

جوابی کے لیے دو صورتیں دی گئی ہیں۔

Global
min

$$y_{\min} = y_{\text{out}} = 3 \times 1 + 2 \times 1 + 3 \times 1 + 2 = 10$$

$$h(k) = 0, \quad w(k) = [1, -1] \quad k \in \mathbb{Z}, \quad x = \begin{bmatrix} 2 \sin\left(\frac{k\pi}{3}\right) \\ \cos\left(\frac{k\pi}{3}\right) \end{bmatrix}$$

$$y_{\min} = 2 \sin\left(\frac{k\pi}{3}\right) - \cos\left(\frac{k\pi}{3}\right)$$

sign	value
$k=1 \rightarrow 2 \times \frac{\sqrt{3}}{2} - \frac{1}{2} = \sqrt{3} - \frac{1}{2}$	1
$k=2 \rightarrow 2 \times \frac{\sqrt{3}}{2} - (-\frac{1}{2}) = \sqrt{3} + \frac{1}{2}$	1
$k=3 \rightarrow 2 \times 0 - (-1) = 1$	1
$k=4 \rightarrow 2 \times (-\frac{\sqrt{3}}{2}) - (-\frac{1}{2}) = -\sqrt{3} + \frac{1}{2}$	-1
$k=5 \rightarrow 2 \times (-\frac{\sqrt{3}}{2}) - \frac{1}{2} = -\sqrt{3} - \frac{1}{2}$	-1
$k=6 \rightarrow 2 \times 0 - 1 = -1$	-1

$$\alpha = 0.5$$

$$w = [1, 2]$$

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$$x_1 = [-1, 3]^T$$

$$x_2 = [2, 1]^T$$

دو

$$x_1 \Rightarrow y = \text{sign}(w \cdot x_1) = \text{sign}(1 + 6) = 1$$

$$\Delta w = \alpha \cdot y \cdot x_1 = 0.5 \times 1 \times [-3, 1] = [-0.5, 1.5]$$

$$w' = w + \Delta w = [0.5, 3.5]$$

$$x_2 \Rightarrow y = \text{sign}(w' \cdot x_2) = \text{sign}(0.5 \times 2 + 3.5 \times 1) = 1$$

$$\Delta w = \alpha \cdot y \cdot x_2 = 0.5 \times 1 \times [2, 1] = [1, 0.5]$$

$$w'' = w' + \Delta w = [1.5, 4]$$

ثلاثة

$$x_1 \Rightarrow y = \text{sign}(w'' \cdot x_1) = \text{sign}(1.5 \times (-1) + 4 \times 3) = 1$$

$$\Delta w = \alpha \cdot y \cdot x_1 = 0.5 \times 1 \times [-1, 3] = [-0.5, 1.5]$$

$$w''' = w'' + \Delta w = [1, 5.5]$$

$$x_2 \Rightarrow y = \text{sign}(w''' \cdot x_2) = \text{sign}(1 \times 2 + 5.5 \times 1) = 1$$

$$\Delta w = \alpha \cdot y \cdot x_2 = 0.5 \times 1 \times [2, 1] = [1, 0.5]$$

$$w^{(4)} = w''' + \Delta w = [2, 6]$$

$$s_1 = (1, -1, -1, -1) \quad b_1 = (-1, 1)$$

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$$s_2 = (1, 1, -1, -1) \quad b_2 = (-1, 1)$$

$$s_3 = (-1, -1, -1, 1) \quad b_3 = (1, -1)$$

$$s_4 = (-1, -1, 1, 1) \quad b_4 = (1, 1)$$

$$s_1 \rightarrow \begin{bmatrix} 1 \\ -1 \\ -1 \\ -1 \end{bmatrix} [-1, 1] = \begin{bmatrix} -1 & 1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix}$$

$$s_2 \rightarrow \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} [-1, 1] = \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix}$$

$$s_3 \rightarrow \begin{bmatrix} -1 \\ -1 \\ -1 \\ 1 \end{bmatrix} [1, -1] = \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ -1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$s_4 \rightarrow \begin{bmatrix} -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} [1, -1] = \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix}$$

$$w = \begin{bmatrix} -1 & 1 \\ 1 & -1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ -1 & 1 \\ 1 & -1 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} -4 & 4 \\ 2 & 3 \\ 2 & -3 \\ 4 & -4 \end{bmatrix}$$

$$d = 1 \quad w = 0$$

$$(1, 1, 1, 1), (-1, 1, -1, -1) \rightarrow 1$$

$$(1, 1, 1, -1), (1, -1, -1, 1) \rightarrow -1$$

التم

input	y_{in}	y	t	Δw_1	Δw_2	Δw_3	Δb	w_1	w_2	w_3	b
1 1 1 1	0	1	1	(1	1	1	(1	(1	1	1	(1
-1 -1 -1 -1	0	1	1	(-1	1	-1	(-1	(-1	1	-1	(-1
1 1 1 -1	0	1	-1	(-1	-1	-1	(1	(-1	-1	-1	(1
1 -1 -1 1	0	1	-1	(-1	1	1	(-1	(-1	1	1	(-1

$$y_{in} = \sum x_i w_i + b$$

(ب)

$$b_{new} = b_{old} + \alpha (t - y_{in})$$

$$w_{new} = w_{old} + \alpha (t - y_{in}) x_i$$

$$(1, 1, 1, 1) \rightarrow 1$$

$$w_1 = 0 + 0.5(1-0)1 = 0.5$$

$$w_2 = 0 + 0.5(1-0)1 = 0.5$$

$$w_3 = 0 + 0.5(1-0)1 = 0.5$$

$$w_4 = 0 + 0.5(1-0)1 = 0.5$$

$$(1, 1, -1, -1) \rightarrow 1$$

$$w_1 = 0 + 0.5(1-0)(-1) = -0.5$$

$$w_2 = 0 + 0.5(1-0)(1) = 0.5$$

$$w_3 = 0 + 0.5(1-0)(-1) = -0.5$$

$$w_4 = 0 + 0.5(1-0)(-1) = -0.5$$

$$(1, 1, 1, -1) \rightarrow -1$$

$$w_1 = w_2 = w_3 = 0 + 0.5(-1-0)(1) = -0.5$$

$$w_4 = 0 + 0.5(-1-0)(-1) = 0.5$$

$$(1, -1, -1, 1) \rightarrow -1$$

$$w_1 = w_4 = 0 + 0.5(-1-0)(1) = -0.5$$

$$w_2 = w_3 = 0 + 0.5(-1-0)(-1) = 0.5$$

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$$f(\text{net}) = \frac{2}{1 + e^{-\text{net}}} - 1$$

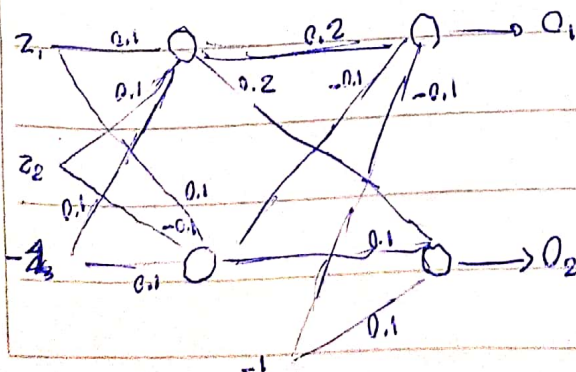
$$\alpha = 0.5$$

$$d_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$z_1 = [1, 1]^T$$

$$d_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$z_2 = [-1, -1]^T$$



$$z_{in_j} = \bar{u}_{0j} + \sum_{i=1}^n x_i u_{ij} \rightarrow z_j = f(z_{in_j}) \quad \text{مخفی}$$

$$y_{in_k} = w_{0k} + \sum_{j=1}^p z_j w_{jk} \rightarrow y_k = f(y_{in_k}) \quad \text{مخفی}$$

$$z_{in_1} = 0.1 [1 \ 1] + 0.1 [1 \ 1] - 0.1$$