Problem 9

from pylab import rcParams

In [2]: rcParams['figure.figsize'] = 20, 10

 $max_time = 4.0$

ax.axis('off')

fig = plt.figure(1)

prepare the axes limits #ax.set_xlim((-25, 25)) #ax.set_ylim((-35, 35)) #ax.set_zlim((5, 55))

 $X, y, z = X_y_z$

Solve for the trajectories

 $x, y, z = x_t[i,:,:].T$

plt.setp(lines, linewidth=2)

In [5]: def solve_lorenz2(sigma=10.0, beta=8./3, rho=28.0):

ax2 = plt.subplot(312, sharex=ax1) ax3 = plt.subplot(313, sharex=ax1)

x0 = -15 + 30 * np.random.random((N, 3))

t = np.linspace(0, max_time, int(250*max_time))

choose a different color for each trajectory colors = plt.cm.viridis(np.linspace(0, 1, N))

lines = ax.plot(x, y, z, '-', c=colors[i])

In [4]: w=interactive(solve_lorenz, sigma=10.0, beta=8./3, rho=(155.0,170.0))

"""Plot a solution to the Lorenz differential equations."""

def lorenz_deriv(x_y_z, t0, sigma=sigma, beta=beta, rho=rho): """Compute the time-derivative of a Lorenz system."""

return [sigma * (y - x), x * (rho - z) - y, x * y - beta * z]

Choose random starting points, uniformly distributed from -15 to 15

np.random.seed(1)

for i in range(N):

ax.view_init(30, angle)

angle = 104

plt.show()

return t, x_t

 $max_time = 4.0$

fig = plt.figure(1) ax1 = plt.subplot(311)

prepare the axes limits ax1.set_xlim((0, 1000)) #ax1.set_ylim((0, 1000)) ax2.set_xlim((0, 1000)) #ax2.set_ylim((0, 1000)) ax3.set_xlim((0, 1000)) #ax3.set_ylim((0, 1000))

 $x, y, z = x_y_z$

Solve for the trajectories

 $x, y, z = x_t[20,:,:].T$

ax1.set_ylabel('\$z\$')

ax2.set_ylabel('\$y\$')

ax3.set_ylabel('\$x\$') ax3.set_xlabel('\$n\$')

ax1.plot(z)

ax2.plot(y)

ax3.plot(x)

plt.show()

return t, x_t

Problem 2

import sympy as sm from sympy import solve

from sympy.abc import x, y, z

XdotZer = sm.Eq(Xdot, 0) YdotZer = sm.Eq(Ydot, 0) ZdotZer = sm.Eq(Zdot, 0)

In [8]: JM2 = sm.Matrix([Xdot, Ydot, Zdot]) JM3 = sm.Matrix([x, y, z])JacobianM = JM2.jacobian(JM3)

In [9]: JM = JacobianM.subs([(x, 0), (y, 0), (z, 0)])

+0.j

+0.j

+0.j

Out[11]: ((1+0j), (1+2.4494897427831783j), (1-2.4494897427831783j))

-0.45883147-0.j

0.6882472 -0.j

Eig[0][0], Eig[0][1], Eig[0][2]

In [16]: def solve_lorenz2(sigma=1, beta=1, rho=1):

prepare the axes limits ax1.set_xlim((0, 1000)) #ax1.set_ylim((0, 1000)) ax2.set_xlim((0, 1000)) #ax2.set_ylim((0, 1000)) ax3.set_xlim((0, 1000)) #ax3.set_ylim((0, 1000))

 $x, y, z = x_y_z$

Solve for the trajectories

 $x, y, z = x_t[20,:,:].T$

ax1.set_ylabel('\$z\$')

ax2.set_ylabel('\$y\$')

ax3.set_ylabel('\$x\$') ax3.set_xlabel('\$n\$')

In [17]: w=interactive(solve_lorenz2, sigma=1, beta=1, rho=1)

ax = fig.add_axes([0, 0, 1, 1], projection='3d')

def lorenz_deriv(x_y_z, t0, sigma=sigma, beta=beta, rho=rho):

Choose random starting points, uniformly distributed from -15 to 15

x_t = np.asarray([integrate.odeint(lorenz_deriv, x0i, t) for x0i in x0])

In [14]: def solve_lorenz(sigma=1, beta=1, rho=1):

 $max_time = 4.0$

ax.axis('off')

np.random.seed(1)

for i in range(N):

ax.view_init(30, angle)

angle = 104

plt.show()

return t, x_t

fig = plt.figure(1)

 $x, y, z = x_y_z$

Solve for the trajectories

 $x, y, z = x_t[i,:,:].T$

In [15]: w=interactive(solve_lorenz, sigma=1, beta=1, rho=1)

plt.setp(lines, linewidth=2)

return [x+2*z,y-3*z,2*y+z]

x0 = -15 + 30 * np.random.random((N, 3))

t = np.linspace(0, max_time, int(250*max_time))

choose a different color for each trajectory colors = plt.cm.viridis(np.linspace(0, 1, N))

lines = ax.plot(x, y, z, '-', c=colors[i])

N = 30

ax1.plot(z)

ax2.plot(y)

ax3.plot(x)

plt.show()

In []:

return t, x_t

np.random.seed(1)

return [x+2*z,y-3*z,2*y+z]

x0 = -15 + 30 * np.random.random((N, 3))

t = np.linspace(0, max_time, int(250*max_time))

x_t = np.asarray([integrate.odeint(lorenz_deriv, x0i, t) for x0i in x0])

Change 20 to any other to test different initial condition

ax2 = plt.subplot(312, sharex=ax1) ax3 = plt.subplot(313, sharex=ax1)

In [12]: rcParams['figure.figsize'] = 20, 10

fig = plt.figure(1) ax1 = plt.subplot(311)

 $max_time = 4.0$

N = 30

In [7]: import numpy as np

Xdot = x+2*zYdot = y-3*zZdot = 2*y+z

CriticalPoints

Out[7]: {x: 0, y: 0, z: 0}

JacobianM

In [10]: JM = np.float64(JM)

array([[1.

Out[10]: (array([1.+0.j

In [11]: # Eigenvalues are

Eig = np.linalg.eig(JM)

[0.

[0.

Out[8]:

Out[9]:

x0 = -15 + 30 * np.random.random((N, 3))

t = np.linspace(0, max_time, int(250*max_time))

In [6]: w=interactive(solve_lorenz2,sigma=10.0,beta=8./3,rho=(155.0,170.0))

CriticalPoints = sm.solve([XdotZer, YdotZer, ZdotZer], x, y, z)

, 1.+2.44948974j, 1.-2.44948974j]),

],

],

+0.56195149j]]))

, 0.

def lorenz_deriv(x_y_z, t0, sigma=sigma, beta=beta, rho=rho):

Choose random starting points, uniformly distributed from -15 to 15

interactive(children=(IntSlider(value=1, description='sigma', max=3, min=-1), IntSlider(value=1, description='...

interactive(children=(IntSlider(value=1, description='sigma', max=3, min=-1), IntSlider(value=1, description='...

, -0.45883147+0.j

, 0.6882472 +0.j

-0.56195149j,

x_t = np.asarray([integrate.odeint(lorenz_deriv, x0i, t) for x0i in x0])

np.random.seed(1)

N = 30

N = 30

In [3]: def solve_lorenz(sigma=10.0, beta=8./3, rho=28.0):

Note: you may need to restart the kernel to use updated packages.

"""Plot a solution to the Lorenz differential equations."""

def lorenz_deriv(x_y_z, t0, sigma=sigma, beta=beta, rho=rho): """Compute the time-derivative of a Lorenz system."""

return [-sigma * (x - y), rho * x - y - x * z, -beta*z+x*y]

Choose random starting points, uniformly distributed from -15 to 15

x_t = np.asarray([integrate.odeint(lorenz_deriv, x0i, t) for x0i in x0])

interactive(children=(FloatSlider(value=10.0, description='sigma', max=30.0, min=-10.0), FloatSlider(value=2.6...

interactive(children=(FloatSlider(value=10.0, description='sigma', max=30.0, min=-10.0), FloatSlider(value=2.6...

 $ax = fig.add_axes([0, 0, 1, 1], projection='3d')$

Plot some time series data for the Lorenz system (8.7) when $\sigma = 10$, b = 8/3 and $166 \le r \le 167$. When r = 166.2, the solution shows

```
In [1]: %pip install -q ipywidgets
import numpy as np
from matplotlib import pyplot as plt
from scipy import integrate
from ipywidgets import interactive, fixed
```

intermittent behavior, and there are occasional chaotic bursts in between what looks like periodic behavior.