigma                      | OT_DOUBLE | 1.000e+10        | Factor limiting the deviation of dual variables from primal estimates. (see IPOPT documentation)  |
| kappa_soc                        | OT_DOUBLE | 0.990            | Factor in the sufficient reduction rule for second order correction. (see IPOPT documentation)  |
| kappa_x_dis                      | OT_DOUBLE | 100              | a parameter used to check if the fast direction can be used asthe line search direction (for Chen-Goldfarb line search). (see IPOPT documentation)  |
| kappa_y_dis                      | OT_DOUBLE | 10000            | a parameter used to check if the fast direction can be<br>used asthe line search direction (for Chen-Goldfarb line<br>search). (see IPOPT documentation)  |
| least_square_init_duals          | OT_STRING | no               | Least square initialization of all dual variables (see IPOPT documentation)   |
| least_square_init_primal         | OT_STRING | no               | Least square initialization of the primal variables (see IPOPT documentation)   |
| limited_memory_aug_solver        | OT_STRING | Sherman-morrison | Strategy for solving the augmented system for low- rank<br>Hessian. (see IPOPT documentation)   |
| limited_memory_init_val          | OT_DOUBLE | 1                | Value for B0 in low-rank update. (see IPOPT documentation)  |
| limited_memory_init_val_max      | OT_DOUBLE | 100000000        | Upper bound on value for B0 in low-rank update. (see IPOPT documentation)   |
| limited_memory_init_val_min      | OT_DOUBLE | 0.000            | Lower bound on value for B0 in low-rank update. (see IPOPT documentation)   |
| limited_memory_initialization    | OT_STRING | scalar1          | Initialization strategy for the limited memory quasi-<br>Newton approximation. (see IPOPT documentation)  |
| limited_memory_max_history       | OT_INT    | 6                | Maximum size of the history for the limited quasi-<br>Newton Hessian approximation. (see IPOPT<br>documentation)  |
| limited_memory_max_skipping      | OT_INT    | 2                | Threshold for successive iterations where update is skipped. (see IPOPT documentation)  |
| limited_memory_special_for_resto | OT_STRING | no               | Determines if the quasi- Newton updates should be special during the restoration phase. (see IPOPT documentation)   |
| limited_memory_update_type       | OT_STRING | bfgs             | Quasi-Newton update formula for the limited memory approximation. (see IPOPT documentation)   |
| line_search_method               | OT_STRING | filter           | Globalization method used in backtracking line search (see IPOPT documentation)   |
| linear_scaling_on_demand         | OT_STRING | yes              | Flag indicating that linear scaling is only done if it seems required. (see IPOPT documentation)  |
| linear_solver                    | OT_STRING | mumps            | Linear solver used for step computations. (see IPOPT documentation)   |
| linear_system_scaling            | OT_STRING | none             | Method for scaling the linear system. (see IPOPT documentation)   |
| ma27_ignore_singularity          | OT_STRING | no               | Enables MA27's ability to solve a linear system even if the matrix is singular. (see IPOPT documentation)   |
| ma27_la_init_factor              | OT_DOUBLE | 5                | Real workspace memory for MA27. (see IPOPT documentation)   |
| ma27_liw_init_factor             | OT_DOUBLE | 5                | Integer workspace memory for MA27. (see IPOPT documentation)  |
| ma27_meminc_factor               | OT_DOUBLE | 2                | Increment factor for workspace size for MA27. (see IPOPT documentation)   |
| ma27_pivtol                      | OT_DOUBLE | 0.000            | Pivot tolerance for the linear solver MA27. (see IPOPT documentation)   |
| ma27_pivtolmax                   | OT_DOUBLE | 0.000            | Maximum pivot tolerance for the linear solver MA27. (see IPOPT documentation)   |
| ma27_skip_inertia_check          | OT_STRING | no               | Always pretend inertia is correct. (see IPOPT documentation)  |
| ma28_pivtol                      | OT_DOUBLE | 0.010            | Pivot tolerance for linear solver MA28. (see IPOPT documentation)   |
| ma57_automatic_scaling           | OT_STRING | no               | Controls MA57 automatic scaling (see IPOPT documentation)   |
| ma57_block_size                  | OT_INT    | 16               | Controls block size used by Level 3 BLAS in MA57BD (see IPOPT documentation)  |
| ma57_node_amalgamation           | OT_INT    | 16               | Node amalgamation parameter (see IPOPT documentation)   |
| ma57_pivot_order                 | OT_INT    | 5                | Controls pivot order in MA57 (see IPOPT documentation)  |
| ma57_pivtol                      | OT_DOUBLE | 0.000            | Pivot tolerance for the linear solver MA57. (see IPOPT documentation)   |
| ma57_pivtolmax                   | OT_DOUBLE | 0.000            | Maximum pivot tolerance for the linear solver MA57. (see IPOPT documentation)   |
| ma57_pre_alloc                   | OT_DOUBLE | 1.050            | Safety factor for work space memory allocation for the linear solver MA57. (see IPOPT documentation)  |
| ma57_small_pivot_flag            | OT_INT    | 0                | If set to 1, then when small entries defined by CNTL(2) are detected they are removed and the corresponding pivots placed at the end of the factorization. This can be particularly efficient if the matrix is highly rank deficient. (see IPOPT documentation) |
| ma77_buffer_lpage                | OT_INT    | 4096             | Number of scalars per MA77 buffer page (see IPOPT documentation)  |
| ma77_buffer_npage                | OT_INT    | 1600             | Number of pages that make up MA77 buffer (see IPOPT documentation)  |
| ma77_file_size                   | OT_INT    | 2097152          | Target size of each temporary file for MA77, scalars per type (see IPOPT documentation)   |
| ma77_maxstore                    | OT_INT    | 0                | Maximum storage size for MA77 in-core mode (see IPOPT documentation)  |

| mar7_print_level   | ma77_nemin                      | OT_INT    | 8                | Node Amalgamation parameter (see IPOPT documentation)  |
|--|---------------------------------|-----------|------------------|--|
| Part   | ma77_order                      | OT_STRING | amd              | Controls type of ordering used by HSL_MA77 (see IPOPT  |
| Mary      | ma77 print level                | OT INT    | -1               | Debug printing level for the linear solver MA77 (see   |
| mar27_static   | <b>–</b> , –                    | _         | 0.000            | •  |
| ma77_umax  | ma77_static                     | _         |                  | ·  |
| 1967   1968   1969      | ma77_u                          | OT_DOUBLE | 0.000            | · · · · · · · · · · · · · · · · · · ·  |
| mass, print_level         OT_STRING         and         documentation)           mass, print_level         OT_STRING         and         controls type of ordering used by HSL_MASS (see IPOPT documentation)           mass, scaling         OT_STRING         mc64         Controls space or ordering used by HSL_MASS (see IPOPT documentation)           mass, static         OT_DOUBLE         O.000         Zero Fivor Threshold (see IPOPT documentation)           mass, sum         OT_DOUBLE         O.000         Static Proting Threshold (see IPOPT documentation)           mass, sum         OT_DOUBLE         O.000         Manumar Prouting Threshold (see IPOPT documentation)           mass, sum         OT_DOUBLE         O.000         Manumar Prouting Threshold (see IPOPT documentation)           mass, mass   | ma77_umax                       | OT_DOUBLE | 0.000            | documentation)   |
| maB6_pint_level  | ma86_nemin                      | OT_INT    | 32               | documentation)   |
|  | ma86_order                      | OT_STRING | amd              | documentation)   |
| MasS   Small   | ma86_print_level                | OT_INT    | -1               |  |
| ma86_umax  | <u> </u>                        | _         |                  | Controls scaling of matrix (see IPOPT documentation)   |
| ma88_umax OT_DOUBLE 0.000 Precing Threshold (see IPOPT documentation) documentation) and provided in the provi | _                               | _         |                  | ·  |
| ma97_remin  | _                               | _         |                  | · · · · · · · · · · · · · · · · · · ·  |
| ma97_remin OT_INT 8 Node Amalgamation parameter (see IPOPT documentation) ma97_order OT_STRING auto Controls type of ordering used by HSL_MA97 (see IPOP accumentation) ma97_print_level OT_INT O Debug printing level for the linear solver MA97 (see IPOP ma97_scaling) OT_STRING dynamic Specifies strategy for scaling in HSL_MA97 (see IPOP ma97_scaling) OT_STRING mc64 Second scaling (see IPOPT documentation) ma97_scaling3 OT_STRING mc64 Second scaling (see IPOPT documentation) ma97_scaling3 OT_STRING mc64 Second scaling (see IPOPT documentation) ma97_small OT_DOUBLE 0.000 Zero Pwor Threshold (see IPOPT documentation) ma97_switch1 OT_STRING no IPOPT documentation) ma97_switch2 OT_STRING no IPOPT documentation) ma97_switch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_switch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING never scaled for solve is enabled. (see IPOPT documentation) ma97_witch3 OT_STRING no Enables magis (see IPOPT documentation) ma97_witch3 OT_STRING no Enables magis (see IPOPT documentation) may rest or solve is solve in the s | ma86_umax                       | OT_DOUBLE | 0.000            | , ·  |
| may print_level OT_NT 0 Debug printing level for the linear solver MA97 (see may 1, soling) and of the linear solver MA97 (see in POPT documentation) and printing level for the linear solver MA97 (see in POPT documentation) and printing level for the linear solver MA97 (see in POPT documentation) and printing level for the linear solver MA97 (see in POPT documentation) and printing level for the linear solver MA97 (see in POPT documentation) and printing level for the linear solver may 1, soling and printing level for the linear solver may 1, soling and printing level for the linear solver may 1, soling and printing level for the linear solver may 1, soling and printing level for the linear solver may 1, soling and printing level for the linear solver may 2, soling 3 (see in POPT documentation) and 37, soling 3 (see in  | ma97_nemin                      | OT_INT    | 8                | Node Amalgamation parameter (see IPOPT   |
| ma97_print_level OT_INT 0 Debug printing level for the linear solver MA97 (see m975_scaling ma97_scaling OT_STRING dynamic Specifies strategy for scaling in St., MA97 linear solver ma97_scaling OT_STRING m64 First scaling, icee IPOPT documentation) m997_scaling2 OT_STRING m64 First scaling, icee IPOPT documentation) m997_scaling2 OT_STRING m64 Third scaling, icee IPOPT documentation) m997_scaling3 OT_STRING m64 Third scaling, icee IPOPT documentation) m997_scaling3 OT_STRING m64 Third scaling, icee IPOPT documentation) m997_scaling3 OT_STRING no Centrols if blass or blass 7 outlines are used for solve (in IPOPT documentation) power to the interview of the inter | ma97_order                      | OT_STRING | auto             | Controls type of ordering used by HSL_MA97 (see IPOPT  |
| ma97_scaling OT_STRING ma97_scaling1 OT_STRING ma97_scaling2 OT_STRING ma97_scaling2 OT_STRING ma97_scaling2 OT_STRING ma97_scaling3 OT_STRING ma97_scaling3 OT_STRING ma97_scaling3 OT_STRING ma97_scaling3 OT_STRING ma97_scaling3 OT_STRING ma97_solve_blas3 OT_STRING ma97_solve_blas3 OT_STRING ma97_solve_blas3 OT_STRING ma97_solve_blas3 OT_STRING ma97_solve_blas3 OT_STRING ma97_switch1 OT_STRING ma97_switch2 OT_STRING ma97_switch3 OT_DOUBLE 0.000 Maximum Pivoride Coursentation) Maximum Pivoride Coursentation Maximum Durber of Every Coursentation Maximum Durber of Interview Coursentation Maximum Durber of Interview Coursentation Maximum Course Coursentation Maximum Course of Interview Coursel Coursel Maximum Course of Interview Coursel Maximum Coursel Maximum Coursel Maxim | ma97_print_level                | OT_INT    | 0                | Debug printing level for the linear solver MA97 (see   |
| ma97_scaling1 OT_STRING mc64 Second scaling, see IPOPT documentation) ma97_scaling2 OT_STRING mc64 Second scaling, see IPOPT documentation) ma97_scaling3 OT_STRING mc64 Second scaling, see IPOPT documentation) mc97_scaling3 OT_STRING mc64 Second scaling, see IPOPT documentation) mc97_scaling3 OT_STRING mc97_solve_blaa3 OT_STRING mc97_u OT_DOUBLE O.000 Plooting_thread blade_blae_blae_blae_blae_blae_blae_blae_bla  | ma97_scaling                    | OT_STRING | dynamic          | Specifies strategy for scaling in HSL_MA97 linear solver   |
| ma97_scaling3 OT_STRING mc64 Third scaling, see IPOPT documentation) ma97_small OT_DOUBLE 0.000 Zero Pivot Threshold (see IPOPT documentation) ma97_solve_blas3 OT_STRING no Control if blaze or blase a routines are used for solve (in IPOPT documentation) ma97_switch1 OT_STRING never Second switch, determine when ma97_scaling1 is enabled (see IPOPT documentation) ma97_switch2 OT_STRING never Second switch, determine when ma97_scaling2 is enabled, (see IPOPT documentation) ma97_witch3 OT_DOUBLE 0.000 Pivoting Threshold (see IPOPT documentation) ma97_umax OT_DOUBLE 0.000 Pivoting Threshold (see IPOPT documentation) ma97_umax OT_DOUBLE 0.000 Pivoting Threshold (see IPOPT documentation) may_tmax OT_DOUBLE 0.000 Pivoting Threshold (see IPOPT documentation) max_cpu_time OT_DOUBLE 0.000 Maximum Pivoting Threshold (see IPOPT documentation) max_cpu_time OT_DOUBLE 1.000+20 Maximum pivoting Threshold (see IPOPT documentation) max_liter_resets OT_INT 3000 Maximum pivoting Threshold (see IPOPT documentation) max_leter OT_INT 3000 Maximum number of filter resets (see IPOPT documentation) max_refinement_steps OT_INT 10 Maximum number of filter resets (see IPOPT documentation) max_refinement_steps OT_INT 10 Maximum number of filter resets (see IPOPT documentation) max_set_rest_leter OT_INT 3000000 Maximum number of filter resets (see IPOPT documentation) max_set_rest_leter OT_INT 10 Maximum number of filterative refinement steps per linear system solve. (see IPOPT documentation) max_set_rest_leter OT_INT 10 Maximum number of filterative refinement steps per linear system solve. (see IPOPT documentation) min_selpha_primal OT_DOUBLE 0.000 Maximum number of filterative refinement steps per linear system solve. (see IPOPT documentation) min_refinement_steps OT_INT 1 Maximum number of filterative refinement steps per linear system solve. (see IPOPT documentation) min_refinement_steps OT_INT 1 Maximum number of filterative refinement steps per linear system solve. (see IPOPT documentation) min_refinement_steps OT_INT 1 Maximum number  | ma97_scaling1                   | OT_STRING | mc64             |  |
| ma97_solve_blas3 OT_STRING no Controls if blas determine when ma97_scaling1 is enable (see IPOPT documentation) (ma97_switch1 OT_STRING no Controls if blas determine when ma97_scaling1 is enable (see IPOPT documentation) (ma97_switch2 OT_STRING never Second switch determine when ma97_scaling1 is enable (see IPOPT documentation) (ma97_switch3 OT_STRING never OT_DOUBLE 0.000 Protoing Threshold (see IPOPT documentation) (ma97_switch3 OT_DOUBLE 0.000 Protoing Threshold (see IPOPT documentation) (ma97_scaling2 is enabled. (see IPOPT documentation) (ma97_scaling2 is enabled. (see IPOPT documentation) (ma97_scaling3 is enabled. (see IPOPT documentation) (ma97_scaling3 is enabled. (see IPOPT documentation) (may may scaling3 is enabled. (see IPOPT documentation) (may scaling3 is enabled. (see IPOPT d | _ 3                             | OT_STRING | mc64             | · · · · · · · · · · · · · · · · · · ·  |
| ma97_switch1 OT_STRING od_hd_reuse   Controls if blas2 or blas3 routines are used for solve (s   POPT documentation)   ma97_switch1 OT_STRING od_hd_reuse   First switch, determine when ma97_scaling1 is enable (see   POPT documentation)   ma97_switch3 OT_STRING never   | •                               | _         |                  | , , , , , , , , , , , , , , , , , , ,  |
| ma97_switch1 OT_STRING od_hd_reuse   IPOPT documentation)   ma97_switch2   | ma97_small                      | OT_DOUBLE | 0.000            | ·  |
| ma97_switch2 ma97_switch2 ma97_switch3 ma97_u ma97_switch3 ma97_u ma00000  ma97_u ma97_u ma97_u ma000000  mayainu man_u mallowed anumber of CPU seconds, (see IPOPT documentation) mayainu m | ma97_solve_blas3                | OT_STRING | no               | IPOPT documentation)   |
| ma97_switch3 ma97_switch3 ma97_umax ma97_umax ma97_umax ma97_umax ma97_umax may7_umax may8_umay8 | ma97_switch1                    | OT_STRING | od_hd_reuse      | (see IPOPT documentation)  |
| ma97_u may. may. may. may. may. may. may. may.   | ma97_switch2                    | OT_STRING | never            | enabled. (see IPOPT documentation)   |
| ma97_u   | ma97_switch3                    | OT_STRING | never            |  |
| mayi_max   | ma97_u                          | OT_DOUBLE | 0.000            | ·  |
| magic_steps  OT_STRING  max_cpu_time  OT_DOUBLE  Tourner  | ma97_umax                       | OT_DOUBLE | 0.000            | ·  |
| max_filter_resets  OT_INT  5   | magic_steps                     | OT_STRING | no               | •  |
| max_inter_resets  OI_INI 5 documentation)  Maximum value of regularization parameter for handle negative curvature, (see IPOPT documentation)  Maximum number of iterations, (see IPOPT documentation)  Maximum number of iterations, (see IPOPT documentation)  Maximum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of secreessive iterations in restoration phase, (see IPOPT documentation)  Maximum number of iterations performed successive in soft restoration phase, (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve, (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier | max_cpu_time                    | OT_DOUBLE | 1000000          |  |
| max_nessan_perturbation  max_iter  OT_INT  3000  Maximum number of iterations, (see IPOPT documentation)  Maximum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  max_resto_iter  OT_INT  3000000  Maximum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Maximum number of successive iterations in restorati phase. (see IPOPT documentation)  Maximum number of successive iterations in restorati phase. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of successive in soft restoration phase. (see IPOPT documentation)  Minimum number of successive in soft restoration phase. (see IPOPT documentation)  Minimum value for the barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter in the adaptive strategy. (see IPOPT document | max_filter_resets               | OT_INT    | 5                | ,  |
| max_refinement_steps  OT_INT  10  Maximum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Maximum number of successive iterations in restorati phase. (see IPOPT documentation)  Maximum number of successive iterations in restorati phase. (see IPOPT documentation)  Maximum number of successive iterations in restorati phase. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Maximum number of second order correction trial ste at each iteration. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Minimum_lessian_perturbation of the Hessian block. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of second or substance in set see IPOPT documentation)  Maximum number of second or substance in set see IPOPT documentation)  Minimum number of second or substance at each terative number of second or substance at each terative number of  | max_hessian_perturbation        | OT_DOUBLE | 1.000e+20        | Maximum value of regularization parameter for handling negative curvature. (see IPOPT documentation)     |
| max_resto_iter max_resto_iter  OT_INT 3000000  Maximum number of successive iterations in restorating phase. (see IPOPT documentation) Maximum number of second order correction trial steat at each iteration, (see IPOPT documentation)  Maximum number of second order correction trial steat at each iteration, (see IPOPT documentation)  Maximum number of second order correction trial steat each iteration, (see IPOPT documentation)  Maximum number of iterations performed successive in soft restoration phase. (see IPOPT documentation)  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  Min_alpha_primal  OT_DOUBLE 0.000  IIFENG WRITES THIS. (see IPOPT documentation)  Minimum number of iterative refinement stee proper documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier paramet | max_iter                        | OT_INT    | 3000             |  |
| max_resto_iter  OT_INT  4  Maximum number of second order correction trial ste at each iteration, (see IPOPT documentation)  max_soft_resto_iters  OT_INT  10  Maximum number of second order correction trial ste at each iteration, (see IPOPT documentation)  mehrotra_algorithm  OT_STRING  no  Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation)  min_alpha_primal  OT_DOUBLE  0.000  ILIFENG WRITES THIS. (see IPOPT documentation)  min_hessian_perturbation  OT_DOUBLE  0.000  Minimum number of iterative refinement steps per documentation)  Minimum value for barrier parameter. (see IPOPT documentatio | max_refinement_steps            | OT_INT    | 10               |  |
| max_soc OT_INT 4 at each iteration. (see IPOPT documentation) max_soft_resto_iters OT_INT 10 Maximum number of iterations performed successive in soft restoration phase. (see IPOPT documentation) mehrotra_algorithm OT_DOUBLE 0.000 Indicates if we want to do Mehrotra's algorithm. (see IPOPT documentation) min_alpha_primal OT_DOUBLE 0.000 LIFENG WRITES THIS. (see IPOPT documentation) min_hessian_perturbation OT_DOUBLE 0.000 Smallest perturbation of the Hessian block. (see IPOP documentation) min_refinement_steps OT_INT 1 Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation) mu_allow_fast_monotone_decrease OT_STRING yes Allow skipping of barrier problem if barrier test is already met. (see IPOPT documentation) mu_linear_decrease_factor OT_DOUBLE 0.100 Initial value for the barrier parameter. (see IPOPT documentation) mu_max OT_DOUBLE 10000 Maximum value for barrier parameter. (see IPOPT documentation) mu_max_fact OT_DOUBLE 10000 Factor initialization of maximum value for barrier parameter. (see IPOPT documentation) mu_min OT_DOUBLE 0.000 Minimum value for barrier parameter. (see IPOPT documentation) mu_min OT_DOUBLE 0.000 Oracle for a new barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  DIPORT documentation or accle for a new barrier parameter. (see IPOPT documentation)  DIPORT documentation or accle for a new barrier parameter. (see IPOPT documentation)   | max_resto_iter                  | OT_INT    | 3000000          | Maximum number of successive iterations in restoration phase. (see IPOPT documentation)                  |
| mehrotra_algorithm  OT_STRING  min_alpha_primal  OT_DOUBLE  O.000  ILIFENG WRITES THIS. (see IPOPT documentation)  min_hessian_perturbation  min_refinement_steps  OT_INT  1  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  mu_allow_fast_monotone_decrease  OT_STRING  mu_linear_decrease_factor  mu_max  OT_DOUBLE  OT_OOO  Minimum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)  Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)  Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)  OTALE strategy for barrier parameter. (see IPOPT documentation)  | max_soc                         | OT_INT    | 4                | Maximum number of second order correction trial steps at each iteration. (see IPOPT documentation)       |
| menotra_algorithm min_alpha_primal OT_DOUBLE O.000 LIFENG WRITES THIS. (see IPOPT documentation)  min_hessian_perturbation OT_DOUBLE O.000 Smallest perturbation of the Hessian block. (see IPOPT documentation)  min_refinement_steps OT_INT 1 Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Allow skipping of barrier problem if barrier test is already met. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Allow skipping of barrier problem if barrier test is already met. (see IPOPT documentation)  Initial value for the barrier parameter. (see IPOPT documentation)  Determines linear decrease rate of barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  OT_DOUBLE O.000  OT_STRING quality-function  OT_STRING Undate strategy (see IPOPT documentation)   | max_soft_resto_iters            | OT_INT    | 10               | Maximum number of iterations performed successively in soft restoration phase. (see IPOPT documentation) |
| min_alpha_primal  min_hessian_perturbation  OT_DOUBLE  O.000  DIFFING WRITES THIS. (see IPOPT documentation)  Smallest perturbation of the Hessian block. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)  Mallow skipping of barrier problem if barrier test is already met. (see IPOPT documentation)  Mu_init  OT_DOUBLE  O.100  Maximum value for the barrier parameter. (see IPOPT documentation)  Determines linear decrease rate of barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Maximum value for barrier parameter. (see IPOPT documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Documentation)  Minimum value for barrier parameter. (see IPOPT documentation)  Undate strategy (see IPOPT documentation)  Undate strategy (see IPOPT documentation)  | mehrotra_algorithm              | OT_STRING | no               |  |
| min_hessian_perturbationOT_DOUBLE0.000Smallest perturbation of the Hessian block. (see IPOP' documentation)min_refinement_stepsOT_INT1Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation)mu_allow_fast_monotone_decreaseOT_STRINGyesAllow skipping of barrier problem if barrier test is already met. (see IPOPT documentation)mu_initOT_DOUBLE0.100Initial value for the barrier parameter. (see IPOPT documentation)mu_linear_decrease_factorOT_DOUBLE0.200Determines linear decrease rate of barrier parameter. (see IPOPT documentation)mu_maxOT_DOUBLE100000Maximum value for barrier parameter. (see IPOPT documentation)mu_max_factOT_DOUBLE1000Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)mu_minOT_DOUBLE0.000Minimum value for barrier parameter. (see IPOPT documentation)mu_oracleOT_STRINGquality-functionOracle for a new barrier parameter in the adaptive strategy, (see IPOPT documentation)   | min alpha primal                | OT DOUBLE | 0.000            |  |
| min_refinement_steps OT_INT 1 Minimum number of iterative refinement steps per linear system solve. (see IPOPT documentation) Allow skipping of barrier problem if barrier test is already met. (see IPOPT documentation) Initial value for the barrier parameter. (see IPOPT documentation)  mu_linear_decrease_factor OT_DOUBLE O.200 Determines linear decrease rate of barrier parameter. (see IPOPT documentation)  mu_max OT_DOUBLE 10000 Maximum value for barrier parameter. (see IPOPT documentation)  mu_max_fact OT_DOUBLE 1000 Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)  mu_min OT_DOUBLE 0.000 Minimum value for barrier parameter. (see IPOPT documentation)  Undate strategy. (see IPOPT documentation)  Undate strategy for barrier parameter. (see IPOPT   | •                               | _         |                  | Smallest perturbation of the Hessian block. (see IPOPT   |
| mu_allow_fast_monotone_decrease       OT_STRING       yes       Allow skipping of barrier problem if barrier test is already met. (see IPOPT documentation)         mu_init       OT_DOUBLE       0.100       Initial value for the barrier parameter. (see IPOPT documentation)         mu_linear_decrease_factor       OT_DOUBLE       0.200       Determines linear decrease rate of barrier parameter. (see IPOPT documentation)         mu_max       OT_DOUBLE       100000       Maximum value for barrier parameter. (see IPOPT documentation)         mu_max_fact       OT_DOUBLE       1000       Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)         mu_min       OT_DOUBLE       0.000       Minimum value for barrier parameter. (see IPOPT documentation)         mu_oracle       OT_STRING       quality-function       Oracle for a new barrier parameter in the adaptive strategy, (see IPOPT documentation)   | min_refinement_steps            | OT_INT    | 1                | Minimum number of iterative refinement steps per   |
| mu_init       OT_DOUBLE       0.100       Initial value for the barrier parameter. (see IPOPT documentation)         mu_linear_decrease_factor       OT_DOUBLE       0.200       Determines linear decrease rate of barrier parameter. (see IPOPT documentation)         mu_max       OT_DOUBLE       100000       Maximum value for barrier parameter. (see IPOPT documentation)         mu_max_fact       OT_DOUBLE       1000       Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)         mu_min       OT_DOUBLE       0.000       Minimum value for barrier parameter. (see IPOPT documentation)         mu_oracle       OT_STRING       quality-function       Oracle for a new barrier parameter in the adaptive strategy, (see IPOPT documentation)   | mu_allow_fast_monotone_decrease | OT_STRING | yes              | Allow skipping of barrier problem if barrier test is   |
| mu_linear_decrease_factor     OT_DOUBLE     0.200     Determines linear decrease rate of barrier parameter. (see IPOPT documentation)       mu_max     OT_DOUBLE     100000     Maximum value for barrier parameter. (see IPOPT documentation)       mu_max_fact     OT_DOUBLE     1000     Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)       mu_min     OT_DOUBLE     0.000     Minimum value for barrier parameter. (see IPOPT documentation)       mu_oracle     OT_STRING     quality-function     Oracle for a new barrier parameter in the adaptive strategy, (see IPOPT documentation)       Undate strategy for barrier parameter. (see IPOPT documentation)   | mu_init                         | OT_DOUBLE | 0.100            | Initial value for the barrier parameter. (see IPOPT  |
| mu_max     OT_DOUBLE     100000     Maximum value for barrier parameter. (see IPOPT documentation)       mu_max_fact     OT_DOUBLE     1000     Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)       mu_min     OT_DOUBLE     0.000     Minimum value for barrier parameter. (see IPOPT documentation)       mu_oracle     OT_STRING     quality-function     Oracle for a new barrier parameter in the adaptive strategy, (see IPOPT documentation)       Undate strategy for barrier parameter. (see IPOPT documentation)   | mu_linear_decrease_factor       | OT_DOUBLE | 0.200            | Determines linear decrease rate of barrier parameter.  |
| mu_max_fact     OT_DOUBLE     1000     Factor for initialization of maximum value for barrier parameter. (see IPOPT documentation)       mu_min     OT_DOUBLE     0.000     Minimum value for barrier parameter. (see IPOPT documentation)       mu_oracle     OT_STRING     quality-function     Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)       Undate strategy for barrier parameter. (see IPOPT documentation)  | mu_max                          | OT_DOUBLE | 100000           | Maximum value for barrier parameter. (see IPOPT  |
| mu_min  OT_DOUBLE  0.000  Minimum value for barrier parameter. (see IPOPT documentation)  Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)  Undate strategy for barrier parameter, (see IPOPT documentation)   | mu_max_fact                     | OT_DOUBLE | 1000             | Factor for initialization of maximum value for barrier   |
| mu_oracle  OT_STRING  quality-function  Oracle for a new barrier parameter in the adaptive strategy. (see IPOPT documentation)  Undate strategy for barrier parameter. (see IPOPT  | mu_min                          | OT_DOUBLE | 0.000            | Minimum value for barrier parameter. (see IPOPT  |
| Undate strategy for harrier parameter, (see IPOPT  | mu_oracle                       | OT_STRING | quality-function | Oracle for a new barrier parameter in the adaptive   |
| mu_strategy documentation)   | mu_strategy                     | OT_STRING | monotone         | Update strategy for barrier parameter. (see IPOPT  |
| mu_superlinear_decrease_power OT_DOUBLE 1.500 Determines superlinear decrease rate of barrier parameter. (see IPOPT documentation)   | mu_superlinear_decrease_power   | OT_DOUBLE | 1.500            | Determines superlinear decrease rate of barrier  |

| mu_target   | OT_DOUBLE           | 0              | Desired value of complementar ity. (see IPOPT documentation)   |
|---|---------------------|----------------|--|
| mult_diverg_feasibility_tol                                 | OT_DOUBLE           | 0.000          | tolerance for deciding if the multipliers are diverging (see IPOPT documentation)  |
| mult_diverg_y_tol   | OT_DOUBLE           | 100000000      | tolerance for deciding if the multipliers are diverging (see IPOPT documentation)  |
| mumps_dep_tol   | OT_DOUBLE           | 0              | Pivot threshold for detection of linearly dependent constraints in MUMPS. (see IPOPT documentation)                        |
| mumps_mem_percent   | OT_INT              | 1000           | Percentage increase in the estimated working space for MUMPS. (see IPOPT documentation)                                    |
| mumps_permuting_scaling                                     | OT_INT              | 7              | Controls permuting and scaling in MUMPS (see IPOPT documentation)  |
| mumps_pivot_order   | OT_INT              | 7              | Controls pivot order in MUMPS (see IPOPT documentation)  |
| mumps_pivtol  | OT_DOUBLE           | 0.000          | Pivot tolerance for the linear solver MUMPS. (see IPOPT documentation)   |
| mumps_pivtolmax   | OT_DOUBLE           | 0.100          | Maximum pivot tolerance for the linear solver MUMPS. (see IPOPT documentation)   |
| mumps_scaling   | OT_INT              | 77             | Controls scaling in MUMPS (see IPOPT documentation) Tolerance for heuristic to ignore wrong inertia. (see                  |
| neg_curv_test_tol   | OT_DOUBLE           | 0              | IPOPT documentation)   |
| never_use_fact_cgpen_direction                              | OT_STRING           | no             | Toggle to switch off the fast Chen- Goldfarb direction (see IPOPT documentation)   |
| never_use_piecewise_penalty_ls                              | OT_STRING           | no             | Toggle to switch off the piecewise penalty method (see IPOPT documentation)  |
| nlp_lower_bound_inf   | OT_DOUBLE           | -1.000e+19     | any bound less or equal this value will be considered -inf (i.e. not lower bounded). (see IPOPT documentation)             |
| nlp_scaling_constr_target_gradient                          | OT_DOUBLE           | 0              | Target value for constraint function gradient size. (see IPOPT documentation)  |
| nlp_scaling_max_gradient                                    | OT_DOUBLE           | 100            | Maximum gradient after NLP scaling. (see IPOPT documentation)  |
| nlp_scaling_method  | OT_STRING           | gradient-based | Select the technique used for scaling the NLP. (see IPOPT documentation)   |
| nlp_scaling_min_value                                       | OT_DOUBLE           | 0.000          | Minimum value of gradient- based scaling values. (see IPOPT documentation)   |
| nlp_scaling_obj_target_gradient                             | OT_DOUBLE           | 0              | Target value for objective function gradient size. (see IPOPT documentation)   |
| nlp_upper_bound_inf   | OT_DOUBLE           | 1.000e+19      | any bound greater or this value will be considered +inf (i.e. not upper bounded). (see IPOPT documentation)                |
| nu_inc  | OT_DOUBLE           | 0.000          | Increment of the penalty parameter. (see IPOPT documentation)  |
| nu_init   | OT_DOUBLE           | 0.000          | Initial value of the penalty parameter. (see IPOPT documentation)  |
| num_linear_variables  | OT_INT              | 0              | Number of linear variables (see IPOPT documentation) Determines the upper bound on the acceptable increase                 |
| obj_max_inc   | OT_DOUBLE           | 5              | of barrier objective function. (see IPOPT documentation) Scaling factor for the objective function. (see IPOPT             |
| obj_scaling_factor  | OT_DOUBLE           | 1              | documentation)   |
| option_file_name  | OT_STRING           | ipopt.opt      | File name of options file. (see IPOPT documentation) File name of desired output file (leave unset for no file             |
| output_file   | OT_STRING           |                | output). (see IPOPT documentation) Maximum Size of Coarse Grid Matrix (see IPOPT   |
| pardiso_iter_coarse_size                                    | OT_INT              | 5000           | documentation) dropping value for incomplete factor (see IPOPT   |
| pardiso_iter_dropping_factor                                | OT_DOUBLE           | 0.500          | documentation) dropping value for sparsify schur complement factor   |
| pardiso_iter_dropping_schur                                 | OT_DOUBLE           | 0.100          | (see IPOPT documentation)  |
| pardiso_iter_inverse_norm_factor<br>pardiso_iter_max_levels | OT_DOUBLE<br>OT_INT | 5000000        | (see IPOPT documentation)  Maximum Size of Grid Levels (see IPOPT  |
| pardiso_iter_max_revets pardiso_iter_max_row_fill           | OT_INT              | 10000000       | documentation) max fill for each row (see IPOPT documentation)   |
| pardiso_iter_relative_tol                                   | OT_DOUBLE           | 0.000          | Relative Residual Convergence (see IPOPT documentation)  |
| pardiso_iterative   | OT_STRING           | no             | Switch on iterative solver in Pardiso library (see IPOPT documentation)  |
| pardiso_matching_strategy                                   | OT_STRING           | complete+2x2   | Matching strategy to be used by Pardiso (see IPOPT documentation)  |
| pardiso_max_droptol_corrections                             | OT_INT              | 4              | Maximal number of decreases of drop tolerance during one solve. (see IPOPT documentation)                                  |
| pardiso_max_iter  | OT_INT              | 500            | Maximum number of Krylov- Subspace Iteration (see IPOPT documentation)   |
| pardiso_max_iterative_refinement_steps                      | OT_INT              | 0              | Limit on number of iterative refinement steps. (see IPOPT documentation)   |
| pardiso_msglvl  | OT_INT              | 0              | Pardiso message level (see IPOPT documentation)  |
| pardiso_order   | OT_STRING           | five           | Controls the fill-in reduction ordering algorithm for the input matrix. (see IPOPT documentation)                          |
| pardiso_redo_symbolic_fact_only_if_inertia_wrong            | OT_STRING           | no             | Toggle for handling case when elements were perturbed by Pardiso. (see IPOPT documentation)                                |
| pardiso_repeated_perturbation_means_singular                | OT_STRING           | no             | Interpretation of perturbed elements. (see IPOPT documentation)  |
| pardiso_skip_inertia_check                                  | OT_STRING           | no             | Always pretend inertia is correct. (see IPOPT documentation)   |
| pass_nonlinear_variables                                    | OT_BOOL             | False          | n/a  |
| pen_des_fact  | OT_DOUBLE           | 0.200          | a parameter used in penalty parameter computation (for Chen- Goldfarb line search). (see IPOPT documentation)              |
| pen_init_fac  | OT_DOUBLE           | 50             | a parameter used to choose initial penalty parameterswhen the regularized Newton method is used. (see IPOPT documentation) |

| pen_theta_max_fact                  | OT_DOUBLE | 10000          | Determines upper bound for constraint violation in the filter. (see IPOPT documentation)   |
|-------------------------------------|-----------|----------------|--|
| penalty_init_max                    | OT_DOUBLE | 100000         | Maximal value for the intial penalty parameter (for Chen-Goldfarb line search). (see IPOPT documentation)  |
| penalty_init_min                    | OT_DOUBLE | 1              | Minimal value for the intial penalty parameter for line search(for Chen-Goldfarb line search). (see IPOPT documentation)                               |
| penalty_max                         | OT_DOUBLE | 1.000e+30      | Maximal value for the penalty parameter (for Chen-   |
| penalty_update_compl_tol            | OT_DOUBLE | 10             | Goldfarb line search). (see IPOPT documentation) LIFENG WRITES THIS. (see IPOPT documentation)   |
| penalty_update_infeasibility_tol    | OT_DOUBLE | 0.000          | Threshold for infeasibility in penalty parameter update test. (see IPOPT documentation)  |
| perturb_always_cd                   | OT_STRING | no             | Active permanent perturbation of constraint linearization. (see IPOPT documentation)   |
| perturb_dec_fact                    | OT_DOUBLE | 0.333          | Decrease factor for x-s perturbation. (see IPOPT documentation)  |
| perturb_inc_fact                    | OT_DOUBLE | 8              | Increase factor for x-s perturbation. (see IPOPT documentation)  |
| perturb_inc_fact_first              | OT_DOUBLE | 100            | Increase factor for x-s perturbation for very first perturbation. (see IPOPT documentation)  |
| piecewisepenalty_gamma_infeasi      | OT_DOUBLE | 0.000          | LIFENG WRITES THIS. (see IPOPT documentation)  |
| piecewisepenalty_gamma_obj          | OT_DOUBLE | 0.000          | LIFENG WRITES THIS. (see IPOPT documentation)  Maximal perturbation of an evaluation point. (see IPOPT   |
| point_perturbation_radius           | OT_DOUBLE | 10             | documentation)  Determines at which iteration frequency the  |
| print_frequency_iter                | OT_INT    | 1              | summarizing iteration output line should be printed.<br>(see IPOPT documentation)  |
| print_frequency_time                | OT_DOUBLE | 0              | Determines at which time frequency the summarizing iteration output line should be printed. (see IPOPT documentation)                                  |
| print_info_string                   | OT_STRING | no             | Enables printing of additional info string at end of   |
| print_level                         | OT_INT    | 5              | iteration output. (see IPOPT documentation) Output verbosity level. (see IPOPT documentation)  |
| print_options_documentation         | OT_STRING | no             | Switch to print all algorithmic options. (see IPOPT  |
| print_options_latex_mode            | OT_STRING | no             | documentation) Undocumented (see IPOPT documentation)  |
| print_time                          | OT_BOOL   | True           | print information about execution time   |
| print_timing_statistics             | OT_STRING | no             | Switch to print timing statistics. (see IPOPT documentation)   |
| print_user_options                  | OT_STRING | no             | Print all options set by the user. (see IPOPT documentation)   |
| quality_function_balancing_term     | OT_STRING | none           | The balancing term included in the quality function for centrality. (see IPOPT documentation)  |
| quality_function_centrality         | OT_STRING | none           | The penalty term for centrality that is included in quality function. (see IPOPT documentation)  |
| quality_function_max_section_steps  | OT_INT    | 8              | Maximum number of search steps during direct search procedure determining the optimal centering parameter. (see IPOPT documentation)                   |
| quality_function_norm_type          | OT_STRING | 2-norm-squared | Norm used for components of the quality function. (see IPOPT documentation)  |
| quality_function_section_qf_tol     | OT_DOUBLE | 0              | Tolerance for the golden section search procedure determining the optimal centering parameter (in the function value space). (see IPOPT documentation) |
| quality_function_section_sigma_tol  | OT_DOUBLE | 0.010          | Tolerance for the section search procedure determining the optimal centering parameter (in sigma space). (see IPOPT documentation)                     |
| recalc_y                            | OT_STRING | no             | Tells the algorithm to recalculate the equality and inequality multipliers as least square estimates. (see IPOPT documentation)                        |
| recalc_y_feas_tol                   | OT_DOUBLE | 0.000          | Feasibility threshold for recomputation of multipliers. (see IPOPT documentation)  |
| replace_bounds                      | OT_STRING | no             | Indicates if all variable bounds should be replaced by inequality constraints (see IPOPT documentation)  |
| required_infeasibility_reduction    | OT_DOUBLE | 0.900          | Required reduction of infeasibility before leaving   |
| residual_improvement_factor         | OT_DOUBLE | 1.000          | restoration phase. (see IPOPT documentation)  Minimal required reduction of residual test ratio in   |
| residual_ratio_max                  | OT_DOUBLE | 0.000          | iterative refinement. (see IPOPT documentation)<br>Iterative refinement tolerance (see IPOPT<br>documentation)   |
| residual_ratio_singular             | OT_DOUBLE | 0.000          | Threshold for declaring linear system singular after failed iterative refinement. (see IPOPT documentation)  |
| resto_failure_feasibility_threshold | OT_DOUBLE | 0              | Threshold for primal infeasibility to declare failure of restoration phase. (see IPOPT documentation)  |
| resto_penalty_parameter             | OT_DOUBLE | 1000           | Penalty parameter in the restoration phase objective function. (see IPOPT documentation)   |
| resto_proximity_weight              | OT_DOUBLE | 1              | Weighting factor for the proximity term in restoration phase objective. (see IPOPT documentation)  |
| rho                                 | OT_DOUBLE | 0.100          | Value in penalty parameter update formula. (see IPOPT documentation)   |
| s_max                               | OT_DOUBLE | 100            | Scaling threshold for the NLP error. (see IPOPT documentation)   |
| s_phi                               | OT_DOUBLE | 2.300          | Exponent for linear barrier function model in the switching rule. (see IPOPT documentation)  |
| s_theta                             | OT_DOUBLE | 1.100          | Exponent for current constraint violation in the switching rule. (see IPOPT documentation)   |
| sb                                  | OT_STRING | no             | (see IPOPT documentation)  |
| sigma_max                           | OT_DOUBLE | 100            | Maximum value of the centering parameter. (see IPOPT documentation)  |

| sigma_min                           | OT_DOUBLE | 0.000   | Minimum value of the centering parameter. (see IPOPT documentation)  |
|-------------------------------------|-----------|---------|--|
| skip_corr_if_neg_curv               | OT_STRING | yes     | Skip the corrector step in negative curvature iteration (unsupported!). (see IPOPT documentation)  |
| skip_corr_in_monotone_mode          | OT_STRING | yes     | Skip the corrector step during monotone barrier parameter mode (unsupported!). (see IPOPT documentation)   |
| skip_finalize_solution_call         | OT_STRING | no      | Indicates if call to NLP::Fi nalizeSolution after optimization should be suppressed (see IPOPT documentation)                                      |
| slack_bound_frac                    | OT_DOUBLE | 0.010   | Desired minimum relative distance from the initial slack to bound. (see IPOPT documentation)   |
| slack_bound_push                    | OT_DOUBLE | 0.010   | Desired minimum absolute distance from the initial slack to bound. (see IPOPT documentation)   |
| slack_move                          | OT_DOUBLE | 0.000   | Correction size for very small slacks. (see IPOPT documentation)   |
| soft_resto_pderror_reduction_factor | OT_DOUBLE | 1.000   | Required reduction in primal-dual error in the soft restoration phase. (see IPOPT documentation)   |
| start_with_resto                    | OT_STRING | no      | Tells algorithm to switch to restoration phase in first iteration. (see IPOPT documentation)   |
| suppress_all_output                 | OT_STRING | no      | Undocumented (see IPOPT documentation)   |
| tau_min                             | OT_DOUBLE | 0.990   | Lower bound on fraction-to- the-boundary parameter tau. (see IPOPT documentation)  |
| theta_max_fact                      | OT_DOUBLE | 10000   | Determines upper bound for constraint violation in the filter. (see IPOPT documentation)   |
| theta_min                           | OT_DOUBLE | 0.000   | LIFENG WRITES THIS. (see IPOPT documentation)  |
| theta_min_fact                      | OT_DOUBLE | 0.000   | Determines constraint violation threshold in the switching rule. (see IPOPT documentation)   |
| tiny_step_tol                       | OT_DOUBLE | 0.000   | Tolerance for detecting numerically insignificant steps. (see IPOPT documentation)   |
| tiny_step_y_tol                     | OT_DOUBLE | 0.010   | Tolerance for quitting because of numerically insignificant steps. (see IPOPT documentation)   |
| tol                                 | OT_DOUBLE | 0.000   | Desired convergence tolerance (relative). (see IPOPT documentation)  |
| var_integer_md                      | OT_DICT   | None    | Integer metadata (a dictionary with lists of integers) about variables to be passed to IPOPT   |
| var_numeric_md                      | OT_DICT   | None    | Numeric metadata (a dictionary with lists of reals) about variables to be passed to IPOPT  |
| var_string_md                       | OT_DICT   | None    | String metadata (a dictionary with lists of strings) about variables to be passed to IPOPT   |
| vartheta                            | OT_DOUBLE | 0.500   | a parameter used to check if the fast direction can be used asthe line search direction (for Chen-Goldfarb line search). (see IPOPT documentation) |
| warm_start_bound_frac               | OT_DOUBLE | 0.001   | same as bound_frac for the regular initializer. (see IPOPT documentation)  |
| warm_start_bound_push               | OT_DOUBLE | 0.001   | same as bound_push for the regular initializer. (see IPOPT documentation)  |
| warm_start_entire_iterate           | OT_STRING | no      | Tells algorithm whether to use the GetWarmStar tlterate method in the NLP. (see IPOPT documentation)   |
| warm_start_init_point               | OT_STRING | no      | Warm-start for initial point (see IPOPT documentation)   |
| warm_start_mult_bound_push          | OT_DOUBLE | 0.001   | same as mult_bound_push for the regular initializer. (see IPOPT documentation)   |
| warm_start_mult_init_max            | OT_DOUBLE | 1000000 | Maximum initial value for the equality multipliers. (see IPOPT documentation)  |
| warm_start_same_structure           | OT_STRING | no      | Indicates whether a problem with a structure identical to the previous one is to be solved. (see IPOPT documentation)                              |
| warm_start_slack_bound_frac         | OT_DOUBLE | 0.001   | same as slack_bound_frac for the regular initializer. (see IPOPT documentation)  |
| warm_start_slack_bound_push         | OT_DOUBLE | 0.001   | same as slack_bound_push for the regular initializer.<br>(see IPOPT documentation)   |
| warm_start_target_mu                | OT_DOUBLE | 0       | Unsupported! (see IPOPT documentation)   |
| watchdog_shortened_iter_trigger     | OT_INT    | 10      | Number of shortened iterations that trigger the watchdog. (see IPOPT documentation)  |
| watchdog_trial_iter_max             | OT_INT    | 3       | Maximum number of watchdog iterations. (see IPOPT documentation)   |
| wsmp_iterative                      | OT_STRING | no      | Switches to iterative solver in WSMP. (see IPOPT documentation)  |