

HANG YUAN

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EDUCATION

Xi'an Jiaotong-Liverpool University (XJTLU)

Suzhou, China

Bachelor of Engineering, Mechatronics and Robotics Systems 09.2020-07.2024 (expected)

University of Liverpool (UoL)

Liverpool, United Kingdom

Bachelor of Engineering, Mechatronics and Robotics Systems 09.2020-07.2024 (expected)

- Weighted Average Mark: 66/100 (British marking criteria)
- GRE General Test: 327+4.5

RESEARCH EXPERIENCE

Research Leader, XJTLU Intelligent Microsystems Laboratory

Suzhou, China

Centrifugation-Assisted Lateral Flow Assay (CLFA) Platform

01.2022-Present

Supervisor: Dr. Pengfei Song, XJTLU

- Addressed the limited sensitivity and uncontrollable incubation time of traditional LFA.
- Developed a CLFA platform that offers adjustable rotation speeds and enables smartphone-based quantitative bioassay detection, displaying results on the custom-designed UI and mobile application.
- Developed a bio-inspired microfluidic channel to enhance the bioassay sensitivity of LFA.
- Outcomes: two posters and one oral presentation (Conference Participation [1, 3, 4]).

Research Leader, XJTLU Intelligent Microsystems Laboratory

Suzhou, China

Microfluidic-Assisted *Caenorhabditis elegans* (*C. elegans*) Sorting

07.2022-06.2023

Supervisor: Dr. Pengfei Song, XJTLU

- Provided a review of the up-to-date microfluidic-assisted *C. elegans* sorting developments, and featured by the renowned organizations *AAAS & EurekaAlert!*.
- Developed a deep learning model using YOLOv7 to automatically detect and recognize *C. elegans* in microfluidic chips, enabling efficient identification and measurement of multiple phenotypes (e.g., size and movement speed).
- Outcomes: two peer-reviewed journal papers (Publications [1, 2]).

Assistant Research Leader, XJTLU Intelligent Microsystems Laboratory

Suzhou, China

Nanocellulose-Paper-Based Microfluidic Platform

07.2022-Present

Supervisors: Prof. Xinyu Liu, University of Toronto & Dr. Pengfei Song, XJTLU

- Developed a facile microembossing process using plastic micro-molds to efficiently fabricate microchannels on nanocellulose paper (nanopaper), optimizing the pattern parameters and saving time.
- Developed fundamental microfluidic devices and functional nanopaper-based analytical devices (NanoPADs).

- Detected untreated glial fibrillary acidic protein (GFAP) in human plasma without pretreatment using SERS on NanoPADs, enabling highly sensitive early screening of Alzheimer's disease.
- Outcomes: two peer-reviewed journal papers (Publications [3, 4]) and one poster (Conference Participation [2]).

Research Assistant, XJTLU Summer Undergraduate Research Fellowships Suzhou, China
Humanoid Robot and Fatigue Analysis 05.2021-10.2021

Supervisors: Dr. Min Chen, XJTLU & Dr. Quan Zhang, XJTLU

- Developed humanoid robots based on Raspberry Pi, and programmed motion sequences.
- Assisted in the numerical and experimental analysis of a specific-sized spindle model to predict and compare fatigue life under various external loading conditions, validating the accuracy and reliability of the numerical simulation.
- Outcomes: national 1st prize and one peer-reviewed conference paper (Publications [8]).

Mechanical Engineer & Investment Manager, XJTLU Embedded Artificial Intelligence Hardware Universities-Enterprises Joint Key Laboratory Suzhou, China
ROBOMASTER National University Robot Competitions 10.2020-10.2022

Supervisors: Prof. Cezhou Zhao, XJTLU & Dr. Chun Zhao, XJTLU

- Designed and fabricated mechanical components for robots, including the launching and mobility mechanisms, using several materials (e.g., carbon fiber, resin, and nylon).
- Authored proposals for companies to support team operations; funded ¥ 60,000.
- Outcomes: national 1st, 2nd, and 3rd prizes and provincial 1st, 2nd, and 3rd prizes.

Visiting Student, Key Laboratory for Advanced Materials Processing Technology of Tsinghua University Beijing, China

Self-Adaptive Robot Hands 01.2018-08.2019

Supervisor: Dr. Wenzeng Zhang, Tsinghua University

- Developed a hedgehog-inspired pin-array robot hand with multiple magnetic pins for adaptive grasping.
- Outcomes: four granted patents (Granted patents [1-4]), and one peer-reviewed conference paper (Publications [7]).

PUBLICATIONS

Peer-Reviewed Journal Papers:

- [1] Yuan, H., Yuan, W. *et al.* (2023) Microfluidic-Assisted *Caenorhabditis elegans* Sorting: Current Status and Future Prospects. *Cyborg and Bionic Systems*, 4, 0011. DOI: [10.34133/cbsystems.0011](https://doi.org/10.34133/cbsystems.0011). [Cover paper]
- [2] Zhang, J.[†], Liu, S.[†], Yuan, H.[†] *et al.* (2023) Deep Learning for Microfluidic-Assisted *Caenorhabditis elegans* Multi-Parameter Identification Using YOLOv7. *Micromachines*, 14, 1339. DOI: [10.3390/mi14071339](https://doi.org/10.3390/mi14071339).
- [3] Yuan, W., Yuan, H. *et al.* (2023) Facile Microembossing Process for Microchannel Fabrication for Nanocellulose-Paper-Based Microfluidics. *ACS Applied Materials & Interfaces*, 15(5), 6420-6430. DOI: [10.1021/acsami.2c19354](https://doi.org/10.1021/acsami.2c19354).
- [4] Yuan, W., Yuan, H. *et al.* (2023) Microembossing: A Convenient Process for Fabricating Microchannels on Nanocellulose Paper-Based Microfluidics. *Journal of Visualized*

Experiments, 200, e65965. DOI: [10.3791/65965](https://doi.org/10.3791/65965).

[5] Zhu, J., **Yuan, H.** *et al.* (2022) The Impact of Short Videos on Student Performance in an Online-Flipped College Engineering Course. *Humanities and Social Sciences Communications* 9, 327. DOI: [10.1057/s41599-022-01355-6](https://doi.org/10.1057/s41599-022-01355-6).

[6] Song, P., Ou, P., Wang, Y., **Yuan, H.** *et al.* (2023) An Ultrasensitive FET Biosensor Based on Vertically Aligned MoS₂ Nanolayers with Abundant Surface Active Sites. *Analytica Chimica Acta*, 341036. DOI: [10.1016/j.aca.2023.341036](https://doi.org/10.1016/j.aca.2023.341036)

Peer-Reviewed Conference Papers:

[7] **Yuan H.**, Zhang W. (2019) A Novel Hedgehog-Inspired Pin-Array Robot Hand with Multiple Magnetic Pins for Adaptive Grasping. In: Yu H. *et al.* (eds.) *12th International Conference on Intelligent Robotics and Applications (ICIRA), Proceedings* 5(12), 684-695. DOI: [10.1007/978-3-030-27541-9_56](https://doi.org/10.1007/978-3-030-27541-9_56).

[8] Wang, L., Zhang, Z., Chen, M., Xie, J., Liu, F., **Yuan, H.** *et al.* (2023) Machine Learning-Based Fatigue Life Evaluation of the Pump Spindle Assembly with Parametrized Geometry. *ASME's International Mechanical Engineering Congress & Exposition (IMECE)*.

† denotes equal contributions.

CONFERENCE PARTICIPATION

[1] **Yuan H.** *et al.* (2023) A Centrifugation-Assisted Lateral Flow Assay Platform for Bioassay Sensitivity and Visualization Enhancement. *45th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC)*, Sydney, Australia, Jul. 24-27. [Poster]

[2] Yuan, W., **Yuan H.** *et al.* (2023) Highly-integrated SERS-Based Immunoassay NanoPADs for Early Diagnosis of Alzheimer's Disease. *45th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC)*, Sydney, Australia, Jul. 24-27. [Poster]

[3] Liu, S., Li, Y., **Yuan, H.** *et al.* (2023) A Bio-inspired Lateral Flow Assay for Improving the Sensitivity of Low Volume Samples. *19th International Meeting on Chemical Sensors (IMCS 2023)*, Changchun, China, Aug. 4-8. [Oral]

[4] Duan, S., Cai, T., Liu, F., **Yuan, H.** *et al.* (2023) An Offline Deep Learning-Assisted Automated Paper-Based Microfluidic Platform. *27th International Conference on Miniaturized Systems for Chemistry and Life Sciences (μ TAS 2023)*, Katowice, Poland, Oct. 15-19. [Poster]

GRANTED PATENTS

[1] **Yuan H.** A Hedgehog-Inspired Magnetic-Driven Self-Adaptive Pin-Array Robot Hand, CN109397278B[P], 2023. [Invention patent]

[2] **Yuan H.**, Zhang W. A Cluster-Tube Self-Adaptive Robot Hand with Controllable Force for Rapid Grasping, CN209533441U[P], 2019. [Utility model patent]

[3] **Yuan H.** A Hedgehog-Inspired Magnetic-Driven Self-Adaptive Pin-Array Robot Hand, CN209190774U[P], 2019. [Utility model patent]

[4] **Yuan H.** A Parallel and Magnetic-Driven Robot Hand with Linkage Mechanisms, CN209453584U[P], 2019. [Utility model patent]

TEACHING EXPERIENCE

Student lecturer, XJTLU Optional Course

03.2021-03.2022

- Lectured undergraduate class of about 50 students; demonstrated mechanical design and

robot hand techniques.

Student lecturer, XJTLU-Affiliated School

09.2021-08.2022

- Lectured high school student class of about 50 students; provided extracurricular courses, including robotics, 3D printing, tea culture, and astronomy.

HONORS

- Excellent Student Cadre (University-wide top 0.1%), Jiangsu Province, China 2022-2023
- Entrepreneurship Star (University-wide top 1%), XJTLU 2021-2022 & 2022-2023
- Outstanding Student (School-wide top 5%), XJTLU 2021-2022
- Excellent Student Cadre (University-wide top 1%), XJTLU 2020-2021

SELECTED AWARDS

- The 1st Prize of 2022 RoboMaster University Championship in the 21st National University Robot Competition *National Regional* 2022-2023
- The 1st Prize of 2022 RoboMaster University Championship in the 21st National University Robot Competition *Standard Robot Strength Award* 2022-2023
- The 1st Prize of RoboWork China Engineering Robotics Competition 2021-2022

SERVICE

- **Executive Director**, Yuanhe Technology (Changzhou) Co., Ltd. 10. 2022-Present
- **Academic Buddy**, XJTLU 09.2021-09.2022
- **President & Liaison Minister**, XJTLU Sagittarius Astronomy Club 03.2021-03.2022
- **Liaison Minister**, XJTLU G-Master Robot Club 03.2021-03.2022
- **Vice President**, XJTLU Tea Club 12.2020-12.2021

SKILLS

Computer Skills & Software:

- *Programming*: C, Arduino, MATLAB
- *CAD/CAE*: SolidWorks, AutoCAD, ANSYS (workbench), Rhino
- *Graphic design*: Adobe Illustrator, Adobe Premiere, Adobe Photoshop, KeyShot, Origin

Experimental Skills:

- *Immunoassays*: Enzyme-linked immunosorbent assay (ELISA), Lateral flow assay (LFA)
- *Chemical synthesis*: AuNPs, AgNPs, Bottlebrush elastomers
- *Characterization*: UV-vis, FTIR, SEM, SERS, XRD

Language: Mandarin (Native), English (English-only instruction)