

lec c)

Introduction to Numerical analysis

Course contents

① The Error analysis

② Finding roots

③ System of linear
equations

④ Decomposition methods

⑤ Interpolation

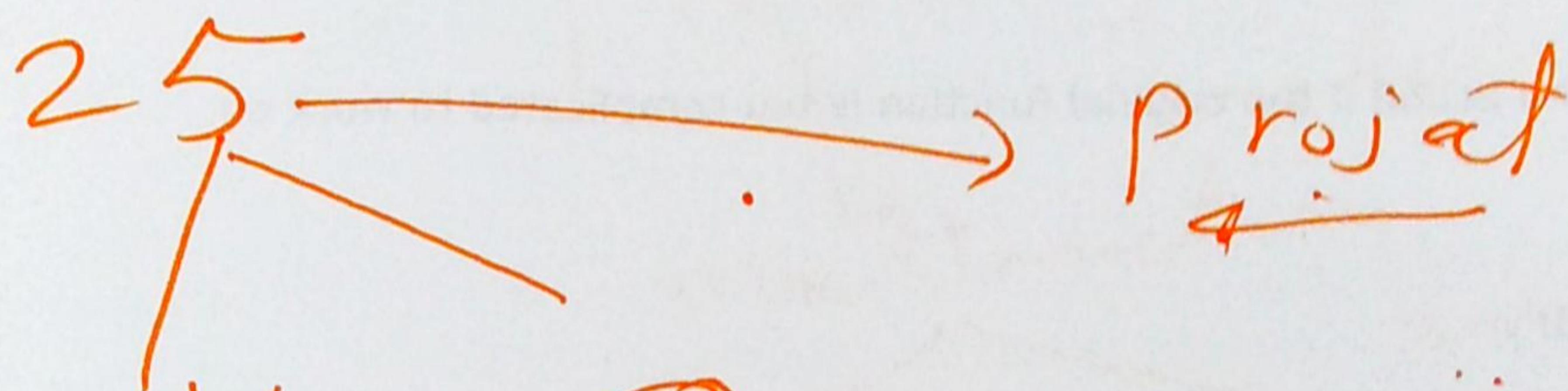
⑥ Numerical Integration

⑦ Numerical Differentiation

⑧ Non linear systems
of equations

② Grades

75 . Final Exam



mid term ⑮
+ Assignment ⑯

←
Reference

① Numerical Techniques
J.S. Chitode

② Numerical Technique
for computer
science.

③ Introduction to
numerical analysis
using Matlab.

③

What is numerical
~~and~~ analysis

Problems

model

mathematical

solutions

exact
solution

$$2x + 3 = 9$$

$$2x = 9 - 3$$

$$2x = 6$$

$$\boxed{\therefore x = 3}$$

Approximate
solution

$$2x + \cancel{3} \sin x$$

$$\int e^{x^2} dx$$

$$3e^x = e^x + c$$

Numerical techniques is
used methematics to find
an approximate solution to
complex problems or problems
that ~~most~~ have exact
solution.

E

①

- Since we have an approximate solution, it means we have error

$$\text{error} = \text{True value} - \text{Approximate value}$$

True (exact)

Ex $\frac{10}{6} = 1.6666\ldots$

→ Solution: $\frac{10}{6} = 1.67$
 $= 1.6667$
 $= 2$

Significant digits

Definitions: Significant digits
the numbers that are those
can be used with ~~confidence~~,
confidence.

(5)

significant digits

Total

decimals
(after)

$$\pi = 3. \underline{141592}65358979 \dots$$

Approximate to 5 total digits

$$3. \underline{14159}$$

5 total digits

- Approximate 5 digits

$$3. \underline{14159}$$

5 digits

Accuracy vs precision

Accuracy is defined as
the closeness of calculated
value to the true value

6

Exact value

5.3168

Approximate
value

5.2917

less
accu

5.3018

more
accu

5.3152

most
accu.

Precision :- ~~n~~ means repetitive
ness of the value

True value

5.3168

5.2917 less
5.2918 accu
5.2919 and
high
precise

5.3146 more
accu

5.3168 accu

5.3149 high
prec

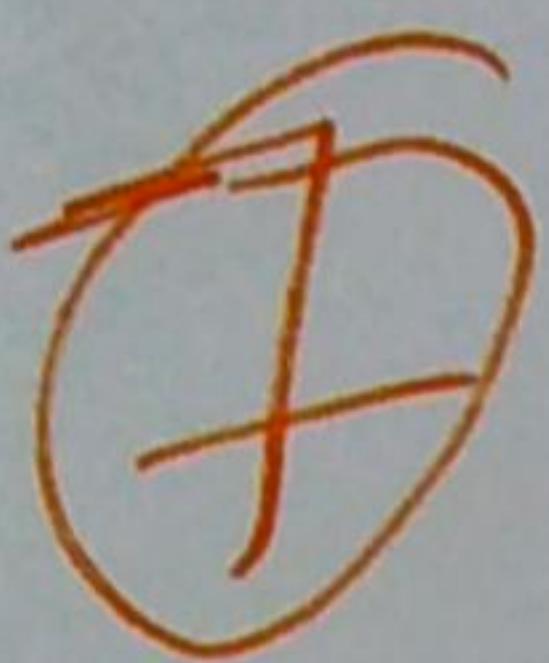
~~5.3189~~
~~5.3185~~

~~5.3111~~

~~4.7118~~

~~4.7119~~

~~4.8111~~



Types of Errors

In general we have two types of errors

(1) Truncation error

(2) Rounding error

Truncation error are generated when only required significant are considered and remaining discarded.

$$\frac{10}{6} = 1.6666\overline{6} \text{ (7)}$$

$$\pi = 3.\overbrace{1415}^{6666} \dots 265$$

Truncate to 4 terms

$$3.1415$$

Truncation in general used in series. ex, $\cos x$, $\sin x$

(8)

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

Rounding Errors

Rounding errors take place
rounding last digits to
nearest value.

nearest 6.

$\frac{10}{6} = 1.666\overline{6}$.

To 4 digits

Round off

1.6667

3.141592

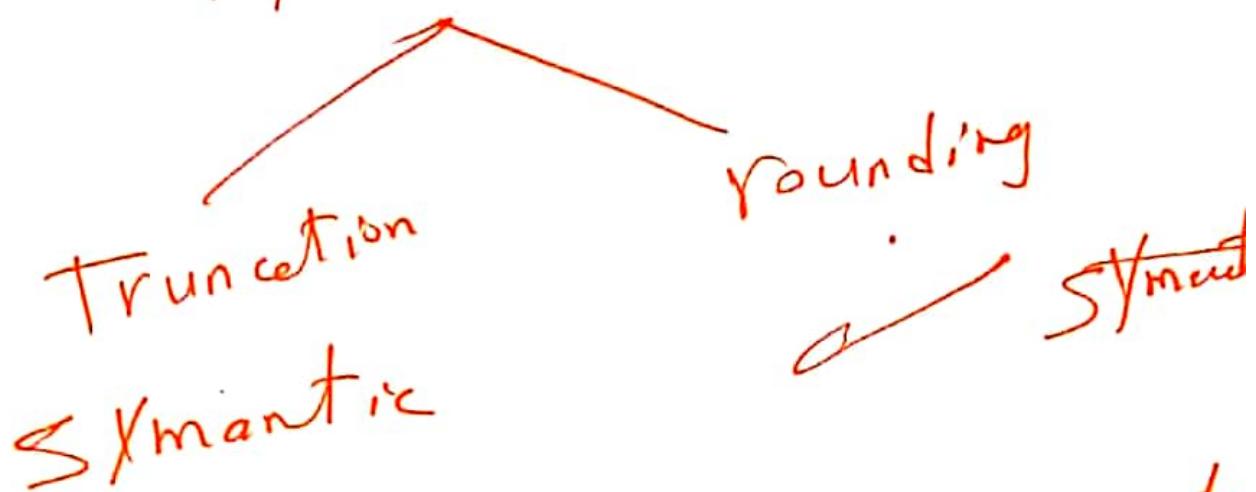
Round to 3 digits

3.142

①

Lec (2)

Types of error



$$\text{Error} = \frac{\text{True value} - \text{Approximate value}}{\text{True value}} \in (\epsilon \text{, } -\epsilon)$$

we call ϵ (epsilon)

$$\text{Absolute Error} = |\text{True} - \text{Approximate}|$$

absolute error

Relative Error =

$$RE = \left| \frac{\text{True} - \text{Approximate}}{\text{True}} \right|$$

$$\text{Percentage RE} = RE \times 100$$

Example

Calculate absolute error and relative error for the following cases and convert

$$\textcircled{1} \quad \text{True value} = 1 \times 10^{-6}$$

$$\text{Approximate value} = 0.5 \times 10^{-6}$$

$$\textcircled{2} \quad \text{True Value} = 1 \times 10^{-6}$$

$$\text{Approximate Value} = 0.99 \times 10^{-6}$$

Sol:

$$\text{Absolute error} = |1 \times 10^{-6} - 0.5 \times 10^{-6}|$$

$$= 0.5 \times 10^{-6}$$

$$RE = \frac{|1 \times 10^{-6} - 0.5 \times 10^{-6}|}{1 \times 10^{-6}}$$

$$\begin{aligned} 0.001 &= 1 \times 10^{-3} \\ 1000 &= 1 \times 10^3 \\ 0.10 &= 1 \times 10^{-1} \\ 0. & \end{aligned}$$

$$\textcircled{2} \quad \text{absolute error} = |1 \times 10^{-6} - 0.99 \times 10^{-6}|$$

$$RE = \frac{|1 \times 10^{-6} - 0.99 \times 10^{-6}|}{1 \times 10^{-6}}$$

$$= 0.01$$

③

How to calculate error
when True is not known.

Absent error = $\frac{\text{current approximation} - \text{previous approximation}}{\text{previous approximation}}$

Relative error = $\frac{\text{current} - \text{previous}}{\text{current}}$

Truncation error in series approximation

Taylor Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

We can write any function
as a polynomial series using
Taylor Series

$$\textcircled{4} \quad x \sim c$$

$$f(x) = f(c) + \frac{f'(c)(x-c)}{1!} + \frac{f''(c)(x-c)^2}{2!} + \frac{f'''(c)(x-c)^3}{3!} + \dots$$

If $c=0$ (Maclaurin series)

$$f(x) = f(0) + \frac{f'(0)x}{1!} + \frac{f''(0)x^2}{2!} + \dots$$

~~using~~ Example
series to expand e^x
use Maclaurin

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

$$f(x) = e^x$$

$$f'(x) = e^x$$

$$e^x$$

5

Example : Calculate e^x up to
five first term and
estimate truncation error
at $x = 1$.

Sol: Using calculator

$\approx e^1 = 2.7182818$ True

$\therefore e^x = \left(1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} \right)$

Using first five terms

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!}$$

$$x = 1 = 1 + 1 + \frac{1^2}{2!} + \frac{1^3}{3!} + \frac{1^4}{4!}$$

$$= 1 + 1 + \frac{1}{2} + \frac{1}{6} + \frac{1}{24}$$

$$\approx 2.7083333$$

Approximate

$$⑥ \text{ Absolute error} = \underline{2.7182818} - \underline{2.708333} \\ = \underline{\underline{0.0099485}}$$

Ex:- Find the value of e^x

using expansion

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

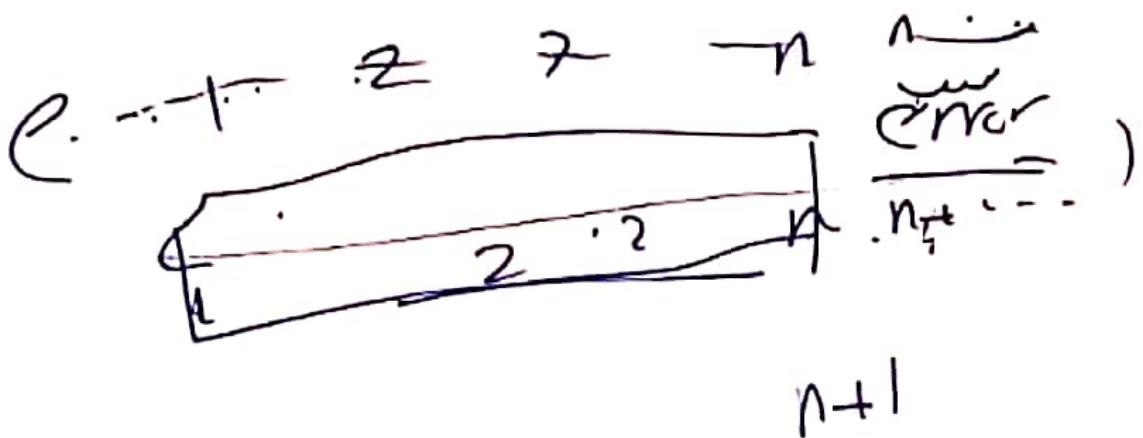
for $x = 0.5$ with absolute error less than $\underline{\underline{0.005}}$

$e^{0.5}$
~~error is given~~
 Since upper bound is 0.005 , we want to determine number of terms to satisfy condition of error.

$$e^x = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^n}{n!}$$

n th term is $\frac{x^n}{n!}$

6)



$$c^{\text{error}} = \frac{x^{n+1}}{(n+1)!}$$

$$\frac{x^{n+1}}{(n+1)!} < 0.005$$

$$\log(x^{n+1}) - \log(n+1)! < \log(0.005)$$
$$(n+1)\log x - \log(n+1)! < -2.30103$$

$\log(x^a) = a\log x$
 $\log(\frac{x}{y}) = \log x - \log y$

$$\log(n+1)! < \frac{(n+1)\log(x)}{2.30103}$$

$$\begin{aligned} x &= 6.5 \\ \cancel{n+1} &= 2 \\ \cancel{-\log(3)!} &= -3\log(0.5) & 2.30103 \\ &= 2.5843312 & 2.3 \end{aligned}$$

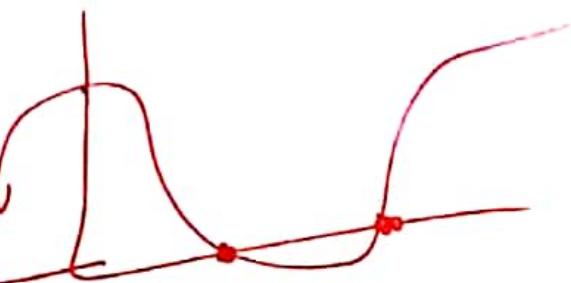
④ Roots of equation

$$\cancel{f(x) = 5}$$

$$f(x) = 0$$

root

$$3x + 6 = 0 \quad x = [-2]$$



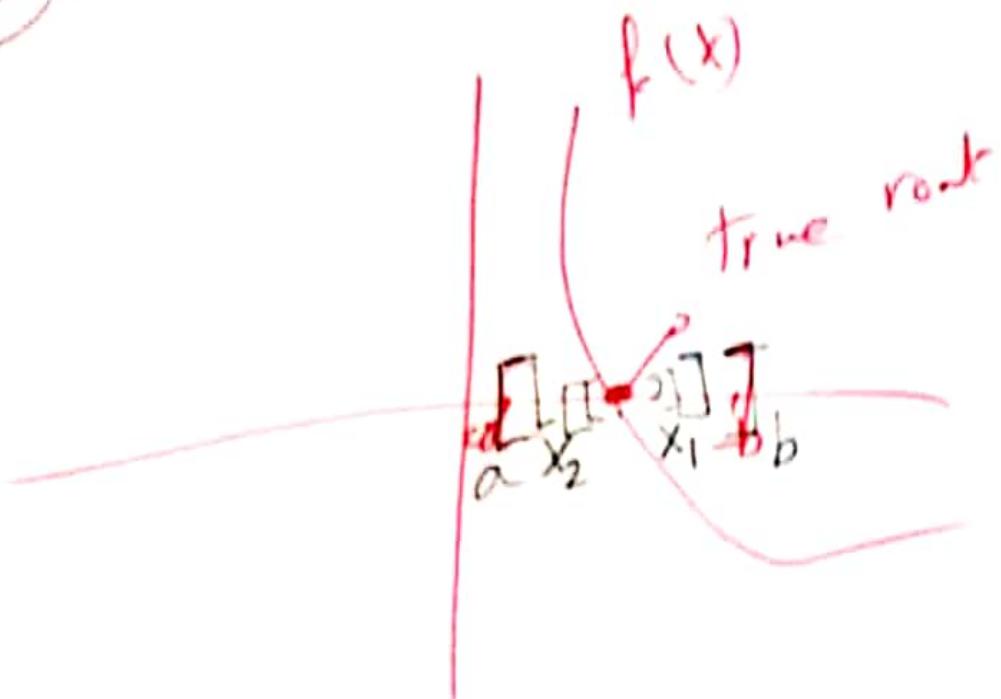
$$f(x) = x^2 + 3x + 2 \rightarrow \text{can find an exact solution}$$

$$f(x) = x^2 + 3x + 2 + e^{2x}$$

$$f(x) = x^{10} + 2x^7 + 3x + 2$$

transcendental function

⑦



In general we have two common methods for finding roots
bracketing open

- There are two initial ticks	at least one point
- are always convergent	can be divergent (gone time)
- More iterations	- less iterations
	Newton, Secant

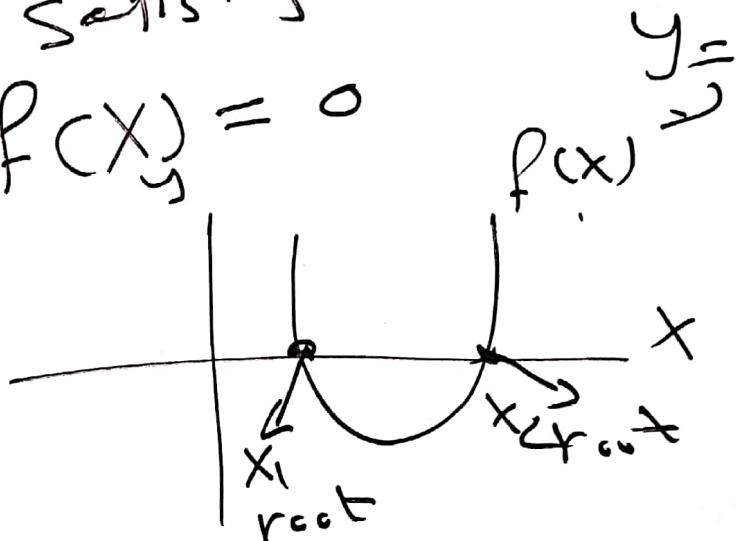
Q)

Lec (3)

Roots of equation

The root is the value of x that satisfy $f(x) = 0$

$f(x)$ intersects x -axis.



~~already~~ we know algebraic polynomial of degree one, two, three if cur can be solved analytically

$$\rightarrow f(x) = x + 2 \quad \text{Find root}$$
$$f(x) = 0$$
$$x + 2 = 0 \Rightarrow x = -2$$

$$\rightarrow f(x) = x^2 + 5x + 6$$
$$(x+2)(x+3) = 0$$
$$x_1 = -2$$
$$x_2 = -3$$

Ex Find the roots of
 $x^7 + x^5 + 3x^4 + 2x^2 + 1 = 0$

In this cases we can't find algebraic solution.

Numeric methods to find an approximate solution

$$f(x) = 0$$

→ Find solution $f(x) = 0$

$$f(x) = x^3 - \cos x + 3$$

$$\ln x - \sin 3x + x = 0$$

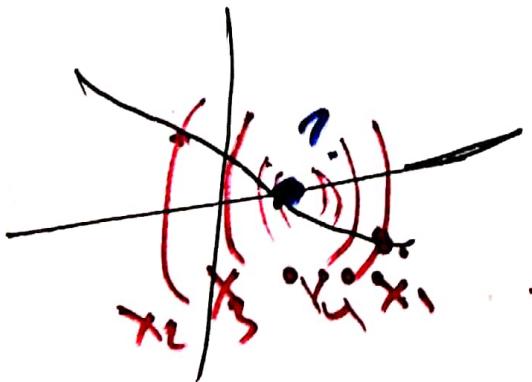
$$f'(x) =$$

→ different ~~and~~ numerical method can be used to find root for higher polynomial ~~and~~ transcendental function.

③

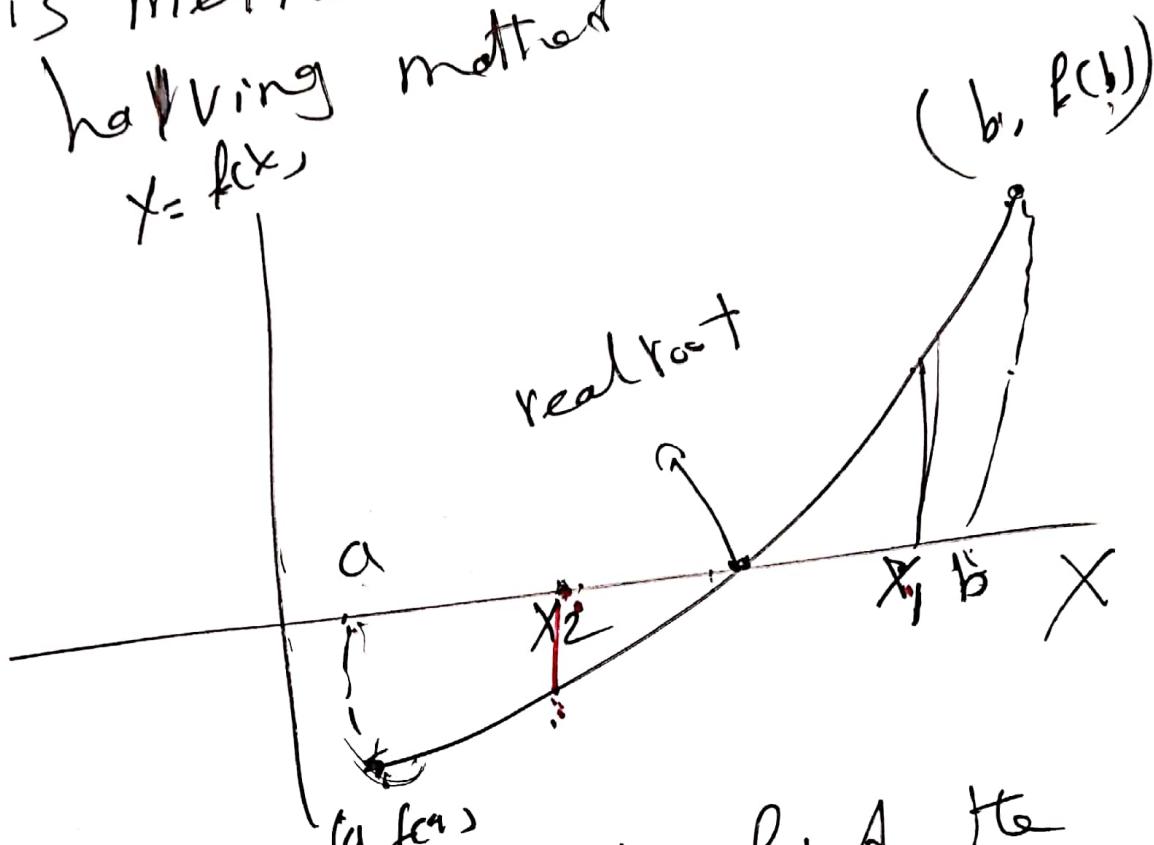
→ Types of methods to obtain root.

Bracketing	Open methods
- Two initial values to start	one or more intervals
- always convergent	sometimes can be divergent
- Need more number of iterations.	- less number of iterations.
Ex:-	<ul style="list-style-type: none"> - Bisection method - Secant method - Fixed Point - regular false



(4) Bisection method

This method is called interval halving method



Suppose we want to find the solution of $f(x) = 0$, $f(x)$ is continuous in $[a, b]$

→ let $f(a)$ - ve $f(b)$ + ve

$$f(a) \cdot f(b) < 0$$

$$x_1 = \frac{a+b}{2} \rightarrow f(x_1) +ve$$

$$E: X_2 = \frac{X_1 + d}{2}$$

$f(x) = 0$? Yes \curvearrowleft root
No \rightarrow continue

$$f(x_2) = v^2$$

$$x_3 = \frac{x_1 + x_2}{2}$$

Stop

~~when~~ when $x_n - x_{n-1} < \epsilon$

$$\epsilon = 0^{\circ} \text{ } \underline{\underline{0.00}} \text{ } /$$

OR $f(x_n) \approx 0$

6

Find a root for the following polynomial using bisection method and error = $\frac{0-0}{0-0}$

$$f(x) = x^3 - x - 2$$

using $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$
 $\begin{pmatrix} a \\ b \end{pmatrix}$

Solution

Let $a = 1$ and $b = 2$

$$f(a) = f(1) = 1^3 - 1 - 2 = -2$$

$$= +1 - 2 = -2$$

-ve

$$f(b) = f(2) = 2^3 - 2 - 2 = +4$$

+ve

$$f(a) \cdot f(b) = f(1) \cdot f(2) = -8 < 0$$

we have root $\underline{\text{root}}$

→ first iteration (iteration ~~root~~)

$$x_1 = \frac{a+b}{2} = \frac{1+2}{2} = \frac{3}{2} = \boxed{1.5}$$

$$- f(x_1) = (1.5)^3 - (1.5) - 2 = -0.125$$

-ve

(7)

Second iteration

$$\cancel{x_1} = 1.5 \quad b = 2$$

$$x_2 = \frac{1.5+2}{2} = 1.75$$

$$f(1.75) = (1.75)^3 - 1.75 - 2$$

$$= 1.609375$$

$$\epsilon = |\cancel{x_2} - x_1| = |1.75 - 1.5|$$

$$= 0.25$$

third iteration

$$x_3 = \frac{x_1 + x_2}{2} = \frac{1.5 + 1.75}{2}$$

$$= 1.625$$

$$f(x_3) = f(1.625)$$

$$= (1.625)^3 - (1.625) - 2$$

$$= 0.6660156$$

$$\epsilon = |x_3 - x_2| = |1.625 - 1.75|$$

$$= 0.125$$

⑧ Fourth iteration $(1.5, 1.625)$
 $X_4 = \frac{1.5 + 1.625}{2}$

$$= 1.5625$$

$$f(1.5625) = 0.2521973$$

$$\epsilon = |X_4 - X_3| = |1.5625 - 1.5625|$$

$$= 0.000000$$

→ Fifth iteration $(1.5, 1.5625)$

$$X_5 = \frac{1.5 + 1.5625}{2} = 1.53125$$

$$f(1.53125) = 0.059113$$

$$\epsilon = |X_5 - X_4|$$

$$= |1.53125 - 1.5625|$$

$$= 0.03125$$

$$X_6 = 1.515625$$

①

Lec 14

Newtons method

- Newton Raphson method

- How to find a root?

- Suppose x_0 be an approximate root of $f(x) = 0$.

- Let actual value of root $\approx x_0 + \boxed{x_1}$ is given as.

$$x_1 = x_0 + h.$$

①

x_1 is true root

$$f(x_1) = 0 \quad f(x_1) = 0$$

$$f(x_1) = 0$$

$$f(x_0 + h) = 0$$

∴ We can use Taylor Series to expand $f(x_0 + h)$

$$f(x_1) = \overbrace{f(x_0) + h f'(x_0)}^{\text{1st}} + \frac{h^2}{2!} \cancel{f''(x_0) + \frac{h^3}{3!} \cancel{f'''(x_0)}} \approx 0$$

as h is very small, we can neglect all the terms above

$$\text{2nd} \quad \therefore f(x_1) = \underbrace{f(x_0) + h f'(x_0)}_{\text{approx}} - f(x_0)$$

$$h f'(x_0) = -f(x_0)$$

$$h = \frac{-f(x_0)}{f'(x_0)}$$

$$\text{In } ① \quad x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

x_1 approximate x_2 true value

$$x_2 = x_1 + h$$

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

③ we can generate the rule
to find root

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

~~Important Notes~~

- (1) $f'(x_0)$ should not equal zero
- (2) $f'(x)$ exist
- (3) For better convergence in Newton method select x_0 such that $f(x_0)$, $f''(x_0)$ is positive. $f''(x_0) > 0$

Example

Find the root
 $f(x) = x^3 - 5x + 3 = 0$
using Newton method using
4 iterations

$$④ x_0 = ?$$

$$f(x) = x^3 - 5x + 3$$

$$f'(x) = 3x^2 - 5$$

$$f''(x) = 6x$$

We want to find Inflection value

$$x_0 ??$$

$$x=0$$

$$f(0) = 3$$

$$f(1) = -1$$

we have root (0, 1)

$$f''(0) = 0, \quad f''(1) = 6$$

$$f(x_0), f''(x_0) > 0$$

b. 1st x_0 , ~~doesn't~~ doesn't satisfy
the condition.

(5)

$$[0_1^1]$$

$$[0_3^1]$$

$$f(0.3) = \frac{(0.3)^3 - 5(0.3) + 3}{= 1.527}$$

∴

$$[0_3^1]$$

$$f''(0.3) = 6(0.3) = 1.8$$

$$f'(0.3) = f''(0.3)$$

$$(1.527) (1.8) > 0$$

$x_0 = 0.3$

general rule

$$x_{n+1} = x_n - \frac{f(x)}{f'(x)}$$

Iteration 1

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

$$= 0.3 - \frac{1.527}{(-4.73)}$$

$x_1 = 0.622833$

⑥

Iteration 2

$$X_2 = X_1 - \frac{f(X_1)}{F'(X_1)}$$

$$= 0.622833 - \frac{f(0.622833)}{F'(0.622833)}$$

$$= 0.622833 - \frac{0.127445}{(-3.83623)} \\ (-3.83623)$$

$$X_2 = 0.656054$$

Iteration 3

$$X_3 = X_2 - \frac{f(X_2)}{F'(X_2)}$$

$$= 0.656054 - \frac{0.002099}{(-3.708778)}$$

$$X_3 = 0.656620$$

Iteration 4 $X_4 = X_3 - \frac{f(X_3)}{F'(X_3)} \quad 0.000 \}$

$$= 0.656620 - \frac{0.000001}{-3.706549}$$

$$= 0.65662043$$

(A)

$$X_3 = \underline{0.65662^{\circ}}$$

$$X_4 = \underline{0.65662^{\circ}43}$$

The root 0.65662°

$$\boxed{X_{n+1} = X_n - \frac{P(X_n)}{P'(X_n)}}$$

- Secant method
- Fixed point iterations

Numerical differentiationIntroduction

* differentiation gives a measure of the rate at which a quantity changes (Rate of change)

* differentiation is important in science, engineering and physics

* velocity, is the derivative of the position with respect to time

$$\frac{\Delta \text{مسافة}}{\Delta \text{زمن}} = \text{سرعة}$$

* acceleration is the derivative of the velocity with respect to time

$$\frac{\Delta \text{سرعة}}{\Delta \text{زمن}} = \text{الجود}$$

* many models in physics & engineering are expressed in terms of rates

* differentiation is also used for finding the maximum & minimum values of a function.

The need for numerical differentiation .

- the function to be differentiated may be given in a table form (set of discrete points) ; in this case the analytical method can't be used , so we have to use numerical differentiation .

- numerical differentiation also plays an important role in some of the numerical methods used for solving differential equations.

P.2

Approaches to numerical differentiation depend on whether

points are equally spaced

Finite difference approximation of derivative at point x_i :

2 points

Forward;
backward;
central

3 points

forward
backward

points are not equally spaced

Lagrange polynomials

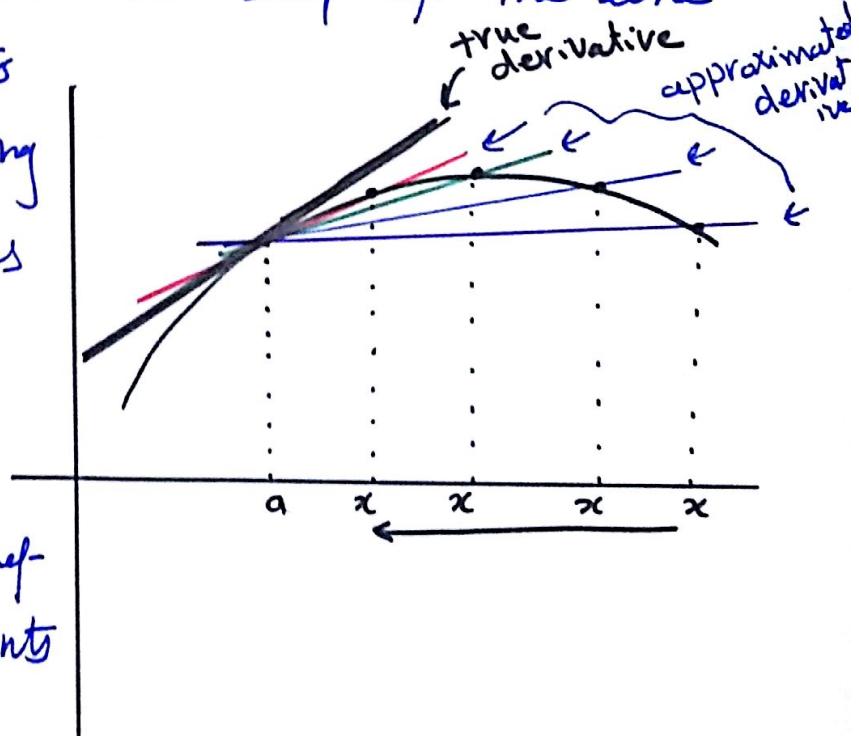
3 formulas for 1st derivative at 3 points

difference formulas

- * Finite difference approximation for the derivative at a point x_i is an approximate calculation based on the value of points in the neighborhood of x_i
- * the accuracy of a finite difference approximation depends on the accuracy of the data points ; the spacing between the points & the formula used for approximating the derivative
- * the simplest formula approximates the derivative as the slope of line that connects 2 adjacent points.

Finite difference approximation of the derivative

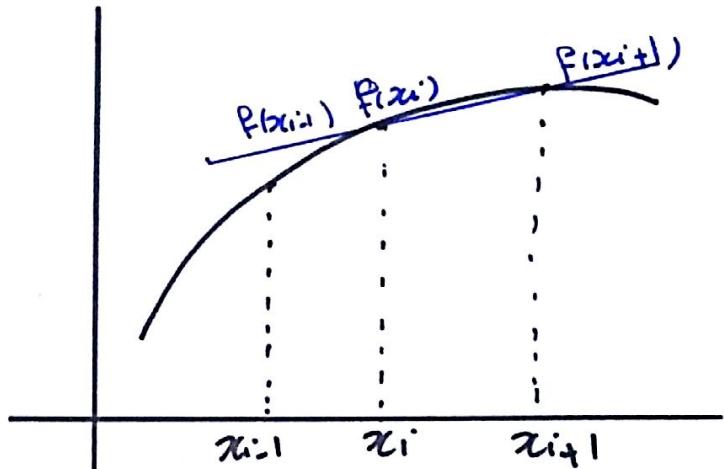
- * the derivative $f'(x)$ of a function $f(x)$ at the point $x=a$ can be obtained graphically by taking a point x near $x=a$ & calculate the slope of the line connects the two points
- * the accuracy of calculating the derivative increases as point x is close to the point a
- * in finite difference approx of the derivative , values of the function at different points in the neighborhood of the point $x=a$ are used for estimating the slope



- Two points

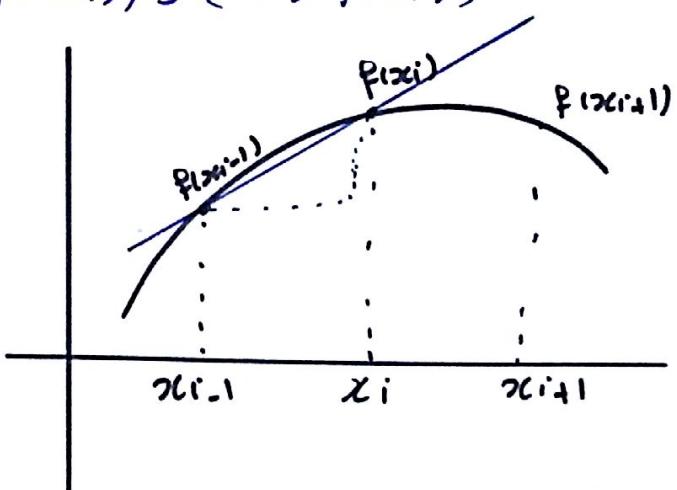
the finite difference approximation 3 formulas for the derivative is calculated from the value of 2 points as follows:

1. forward difference: is the slope of the line connects the points $(x_i, f(x_i))$ & $(x_{i+1}, f(x_{i+1}))$



$$\left. \frac{df}{dx} \right|_{x=x_i} = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} \rightarrow \text{eq A}$$

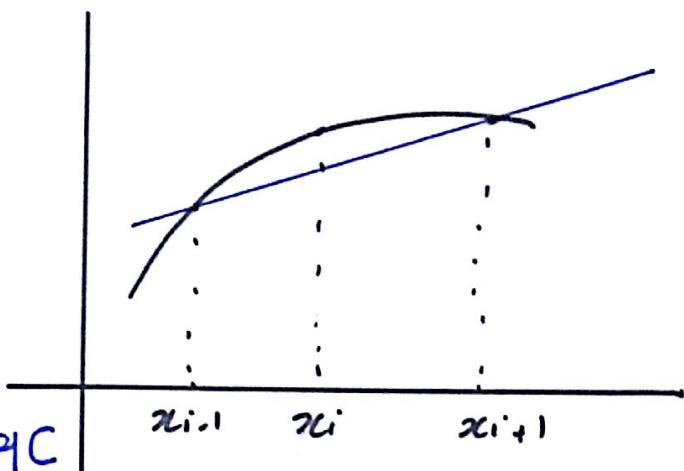
2. backward difference: is the slope of the line connects the points $(x_{i-1}, f(x_{i-1}))$ & $(x_i, f(x_i))$



$$\left. \frac{df}{dx} \right|_{x=x_i} = \frac{f(x_i) - f(x_{i-1})}{x_i - x_{i-1}} \rightarrow \text{eq B}$$

central difference: is the slope of the line

that connects point $(x_{i-1}, f(x_{i-1}))$ & $(x_{i+1}, f(x_{i+1}))$



$$\left. \frac{df}{dx} \right|_{x=x_i} = \frac{f(x_{i+1}) - f(x_{i-1})}{x_{i+1} - x_{i-1}}$$

→ eq C

* these formulas can be obtained by using Taylor series expansion; see Gilat & Subramaniam p.240

ex
consider the function $f(x) = x^3$. calculate its 1st derivative at point $x=3$ numerically with the forward, backward & central finite difference formulas & using:

- points $x=2, x=3, x=4$
- points $x=2.75, x=3$ & $x=3.25$

compare the results with the exact (analytical) derivative.

sol

* analytical diff

$$f'(x) = 3x^2 \quad \& \quad f'(3) = 3(3)^2 = 27$$

* numerical diff

a.	$x = 2$	3	4
	$f(x) = 8$	27	64

1. forward finite difference

$$\left. \frac{df}{dx} \right|_{x=3} = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} = \frac{f(4) - f(3)}{4 - 3} = \frac{64 - 27}{1}$$

$$= 37 \quad \rightarrow \quad \epsilon = \left| \frac{37 - 27}{27} \right| \times 100 = 37.04\%$$

2. backward finite difference

$$\left. \frac{df}{dx} \right|_{x=3} = \frac{f(x_i) - f(x_{i-1})}{x_i - x_{i-1}} = \frac{f(3) - f(2)}{3 - 2} = \frac{27 - 8}{1}$$

$$= 19 \quad \rightarrow \quad \epsilon = \left| \frac{19 - 27}{27} \right| \times 100 = 29.63\%$$

3. central finite difference

$$\left. \frac{df}{dx} \right|_{x=3} = \frac{f(x_{i+1}) - f(x_{i-1})}{x_{i+1} - x_{i-1}} = \frac{f(4) - f(2)}{4 - 2} = \frac{64 - 8}{2}$$

$$= 28 \quad \rightarrow \quad \epsilon = \left| \frac{28 - 27}{27} \right| \times 100 = 3.704\%$$

b. $x = 2.75 \quad 3 \quad 3.25$

$$f(x) = 20.7969 \quad 27 \quad 34.3281$$

1. forward finite difference

$$\left. \frac{df}{dx} \right|_{x=3} = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} = \frac{34.3281 - 27}{3.25 - 3} = 29.3125$$

$$\epsilon \rightarrow = \left| \frac{29.3125 - 27}{27} \right| \times 100$$

$$\epsilon = 8.565\%$$

2. backward finit difference

$$\frac{df}{dx} \Big|_{x=3} = \frac{f(3) - f(2.75)}{3 - 2.75} = \frac{27 - 20.7969}{0.25} = 24.8125$$

$$\rightarrow \epsilon = \left| \frac{24.8125 - 27}{27} \right| \times 100 = 8.102\%$$

3. central finit difference

$$\frac{df}{dx} \Big|_{x=3} = \frac{f(3.25) - f(2.75)}{3.25 - 2.75} = \frac{34.3281 - 20.7969}{3.25 - 2.75} = 27.0625$$

$$\rightarrow \epsilon = \left| \frac{27.0625 - 27}{27} \right| \times 100 = 0.2315\%$$

* the central finit difference formula gives a more accurate approximation. Also smaller separation between points gives more accurate approximation

- Three points

The finite difference approximation 2 formulas for the derivative is calculated from the value of 3 points as follows:

1. 3 points forward difference

$$f'(x_i) = \frac{-3 f(x_i) + 4 f(x_{i+1}) - f(x_{i+2})}{2h} + O(h^2)$$

eq D

truncation error

$$h = x_{i+1} - x_i = x_{i+2} - x_{i+1}$$

since the points are all equally spaced

is the distance between the points

* this formula can be used for calculating the derivative at the first point of a function that is given by a set of n discrete points

2. 3 points backward difference

$$f'(x_i) = \frac{f(x_{i-2}) - 4 f(x_{i-1}) + 3 f(x_i)}{2h} + O(h^2)$$

truncation error

↑ eq E

ex Consider the function $f(x) = x^3$. Calculate the 1st derivative at point $x=3$ numerically with the 3 points forward difference formula using

a- points $x=3, x=4, x=5$

b- points $x=3, x=3.25, x=3.5$

Compare the results with the exact value of the derivative obtained numerically.

sol

- analytical differentiation

$$f'(x) = 3x^2 \quad \& \quad f'(3) = 3(3)^2 = \boxed{27}$$

- Numerical differentiation

$$\begin{array}{ccc} a. & x = & 3 & 4 & 5 \\ & f(x) = & 27 & 64 & 125 \end{array}$$

- the 1st derivative using 3 points forward difference formula is

$$f'(x_i) = \frac{-3f(x_i) + 4f(x_{i+1}) - f(x_{i+2})}{2 \cdot h} = \frac{-3f(3) + 4f(4) - f(5)}{2 \cdot 1}$$

$$= \frac{-3(27) + 4(64) - 125}{2} = 25$$

$$\begin{aligned} \epsilon &= \left| \frac{25 - 27}{27} \right| \times 100 \\ &= 7.41 \% \end{aligned}$$

b. $x = 3 \quad 3.25 \quad 3.5$ P.16

$$f(x) = 27 \quad 34.3281 \quad 42.875$$

- the 1st derivative using 3 points forward formula is

$$f'(x_i) = \frac{-3f(x_i) + 4f(x_{i+1}) - f(x_{i+2})}{2h} = \frac{-3f(3) + 4f(3.25) - f(3.5)}{2(1)}$$

$$= \frac{-3(27) + 4(34.3281) - 42.875}{2} = 26.875$$

$$\epsilon = \left| \frac{26.875 - 27}{27} \right| \times 100$$

$$\epsilon = 0.46\%$$

Comparing the results for 3 points with 2 points we can see that:

the results show that the 3 points forward difference gives more accurate value than the 2 points forward difference for $h=1$ & for $h=0.25$

P.11

differentiation formulas using Lagrange Polynomials

- this formula can be used when the distance between the points are not equally spaced.

formula \rightarrow depending on 3 points (x_i, y_i) , (x_{i+1}, y_{i+1}) & (x_{i+2}, y_{i+2}) is :-

$$f'(x) = \frac{2x - x_{i+1} - x_{i+2}}{(x_i - x_{i+1})(x_i - x_{i+2})} y_i + \frac{2x - x_i - x_{i+2}}{(x_{i+1} - x_i)(x_{i+1} - x_{i+2})} y_{i+1}$$
$$+ \frac{2x - x_i - x_{i+1}}{(x_{i+2} - x_i)(x_{i+2} - x_{i+1})} \cdot y_{i+2} \quad \rightarrow \text{eq 1}$$

the 1st derivative at either one of the three points is calculated by substituting the corresponding value of x (x_i, x_{i+1}, x_{i+2}) in eq 1 of this gives the following three formulas for the first derivative at the three points x_i, x_{i+1}, x_{i+2} \rightarrow

$$\textcircled{1} \quad P'(x_i) = \frac{2x_i - x_{i+1} - x_{i+2}}{(x_i - x_{i+1})(x_i - x_{i+2})} \cdot y_i + \frac{x_i - x_{i+2}}{(x_{i+1} - x_i)(x_{i+1} - x_{i+2})} y_{i+1}$$

$$+ \frac{x_i - x_{i+1}}{(x_{i+2} - x_i)(x_{i+2} - x_{i+1})} y_{i+2} \rightarrow \text{eq 2}$$

$$\textcircled{2} \quad P'(x_{i+1}) = \frac{x_{i+1} - x_{i+2}}{(x_i - x_{i+1})(x_i - x_{i+2})} y_i + \frac{2x_{i+1} - x_i - x_{i+2}}{(x_{i+1} - x_i)(x_{i+1} - x_{i+2})} y_{i+1}$$

$$+ \frac{x_{i+1} - x_i}{(x_{i+2} - x_i)(x_{i+2} - x_{i+1})} y_{i+2} \rightarrow \text{eq 3}$$

$$\textcircled{3} \quad P'(x_{i+2}) = \frac{x_{i+2} - x_{i+1}}{(x_i - x_{i+1})(x_i - x_{i+2})} y_i + \frac{x_{i+2} - x_i}{(x_{i+1} - x_i)(x_{i+1} - x_{i+2})} y_{i+1}$$

$$+ \frac{2x_{i+2} - x_i - x_{i+1}}{(x_{i+2} - x_i)(x_{i+2} - x_{i+1})} y_{i+2} \rightarrow \text{eq 4}$$

H.W

proof that when the points are equally spaced
 then $\textcircled{1}$ eq 2 will reduced to the 3 points forward difference

- $\textcircled{2}$ eq 3 will reduced to the 2 points central diff
 " " " " " " " " 3 points backward "
- $\textcircled{3}$ eq 4 " " " " " " " " 3 points forward "

hints $x_i = (x_i)$
 $x_{i+1} = (x_i + h)$
 $x_{i+2} = (x_i + 2h)$

ex

compute from the following table the value of the derivative of $f(x)$ at $x=0.6$; where

x	x_i	x_{i+1}	x_{i+2}
	0.4	0.6	0.7
$f(x)$	3.3835	4.2442	4.7225

soln

since the distances between the points are not equally spaced so we have to use Lagrange polynomial

$$f'(x_{i+1}) = \frac{x_{i+1} - x_{i+2}}{(x_i - x_{i+1})(x_i - x_{i+2})} y_i + \frac{2x_{i+1} - x_i - x_{i+2}}{(x_{i+1} - x_i)(x_{i+1} - x_{i+2})} y_{i+1}$$

$$+ \frac{x_{i+1} - x_i}{(x_{i+2} - x_i)(x_{i+2} - x_{i+1})} y_{i+2}$$

$$f'(0.6) = \frac{0.6 - 0.7}{(0.4 - 0.6)(0.4 - 0.7)} \times 3.3835 + \frac{2(0.6) - 0.4 - 0.7}{(0.6 - 0.4)(0.6 - 0.7)} \times 4.2442$$

$$+ \frac{0.6 - 0.4}{(0.7 - 0.4)(0.7 - 0.6)} 4.7225$$

$$f'(0.6) = 4.6228$$

1- use the forward & backward 2 points difference formulas to determine the missing entry in the following table

a. x	$f(x)$	$f'(x)$
0.5	0.4794	
0.6	0.5646	
0.7	0.6442	

b. x	$f(x)$	$f'(x)$
0	0	
0.2	0.7414	
0.4	0.3718	

2. use the most accurate 3 point formula to determine each missing entry in the following tables

a. x	$f(x)$	$f'(x)$
1.1	9.025013	
1.2	11.02318	
1.3	13.46374	
1.4	16.44465	

b. x	$f(x)$	$f'(x)$
8.1	16.94416	
8.3	17.56492	
8.5	18.14056	
8.7	18.82091	

3-the following data was collected for the distance traveled versus time for a rocket

t, s	0	25	50	75	100	125
x, km	0	32	58	78	92	100

use numerical differentiation to estimate the rocket's velocity (1st derivative) at each time

4- obtain the 1st derivative for the following function
at $x = 1.5$ & $x = 1.6$

x	1	1.5	1.6	2.5	3.5
$f(x)$	0.6767	0.3734	0.3261	0.0842	0.0159

compare your results with the true derivatives

$$\text{where } f(x) = 5e^{-2x} \cdot x$$

Numerical integration

Introduction to numerical

Integration [quadrature] :-

- * in general integration is very important in engineering & science. Integration & Integrals are also used when solving differential equations.
- * the general form of a definite integral (also called an anti-derivative) is

$$I = \int_a^b f(x) dx$$

where $f(x)$ called the integrand

- * the need for numerical integration

the integrand can be analytical function or a set of discrete points (tabulated data). Numerical integration is needed when analytical integration is difficult or not possible ; and when the integrand is given as a set of discrete points.

The goal is to approximate the definite integral of $f(x)$ over the interval $[a, b]$ by evaluating $f(x)$ at a finite number of sample points which called "quadrature" or numerical integration.

* the integral $I = \int_a^b f(x) dx \approx \int_a^b F(x) dx$
 is evaluated by direct analytical methods from calculus.

+ the simplest approximation for $\int_a^b f(x) dx$ is to take $f(x)$ over the interval $x \in [a, b]$ as a constant equal to the value of $f(x)$ at either one of the endpoints. So

$$I = \int_a^b f(x) dx \approx \int_a^b f(a) dx = f(a)(b-a)$$

$$\text{or } \approx \int_a^b f(b) dx = f(b)(b-a)$$

→ this called "Rectangle method"

* the error using this method is very large.

1- mid point method

* We shall consider estimating $\int_a^b f(x) dx$ as the area under the curve $f(x)$ between $x=a$ & $x=b$

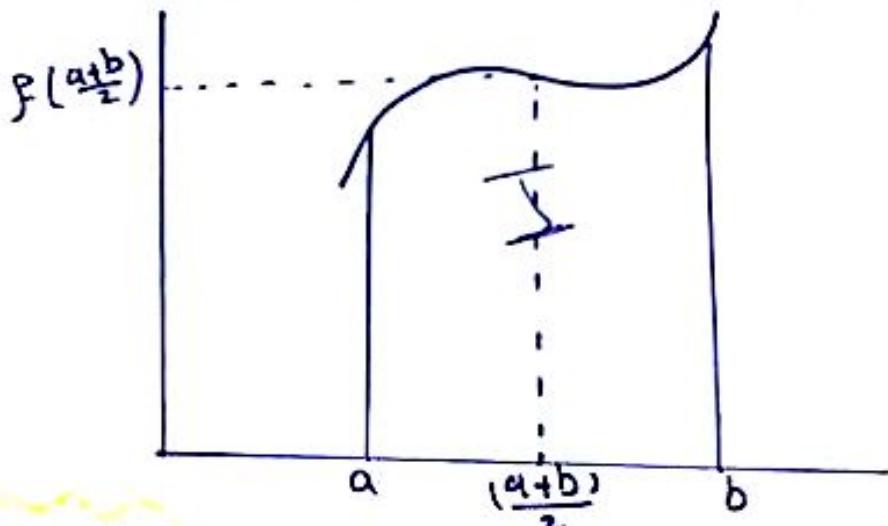
* instead of approximating the integral by the values of the function at $x=a$ or at $x=b$, the value of the integral at the middle of the interval, that is, $f\left(\frac{a+b}{2}\right)$ is used

so

$$\int_a^b f(x) dx$$

$$= \int_a^b f\left(\frac{a+b}{2}\right) dx$$

$$= f\left(\frac{a+b}{2}\right) (b-a)$$



$$I_M = f\left(\frac{a+b}{2}\right) (b-a) + E_M$$

Where

$$E_M = \frac{(b-a)^3}{24} f''(\xi)$$

ξ is some points between a & b

2. Trapezoidal method

P.4

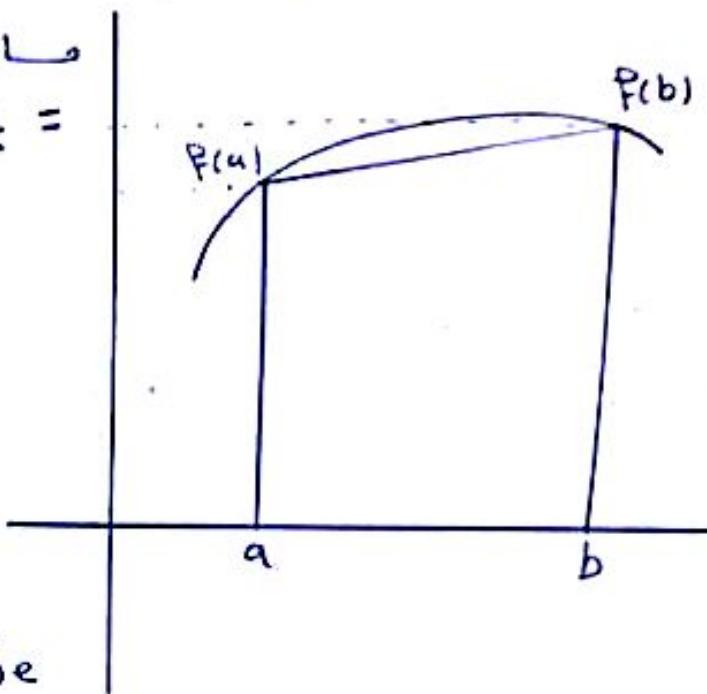
the trapezoidal method approximates I by the area of the trapezoidal $a b f(b) f(a)$

مساحة متوازي الاضلاع $\times (\text{ارتفاع}) \frac{1}{2} =$

$$I_T = \frac{f(a) + f(b)}{2} * (b - a)$$

§

$$E_T = -\frac{(b-a)^3}{12} f''(x)$$



the Trapezoidal rule can be also derived by approximating $f(x)$ by a linear function say $L_1(x)$ at points $(a, f(a))$ & $(b, f(b))$

$$L_1(x) = \left[\frac{x-b}{a-b} f(a) + \frac{x-a}{b-a} f(b) \right]$$

$$I_T = \int_a^b L_1(x) dx = \int_a^b \left[\left(\frac{x-b}{a-b} \right) f(a) + \left(\frac{x-a}{b-a} \right) f(b) \right] dx$$

$$= \frac{f(a)}{a-b} \int_a^b (x-b) dx + \frac{f(b)}{b-a} \int_a^b (x-a) dx$$

$$= \frac{f(a)}{a-b} \left[\frac{x^2}{2} - bx \right]_a^b + \frac{f(b)}{b-a} \left[\frac{x^2}{2} - ax \right]_a^b$$

↓ which will be

$$\frac{I}{T} = \frac{1}{2} (b-a) [f(a) + f(b)]$$

3. Simpson's method

the trapezoidal method approximate the integrand by a linear function. A better approximation can possibly be obtained by approximating the integrand with a non linear function that can be easily integrated.

* Consider the three points $x_0 = a$, $x_2 = b$ &
 $x_1 = \frac{a+b}{2}$

$$L_2(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1)$$

$$+ \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2)$$

$$L_2(x) = \int_{x_0}^{x_2} \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) dx + \int_{x_0}^{x_2} \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1) dx$$

$$+ \int_{x_0}^{x_2} \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2) dx$$



which will be

$$\hat{I}_s = \frac{h}{3} [f(a) + 4f\left(\frac{a+b}{2}\right) + f(b)]$$

where $h = \frac{b-a}{2}$

$$E_s = \frac{-1}{90} \left[\left(\frac{b-a}{2} \right)^5 \right] f^{(4)}(x)$$

ex

Approximate the integral

$$I = \int_0^1 \frac{1}{1+x^2} dx$$

by using the three methods of approximation

soln

1. mid point method

$$I_M = f\left(\frac{a+b}{2}\right)(b-a)$$

$$+ \frac{a+b}{2} = \frac{0+1}{2} = 0.5$$

$$f(0.5) = \frac{1}{1+(0.5)^2}$$

$$I_M = \frac{1}{1+(0.5)^2} (1-0) = \frac{4}{5} = 0.8$$

2. Trapezoidal method

$$I_T = \left(\frac{b-a}{2} \right) [f(a) + f(b)]$$

$$= \left(\frac{1-0}{2} \right) \left[\frac{1}{1+0^2} + \frac{1}{1+1^2} \right] = \frac{3}{4} = 0.75$$

③ the simpson's method

P.7

$$I_s = \frac{h}{3} [f(a) + 4f\left(\frac{a+b}{2}\right) + f(b)]$$

$$h = \frac{b-a}{2} = \frac{1-0}{2} = 0.5$$

$$I_s = \frac{0.5}{3} \left[\frac{1}{1+0^2} + 4 \cdot \frac{1}{1+(0.5)^2} + \frac{1}{1+1^2} \right]$$

$$= \frac{1}{6} \left[1 + \frac{16}{5} + \frac{1}{2} \right] = \frac{1}{6} \left[\frac{47}{10} \right] = 0.7833$$

ex (H.W)

use the mid point, Trapezoidal, Simpson's Rules to approximate $\int_0^2 f(x) dx$ when $f(x)$

is

a. x^2

c. $(x+1)^{-1}$

e. $\sin(x)$

b. x^4

d. $\sqrt{1+x^2}$

f. e^x

& compare the results with the analytical solution in each case

H.W Fairs & Burden P. 202

No, 1 & 2 & 5, 6, 9, 10