### Game Programming with DirectX

# Direct3D Graphics Pipeline (Shader Samples)

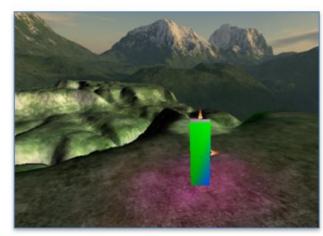
**Cube Mapping** 

· 큐브 매핑(Cube Mapping)



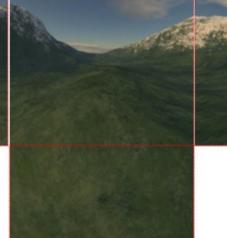
스카이 박스(Sky Box) – 텍스쳐 배열

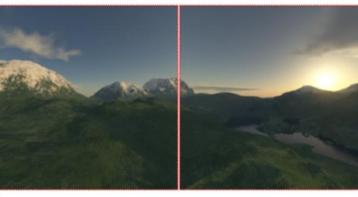
Тор





Left





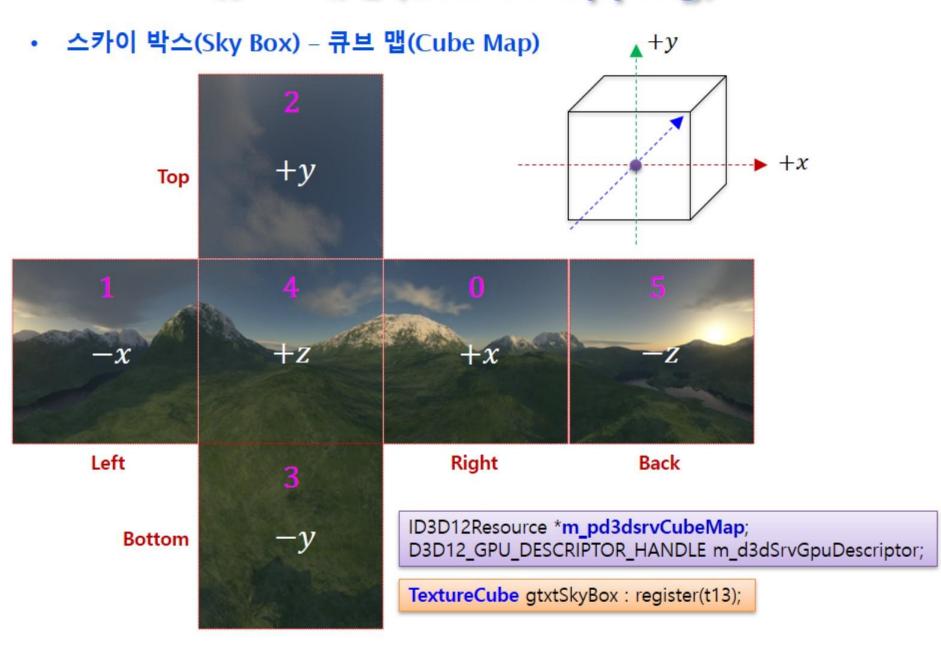
Right Back

**Bottom** 

ID3D12Resource \*m\_ppd3dTextures[6];

Texture2D gtxtSkyBox : register(t13);

Texture2DArray gtxtSkyBox : register(t13);



큐브 맵(Cube Map) 생성

C:\Program Files (x86)\Microsoft DirectX SDK (June 2010)\Utilities\bin\x86\DxTex.exe

 File → New Texture... ② View → Cube Map Face → Positive X X New Texture Negative X X Texture Type Positive Y Standard Texture Negative Y Cubemap Texture Positive Z Z O Volume Texture Negative Z Z Dimensions ③ File → Open Onto Cubemap Face... (텍스쳐 불러오기) 256 Volume Depth: Width: 256 MipMap Levels: Height: (1) Positive X (2) Negative X (3) Positive Y Surface/Volume Format (4) Negative Y Unsigned 32-bit: A8R8G8B8 (5) Positive Z (6) Negative Z Description **DDS** 32-bit RGB pixel format, where 8 bits are reserved for each color. ④ File → Save As... (큐브 맵 저장하기) "SkyBox.dds" https://developer.nvidia.com/legacy-texture-tools OK Cancel http://planetside.co.uk/products/terragen3

#### • 큐브 맵(Cube Map) 생성

https://github.com/Microsoft/DirectXTex

DirectXTex\_Desktop\_2017.sln

cube

array

volume

cubearray

DirectXTex-master\Texassemble\Bin\Desktop\_2017\Win32\Debug\texassemble.exe

texassemble < command > < options > < files >

texassemble cube -o skybox.dds -y skybox01.bmp ... skybox06.bmp

입력 파일의 크기와 형식이 같아야 함 입력 파일은 밉맵 레벨이 1이어야 함 출력 파일은 항상 dds 형식임

texassemble <command> <options> <files>

-r wildcard filename search is recursive

-w <n> width

-h <n> height

-f <format> format -if <filter> image filtering

-srgb{i|o} sRGB {input, output}
-o <filename> output filename

-o <filename> output filename
-y overwrite existing output file (if any)

-sepalpha resize alpha channel separately from color channels

-wrap, -mirror texture addressing mode (wrap, mirror, or clamp)
-alpha convert premultiplied alpha to straight alpha

-dx10 Force use of 'DX10' extended header

-nologo suppress copyright message

-tonemap apply a tonemap operator based on maximum luminance

POINT LINEAR CUBIC FANT

BOX TRIANGLE

POINT\_DITHER LINEAR\_DITHER

CUBIC\_DITHER FANT\_DITHER

BOX\_DITHER
TRIANGLE\_DITHER

TRIANGLE\_DITTLER

...

R32G32B32A32\_FLOAT

R32G32B32A32\_UINT R32G32B32A32\_SINT

R32G32B32\_FLOAT

R32G32B32\_UINT R32G32B32\_SINT

R32G32B32\_SINT R16G16B16A16\_FLOAT

R8G8B8A8\_UNORM

R8G8B8A8\_UNORM\_SRGB

R8G8B8A8\_UINT R8G8B8A8\_SNORM

R8G8B8A8\_SINT R32 FLOAT

R32\_UINT

R32\_SINT

\*\*\*

#### • 큐브 맵(Cube Map) 텍스쳐 좌표

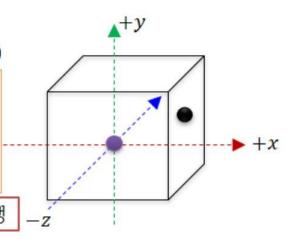
점(픽셀) 위치 벡터: (x, y, z), 큐브의 중심에서 점까지의 벡터: (x, y, z)

위치 벡터가 주어지면 큐브의 면과 텍스쳐 좌표를 계산할 수 있음

- ① 위치 벡터의 각 성분의 절대값의 최대값(α)과 부호에 해당하는 **면**을 선택 2개 이상의 성분이 절대값이 같으면 z, y, x의 순서로 선택
- ② 나머지 두 성분을 α로 나눔(-1.0 ~ +1.0)

**Bottom** 

③ 두 성분에 1.0을 더하고 2로 나누면 텍스쳐 좌표(0~1.0)를 얻음

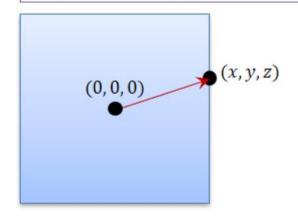




$$(-3.2, 5.1, -8.4) \rightarrow -z$$

$$(-3.2, 5.1, -8.4) \rightarrow \left(\frac{-3.2}{8.4}, \frac{5.1}{8.4}\right)$$

$$\left(\left(\frac{-3.2}{8.4} + 1\right) * 0.5, \left(\frac{5.1}{8.4} + 1\right) * 0.5\right) \rightarrow (0.31, 0.80)$$

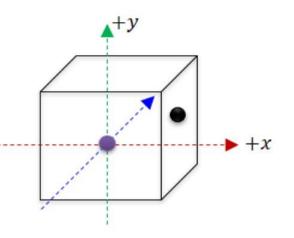


그래픽 하드웨어(Direct3D 샘플러)는 위치 벡터로부터 큐브의 면과 텍스쳐 좌표를 계산하여 샘플링을 수행

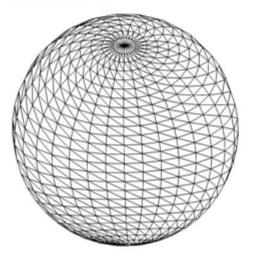
### • 큐브 맵(Cube Map) 텍스쳐 좌표

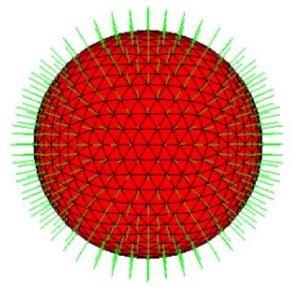
점(픽셀) 위치 벡터: (x, y, z), 큐브의 중심에서 점까지의 벡터: (x, y, z)

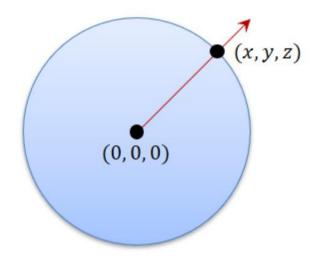
면(Face)	и	v	행렬 M <sub>face→camera</sub>
+x	$\frac{1}{2}\left(1-\frac{z}{x}\right)$	$\frac{1}{2}\left(1-\frac{y}{x}\right)$	$\begin{bmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ +1 & 0 & 0 \end{bmatrix}$
-x	$\frac{1}{2}\left(1-\frac{z}{x}\right)$	$\frac{1}{2}\left(1+\frac{y}{x}\right)$	$\begin{bmatrix} 0 & 0 & +1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{bmatrix}$
+y	$\frac{1}{2}\left(1+\frac{x}{y}\right)$	$\frac{1}{2}\left(1+\frac{z}{y}\right)$	$\begin{bmatrix} +1 & 0 & 0 \\ 0 & 0 & +1 \\ 0 & +1 & 0 \end{bmatrix}$
-у	$\frac{1}{2}\left(1-\frac{x}{y}\right)$	$\frac{1}{2}\left(1+\frac{z}{y}\right)$	$\begin{bmatrix} +1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}$
+z	$\frac{1}{2}\left(1+\frac{x}{z}\right)$	$\frac{1}{2}\left(1-\frac{y}{z}\right)$	$\begin{bmatrix} +1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & +1 \end{bmatrix}$
-z	$\frac{1}{2}\left(1+\frac{x}{z}\right)$	$\frac{1}{2}\left(1+\frac{y}{z}\right)$	$\begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$

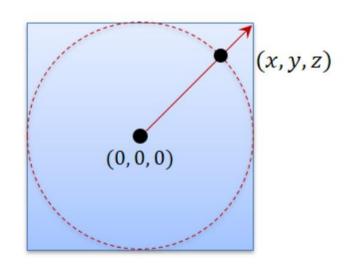


- 큐브 매핑(Cube Mapping)
  - 구(Sphere)





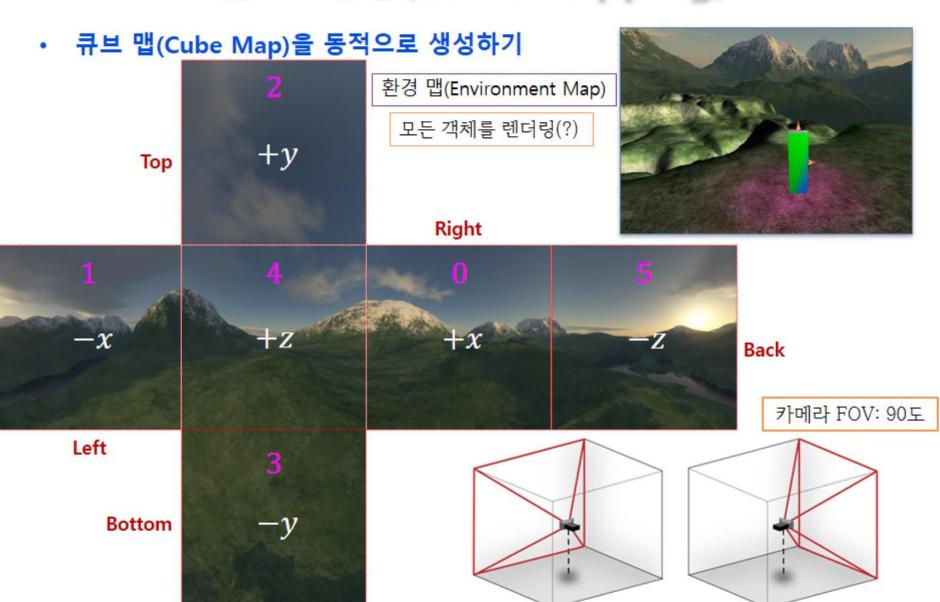




#### 큐브 맵핑(Cube Mapping)

스카이 박스(Sky Box)

```
CTexture *pSkyBoxTexture = new CTexture(1, RESOURCE_TEXTURE_CUBE, 0);
pSkyBoxTexture->LoadTextureFromFile(pd3dDevice, pd3dCommandList, L"SkyBox.dds", 0);
pd3dInputElementDescs[0] ={ "POSITION", 0, DXGI FORMAT R32G32B32 FLOAT, 0, 0, ..., 0 };
                                                             struct VS SKYBOX INPUT
   스카이 박스 메쉬(육면체)의 모든 면들은 안쪽을 향해야 함
                                                               float3 position : POSITION;
   큐브 맵 텍스쳐를 리소스로 사용
     텍스쳐 좌표는 샘플링을 할 때 자동적으로 계산됨
                                                             struct VS SKYBOX OUTPUT
                                                               float3 position : POSITION;
VS_SKYBOX_OUTPUT VSSkyBox(VS_SKYBOX_INPUT input)
                                                               float4 positionH: SV POSITION;
 VS SKYBOX OUTPUT output = (VS_SKYBOX_OUTPUT)0;
 output.positionH = mul(mul(float4(input.position, 1.0f), gmtxWorld), gmtxView), gmtxProjection);
 output.position = input.position;
 return(output);
                                                     TextureCube gtxtCubeMapSkyBox : register(t1);
                                                     SamplerState gssSkyBox : register(s1);
float4 PSSkyBox(VS_SKYBOX_OUTPUT input) : SV_Target
 float4 cColor = gtxtCubeMapSkyBox.Sample(gssSkyBox, input.position);
 return(cColor);
```

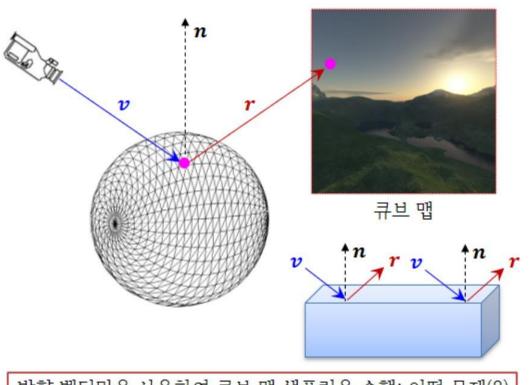


큐브 매핑을 할 객체의 위치에서 카메라가 90도씩 회전하면서 렌더링(사진을 찍음)하여 6개의 텍스쳐를 구하면 됨

n

여러 객체가 하나의 환경 맵을 공유할 수 있음

#### 큐브 매핑(Cube Mapping)





방향 벡터만을 사용하여 큐브 맵 샘플링을 수행: 어떤 문제(?)

v = A 위치 벡터 - 카메라 위치 벡터 벡터 v의 반사 벡터 r을 구함 큐브 맵에서 반사 벡터 r을 사용하여 샘플링

r = (x, y, z)의 가장 큰 요소가 면을 결정 나머지 요소는 텍스쳐 좌표  $n \qquad r = v - 2(v \cdot n)n$   $-(v \cdot n)n$ 

• 큐브 매핑(Cube Mapping) – 환경 매핑(Environmental Mapping)

```
void CCubeMappingShader::CreateShader(ID3D12Device *pd3dDevice) {
  D3D12 INPUT ELEMENT DESC d3dInputLayout[] = {
    { "POSITION", 0, DXGI_FORMAT_R32G32B32_FLOAT, 0, 0, D3D12_INPUT_PER_VERTEX_DATA, 0 },
    { "NORMAL", 0, DXGI FORMAT R32G32B32 FLOAT, 0, 12, D3D12 INPUT PER VERTEX DATA, 0 }
  UINT nElements = ARRAYSIZE(d3dInputLayout);
  CreateVertexShaderFromFile(pd3dDevice, L"Effect.fx", "VSLightingColor", ..., &m_pd3dVertexLayout);
  CreatePixelShaderFromFile(pd3dDevice, L"Effect.fx", "PSCubeMapping", "ps_4_0", &m_pd3dPixelShader);
VS LIGHTING OUTPUT VSLightingColor(VS LIGHTING INPUT input) {
  VS LIGHTING OUTPUT output = (VS LIGHTING OUTPUT)0;
                                                                            struct VS_LIGHTING_INPUT {
  output.normalW = mul(input.normal, (float3x3)gmtxWorld);
                                                                             float3 position: POSITION;
                                                                             float3 normal: NORMAL;
  output.positionW = mul(input.position, (float3x3)gmtxWorld);
  output.position = mul(float4(input.position, 1.0f), mtxWorldViewProjection);
  return(output);
                                                                            struct VS LIGHTING OUTPUT {
                                                                              float4 position: SV_POSITION;
                                                                             float3 positionW: POSITION;
float4 PSCubeMapping(VS LIGHTING OUTPUT input) : SV Target {
                                                                             float3 normalW: NORMAL:
  float4 clllumination = Lighting(input.positionW, input.normalW);
  float3 vFromCamera = normalize(input.positionW - gvCameraPosition.xyz);
  float3 vReflected = normalize(reflect(vFromCamera, input.normalW)); //정점 쉐이더에서 계산하면?
  float4 cCubeTextureColor = gtxtCubeMapped.Sample(gssCubeMapped, vReflected);
  return(clllumination * cCubeTextureColor);
                                                             TextureCube gtxtCubeMap : register(t6);
                                                             SamplerState gssCubeMap: register(s5);
```

• 큐브 매핑(Cube Mapping) – 환경 매핑(Environmental Mapping)

```
VS_SKYBOX_OUTPUT VSToCubeMap(VS_SKYBOX_INPUT input) {
                                                                          struct VS SKYBOX INPUT {
  VS SKYBOX OUTPUT output = (VS SKYBOX OUTPUT)0;
                                                                            float3 position: POSITION;
  output.position = mul(float4(input.position, 1.0f), gmtxWorld);
  output.positionL = input.position;
                                                                          struct VS SKYBOX OUTPUT {
  return(output);
                                                                            float3 positionL: POSITION;
                                                                            float4 position: SV_POSITION;
[maxvertexcount(18)]
void GSSkyBox(triangle VS_SKYBOX_OUTPUT input[3], inout TriangleStream < GS_SKYBOX_OUTPUT > s) {
  for (int i = 0; i < 6; i++) {
    GS SKYBOX OUTPUT output;
    output.renderTarget = i;
    matrix mtxViewProjection = mul(gmtxCubeMappingViews[i], gmtxCubeMappingProjection);
    for (int j = 0; j < 3; j++) {
      output.position = mul(input[j].position, mtxViewProjection);
      output.positionL = input[j].positionL;
                                                                struct GS_SKYBOX_OUTPUT {
      s.Append(output);
                                                                  float3 positionL: POSITION;
                                                                  float4 position: SV_POSITION;
                                                                  uint renderTarget : SV_RenderTargetArrayIndex;
    s.RestartStrip();
float4 PSToCubeMap(GS_SKYBOX_OUTPUT input) : SV_Target {
```

```
float4 cColor = gtxtSkyBox.Sample(gssSkyBox, input.positionL);
                                                                    cbuffer cbCubeMappingRender : register(b0) {
return(cColor);
                                                                      matrix gmtxCubeMappingViews[6];
                   TextureCube gtxtSkyBox : register(t13);
                                                                      matrix gmtxCubeMappingProjection;
                   SamplerState gssSkyBox : register(s4);
```

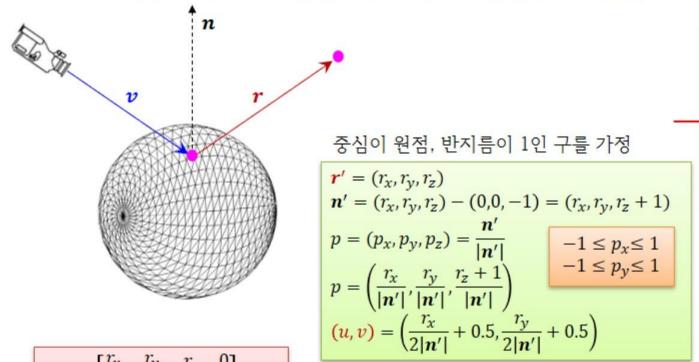
```
• 큐브 매핑(Cube Mapping) – 환경 매핑(Environmental Mapping)
VS SKYBOX OUTPUT VSToCubeMap(VS SKYBOX INPUT input) {
                                                                        struct VS SKYBOX INPUT {
  VS_SKYBOX_OUTPUT output = (VS_SKYBOX_OUTPUT)0;
                                                                          float3 position: POSITION;
  output.position = mul(float4(input.position, 1.0f), gmtxWorld);
  output.positionL = input.position;
                                                                        struct VS SKYBOX OUTPUT {
  return(output);
                                                                          float3 positionL: POSITION;
                                                                          float4 position: SV_POSITION;
[maxvertexcount(3)]
[Instance(6)]
void GSSkyBox(triangle VS_SKYBOX_OUTPUT input[3], uint nInstance: SV_GSInstanceID, inout
TriangleStream < GS SKYBOX OUTPUT > stream) {
  GS_SKYBOX_OUTPUT output;
  output.renderTarget = nInstance; //+x, -x, +y, -y, +z, -z
  matrix mtxViewProjection = mul(gmtxCubeMappingViews[nInstance], gmtxCubeMappingProjection);
  for (int j = 0; j < 3; j++) {
    output.position = mul(input[j].position, mtxViewProjection);
    output.positionL = input[j].positionL;
                                                              struct GS SKYBOX OUTPUT {
    stream.Append(output);
                                                                float3 positionL: POSITION;
                                                                float4 position: SV_POSITION;
  stream.RestartStrip();
                                                                uint renderTarget : SV_RenderTargetArrayIndex;
float4 PSToCubeMap(GS SKYBOX OUTPUT input) : SV Target {
                                                                  cbuffer cbCubeMappingRender : register(b0) {
  float4 cColor = gtxtSkyBox.Sample(gssSkyBox, input.positionL);
                                                                    matrix gmtxCubeMappingViews[6];
  return(cColor);
                    TextureCube gtxtSkyBox : register(t13);
```

SamplerState gssSkyBox : register(s4);

matrix gmtxCubeMappingProjection;

# 구 매핑(Sphere Mapping)

- 구 환경 매핑(Spherical Environment Mapping)
  - 구 맵(Sphere Map) 주변의 환경을 반사하는 구를 사진을 찍어서 생성(반구만 보임)



$$v' = vB^{-1}$$

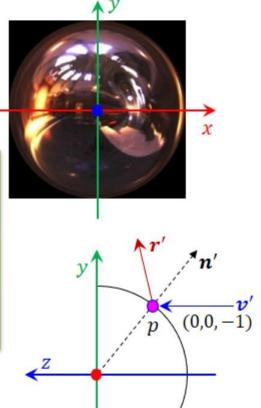
$$n' = nB^{-1}$$

$$r' = v' - 2(v' \cdot n')n'$$

카메라 좌표계

$$u = asin(\mathbf{n}_x)/\pi + 0.5$$
$$v = asin(\mathbf{n}_y)/\pi + 0.5$$

 $u = 0.5n_r + 0.5$  $v = 0.5n_v + 0.5$ 



카메라 좌표계

반지름=1