

DEPARTMENT OF INFORMATION TECHNOLOGY

COURSE CODE: DJS22ITL603

COURSE NAME: Image Processing and Computer Vision Laboratory CLASS: TYB. TECH

NAME: Anish Sharma ROLL: I011 DIV: IT1-1

EXPERIMENT NO. 5

CO/LO: Apply Image Enhancement Techniques.

AIM / OBJECTIVE: To apply Spatial Filtering Enhancement Operations on a given image.

EXERCISE

Implement spatial domain filtering such as LPF (Average and Median Filter), HPF, High Boost filters and observe its blurring or smoothening or sharpening effects on the image using PIL/OpenCV libraries:

- 1. Read the image.
- 2. Convert into grayscale if it is colored.
- 3. Convert into the double format.
- 4. Use appropriate masks or filters.
- 5. Apply convolution operation over the given image.
- 6. Display the enhanced images.



Shri Vile Parle Kelavani Mandal's

DWARKADAS J. SANGHVI COLLEGE OF ENGINEERING



(Autonomous College Affiliated to the University of Mumbai) NAAC Accredited with "A" Grade (CGPA : 3.18)

```
CODE:
import numpy as np
import cv2 from PIL
import Image
import matplotlib.pyplot as plt

# Step 1: Read the image
image_path = 'images.jpg'
image = Image.open(image_path)

# Step 2: Convert the image into grayscale if it is colored image_gray
= image.convert('L')  # 'L' mode is for grayscale image_gray =
np.array(image_gray)

# Step 3: Convert the image into double format
(float64) image_gray_double = np.float64(image_gray)
```



Shri Vile Parle Kelavani Mandal's

DWARKADAS J. SANGHVI COLLEGE OF ENGINEERING



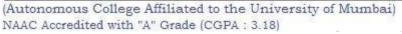
(Autonomous College Affiliated to the University of Mumbai) NAAC Accredited with "A" Grade (CGPA: 3.18)

```
# Function to apply convolution using a given kernel def
apply_convolution(image, kernel):
   return cv2.filter2D(image, -1, kernel)
# 1. Low Pass Filters (LPF) - Average Filter average filter =
np.ones((3, 3), np.float32) / 9 # 3x3 Average Filter lpf_image =
apply_convolution(image_gray_double, average_filter)
# 2. Median Filter (LPF) median filter image =
cv2.medianBlur(image_gray, 3) # 3x3 Median Filter
# 3. High Pass Filter (HPF) - Using a simple kernel
hpf_kernel
            = np.array([[-1, -1,
[-1, 8, -1],
                       [-1, -1, -1]]) # HPF Kernel (Laplacian)
hpf_image = apply_convolution(image_gray_double, hpf_kernel)
# 4. High Boost Filter high_boost_kernel
= np.array([[0, -1, 0],
                              [-1, 5, -1],
                              [0, -1, 0]]) # Simple High Boost Filter Kernel
high_boost_image = apply_convolution(image_gray_double, high_boost_kernel)
fig, axes = plt.subplots(2, 3, figsize=(12, 8))
# Original image display axes[0,
0].imshow(image_gray, cmap='gray') axes[0,
0].set_title('Original Grayscale Image') axes[0,
0].axis('off')
# LPF - Average Filter axes[0,
1].imshow(lpf_image, cmap='gray') axes[0,
1].set title('LPF - Average Filter') axes[0,
1].axis('off')
# Median Filter (LPF) axes[0,
2].imshow(median_filter_image, cmap='gray') axes[0,
2].set title('Median Filter (LPF)') axes[0,
2].axis('off')
# HPF axes[1, 0].imshow(hpf_image,
cmap='gray') axes[1, 0].set_title('HPF - High
Pass Filter') axes[1, 0].axis('off')
# High Boost Filter axes[1,
1].imshow(high_boost_image, cmap='gray') axes[1,
1].set_title('High Boost Filter') axes[1,
1].axis('off')
# Show the plots
plt.tight layout()
```



Shri Vile Parle Kelavani Mandal's

DWARKADAS J. SANGHVI COLLEGE OF ENGINEERING

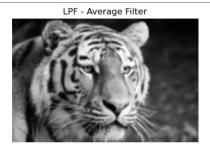


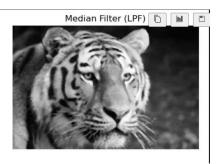


plt.show()

OUTPUT:







HPF - High Pass Filter



High Boost Filter



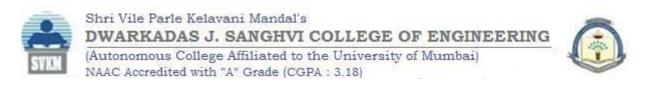
QUESTIONS:

- 1. Write masks and give the mechanics of spatial filtering?
- 2. What is salt and pepper noise and how it can be removed effectively?
- 3. Compare smoothening and sharpening filters.

CONCLUSION:

In conclusion, the implementation of spatial domain filtering techniques—such as Low Pass Filters (Average and Median), High Pass Filters (Laplacian), and High Boost Filters—demonstrates the ability to manipulate images for various effects like smoothing, blurring, sharpening, and edge enhancement. The average and median filters reduce noise and smooth images, while the high-pass filter highlights edges and details, and the high-boost filter enhances the sharpness of the image. By using convolution with appropriate kernels, these filters allow for effective image enhancement, which can be useful in applications like image processing, computer vision, and noise reduction.

REFERENCES:



Website References:

- 1. Kaggle, "Spatial Filtering OpenCV," Available: https://www.kaggle.com/code/bhavinmoriya/spatial-filtering-opencv.
- 2. OpenCV "Image Filtering," *OpenCV Documentation*. Available: https://docs.opencv.org/4.x/dd/d6a/tutorial_js_filtering.html#:~:text=As%20in%20one%2Ddimensional%20signals,finding%20edges%20in%20the%20images...