Damping in the Winter's Model

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May 11, 2018

Using the terminology of Kraig Winters we need to define a reasonable coefficient for damping.

Given that,

$$\frac{\partial u}{\partial t} = \nu \nabla^{2n} u \tag{1}$$

is spectrally,

$$\frac{\partial u}{\partial t} = \nu (ik2\pi)^{2n} u \tag{2}$$

which has the solution

$$u = e^{\nu(ik2\pi)^{2n}t}. (3)$$

We want to convert this into an e-fold time, so we want

$$e^{-t/T} = e^{\nu(ik2\pi)^{2n}t}. (4)$$

Using that $k = \frac{1}{2\Delta}$ where Δ is the sample interval and solving for ν in terms of the other variables,

$$\nu = \frac{(-1)^{n+1}}{T} \left(\frac{\Delta}{\pi}\right)^{2n} \tag{5}$$

Now add some forcing,

$$\frac{\partial \hat{u}}{\partial t} = \hat{F} + \nu (ik2\pi)^{2n} \hat{u} \tag{6}$$

solution

$$\hat{u} = u_0 e^{\nu(-1)^n (k2\pi)^{2n} t} - (-1)^n \frac{F}{\nu(k2\pi)^{2n}}$$
(7)

Then, in steady state,

$$\hat{u}\hat{u}^* = \frac{F^2}{\nu^2} (2\pi k)^{-4n} \tag{8}$$

• We can compute the wavenumber at which damping drops the amplitude more than 50 percent during the length of the simulation.

• We can compute, given U, the cfl criteria, and then ask that the Reynolds number be one at the grid scale.

How does this hyperviscous ν compare to the usual ν_0 ?

$$\nu(k2\pi)^{2n}u = \nu_0(k2\pi)^2u \tag{9}$$

$$\nu_0 = \nu (k2\pi)^{2n-2} \tag{10}$$

$$\nu_0 = \frac{1}{T} \left(\frac{\Delta}{\pi}\right)^2 \tag{11}$$

$$\frac{U\Delta}{\nu_0} = 1\tag{12}$$

$$\frac{(-1)^{n+1}}{U\Delta} \left(\frac{\Delta}{\pi}\right)^2 = T \tag{13}$$

For one simulation, we have that U = 0.0365 m/s and $\Delta = 6750$ m with n = 3. This suggests a damping time scale of T = 18000s. The actually simulation used twice that.

The linear wave mode propagation speed seems to be the maximum velocity in these simulations. Wait. There's no surface, so that can't matter.

1 Decorrelation time

$$R(\tau \ge 0) = \int_0^\infty u(t)u(t+\tau) dt \tag{14}$$

$$= \int_{0}^{\infty} e^{\nu(ik2\pi)^{2n}t} e^{\nu(ik2\pi)^{2n}(t+\tau)} dt$$
 (15)

$$= \frac{e^{\nu(ik2\pi)^{2n}(2t+\tau)}}{2\nu(ik2\pi)^{2n}} \Big|_{0}^{\infty}$$
 (16)

So what is $\nu(k2\pi)^{2n}$?

$$\nu(ik2\pi)^{2n} = \frac{(-1)^{n+1}}{T} \left(\frac{\Delta}{\pi}\right)^{2n} (ik2\pi)^{2n}$$
 (17)

$$= -\frac{(k2\Delta)^{2n}}{T} \tag{18}$$

So then,

$$R(\tau) = -\frac{T}{2(k2\Delta)^{2n}} e^{-(k2\Delta)^{2n} \frac{\tau}{T}}$$
(19)

If we normalize by the total variance of the integrated velocity, then we have that,

$$R(\tau) = e^{-(k2\Delta)^{2n} \frac{\tau}{T}} \tag{20}$$

So how long does it take for each wavenumber to decay to $\epsilon = 0.5$?

$$\ln \epsilon = -\left(k2\Delta\right)^{2n} \frac{\tau}{T} \tag{21}$$

$$\tau = \frac{T \ln \epsilon}{-(k2\Delta)^{2n}} \tag{22}$$

I also want to know which wavenumbers take a certain amount of time to decay.

$$(k2\Delta)^{2n} = -\frac{T\ln\epsilon}{\tau} \tag{23}$$

$$k = \frac{1}{2\Delta} \left(-\frac{T \ln \epsilon}{\tau} \right)^{\frac{1}{2n}} \tag{24}$$

In terms of mode number,

$$\frac{j}{2N\Delta} = \frac{1}{2\Delta} \left(-\frac{T\ln\epsilon}{\tau} \right)^{\frac{1}{2n}} \tag{25}$$

$$j = N \left(-\frac{T \ln \epsilon}{\tau} \right)^{\frac{1}{2n}} \tag{26}$$

2 2D Decorrelation time

In two-dimensions the damping solution is,

$$u = e^{(\lambda_x + \lambda_z)t}. (27)$$

So,

$$R(\tau \ge 0) = \int_0^\infty u(t)u(t+\tau) dt \tag{28}$$

$$= \int_0^\infty e^{(\lambda_x + \lambda_z)t} e^{(\lambda_x + \lambda_z)(t+\tau)} dt$$
 (29)

$$\begin{aligned}
& = \frac{e^{(\lambda_x + \lambda_z)(2t + \tau)}}{2(\lambda_x + \lambda_z)} \Big|_0^{\infty} \\
& = \frac{e^{(\lambda_x + \lambda_z)\tau}}{2(\lambda_x + \lambda_z)}
\end{aligned} (30)$$

$$=\frac{e^{(\lambda_x + \lambda_z)\tau}}{2(\lambda_x + \lambda_z)}\tag{31}$$

Normalized, this is quite simply,

$$R(\tau \ge 0) = e^{(\lambda_x + \lambda_z)\tau} \tag{32}$$