#### **HANG YUAN**

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## **EDUCATION**

### Xi'an Jiaotong-Liverpool University (XJTLU)

Bachelor of Engineering, Mechatronics and Robotics Systems University of Liverpool (UoL)

Bachelor of Engineering, Mechatronics and Robotics Systems

• Weighted Average Mark: 66/100 (British marking criteria)

• GRE General Test: 327+4.5

Suzhou, China 09.2020-07.2024 (expected) Liverpool, United Kingdom 09.2020-07.2024 (expected)

#### RESEARCH EXPERIENCE

Research Leader, XJTLU Intelligent Microsystems Laboratory

Centrifugation-Assisted Lateral Flow Assay (CLFA) Platform

01.2022-Present

Supervisor: Dr. Pengfei Song, XJTLU

- Addressed the limited sensitivity and uncontrollable incubation time of traditional LFA.
- Developed a CLFA platform that offers adjustable rotation speeds and enables smartphonebased quantitative bioassay detection, displaying results on the custom-designed UI and mobile application.
- Developed a bio-inspired microfluidic channel to enhance the bioassay sensitivity of LFA.
- Outcomes: two posters and one oral presentation (Conference Participation [1, 3, 4]).

Research Leader, XJTLU Intelligent Microsystems Laboratory

Microfluidic-Assisted Caenorhabditis elegans (C. elegans) Sorting
Supervisor: Dr. Pengfei Song, XJTLU
07.2022-06.2023

- Provided a review of the up-to-date microfluidic-assisted *C. elegans* sorting developments, and featured by the renowned organizations *AAAS* & *EurekAlert!*.
- Developed a deep learning model using YOLOv7 to automatically detect and recognize *C. elegans* in microfluidic chips, enabling efficient identification and measurement of multiple phenotypes (*e.g.*, size and movement speed).
- Outcomes: two peer-reviewed journal papers (Publications [1, 2]).

Assistant Research Leader, XJTLU Intelligent Microsystems Laboratory

#### Nanocellulose-Paper-Based Microfluidic Platform

07.2022-Present

Supervisors: Prof. Xinyu Liu, University of Toronto & Dr. Pengfei Song, XJTLU

- Developed a facile microembossing process using plastic micro-molds to efficiently fabricate microchannels on nanocellulose paper (nanopaper), optimizing the pattern parameters and saving time.
- Developed fundamental microfluidic devices and functional nanopaper-based analytical devices (NanoPADs).

- Detected untreated glial fibrillary acidic protein (GFAP) in human plasma without pretreatment using SERS on NanoPADs, enabling highly sensitive early screening of Alzheimer's disease.
- Outcomes: two peer-reviewed journal papers (Publications [3, 4]) and one poster (Conference Participation [2]).

Research Assistant, XJTLU Summer Undergraduate Research Fellowships Project

Humanoid Robot and Fatigue Analysis 05.2021-10.2021

Supervisors: Dr. Min Chen, XJTLU & Dr. Quan Zhang, XJTLU

- Developed humanoid robots based on Raspberry Pi, and programmed motion sequences.
- Assisted in the numerical and experimental analysis of a specific-sized spindle model to
  predict and compare fatigue life under various external loading conditions, validating the
  accuracy and reliability of the numerical simulation.
- Outcomes: national 1<sup>st</sup> prize and one peer-reviewed conference paper (Publications [8]).

**Mechanical Engineer & Investment Manager**, XJTLU Embedded Artificial Intelligence Hardware Universities-Enterprises Joint Key Laboratory

ROBOMASTER National University Robot Competitions 10.2020-10.2022 Supervisors: Prof. Cezhou Zhao, XJTLU & Dr. Chun Zhao, XJTLU

- Designed and fabricated mechanical components for robots, including the launching and mobility mechanisms, using several materials (e.g., carbon fiber, resin, and nylon).
- Authored proposals for companies to support team operations; funded  $\frac{1}{2}$  60,000.
- Outcomes: national  $1^{st}$ ,  $2^{nd}$ , and  $3^{rd}$  prizes and provincial  $1^{st}$ ,  $2^{nd}$ , and  $3^{rd}$  prizes.

Visiting Student, Tsinghua Key Laboratory of Advanced Materials Processing Technology Self-Adaptive Robot Hands 01.2018-08.2019

Supervisor: Dr. Wenzeng Zhang, Tsinghua University

- Developed a hedgehog-inspired pin-array robot hand with multiple magnetic pins for adaptive grasping.
- Outcomes: four granted patents (Granted patents [1-4]), and one peer-reviewed conference paper (Publications [7]).

# **PUBLICATIONS**

### **Peer-Reviewed Journal Papers:**

- [1] **Yuan, H.**, Yuan, W. et al. (2023) Microfluidic-Assisted Caenorhabditis elegans Sorting: Current Status and Future Prospects. Cyborg and Bionic Systems, 4, 0011. DOI: 10.34133/cbsystems.0011. [Cover paper]
- [2] Zhang, J.<sup>†</sup>, Liu, S.<sup>†</sup>, **Yuan, H.**<sup>†</sup> *et al.* (2023) Deep Learning for Microfluidic-Assisted *Caenorhabditis elegans* Multi-Parameter Identification Using YOLOv7. *Micromachines*, *14*, 1339. DOI: 10.3390/mi14071339.
- [3] Yuan, W., **Yuan**, **H.** *et al.* (2023) Facile Microembossing Process for Microchannel Fabrication for Nanocellulose-Paper-Based Microfluidics. *ACS Applied Materials & Interfaces*, 15(5), 6420-6430. DOI: 10.1021/acsami.2c19354.
- [4] Yuan, W., **Yuan**, **H.** *et al.* (2023) Microembossing: A Convenient Process for Fabricating Microchannels on Nanocellulose Paper-Based Microfluidics. *Journal of Visualized Experiments*, 200, e65965. DOI: 10.3791/65965.

- [5] Zhu, J., **Yuan, H.** *et al.* (2022) The Impact of Short Videos on Student Performance in an Online-Flipped College Engineering Course. *Humanities and Social Sciences Communications* 9, 327. DOI: 10.1057/s41599-022-01355-6.
- [6] Song, P., Ou, P., Wang, Y., **Yuan, H.** *et al.* (2023) An Ultrasensitive FET Biosensor Based on Vertically Aligned MoS<sub>2</sub> Nanolayers with Abundant Surface Active Sites. *Analytica Chimica Acta*, 341036. DOI: 10.1016/j.aca.2023.341036

### **Peer-Reviewed Conference Papers:**

- [7] **Yuan H.**, Zhang W. (2019) A Novel Hedgehog-Inspired Pin-Array Robot Hand with Multiple Magnetic Pins for Adaptive Grasping. In: Yu H. *et al.* (eds.) 12<sup>th</sup> International Conference on Intelligent Robotics and Applications (ICIRA), Proceedings 5(12), 684-695. DOI: 10.1007/978-3-030-27541-9 56.
- [8] Wang, L., Zhang, Z., Chen, M., Xie, J., Liu, F., **Yuan, H.** et al. (2023) Machine Learning-Based Fatigue Life Evaluation of the Pump Spindle Assembly with Parametrized Geometry. *ASME's International Mechanical Engineering Congress & Exposition (IMECE)*.

  † denotes equal contributions.

# **CONFERENCE PARTICIPATION**

- [1] **Yuan H.** *et al.* (2023) A Centrifugation-Assisted Lateral Flow Assay Platform for Bioassay Sensitivity and Visualization Enhancement. 45<sup>th</sup> Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC), Sydney, Australia, Jul. 24-27. [Poster] [2] Yuan, W., **Yuan H.** *et al.* (2023) Highly-integrated SERS-Based Immunoassay NanoPADs for Early Diagnosis of Alzheimer's Disease. 45<sup>th</sup> Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC), Sydney, Australia, Jul. 24-27. [Poster] [3] Liu, S., Li, Y., **Yuan, H.** *et al.* (2023) A Bio-inspired Lateral Flow Assay for Improving the Sensitivity of Low Volume Samples. 19<sup>th</sup> International Meeting on Chemical Sensors (IMCS 2023), Changchun, China, Aug. 4-8. [Oral]
- [4] Duan, S., Cai, T., Liu, F., **Yuan, H.** et al. (2023) An Offline Deep Learning-Assisted Automated Paper-Based Microfluidic Platform. 27<sup>th</sup> International Conference on Miniaturized Systems for Chemistry and Life Sciences (µTAS 2023), Katowice, Poland, Oct. 15-19. [Poster]

### **GRANTED PATENTS**

- [1] **Yuan H.** A Hedgehog-Inspired Magnetic-Driven Self-Adaptive Pin-Array Robot Hand, CN109397278B[P], 2023. [Invention patent]
- [2] **Yuan H.**, Zhang W. A Cluster-Tube Self-Adaptive Robot Hand with Controllable Force for Rapid Grasping, CN209533441U[P], 2019. [Utility model patent]
- [3] **Yuan H.** A Hedgehog-Inspired Magnetic-Driven Self-Adaptive Pin-Array Robot Hand, CN209190774U[P], 2019. [Utility model patent]
- [4] **Yuan H.** A Parallel and Magnetic-Driven Robot Hand with Linkage Mechanisms, CN209453584U[P], 2019. [Utility model patent]

#### TEACHING EXPERIENCE

#### Student lecturer, XJTLU Optional Course

03.2021-03.2022

• Lectured undergraduate class of about 50 students; demonstrated mechanical design and robot hand techniques.

#### Student lecturer, XJTLU-Affiliated School

09.2021-08.2022

• Lectured high school student class of about 50 students; provided extracurricular courses, including robotics, 3D printing, tea culture, and astronomy.

# **HONORS**

- Excellent Student Cadre (University-wide top 0.1%), Jiangsu Province, China 2022-2023
- Entrepreneurship Star (University-wide top 1%), XJTLU 2021-2022 & 2022-2023
- Outstanding Student (School-wide top 5%), XJTLU 2021-2022
- Excellent Student Cadre (University-wide top 1%), XJTLU 2020-2021

### SELECTED AWARDS

- The 1<sup>st</sup> Prize of 2022 RoboMaster University Championship in the 21<sup>st</sup> National University Robot Competition *National Regional* 2022-2023
- The 1<sup>st</sup> Prize of 2022 RoboMaster University Championship in the 21<sup>st</sup> National University Robot Competition *Standard Robot Strength Award* 2022-2023
- The 1<sup>st</sup> Prize of RoboWork China Engineering Robotics Competition 2021-2022

### **SERVICE**

•	Executive Director, Yuanhe Technology (Changzhou) Co., Ltd.	10. 2022-Present
•	Academic Buddy, XJTLU	09.2021-09.2022
•	President & Liaison Minister, XJTLU Sagittarius Astronomy Club	03.2021-03.2022
•	Liaison Minister, XJTLU G-Master Robot Club	03.2021-03.2022
•	Vice President, XJTLU Tea Club	12.2020-12.2021

### **SKILLS**

#### **Computer Skills & Software:**

- *Programming*: C, Arduino, MATLAB
- CAD/CAE: SolidWorks, AutoCAD, ANSYS (workbench), Rhino
- Graphic design: Adobe Illustrator, Adobe Premiere, Adobe Photoshop, KeyShot, Origin

**Language:** Mandarin (Native), English (English-only instruction)