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Take Home Exam #2

Problem 1

Below is the equation to be solved using methhod of multiple scales

$$\ddot{x} + rac{k_1}{m}x = g - \epsilon(rac{k_3}{m}x^3)$$

Since there is a constant forcing term the above expression will have to be shifted to the equilibrium position before method of multiple scales can be applied.

Equilibrium position position can be calculated by setting $\ddot{x}=0$ and solving for equilibrium points.

For this instance the shifing term will be denoted as ϕ such that $x_1=x+\phi$

Out[141]:
$$\ddot{x} - g + rac{k_1 x_1}{m} + rac{k_3 x_1^3}{m}$$

Out[142]:
$$\ddot{x}-g+rac{k_1\phi}{m}+rac{k_1x}{m}+rac{k_3\phi^3}{m}+rac{3k_3}{m}\phi^2x+rac{3k_3}{m}\phi x^2+rac{k_3x^3}{m}$$

In the above expression following terms sum to zero ($\frac{k_1\phi}{m}+\frac{k_3\phi^3}{m}-g$). This leaves the following equation that can be used for analysis

Out[143]:
$$\ddot{x} + rac{3k_3}{m}\phi x^2 + rac{k_3 x^3}{m} + x\left(rac{k_1}{m} + rac{3k_3}{m}\phi^2
ight)$$

To make the algebra easier to deal with the above equation will be simplified to the following form:

Out[144]:
$$Ex^2 + Fx^3 + Gx + \ddot{x}$$
 Non-linear parts multiplied by epsilon

Where
$$G=rac{k_1}{m}+rac{3k_3\phi^2}{m}$$
 , $E=rac{3k_3\phi}{m}$, and $F=rac{k_3}{m}$

Next define definitions for the differential operators $\frac{d}{dt}$ and $\frac{d^2}{dt^2}$

Out[145]:
$$D_1\epsilon + D_2\epsilon^2 + D_o$$

Out[146]:
$$2D_1D_o\epsilon + D_o^2 + \epsilon^2\left(D_1^2 + 2D_2D_o\right)$$

Next step is to define assumed solution for the system, which can be seen below:

Out[203]:
$$\epsilon x_1 + x_o$$

Next define the complete expression using definitions above

Out[208]:
$$G\left(\epsilon x_1+x_o\right)+\epsilon\left(E(\epsilon x_1+x_o)^2+F(\epsilon x_1+x_o)^3\right)\\ +\left(\epsilon x_1+x_o\right)\left(2D_1D_o\epsilon+D_o^2+\epsilon^2\left(D_1^2+2D_2D_o\right)\right)$$

$$\begin{array}{c} \mathsf{Out[209]:} & D_1^2 \epsilon^3 x_1 + D_1^2 \epsilon^2 x_o + 2 D_1 D_o \epsilon^2 x_1 + 2 D_1 D_o \epsilon x_o + 2 D_2 D_o \epsilon^3 x_1 \\ & + 2 D_2 D_o \epsilon^2 x_o + D_o^2 \epsilon x_1 + D_o^2 x_o + E \epsilon^3 x_1^2 + 2 E \epsilon^2 x_1 x_o + E \epsilon x_o^2 + F \epsilon^4 x_1^3 \\ & + 3 F \epsilon^3 x_1^2 x_o + 3 F \epsilon^2 x_1 x_o^2 + F \epsilon x_o^3 + G \epsilon x_1 + G x_o \end{array}$$

From the expression above extract terms associated with ϵ^0 , ϵ^1

Expanded version

Expression for x_o

Out[206]: $D_o^2x_o + Gx_o$

Expression for xo

Next define equation for x_1

Out[207]:
$$2D_1D_ox_o + D_o^2x_1 + Ex_o^2 + Fx_o^3 + Gx_1$$

Out[152]:
$$D_o^2 x_1 + G x_1$$

Out[153]:
$$2D_1D_ox_o + Ex_o^2 + Fx_o^3$$

$$D_o^2x_1+Gx_1$$
'='
 $-2D_1D_ox_o-Ex_o^2-Fx_o^3$
Expression for x1

For the first ODE $D_o^2x_o+Gx_o=0$ assume following solution

Out[155]:
$$A(T_1,T_2)e^{i\sqrt{G}T_o}+e^{-i\sqrt{G}T_o}\overline{A(T_1,T_2)}$$

Assumed solution satisfies the characteristic portion of the ODE

Out[156]: 0

Next substitute expression into x_1

$$\begin{array}{c} \text{Out[200]:} & -2D_1D_oA(T_1,T_2)e^{i\sqrt{G}T_o} - 2D_1D_oe^{-i\sqrt{G}T_o}\overline{A(T_1,T_2)} \\ & -EA^2(T_1,T_2)e^{2i\sqrt{G}T_o} - 2EA(T_1,T_2)\overline{A(T_1,T_2)} - Ee^{-2i\sqrt{G}T_o}\overline{A(T_1,T_2)}^2 \\ & -FA^3(T_1,T_2)e^{3i\sqrt{G}T_o} - 3FA^2(T_1,T_2)e^{i\sqrt{G}T_o}\overline{A(T_1,T_2)} \\ & -3FA(T_1,T_2)e^{-i\sqrt{G}T_o}\overline{A(T_1,T_2)}^2 - Fe^{-3i\sqrt{G}T_o}\overline{A(T_1,T_2)}^3 \end{array}$$

Keep only real part

From above exprssion two terms will drive the system at resonance, therefore we must ensure that they sum to zero.

extract resonant term

Out[159]:
$$-2D_1D_oA(T_1,T_2)e^{i\sqrt{G}T_o}-3FA^2(T_1,T_2)e^{i\sqrt{G}T_o}\overline{A(T_1,T_2)}$$

Define non-resonant terms for later use:

Out[160]:
$$-EA^2(T_1,T_2)e^{2i\sqrt{G}T_o}-EA(T_1,T_2)\overline{A(T_1,T_2)}-FA^3(T_1,T_2)e^{3i\sqrt{G}T_o}$$

Assume A is of the form $rac{1}{2} lpha e^{i eta}$ and substitute into right hand side of equation for x_1

Out[161]:
$$rac{1}{2}lpha(T_1)e^{ieta(T_1)}$$

 $ar{A}$ definition

Out[162]:
$$rac{1}{2}lpha(T_1)e^{-ieta(T_1)}$$

Substitute assumed solution into the right hand side of equation for x_1

$${\sf Out[163]:} \quad -D_1 D_o \alpha(T_1) e^{i\beta(T_1)} e^{i\sqrt{G}T_o} - \frac{3F}{8} \alpha^3(T_1) e^{i\beta(T_1)} e^{i\sqrt{G}T_o}$$

Next get the derivatives per the expression above, there is only one.

To perform the differentiation, need to extract the values that need to be differentiated.

Term for $D_o D_1$ differentiation:

Out[164]:
$$-lpha(T_1)e^{ieta(T_1)}e^{i\sqrt{G}T_o}$$

Next perform differentiation with respect to $D_{o}D_{1}$ term

Out[165]:
$$\sqrt{G}\left(lpha(T_1)rac{d}{dT_1}eta(T_1)-irac{d}{dT_1}lpha(T_1)
ight)e^{i\left(\sqrt{G}T_o+eta(T_1)
ight)}$$

Extract constant term:
See next page

Out[166]:
$$-rac{3F}{8}lpha^3(T_1)e^{ieta(T_1)}e^{i\sqrt{G}T_o}$$

Constant term from the resonant expression

Combine all terms together to get differentiated expression

$$\mathsf{Out[197]:} \ \left(-\frac{3F}{8} \alpha^3(T_1) + \sqrt{G} \alpha(T_1) \frac{d}{dT_1} \beta(T_1) - i \sqrt{G} \frac{d}{dT_1} \alpha(T_1) \right) e^{i \left(\sqrt{G} T_o + \beta(T_1) \right)}$$

Extract real and imaginary parts needed to solve for α and β .

Out[198]:
$$-rac{3F}{8}lpha^3(T_1)+\sqrt{G}lpha(T_1)rac{d}{dT_1}eta(T_1)$$
 Real

Out[169]:
$$-\sqrt{G} \frac{d}{dT_1} \alpha(T_1)$$
 Imaginary

From the imaginary part lpha is a constant $lpha=lpha_c$

Next solve for β :

Out[170]:
$$\left[\frac{3F}{8\sqrt{G}} \alpha^2(T_1) \right]$$

Out[171]:
$$\frac{3F\alpha^2}{8\sqrt{G}}$$

Next solve for β by integrating

Out[172]:
$$3FT_1\alpha^2\over 8\sqrt{G}$$
 Solution for Beta

Next plug in the solution for A into the expression for x_1 .

First start by defining the solution for A and $ar{A}$

Out[173]:
$$\frac{\alpha}{2}e^{\frac{3iFT_1}{8\sqrt{G}}\alpha^2}$$

Out[174]:
$$\frac{\alpha}{2}e^{-\frac{3iFT_1}{8\sqrt{G}}\alpha^2}$$

Above solution for A checks out since the secular term in expression for x_1 sums to zero as seen below.

In short:
$$-2D_1D_oA(T_1,T_2)e^{i\sqrt{G}T_o}-3FA^2(T_1,T_2)e^{i\sqrt{G}T_o}\overline{A(T_1,T_2)}=0$$

Out[175]: 0

Since solution for A above will make the secular terms sum to zero, expression for x_1 on the right hand side will become the following (i.e. non-resonant terms):

$$-EA^2(T_1,T_2)e^{2i\sqrt{G}T_o}-EA(T_1,T_2)\overline{A(T_1,T_2)}-FA^3(T_1,T_2)e^{3i\sqrt{G}T_o}$$

$$\mathsf{Out[176]:} \quad -\frac{E\alpha^2}{4}e^{2i\sqrt{G}T_o}e^{\frac{3iFT_1}{4\sqrt{G}}\alpha^2} - \frac{E\alpha^2}{4} - \frac{F\alpha^3}{8}e^{3i\sqrt{G}T_o}e^{\frac{9iFT_1}{8\sqrt{G}}\alpha^2}$$

After substituting for A and Abar

Extract 3 terms above for simplicity:

Out[177]:
$$-rac{Flpha^3}{8}e^{rac{3i}{8\sqrt{G}}\left(3FT_1lpha^2+8GT_o
ight)}$$

Out[178]:
$$-rac{Elpha^2}{4}e^{rac{i}{4\sqrt{G}}\left(3FT_1lpha^2+8GT_o
ight)}$$

Out[179]:
$$-\frac{E\alpha^2}{4}$$

Since expression for x_1 is a linear ODE the particular solution can be solved in 3 parts.

- Part 1, particular solution for: $-\frac{F lpha^3}{8} e^{rac{3i}{8\sqrt{G}} \left(3FT_1 lpha^2 + 8GT_o
 ight)}$
- Part 2, particular solution for: $-\frac{E\alpha^2}{4}e^{\frac{i}{4\sqrt{G}}\left(3FT_1\alpha^2+8GT_o\right)}$
- Part 3, particular solution for: $-\frac{E\alpha^2}{4}$

For part 1 the solution becomes:

Out[180]:
$$rac{Flpha^3}{64G}e^{rac{3i}{8\sqrt{G}}\left(3FT_1lpha^2+8GT_o
ight)}$$

Check

Out[181]:
$$-rac{Flpha^3}{8}e^{rac{3i}{8\sqrt{G}}\left(3FT_1lpha^2+8GT_o
ight)}$$

For part 2 solution becomes:

Out[182]:
$$\frac{E lpha^2}{12G} e^{\frac{i}{4\sqrt{G}} \left(3FT_1lpha^2 + 8GT_o\right)}$$

Check

Out[183]:
$$-\frac{E\alpha^2}{4}e^{\frac{i}{4\sqrt{G}}\left(3FT_1\alpha^2+8GT_o\right)}$$

For part 3 solution becomes:

Out[184]:
$$-\frac{E\alpha^2}{4G}$$

Check

Out[185]:
$$-\frac{E\alpha^2}{4}$$

Complete solution for x_1 becomes, keeping only real terms:

$$\begin{array}{ll} {\tt Out[186]:} & \frac{E\alpha^2}{12G} e^{\frac{i}{4\sqrt{G}} \left(3FT_1\alpha^2 + 8GT_o\right)} - \frac{E\alpha^2}{4G} + \frac{F\alpha^3}{64G} e^{\frac{3i}{8\sqrt{G}} \left(3FT_1\alpha^2 + 8GT_o\right)} \end{array}$$

Solution for x_1 satisfies the condition on the right hand side as seen below

$$\mathsf{Out[187]:} \quad -\frac{E\alpha^2}{4}e^{2i\sqrt{G}T_o}e^{\frac{3iFT_1}{4\sqrt{G}}\alpha^2} - \frac{E\alpha^2}{4} - \frac{F\alpha^3}{8}e^{3i\sqrt{G}T_o}e^{\frac{9iFT_1}{8\sqrt{G}}\alpha^2}$$

Finally x_1 expressed in complete form takes the following expression:

Out[194]:
$$\frac{E\alpha^2}{6G}\cos\left(\frac{1}{4\sqrt{G}}\left(3FT_1\alpha^2+8GT_o\right)\right)-\frac{E\alpha^2}{2G} \\ +\frac{F\alpha^3}{32G}\cos\left(\frac{1}{8\sqrt{G}}\left(9FT_1\alpha^2+24GT_o\right)\right)$$

In similar form x_o is expressed as:

Out[195]:
$$lpha\cos\left(rac{1}{8\sqrt{G}}\left(3FT_1lpha^2+8GT_o
ight)
ight)$$

Finally $x(t,\epsilon)=x_o+\epsilon x_1$ can be expressed as:

Out[196]:
$$\epsilon \left(\frac{E\alpha^2}{6G} \cos \left(\frac{1}{4\sqrt{G}} \left(3FT_1\alpha^2 + 8GT_o \right) \right) - \frac{E\alpha^2}{2G} + \frac{F\alpha^3}{32G} \cos \left(\frac{1}{8\sqrt{G}} \left(9FT_1\alpha^2 + 24GT_o \right) \right) \right) + \alpha \cos \left(\frac{1}{8\sqrt{G}} \left(3FT_1\alpha^2 + 8GT_o \right) \right)$$

Where E, F, and G are the following:

$$E = \frac{3k_3\phi}{m}$$

$$F = \frac{k_3}{m}$$

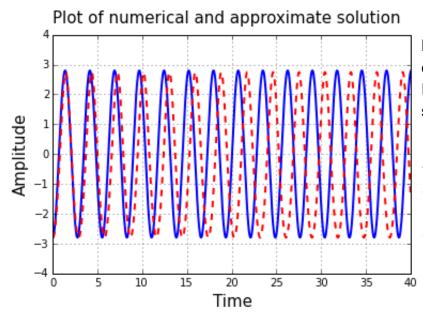
•
$$F=\frac{k_3''}{k_3}$$

$$\bullet \ \ G = \frac{k_1}{m} + \frac{3k_3\phi^2}{m}$$

The above solution shall now be compared to the numerical solution. For simplicity only the first term will be ploted for the comparison. Numerical solution will be shifted by half amplitude to oscilate about 0.

Value for ϕ is the fixed point of the original expression with following values m=1 , $k_1=2$, $k_3=0.1$, and g=9.81

With above values the fixed point value is $\phi=3.22$



Blue = 1st term of solution Red dotted = numerical solution

The amplitudes match well, but the frequency has a slight shift. This will probably improve if second term is also 40 included.

Problem 2)

$$\dot{x} = x^3 + \delta x^2 - \mu x$$

Find fixed points:

Out[56]:
$$\left[0, -rac{\delta}{2}-rac{1}{2}\sqrt{\delta^2+4\mu}, -rac{\delta}{2}+rac{1}{2}\sqrt{\delta^2+4\mu}
ight]$$

Next linearize the system to determine system behavior at fixed points:

Out[57]:
$$2\delta x - \mu + 3x^2$$

Following the result from the linearization above the expression becomes $\dot{y}=(2\delta x-\mu+3x^2)y$, so $\lambda=2\delta x-\mu+3x^2$.

At the trivial point x=0 , λ becomes:

Out[58]:
$$-\mu$$

For x=0 when $\mu \leq 0$ system is unstable and becomes stable when $\mu \geq 0$.

At
$$x=-rac{\delta}{2}-rac{1}{2}\sqrt{\delta^2+4\mu}$$
, λ becomes: \longleftarrow See next page

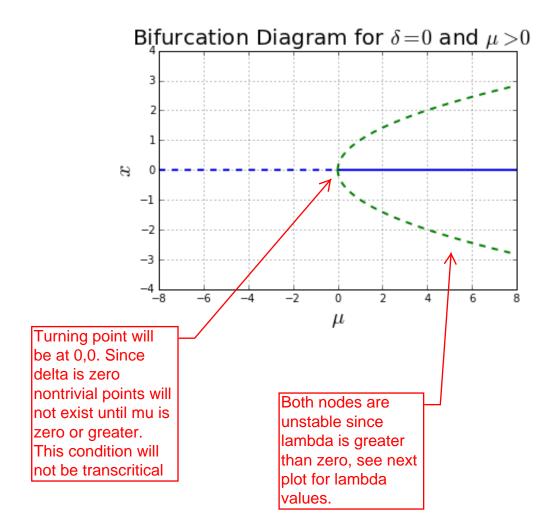
Out[59]:
$$rac{\delta^2}{2}+rac{\delta}{2}\sqrt{\delta^2+4\mu}+2\mu$$

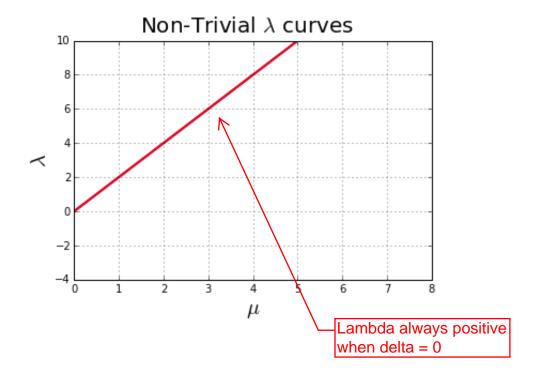
At
$$x=-rac{\delta}{2}+rac{1}{2}\sqrt{\delta^2+4\mu}$$
 , λ becomes:

Out[60]:
$$rac{\delta^2}{2} - rac{\delta}{2} \sqrt{\delta^2 + 4\mu} + 2\mu$$

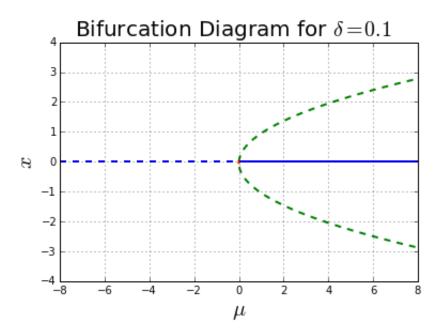
Plot bifurcation diagram for various values of δ :

For $\delta=0$



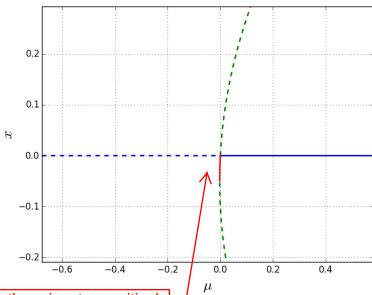


For $\delta=0.1$



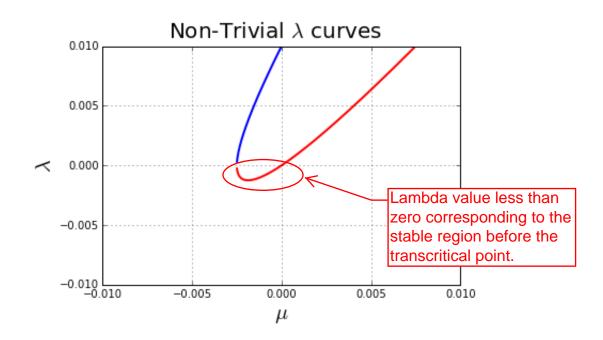
Plot zooming on to $\mu=0$ for $\delta=0.1$



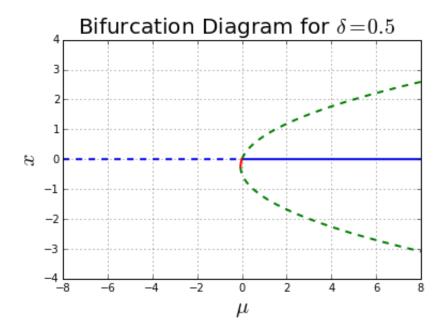


For delta = 0.1 there is a transcritical bifurcation where trivial and non-trivial solutions change from stable to unstable.

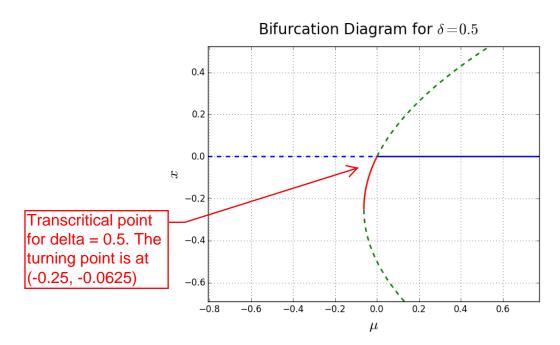
It can also be seen in the zoomed in figure that turning point occurs at approximately (-0.05, -0.0025)

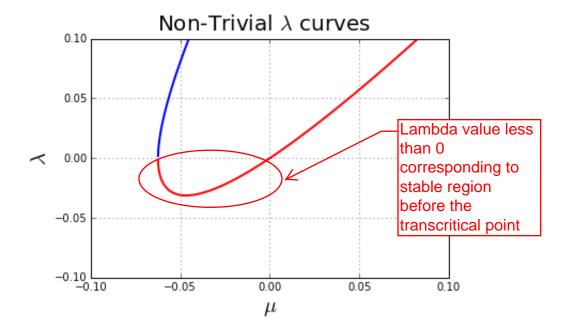




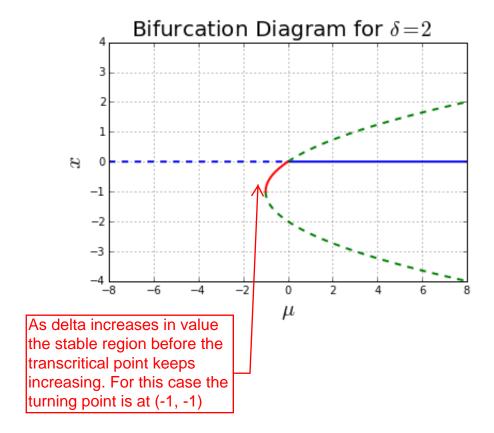


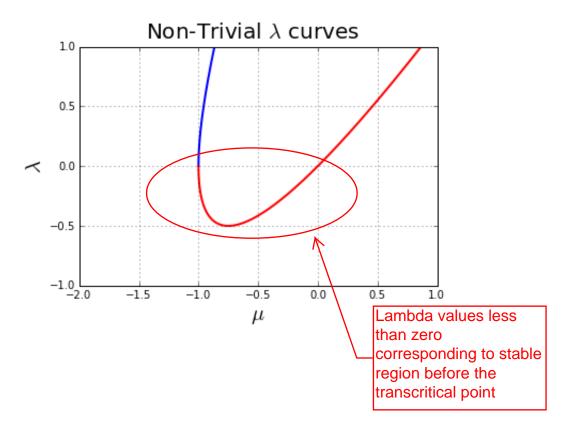
Plot zooming on to $\mu=0$ for $\delta=0.5$



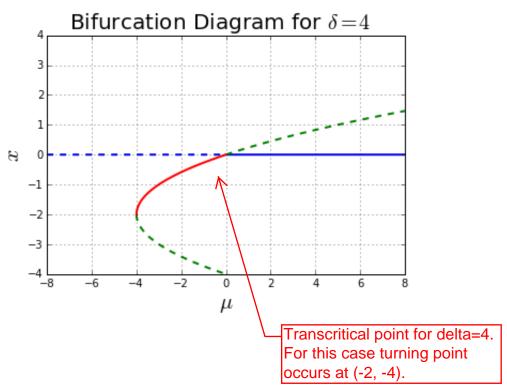


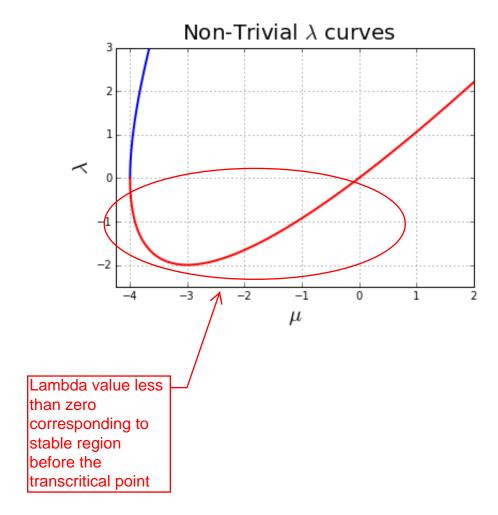
For $\delta=2$





For $\delta=4$





TO SEE CODE FOR ALL THE OUTPUTS PLEASE REFER TO THE IPYTHON NOTEBOOK FILE SUPPLIED IN THE HW FOLDER