# HANG YUAN

C4-1-402, 725 family Community, Tianjin Road, Jian'xi District, Luoyang, Henan,471000
Tel. (+86) 15824969252 | Email: <a href="https://enderhangyuan.github.io/">Hang.Yuan20@student.xjtlu.edu.cn</a> | Website: <a href="https://enderhangyuan.github.io/">https://enderhangyuan.github.io/</a>
Google Scholar: <a href="https://scholar.google.com/citations?hl=zh-CN&user=xaBXiK8AAAAJ</a>

## **EDUCATION**

## Xi'an Jiaotong-Liverpool University (XJTLU), Suzhou, China | B.Eng.

2020-Current

Year 3 | Major in Mechatronics and Robotics Systems (GPA: Top 15% ranking)

## **PUBLICATIONS**

#### Journal:

- [1] **Yuan**, **H.**, Yuan, W., Duan, S. *et al.* (2023) Microfluidic-Assisted *Caenorhabditis elegans* Sorting: Current Status and Future Prospects. *Cyborg and Bionic Systems*, *4*, 0011. https://spj.science.org/doi/10.34133/cbsystems.0011.
- [2] Zhang, J.<sup>†</sup>, Liu, S.<sup>†</sup>, **Yuan, H.**<sup>†</sup> *et al.* (2023) Deep Learning for Microfluidic-Assisted *Caenorhabditis elegans* Multi-Parameter Identification Using YOLOv7. *Micromachines*, *14*, 1339. https://doi.org/10.3390/mi14071339.
- [3] Yuan, W., **Yuan**, H., Jiao, K. *et al.* (2023) Facile Microembossing Process for Microchannel Fabrication for Nanocellulose-Paper-Based Microfluidics. *ACS Applied Materials & Interfaces*, 15(5), 6420-6430. <a href="https://pubs.acs.org/doi/10.1021/acsami.2c19354">https://pubs.acs.org/doi/10.1021/acsami.2c19354</a>.
- [4] Zhu, J., **Yuan, H.**, Zhang, Q. *et al.* (2022) The Impact of Short Videos on Student Performance in an Online-Flipped College Engineering Course. *Humanities and Social Sciences Communications* 9, 327. <a href="https://doi.org/10.1057/s41599-022-01355-6">https://doi.org/10.1057/s41599-022-01355-6</a>.
- [5] Song, P., Ou, P., Wang, Y., **Yuan, H.** et al. (2023) An Ultrasensitive FET Biosensor Based on Vertically Aligned MoS<sub>2</sub> Nanolayers with Abundant Surface Active Sites. Analytica Chimica Acta, 341036. https://www.sciencedirect.com/science/article/pii/S000326702300257X.

#### **Conference:**

- [6] **Yuan H.**, Yong, R., Liu, S. *et al.* (2023) A Centrifugation-Assisted Lateral Flow Assay Platform for Bioassay Sensitivity and Visualization Enhancement. 45<sup>th</sup> Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC'23). [Poster]
- [7] **Yuan H.**, Zhang W. (2019) A Novel Hedgehog-Inspired Pin-Array Robot Hand with Multiple Magnetic Pins for Adaptive Grasping. In: Yu H. *et al.* (eds.) *Intelligent Robotics and Applications: 12<sup>th</sup> International Conference on (ICIRA)*, *Proceedings 5*(12), 684-695. <a href="https://doi.org/10.1007/978-3-030-27541-9">https://doi.org/10.1007/978-3-030-27541-9</a> 56.
- [8] Yuan, W., **Yuan H.**, Duan, S. *et al.* (2023) Highly-integrated SERS-Based Immunoassay NanoPADs for Early Diagnosis of Alzheimer's Disease. 45<sup>th</sup> Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC'23). [Poster]
- [9] Liu, S., Li, Y., **Yuan, H.** *et al.* (2023) A Bio-inspired Lateral Flow Assay for Improving the Sensitivity of Low Volume Samples. 19<sup>th</sup> International Meeting on Chemical Sensors (IMCS 2023). [Oral presentation]
- [10] Wang, L., Zhang, Z., Chen, M., Xie, J., Liu, F., **Yuan, H.** et al. (2023) Machine Learning-Based Fatigue Life Evaluation of the Pump Spindle Assembly with Parametrized Geometry. *ASME's International Mechanical Engineering Congress & Exposition (IMECE)* (accepted). [Full-length paper]

### GRANTED PATENTS

- [1] **Yuan H.**, Zhang W. A Cluster-Tube Self-Adaptive Robot Hand with Controllable Force for Rapid Grasping, CN109571539A[P], 2019.
- [2] Yuan H. A Hedgehog-Inspired Magnetic-Driven Self-Adaptive Pin-Array Robot Hand, CN109397278A[P], 2019.
- [3] Yuan H. A Parallel and Magnetic-Driven Robot Hand with Linkage Mechanisms, CN109531610A[P], 2019.

## RESEARCH EXPERIENCES

### Centrifugation-Assisted Lateral Flow Assay (CLFA) Platform | Research Leader

01.2022-Current

Supervisor: Pengfei Song

XJTLU Intelligent Microsystems Laboratory

- Addressed the limited sensitivity and uncontrollable incubation time of traditional LFA.
- Developed a CLFA platform that offers adjustable rotation speeds and enables smartphone-based quantitative bioassay detection, displaying results on the custom-designed UI and mobile application.
- Developed a bio-inspired microfluidic channel to enhance the sensitivity of LFA in bioassays.
- Outcomes: two international conference papers (Publications [6, 9]).

### Microfluidic-Assisted Caenorhabditis elegans (C. elegans) Sorting | Research Leader

07.2022-06.2023

XJTLU Intelligent Microsystems Laboratory

Supervisor: Pengfei Song

- Provided a comprehensive review of the up-to-date microfluidic-assisted C. elegans sorting developments from several angles to suit researchers with different backgrounds.
- Accepted as a cover paper and featured by the renowned organization AAAS & EurekAlert!.
- Developed a deep learning model using YOLOv7 to automatically detect and recognize C. elegans in microfluidic chips, enabling efficient identification and measurement of multiple phenotypes (e.g., size and movement speed).
- Outcomes: two journal papers (Publications [1, 2]).

#### Nanocellulose-Paper-Based Microfluidic Platform | Assistant Research Leader

07.2022-Current

XJTLU Intelligent Microsystems Laboratory

Supervisor: Xinyu Liu & Pengfei Song

- Developed a facile microembossing process using plastic micro-molds to efficiently fabricate microchannels on nanocellulose paper (nanopaper), optimizing the pattern parameters and saving time.
- Developed fundamental microfluidic devices and functional nanopaper-based analytical devices (NanoPADs).
- Performed colorimetric experiments and tested the droplet generation.
- Detected untreated glial fibrillary acidic protein (GFAP) in human plasma without pretreatment using SERS on NanoPADs, enabling highly sensitive early screening of Alzheimer's disease.
- Outcomes: one journal paper and one international conference paper (Publications [3, 8]).

#### Humanoid Robot and Fatigue Analysis | Research Assistant

05.2021-10.2021

XJTLU Summer Undergraduate Research Fellowships (SURF) Project

Supervisor: Min Chen & Quan Zhang

- Developed humanoid robots based on Raspberry Pi or Arduino, and programmed motion sequences.
- Assisted in the numerical and experimental analysis of a specific-sized spindle model to predict and compare fatigue life under various external loading conditions, validating the accuracy and reliability of the numerical simulation.
- Outcomes: national  $1^{st}$  prize and one international conference paper (Publication [10]).

## ROBOMASTER National University Robot Competitions | Mechanical Engineer & Investment Manager

XJTLU Embedded Artificial Intelligence Hardware Universities-Enterprises Joint Key Laboratory 10.2020-10.2022

Supervisor: Cezhou Zhao & Chun Zhao

- Designed mechanical components for an automated sentry robot, including the launching and mobility mechanisms, enabling the launch of 17mm projectiles and rapid disassembly from the track.
- Fabricated robots using appropriate materials (e.g., fiberglass, carbon fiber, resin, and nylon).
- Authored business proposals and secured enterprise sponsorships to support team funding and operations.
- Outcomes: national  $1^{st}$ ,  $2^{nd}$ , and  $3^{rd}$  prizes and provincial  $1^{st}$ ,  $2^{nd}$ , and  $3^{rd}$  prizes.

# Self-Adaptive Robot Hands | Visiting Student

01.2018-08.2019

Key Laboratory for Advanced Materials Processing Technology of Tsinghua University Supervisor: Wenzeng Zhang

- Developed a hedgehog-inspired pin-array robot hand with multiple magnetic pins for adaptive grasping.
- Developed a self-adaptive robot hand with controllable gripping force and a magnetic-driven robot hand for parallel gripping, enabling quickly grasping objects with diverse shapes.
- Outcomes: three granted patents, and one international conference paper (Publication [7]).

# **HONOURS & AWARDS:**

•	Three $1^{st}$ prizes, one $2^{nd}$ prizes, and three $3^{rd}$ prizes in national-level competitions	2021-2023
•	Two $1^{st}$ prizes, five $2^{nd}$ prizes, and six $3^{rd}$ prizes in provincial-level competitions	2021-2023
•	Three $1^{st}$ prizes in university-level competitions	2021-2023
•	Excellent Student Cadre (University-wide top 0.1%), Jiangsu Province	2022-2023
•	Outstanding Student (School-wide top 5%), XJTLU	2021-2022
•	Excellent Student Cadre & Outstanding Class Cadre (University-wide top 1%), XJTLU	2020-2021
•	Entrepreneurship Star (University-wide top 1%), XJTLU	2021-2022 & 2022-2023

# **TEACHING ACTIVITIES**

## Student lecturer, XJTLU Optional Course

03.2021-03.2022

• Delivered lectures for the optional "Unlocking Robot Hands" course on mechanical design and robot hands.

### Student Mentor, XJTLU-Affiliated school

09.2021-08.2022

• Taught extracurricular courses to high school students, including robotics, 3D printing, tea culture, and astronomy.

# **SKILLS**

## Computer Skills & Software:

- Programming: C, Arduino, MATLAB
- CAD/CAE: SolidWorks, AutoCAD, ANSYS (workbench), Rhino
- Graphic design: Adobe Illustrator, Adobe Premiere, Adobe Photoshop, KeyShot, Origin

Language: Mandarin (Native), English