

# Enes Ulas Dincer

Research and Teaching Assistant

September 15, 1999

Sariyer / Istanbul, Turkey

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<https://www.linkedin.com/in/enesulasdincer>

[enesulasdincer.github.io](https://enesulasdincer.github.io)



## CORE COMPETENCIES

Physical Human-Robot Interaction

Robot Control

Deep Learning

Control Theory

Robust Control

## EDUCATION

### Master of Science (2022 – Present)

#### Koç University, Turkey

[In QS 2024, ranked **431<sup>th</sup>** in the overall ranking and **331<sup>th</sup>** in the engineering & technology subject area]

Mechanical Engineering (**GPA: 3.81 / 4.0**)

Graduate School of Science and Engineering

Robotics and Mechatronics Laboratory

KUIS Artificial Intelligence Center

**Supervisor:** Prof. Cagatay Basdogan

- Teaching Experiences

Mechanical Engineering Design (Fall 2024)

Dynamic Modeling and Control (Spring 2023, Fall 2023)

- Publications

#### Can a Robot Resolve Conflicts with a Human During Co-Manipulation? (Submitted)

ACM Transaction on Human-Robot Interaction [Impact Factor: 5.]

[Enes Ulas Dincer](#), Zaid Al-Saadi, Yahya M. Hamad, Yusuf Aydin, Ayse Kucukyilmaz, Cagatay Basdogan

- Courses

- Robotics
- Deep Learning
- Reinforcement Learning
- Human-Robot Interaction
- Computer Graphics

### Bachelor of Science (2017 – 2022)

#### Istanbul Technical University, Turkey

[In QS 2023, ranked **404<sup>th</sup>** in the overall ranking and **108<sup>th</sup>** in the engineering & technology subject area]

Control and Automation Engineering (**GPA: 3.87 / 4.0**), **Valedictorian**

Faculty of Electrical and Electronics Engineering

**Thesis Title:** “Implementing a New Algebraic Technique for MIMO Systems Stability in Modern Automatic Flight Control”

**Thesis Supervisor:** Doç. Dr. İlker Üstoğlu

- Courses

- System Modelling and Simulation
- Feedback Control Systems
- Computer Controlled Systems
- Robot Control
- State Space Methods in Control Systems
- Optimal Control Theory
- Introduction to Nonlinear Control Systems

## AWARDS

2022	<b>Koc University - Is Bankasi Artificial Intelligence Center Fellowship</b> [Fellows were selected by examination in mathematics and computer programming.]
2022	<b>Istanbul Technical University – Control and Automation Engineering</b> Highest ranked student of the department
2017	<b>Istanbul Technical University – Chess Tournament</b> First Ranked

## WORK EXPERIENCES

January 2022 – February 2022	<b>Baykar Makina, Istanbul, Turkey</b> Part-Time Working Student Design of a Hardware-in-the-Loop (HIL) System for Armed and Unarmed Unmanned Aerial Vehicle (UAV) Projects
August 2021 – September 2021	<b>Baykar Makina, Istanbul, Turkey</b> Engineering Intern

## COMPUTER & HARDWARE SKILLS

<b>Programming Languages</b>	<b>C++</b> ●●●●●	<b>Python</b> ●●●●●
	<b>MATLAB</b> ●●●●●	
<b>Software Packages</b>	Simulink, Mathematica	
<b>Deep Learning Frameworks</b>	TensorFlow w/Keras	

## ACTIVITIES

2021 - 2022	<b>ITU – Lagari Thrust Rocket Team</b>
2017 - 2018	<b>ITU - Fencing</b>

## LATEST PROJECTS (More Details: [https://enesulasdincer.github.io/#research\\_projects](https://enesulasdincer.github.io/#research_projects))

### Can a Robot Resolve Conflicts with a Human During Co-Manipulation?

Universal Robot UR5, ATI Mini 45 F/T Sensors

C++, Python (Keras), MATLAB

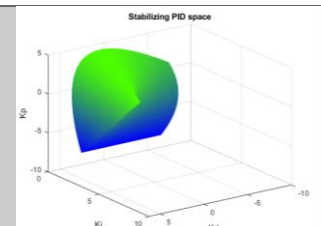
Adaptive Admittance Controller, Machine Learning



### Fast Calculation of Robust Stabilizing PID Controllers for SISO systems

MATLAB, Mathematica

PID Controllers, Robust Control, Stabilization, Controller Design



**Robust Control of TITO Systems  
Under Multiplicative Uncertainty  
and a Case Study: Longitudinal  
Control of a Fixed-Wing Aircraft**

MATLAB, Mathematica  
Robust Control, System  
Modelling, Flight Dynamics,  
Stability Analysis



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## LANGUAGES

***Turkish: Native***

***English: Advanced***

***German: Basic***

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## INTERESTS

*Basketball (Played 6 seasons in the Turkish Basketball Federation, with 3 league championships titles.), Chess (First ranked in ITU), Reading, Etymology*

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## REFERENCES

***Prof. Çağatay Başdoğan***

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Koç University, Istanbul,  
Turkey*

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