

Velocity analysis

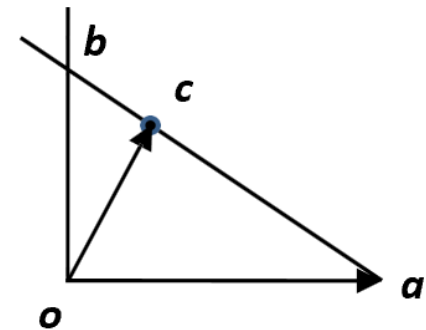
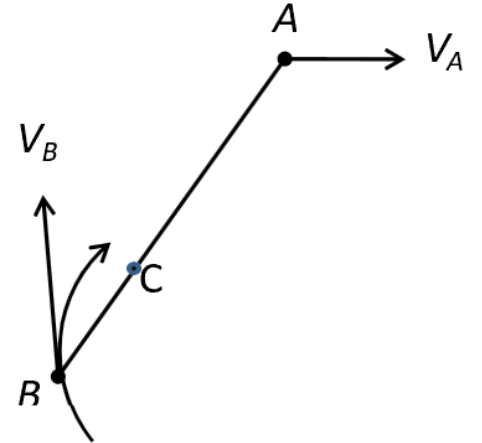
Velocity Vector Diagram – VVD

Relative velocity method

Velocity of any point on a link

- Consider a link AB where the directions of motion of its ends are shown.
- The velocity vectors are.
 - oa – velocity of the end A
 - ob – velocity of the end B
 - ab – velocity of B with respect to A

$$v_{ba} = v_b - v_a$$



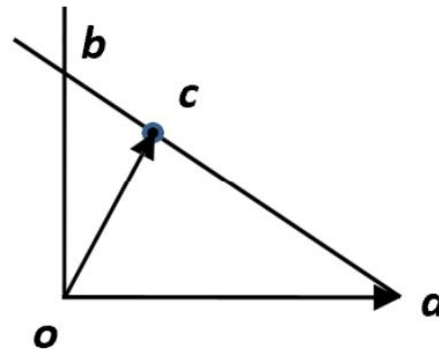
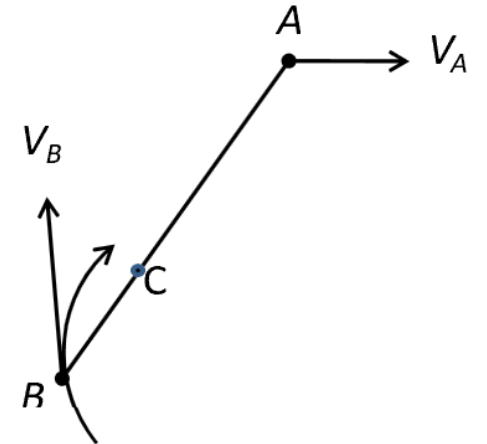
- Velocity of any point C on the link can be determined by dividing the vector \mathbf{ab} at \mathbf{c} such that

$$\frac{ab}{AB} = \frac{ac}{AC}$$

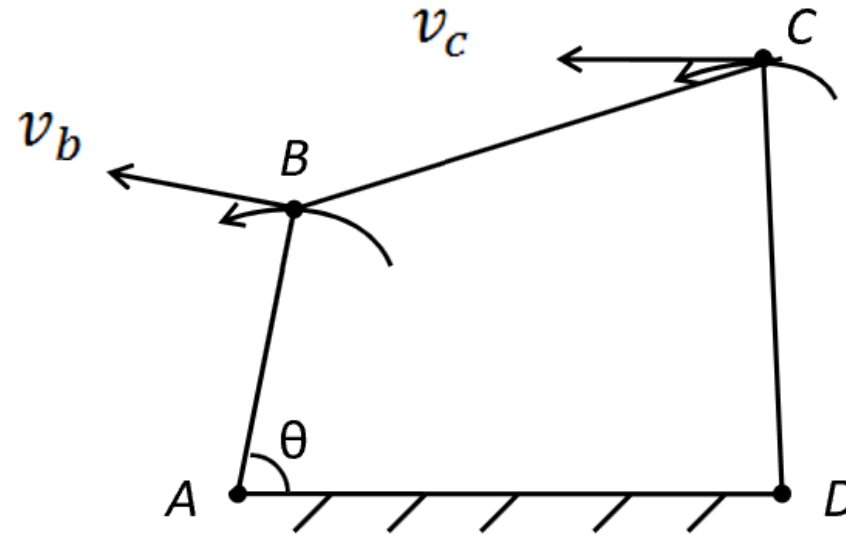
- Then, the velocity of C with respect to A

$$\mathbf{v}_{ca} = \mathbf{v}_c - \mathbf{v}_a$$

- Hence, the vector \mathbf{oc} represents the velocity of point C .



Velocity diagram for four bar chain



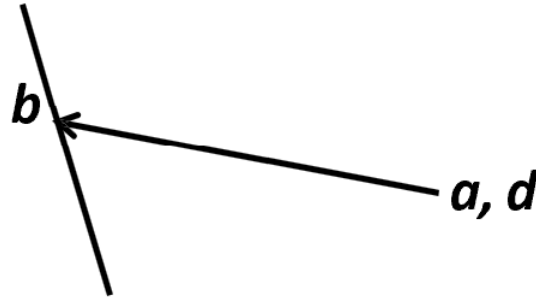
Given the dimensions of all the links, angular velocity of crank AB and position of the crank.

Draw the velocity vector diagram.

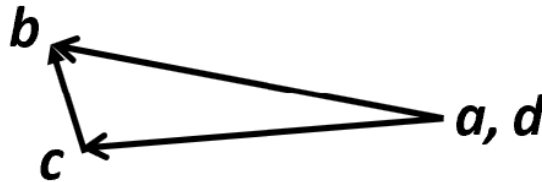
1. Draw a vector ***ab*** perpendicular to link *AB* of length $AB \times \omega$ (to a suitable scale).



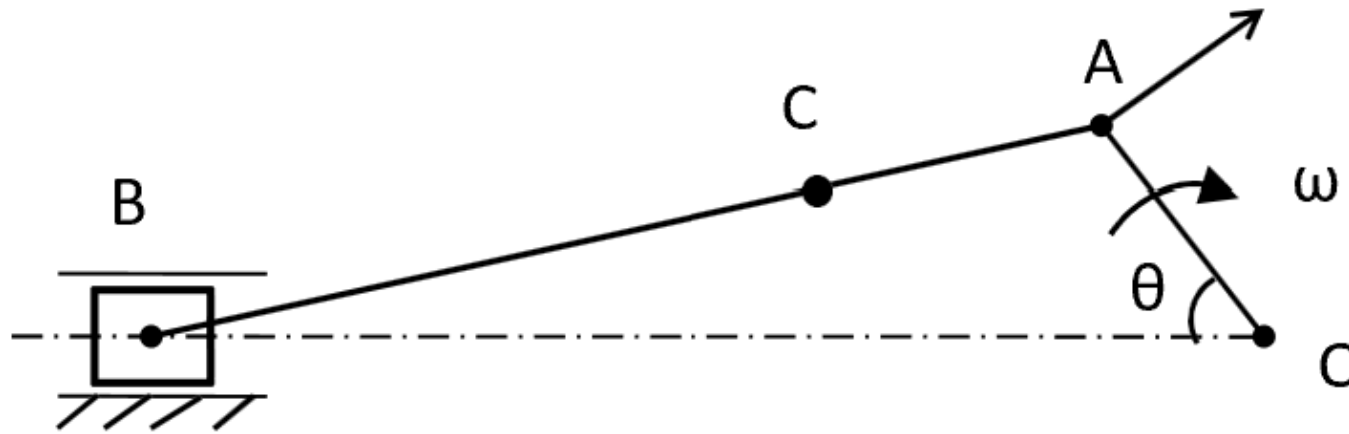
2. Draw a vector line through ***b*** in direction **perpendicular to the link *BC***.



3. Draw a vector through ***d*** in a direction perpendicular to the link ***CD***. This will intersect the vector ***bc*** in ***c***.



Slider crank chain



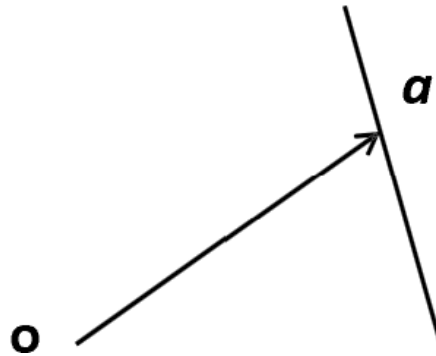
Given the dimensions of all the links, angular velocity of the crank OA and position of the crank.

- i. Draw VVD.
- ii. Find the velocity of point C on link AB.

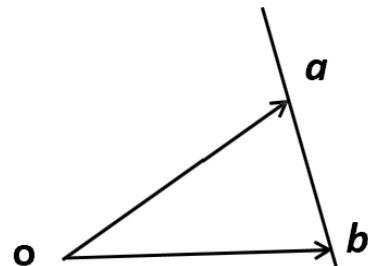
1. Draw a vector ***oa*** of length $OA \times \omega$ (taking a suitable scale) in a direction perpendicular to OA .



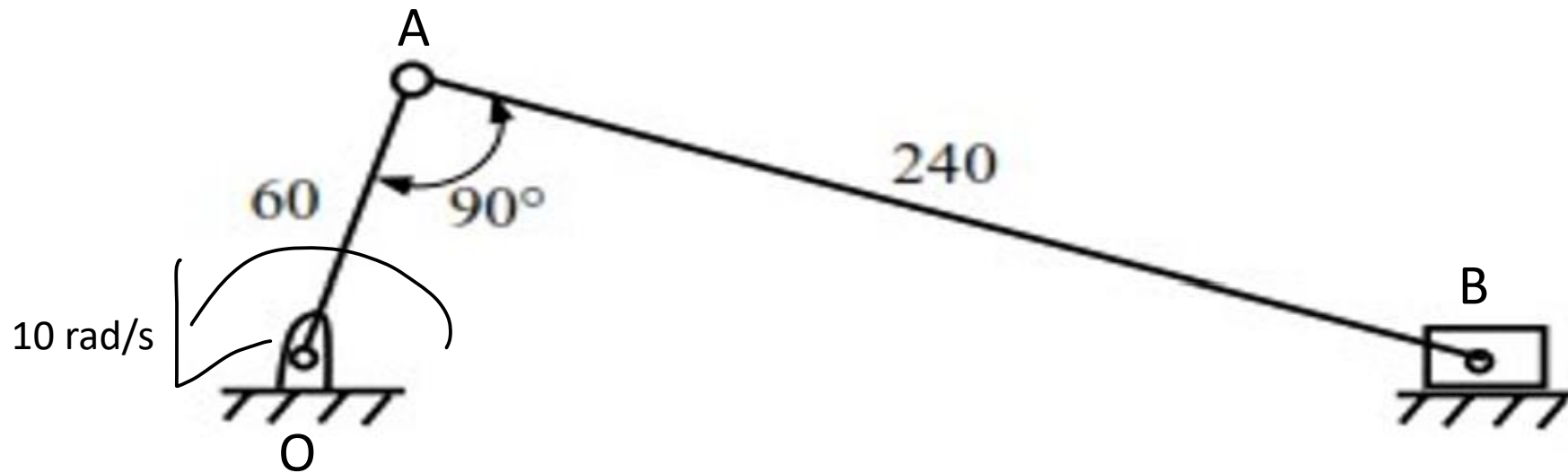
2. Draw a vector line through ***a*** in a direction perpendicular to the link ***AB***. (draw some length on either side of ***a***.)



3. Draw the vector ***ob*** parallel to OB to intersect the vector ***ab*** at ***b***.



A slider-crank mechanism with crank radius, OA 60 mm and connecting rod, AB length 240 mm is shown in figure. The crank is rotating with a uniform angular speed of 10 rad/s in counter clockwise direction. For the given configuration, find the velocity of the slider.

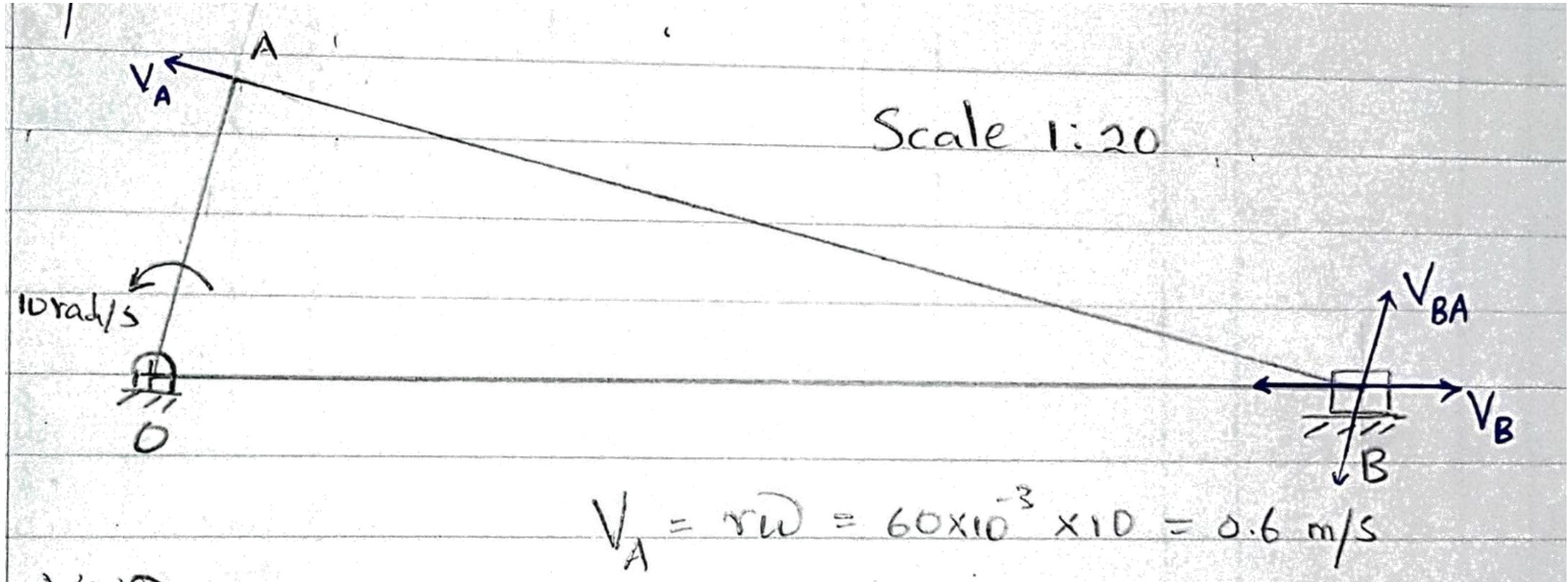


Scale

Space diagram 1:20

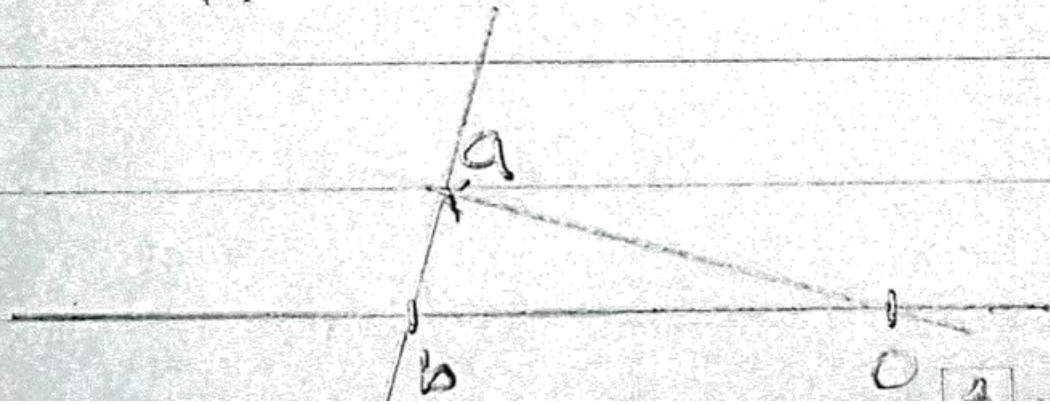
VVD 1cm : 0.2 m/s

Space diagram



VVD

Scale 1cm : 0.2 m/s



$$ob = 3.1 \text{ cm}$$
$$V_B = \overleftarrow{0.62 \text{ m/s}}$$

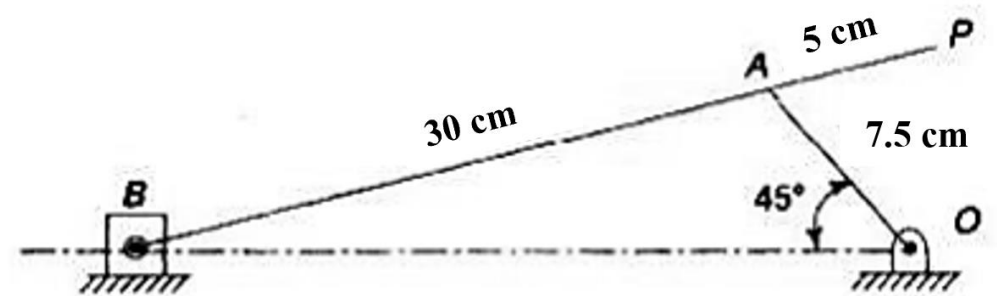
In the slider crank mechanism, the crank OA rotates with a uniform velocity of 600 rev/min in clockwise direction. For the given configuration;

- i. draw space diagram, velocity vector diagram and determine;
- ii. velocity of the slider B
- iii. velocity of point P located on the extended connecting rod

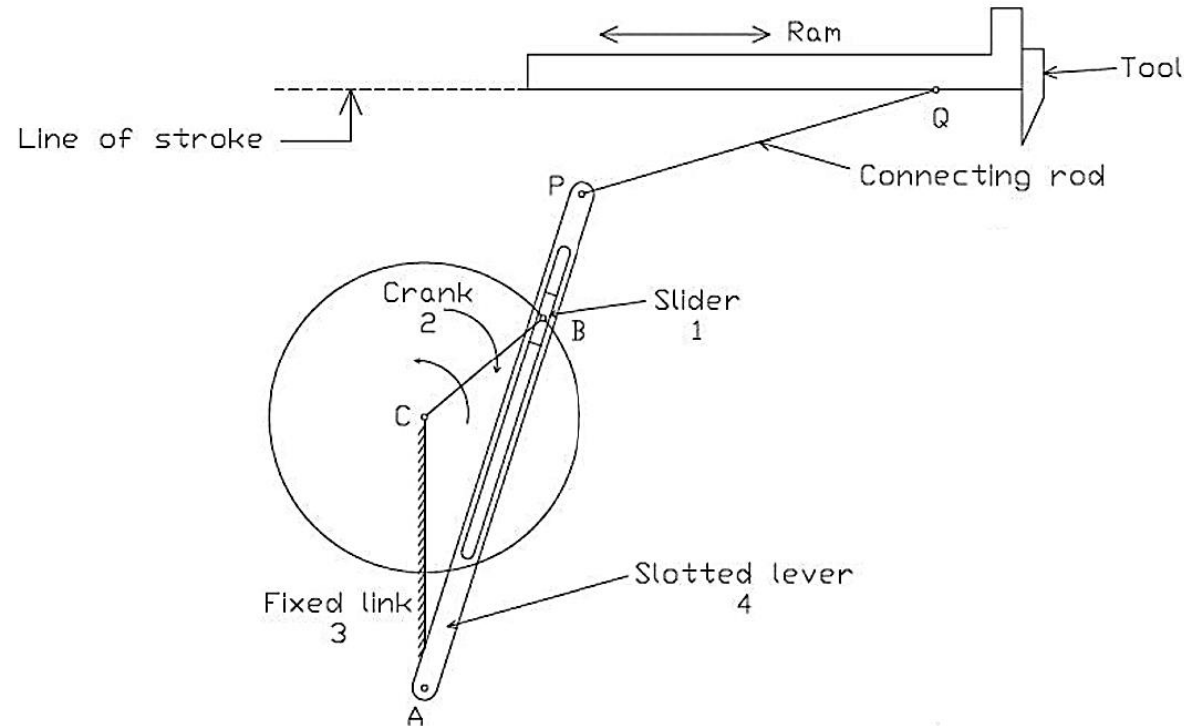
Scale

Space diagram 1 cm = 5 cm

Velocity vector diagram 1 cm = 1 m/s

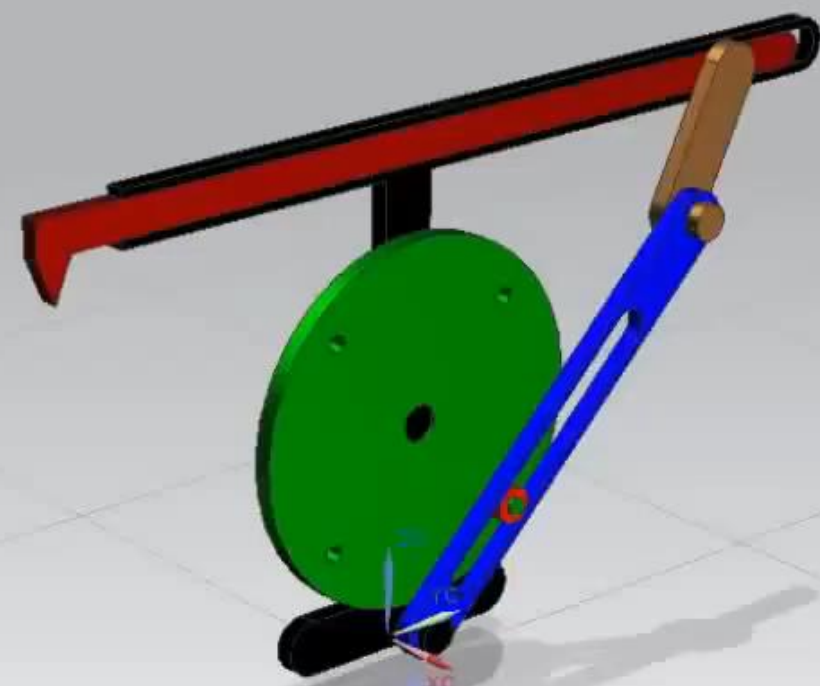


Crank-slotted lever mechanism



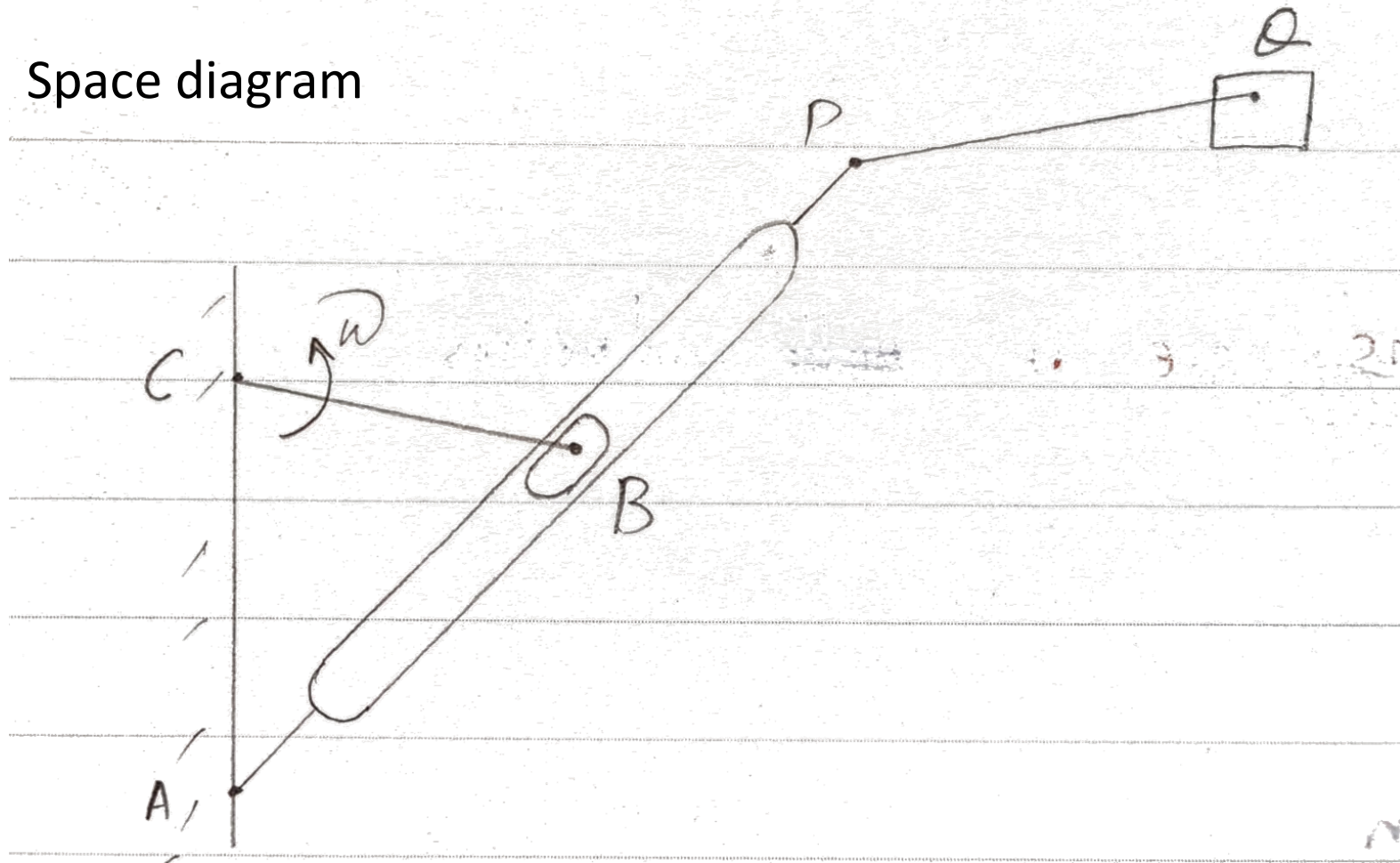
Given the crank CB rotates with uniform angular velocity ω about C in anti-clock wise direction and dimensions of all the links.

Time 0.00000
Step 0

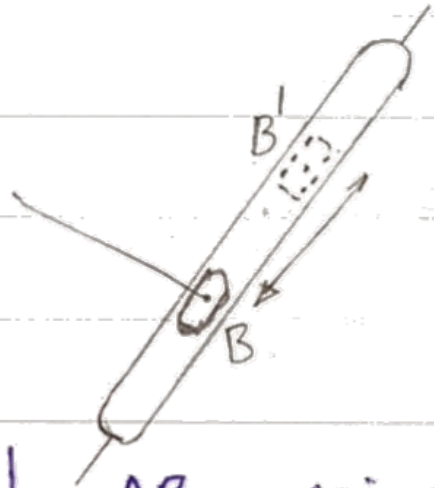


How Crank and Slotted lever Quick Return Motion mechanism works

Space diagram



Slider B motion in slotted link.

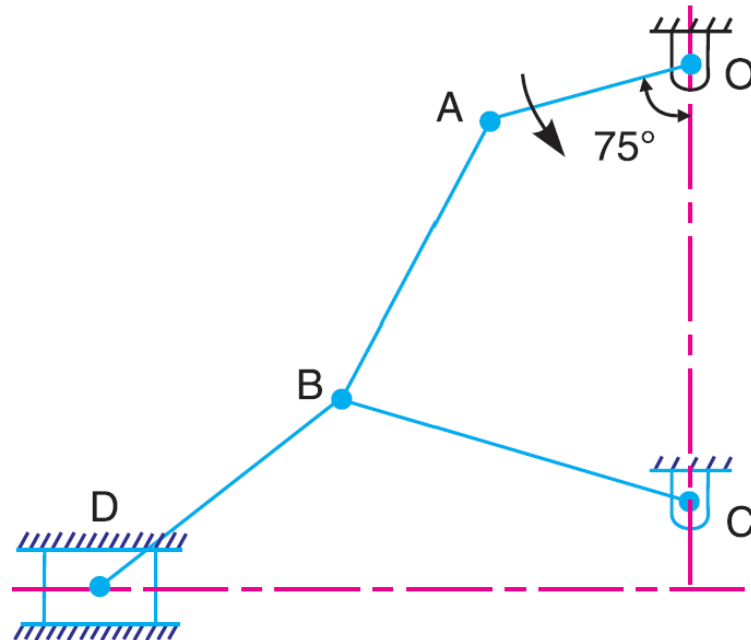


B' is on link AP coinciding with B .

BB' gives the linear motion of slider B inside the slot.

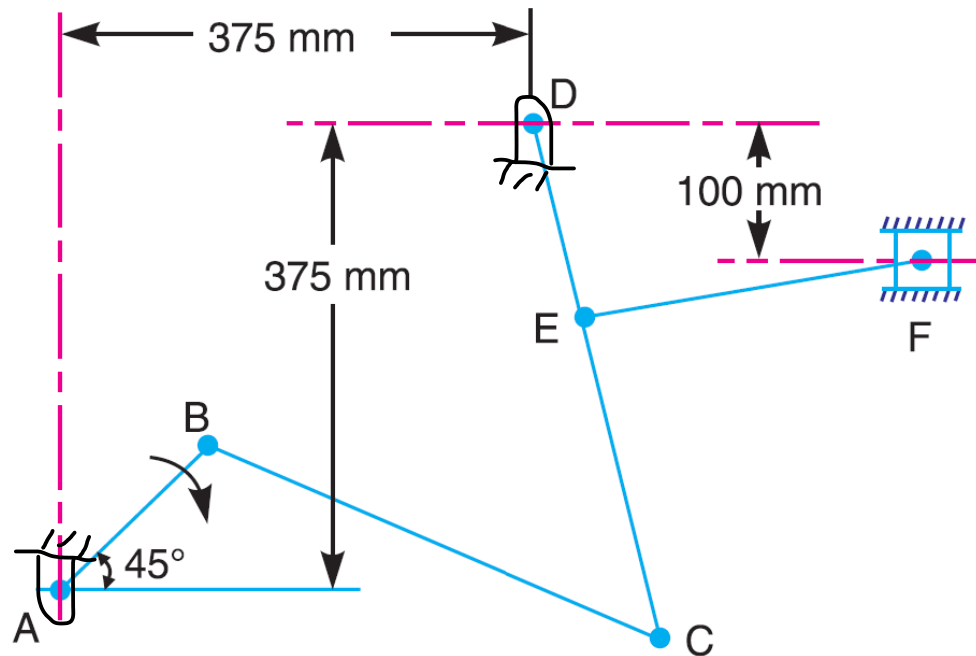
The angular velocity of the crank OA is 600 rev/min . Determine the linear velocity of the slider D and the angular velocity of the link BD , when the crank is inclined at an angle of 75° to the vertical.

The dimensions of various links are : $OA = 28 \text{ mm}$; $AB = 44 \text{ mm}$; $BC = 49 \text{ mm}$; and $BD = 46 \text{ mm}$. The centre distance between the centres of rotation O and C is 65 mm . The path of travel of the slider is 11 mm below the fixed point C . The slider moves along a horizontal path and OC is vertical.



The crank AB makes an angle of 45° with the horizontal and rotates about A in the clockwise direction at a uniform speed of 120 rev/min. The lever DC oscillates about the fixed point D , which is connected to AB by the coupler BC . The block F moves in the horizontal guides, being driven by the link EF . Determine: **1. velocity of the block F , 2. angular velocity of DC**

$AB = DE = 150 \text{ mm}$; $BC = CD = 450 \text{ mm}$; $EF = 375 \text{ mm}$.



The crank OA is 100 mm long and rotates clockwise about O at 120 rev/min. The connecting rod AB is 400 mm long.

At a point C on AB , 150 mm from A , the rod CE 350 mm long is attached. This rod CE slides in a slot in a trunnion at D . The end E is connected by a link EF , 300 mm long to the horizontally moving slider F .

For the mechanism in the position shown, find **1. velocity of F** , **2. velocity of sliding of CE in the trunnion**, and **3. angular velocity of CE** .

