

African Master's Of Machine Intelligence

AMMI

# Densely Connected Convolutional Networks

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AMMI Student

BootCamp - Week 1

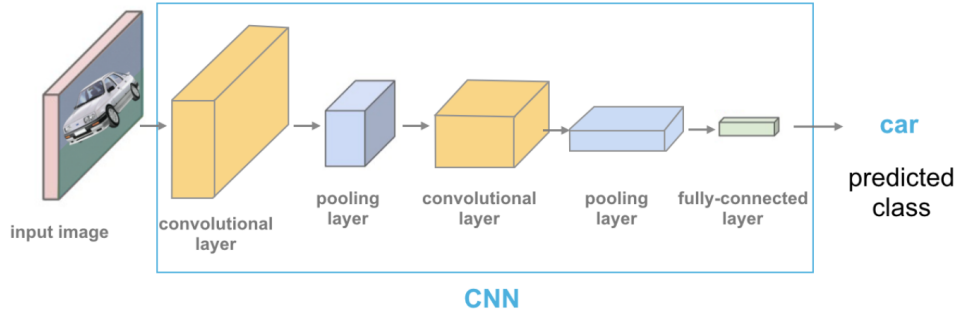
August 20, 2021

# Content

- Convolutional Neural Network (CNN)
- DenseNet Architecture
- Multiple densely connected blocks
- Dense connectivity
- DenseNet architecture for ImageNet
- Results
- Conclusion and perspective

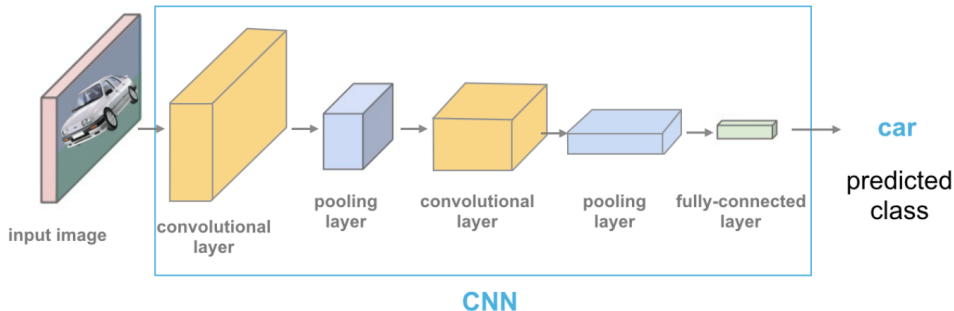
# Convolutional Neural Network (CNN)

How do we define CNN?



# Convolutional Neural Network (CNN)

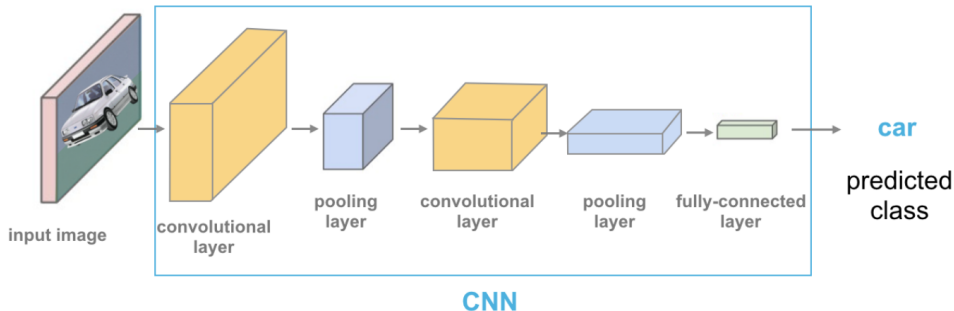
How do we define CNN?



- CNN is a class of deep neural networks, designed for processing structured arrays of data such as images.

# Convolutional Neural Network (CNN)

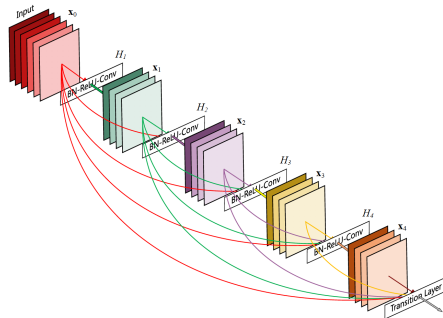
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- Types: AlexNet - VGGNet - GoogLeNet - ResNet.

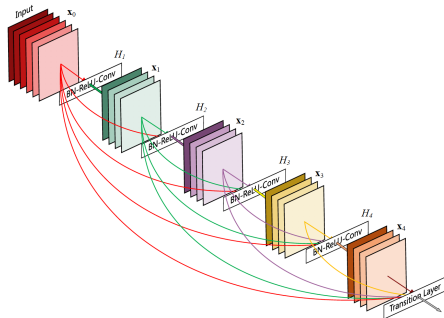
# DenseNet Architecture

Why DenseNet?



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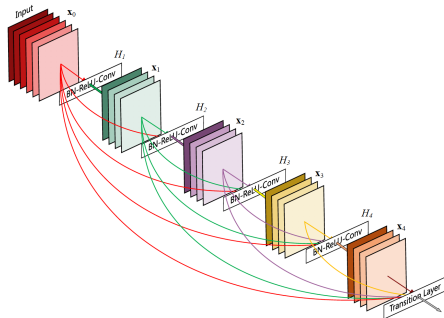
## Why DenseNet?



- Every layer is connected to every other layer.

# DenseNet Architecture

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- Every layer is connected to every other layer.
- The input of a layer inside DenseNet is the concatenation of feature maps from previous layers.



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DenseNets have several compelling advantages.

- they alleviate the vanishing-gradient problem.
- strengthen feature propagation.
- encourage feature reuse.
- substantially reduce the number of parameters.

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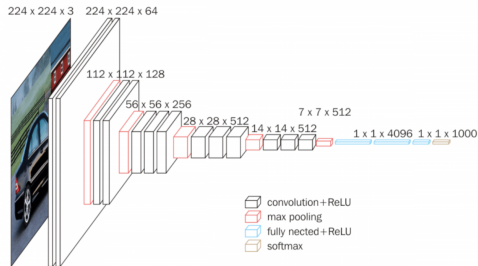


Figure: VGG architecture.

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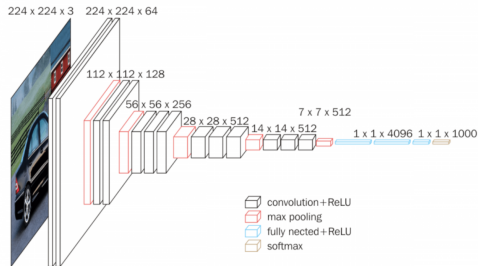
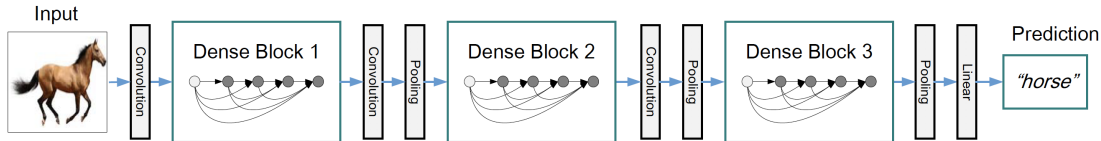


Figure: VGG architecture.

- Essential part of convolutional networks: down-sampling layers that change the size of feature maps.

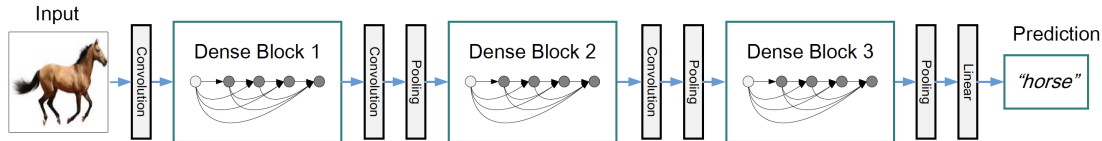
# Multiple densely connected blocks



- **Solution:** divided the network into multiple densely connected dense blocks.

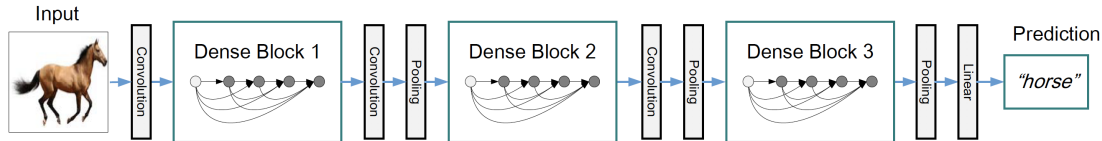


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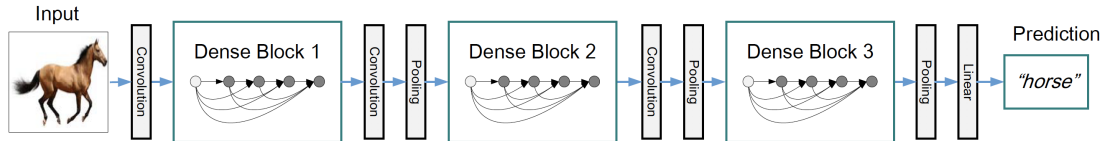
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- **Solution:** divided the network into multiple densely connected dense blocks.
- Inside the dense blocks the feature map size remains the same.
- The size of the feature map grows after a pass through each dense layer and the new features are concatenated to the existing features.
- Each layer adds  $k$  features on top to the global state,  $k$  growth rate of the network.

# Dense connectivity

- Traditional convolutional feed-forward networks connect the output of the  $\ell^{th}$  layer to the  $(\ell + 1)^{th}$  layer. Layer transition:  $\mathbf{x}_\ell = \mathbf{H}_\ell(\mathbf{x}_{\ell-1})$ .

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- In DenseNet architecture, the dense connectivity can be represented as:

$$\mathbf{x}_\ell = \mathbf{H}_\ell([\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{\ell-1}]) \quad (2)$$

# DenseNet architectures for ImageNet

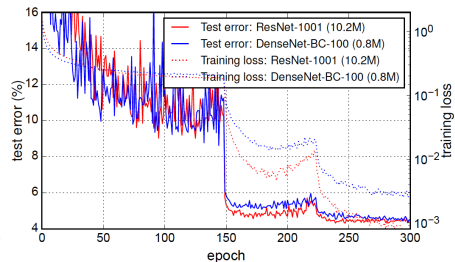
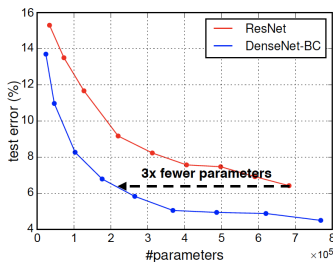
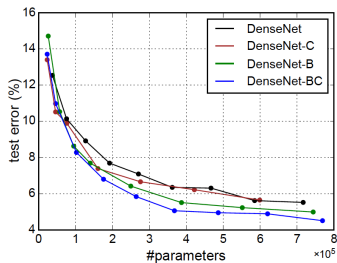
Layers	Output Size	DenseNet-121	DenseNet-169	DenseNet-201	DenseNet-264
Convolution	$112 \times 112$	$7 \times 7$ conv, stride 2			
Pooling	$56 \times 56$	$3 \times 3$ max pool, stride 2			
Dense Block (1)	$56 \times 56$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 6$
Transition Layer (1)	$56 \times 56$	$1 \times 1$ conv			
	$28 \times 28$	$2 \times 2$ average pool, stride 2			
Dense Block (2)	$28 \times 28$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 12$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 12$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 12$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 12$
Transition Layer (2)	$28 \times 28$	$1 \times 1$ conv			
	$14 \times 14$	$2 \times 2$ average pool, stride 2			
Dense Block (3)	$14 \times 14$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 24$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 32$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 48$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 64$
Transition Layer (3)	$14 \times 14$	$1 \times 1$ conv			
	$7 \times 7$	$2 \times 2$ average pool, stride 2			
Dense Block (4)	$7 \times 7$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 16$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 32$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 32$	$\begin{bmatrix} 1 \times 1 \text{ conv} \\ 3 \times 3 \text{ conv} \end{bmatrix} \times 48$
Classification Layer	$1 \times 1$	$7 \times 7$ global average pool			
		1000D fully-connected, softmax			

# Result: Error rate

Method	Depth	Params	C10	C10+	C100	C100+	SVHN
Network in Network [22]	-	-	10.41	8.81	35.68	-	2.35
All-CNN [32]	-	-	9.08	7.25	-	33.71	-
Deeply Supervised Net [20]	-	-	9.69	7.97	-	34.57	1.92
Highway Network [34]	-	-	-	7.72	-	32.39	-
FractalNet [17]	21	38.6M	10.18	5.22	35.34	23.30	2.01
with Dropout/Drop-path	21	38.6M	7.33	4.60	28.20	23.73	1.87
ResNet [11]	110	1.7M	-	6.61	-	-	-
ResNet (reported by [13])	110	1.7M	13.63	6.41	44.74	27.22	2.01
ResNet with Stochastic Depth [13]	110	1.7M	11.66	5.23	37.80	24.58	1.75
	1202	10.2M	-	4.91	-	-	-
Wide ResNet [42]	16	11.0M	-	4.81	-	22.07	-
	28	36.5M	-	4.17	-	20.50	-
	16	2.7M	-	-	-	-	1.64
ResNet (pre-activation) [12]	164	1.7M	11.26*	5.46	35.58*	24.33	-
	1001	10.2M	10.56*	4.62	33.47*	22.71	-
DenseNet ( $k = 12$ )	40	1.0M	<b>7.00</b>	5.24	<b>27.55</b>	24.42	1.79
DenseNet ( $k = 12$ )	100	7.0M	<b>5.77</b>	<b>4.10</b>	<b>23.79</b>	<b>20.20</b>	1.67
DenseNet ( $k = 24$ )	100	27.2M	<b>5.83</b>	<b>3.74</b>	<b>23.42</b>	<b>19.25</b>	<b>1.59</b>
DenseNet-BC ( $k = 12$ )	100	0.8M	<b>5.92</b>	4.51	<b>24.15</b>	22.27	1.76
DenseNet-BC ( $k = 24$ )	250	15.3M	<b>5.19</b>	<b>3.62</b>	<b>19.64</b>	<b>17.60</b>	1.74
DenseNet-BC ( $k = 40$ )	190	25.6M	-	<b>3.46</b>	-	<b>17.18</b>	-



# Result: Comparison of the parameter



# Conclusion and perspective

- DenseNets achieved state-of-the-art results on several highly competitive datasets.

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- DenseNets achieved state-of-the-art results on several highly competitive datasets.
- They require far fewer parameters and less computation to achieve the best performance.
- **Future work:** study such feature transfer with DenseNets

Gao Huang, Zhuang Liu, Laurens van der Maaten, Kilian Q. Weinberger; *Densely Connected Convolutional Networks*. CVPR 2017.

End

Thank you for your attention!