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# CHARACTERIZATION OF COMPUTATION-ACTIVATION NETWORKS BY SUFFICIENT STATISTICS

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RESEARCH NOTES IN THE ENEXA AND QROM PROJECTS

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## 1 Foundations

### 1.1 Information Theory [Cover, Thomas - Section 2.10]

Consider two variables  $Z$  and  $X$  with a joint distribution  $\mathbb{P}^{Z,X}$ , and a function  $T$  on the states of  $X$ . We augment this joint distribution by a variable  $Y_T$ , which is the head variable to the function  $T$

$$\mathbb{P}[Z, X, Y_T] = \langle \mathbb{P}[Z, X], \beta^T[Y_T, X] \rangle [Z, X, Y_T]$$

Then we have

$$(Y_T \perp Z) | X$$

since

$$\mathbb{P}[Y_T | Z, X] = \beta^T[Y_T, X] \otimes \mathbb{I}[Z] .$$

Thus, the variables are a Markov Chain  $Z \rightarrow X \rightarrow Y$ .

**Definition 1.** We call  $T$  sufficient statistic of  $Z$ , if and only if

$$I(Z; X) = I(Z; T(X)) .$$

**Lemma 1.** If there is a function  $Q$  such that

$$\mathbb{P}[Z, X] = \langle \mathbb{P}[X], \beta^Q[Z, X] \rangle [Z, X] ,$$

and  $T$  is sufficient for  $Z$ , then there is a function  $R$  such that

$$Q = R \circ T .$$

*Proof.* Since  $Z$  has a deterministic dependence on  $X$  we have  $\mathbb{H}[Z|X] = 0$  and by the sufficient statistic assumption (using that  $I(X; Y_T) = H(Y_T) - H(X|Y_T)$ ) we have

$$\mathbb{H}[Z|Y_T] = \mathbb{H}[Z|X] = 0.$$

Now,  $\mathbb{H}[Z|Y_T]$  is equal to the existence of a function  $R$  mapping the states of  $Y$  to  $Z$ , such that for any state  $y$

$$\mathbb{P}[Z|Y_T = y] = \epsilon_{R(y)}[Z].$$

Since  $Y$  itself is computable by  $X$  with the function  $T$ , and  $Z$  with  $Q$ , we have

$$Q = R \circ T.$$

□

This lemma is applied when characterizing sufficient statistics for  $Z = \mathbb{P}[X]$ .

## 1.2 Mathematical Statistic [Hogg - Chapter 2]

In mathematical statistic, sufficient statistics are used to characterize parameter estimation problems, i.e. where  $Z$  is a parameter variable  $\Theta$  of a parametrized family. The joint distribution of  $\Theta$  and  $X$  is constructed by drawing the parameter variable  $\Theta$  first with outcome  $\theta$  and then drawing  $X$  from  $\mathbb{P}^\theta$ .

### 1.3 Equivalent definitions of sufficient statistics

**Theorem 1** (Factorization Theorem of Fisher and Neyman). *Let  $\mathbb{P}$  be a joint distribution of variables  $Z, X$  with values  $\text{val}(Z)$ ,  $\text{val}(X)$  and let  $T(X)$  be a statistic. The following are equivalent:*

i) *The Data Processing Inequality holds straight, i.e.*

$$I(Z; X) = I(Z; Y_T).$$

ii)  *$Z \rightarrow Y_T \rightarrow X$  is a Markov Chain, i.e.*

$$(Z \perp X) | Y_T$$

iii) *There are functions  $g : \text{im}(T) \times \text{val}(Z) \rightarrow \mathbb{R}$  and  $h : \text{val}(X) \rightarrow \mathbb{R}$  such that for any  $(x, z) \in \text{val}(Z) \times \text{val}(X)$*

$$\mathbb{P}[Z = z, X = x] = g(T(x), z) \cdot h(x).$$

*Proof.*  $i) \Leftrightarrow ii)$ : We have always

$$I(Z; X) = I(Z; X, Y_T) = I(Z; Y_T) + I(Z; X|Y_T)$$

and thus if and only if  $i)$  holds

$$I(Z; X|Y_T) = 0.$$

Using the KL-divergence characterization of the mutual information, this is equal to

$$\mathbb{P}[Z, X|Y_T] = \langle \mathbb{P}[Z|Y_T], \mathbb{P}[X|Y_T] \rangle [Z, X, Y_T].$$

This is equivalent to the conditional independence statement  $ii)$ .

$ii) \Rightarrow iii)$ : For all  $z \in \text{val}(Z)$  and  $x \in \text{val}(X)$  we have

$$\begin{aligned} \mathbb{P}[Z = z|X = x] &= \mathbb{P}[Z = z|X = x, Y_T = T(x)] \\ &= \mathbb{P}[Z = z|Y_T = T(x)] \end{aligned}$$

Here we used that  $Y_T$  has a deterministic dependence on  $X$  and  $ii)$ . There is thus a function  $g$  such that for all  $z \in \text{val}(Z)$  and  $x \in \text{val}(X)$

$$g(T(x), z) = \mathbb{P}[Z = z|X = x].$$

We further define a function  $h(x) = \mathbb{P}[X = x]$  and get

$$\begin{aligned} \mathbb{P}[Z = z, X = x] &= \mathbb{P}[X = x] \cdot \mathbb{P}[Z = z|X = x] \\ &= g(T(x), z) \cdot h(x). \end{aligned}$$

$iii) \Rightarrow ii)$ : Using  $iii)$  we have for all supported  $(x, z) \in \text{val}(Z) \times \text{val}(X)$

$$\begin{aligned}
 \mathbb{P}[Z = z | X = x] &= \frac{\mathbb{P}[Z = z, X = x]}{\mathbb{P}[X = x]} \\
 &= \frac{g(T(x), z) \cdot h(x)}{\int g(T(x), z) \cdot h(x) dz} \\
 &= \frac{g(T(x), z)}{\int g(T(x), z) dz} \\
 &= \frac{\left( \int_{\tilde{x}: T(\tilde{x})=T(x)} h(\tilde{x}) d\tilde{x} \right) \cdot g(T(x), z)}{\left( \int_{\{\tilde{x}: T(\tilde{x})=T(x)\}} h(\tilde{x}) d\tilde{x} \right) \cdot \int g(T(x), z) dz} \\
 &= \frac{\mathbb{P}[Z = z, Y_T = T(x)]}{\mathbb{P}[Y_T = T(x)]} \\
 &= \mathbb{P}[Z = z | Y_T = T(x)]
 \end{aligned}$$

We have at almost all  $y \in \text{val}(Y_T)$ ,  $z \in \text{val}(Z)$  and  $x \in \text{val}(X)$  that  $y = T(x)$  and

$$\mathbb{P}[Z = z | X = x, Y_T = y] = \mathbb{P}[Z = z | X = x]$$

and with the above at thus at almost all such pairs

$$\mathbb{P}[Z = z | X = x, Y_T = y] = \mathbb{P}[Z = z | Y_T = y].$$

This is equivalent to  $ii)$ . □

## 2 Sufficient Statistic for Parametrized Families

Sufficient statistics are treated in mathematical statistics and in information theory. We here choose a definition of information theory and apply a factorization theorem of mathematical statistics to relate with Computation-Activation Networks. The distribution of a canonical parameter is now drawn from a (possibly continuous) random variable  $\Theta$ , which takes values  $\theta \in \Gamma$  with probability

$$\tilde{\mathbb{P}}[\Theta = \theta].$$

**Definition 2** (Sufficient statistics for Parameters). *Let  $\{\mathbb{P}^\theta[X_{[d]}] : \theta \in \Gamma\}$  be a family of probability distributions and*

$$\mathcal{S} : \prod_{k \in [d]} [m_k] \rightarrow \prod_{l \in [p]} [p_l]$$

*be a function. We say that  $\mathcal{S}$  is sufficient for  $\Theta$ , if for any distribution  $\tilde{\mathbb{P}}[\Theta]$  of  $\Theta$ , when drawing  $X_{[d]}$  from  $\mathbb{P}^\theta[X_{[d]}]$  with probability  $\tilde{\mathbb{P}}[\Theta = \theta]$ , we have that*

$$(\Theta \perp X_{[d]}) | \mathcal{S}(X_{[d]}).$$

We can characterize Computation-Activation Networks with arbitrary base measures based on sufficient statistics.

**Theorem 2** (Characterization of Computation-Activation Networks). *Let  $\{\mathbb{P}^\theta[X_{[d]}] : \theta \in \Gamma\}$  be a family of probability distributions with a sufficient statistic  $\mathcal{S}$ . Then there is a non-negative (possibly non-Boolean) base measure  $\nu[X_{[d]}]$  and a map*

$$h : \Gamma \rightarrow \bigotimes_{l \in [p]} \mathbb{R}^{p_l}$$

*such that for all  $\theta \in \Gamma$*

$$\mathbb{P}^\theta[X_{[d]}] = \langle h(\Gamma)[Y_{[p]}], \beta^{\mathcal{S}}[Y_{[p]}, X_{[d]}], \nu[X_{[d]}] \rangle [X_{[d]} | \emptyset].$$

*We further have that for a set  $\{\mathbb{P}^\theta[X_{[d]}] : \theta \in \Gamma\}$   $\mathcal{S}$  is a sufficient statistic, if and only if there is a non-negative (possibly non-Boolean) base measure  $\nu[X_{[d]}]$  with*

$$\{\mathbb{P}^\theta[X_{[d]}] : \theta \in \Gamma\} \subset \Lambda^{\mathcal{S}, \text{MAX}, \nu}.$$

*Proof.* By the Fisher-Neyman Factorization Thm. 1 we have that  $\mathcal{S}$  is a sufficient statistic if and only if there are real-valued functions  $g$  on  $\left(\times_{l \in [p]} [p_l]\right) \times \Gamma$  and  $h$  on  $\times_{k \in [d]} [m_k]$  such that

$$\mathbb{P}^\theta [X_{[d]} = x_{[d]}] = g(\mathcal{S}(x_{[d]}), \Gamma) \cdot h(x_{[d]}). \quad (1)$$

We define a base measure by the coordinate encoding of  $h$  by

$$\nu [X_{[d]}] = \sum_{x_{[d]} \in \times_{k \in [d]} [m_k]} h(x_{[d]}) \epsilon_{x_{[d]}} [X_{[d]}]$$

and for each  $\theta \in \Gamma$  an activation tensor

$$\xi^\theta [Y_{[p]}] = \sum_{y_{[p]}} g(y_{[p]}, \theta) \epsilon_{y_{[p]}} [Y_{[p]}].$$

With this we have for any  $\theta \in \Gamma$

$$\langle h(\Gamma)[Y_{[p]}], \beta^{\mathcal{S}} [Y_{[p]}, X_{[d]}], \nu [X_{[d]}] \rangle [\emptyset] = 1$$

and thus for any  $x_{[d]} \in \times_{k \in [d]} [m_k]$  applying basis calculus

$$\begin{aligned} \langle h(\Gamma)[Y_{[p]}], \beta^{\mathcal{S}} [Y_{[p]}, X_{[d]}], \nu [X_{[d]}] \rangle [X_{[d]} = x_{[d]} | \emptyset] &= h(\Gamma)[Y_{[p]} = \mathcal{S}(x_{[d]})] \cdot \nu [X_{[d]} = x_{[d]}] \\ &= g(\mathcal{S}(x_{[d]}), \Gamma) \cdot h(x_{[d]}) \\ &= \mathbb{P}^\theta [X_{[d]} = x_{[d]}]. \end{aligned}$$

We therefore find for any  $\mathbb{P}^\theta [X_{[d]}]$  a representation as a Computation-Activation Network in  $\Lambda^{\mathcal{S}, \text{MAX}, \nu}$  with the activation tensor  $h(\Gamma)[Y_{[p]}]$ .

To show the second claim, we are left to show that any set of Computation-Activation Networks in  $\Lambda^{\mathcal{S}, \text{MAX}, \nu}$  has  $\mathcal{S}$  as a sufficient statistic. Let us thus consider a parametric family

$$\{\mathbb{P}^\theta [X_{[d]}] : \theta \in \Gamma\} \subset \Lambda^{\mathcal{S}, \text{MAX}, \nu}.$$

By this inclusion we find for any  $\theta \in \Gamma$  an activation core  $\alpha^\theta [Y_{[p]}]$ . We then construct functions  $g$  and  $h$  by

$$g(y_{[p]}, \Gamma) = \alpha^\theta [Y_{[p]} = y_{[p]}] \quad \text{and} \quad h(x_{[d]}) = \nu [X_{[d]} = x_{[d]}]$$

and notice that the equivalent condition (1) to  $\mathcal{S}$  being a sufficient statistic is satisfied.  $\square$

### 3 Sufficient Statistic for the Probability

We here consider sufficient statistics for the parameter of a parametrized family, while in the report we considered sufficient statistics for the probability mass as a random variable. In both cases this results from the information theoretic viewpoint, that a function  $T$  of  $X$  is a sufficient statistic for a variable  $Z$ , if

$$(Z \perp X) | T(X).$$

While we choose for  $Z$   $Y_\theta$  above, we now choose for  $Z$  the variable  $Y_{\mathbb{P}}$ . This variable can be computed by contraction with

$$\beta^{\mathbb{P}} [Y_{\mathbb{P}}, X_{[d]}].$$

If  $T$  is a sufficient statistic for  $Y_{\mathbb{P}}$ , we call it probability sufficient for  $\mathbb{P}$ .

**Theorem 3** (Theorem 2.19 in the report). *If and only if a statistic  $\mathcal{S}$  is probability sufficient for  $\mathbb{P} [X_{[d]}]$ , then*

$$\mathbb{P} [X_{[d]}] \in \Lambda^{\mathcal{S}, \text{MAX}, \mathbb{I}}.$$

*Proof.* By Lem. 1 we have a function  $R$  such that for all  $x_{[d]} \in \times_{k \in [d]} [m_k]$

$$\mathbb{P} [X_{[d]} = x_{[d]}] = (R \circ \mathcal{S})(x_{[d]}).$$

By basis calculus it follows that

$$\mathbb{P} [X_{[d]}] = \langle R(I_{\mathcal{S}}[Y_{[p]}]), \beta^{\mathcal{S}} [Y_{[p]}, X_{[d]}] \rangle [X_{[d]}]$$

and thus

$$\mathbb{P} [X_{[d]}] \in \Lambda^{\mathcal{S}, \text{MAX}, \mathbb{I}}. \quad \square$$

Note that by this theorem we can restrict ourselves to the Computation-Activation Networks with trivial base measure for the characterization of distributions with a probability sufficient statistic.