

# **Strength of Materials Problem Exercises**

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# Welcome to Demo Site

Welcome to this demonstration site of the Strength of Materials Open Problem Exercises companion to the Strength of Materials Open Textbook.

At this time, we are simply using this site as a demonstration and shell for our ongoing work. The intent is to demonstrate a more traditional static style problem exercise pack along with dynamic versions which allow students to quickly check answers and receive basic feedback, and/or to input their math in an interactive interface which will provide them with targeted feedback based on their attempted solution.

This work is still very much in progress and you may find bugs. We would welcome any input or feedback you have about this. Thanks!

**Part I**

**Problem 1**

# Static Problem Statement

This is a static rendering of the problem with fixed variables that correspond to the variables used in the problem solution provided.

Can i change this?

## Problem Statement

A city planner is installing a new traffic light. Light A weighs 65 lb, while lights B and C weigh 50 lb each. The post at O has a hollow circular cross-section with an outer diameter of 5 inches and a wall thickness of 0.2 inches. Please calculate the magnitude of the maximum combined stress in the post. You may ignore the weight of the post.



Figure 0.1: Figure 1: Three traffic light installation with loads

## Worked Out Solution

This demonstrates a worked out solution to the problem. The best way to begin is by drawing a free body diagram.

Use equilibrium equations to find the internal loads:

$$\Sigma F_y = 0 : N - 65 - 50 - 50 = 0$$



Figure 0.2: Figure 3: Three traffic light installation with loads

$$N = 165 \text{ lbs}$$

$$\Sigma M_O = 0 : -M + (50 \times 7) + (50 \times 11) + (65 \times 15) = 0$$

$$M = 1875 \text{ lb} \cdot \text{ft} = 22500 \text{ lb} \cdot \text{in}$$

Now, determine the cross-sectional properties:

$$A = \pi(r_o^2 - r_i^2) = \pi(2.5^2 - 2.3^2) = 3.02 \text{ in}^2$$

$$I = \frac{\pi}{4}(r_o^4 - r_i^4) = \frac{\pi}{4}(2.5^4 - 2.3^4) = 8.70 \text{ in}^4$$

Calculate stress due to normal force:

$$\sigma_n = \frac{F}{A} = \frac{-165 \text{ lbs}}{3.02 \text{ in}^2} = -54.7 \text{ psi}$$

Calculate maximum stress due to bending moment (will have same magnitude in both tension and compression):

$$\sigma_m = \pm \frac{M_c}{I} = \pm \frac{22500 \times 2.5}{8.70} = \pm 6460 \text{ psi}$$

Determine combined tensile stress:  $\sigma_T = -54.7 + 6460 = 6410 \text{ psi}$

Determine combined compressive stress:  $\sigma_T = -54.7 - 6460 = -6520 \text{ psi}$

# Dynamic Problem Statement

This is a dynamic rendering of the problem with dynamic variables based on the username entered. Please note at this time that the figure displays incorrect values. This will be corrected when drawn by the graphic artist.

## Problem Image



Figure 0.3: Figure 1: Three traffic light installation with loads

```
#| standalone: true
#| viewerHeight: 600
#| components: [viewer]

from shiny import App, render, ui, reactive
import random
import asyncio
import io
import math
from datetime import datetime
from pathlib import Path

problem_ID="1"
light_a=reactive.Value("__")
```

```

lights_bc=reactive.Value("__")
attempts=["Timestamp,Attempt,Answer,Feedback\n"]

app_ui = ui.page_fluid(
    ui.markdown("**Please enter your ID number from your instructor and click to generate"),
    ui.input_text("ID","", placeholder="Enter ID Number Here"),
    ui.input_action_button("generate_problem", "Generate Problem", class_="btn-primary"),
    ui.markdown("**Problem Statement**"),
    ui.output_ui("ui_problem_statement"),
    ui.input_text("answer","Your Answer in units of psi", placeholder="Please enter your a"),
    ui.input_action_button("submit", "Submit Answer", class_="btn-primary"),
    ui.download_button("download", "Download File to Submit", class_="btn-success"),
)

def server(input, output, session):
    @output
    @render.ui
    def ui_problem_statement():
        return[ui.markdown(f"A city planner is installing a new traffic light. Light A wei

    @reactive.Effect
    @reactive.event(input.generate_problem)
    def randomize_vars():
        random.seed(input.ID())
        light_a.set(round(65+65*(.5-random.random())*.2))
        lights_bc.set(round(50+50*(.5-random.random())*.2))

    @reactive.Effect
    @reactive.event(input.submit)
    def _():
        instr= (light_a()+2*lights_bc())/math.pi*(2.5**2 - 2.3**2))+ ((-1*lights_bc()*7- li
        #check=math.isclose(float(input.answer()),instr,rel_tol=0.001)
        if math.isclose(float(input.answer()),instr,rel_tol=0.001):
            check="*Correct*"
        else:
            check="*Not Correct.*"

        if check=="*Not Correct.*" and math.isclose(abs(float(input.answer())),abs(instr),
            extra_check="An extra check says you may have a sign error."
        else:

```



```

        extra_check=""
        #extra_check = "An extra check says you may have a sign error." if math.isclose(ab
        feedback=ui.markdown(f"Your answer of {input.answer()} is {check} {extra_check} Fo
        attempts.append(f"{datetime.now()}, {input.submit()}, {input.answer()}, {check}\n")
        m=ui.modal(
            feedback,
            title="Feedback",
            easy_close=True
        )
        ui.modal_show(m)

@session.download(
    filename=lambda: f"Problem_Log-{problem_ID}-{input.ID()}.csv"
)
async def download():
    # This version uses a function to generate the filename. It also yields data
    # multiple times.
    await asyncio.sleep(0.25)
    yield f"{problem_ID}_{input.submit()}_{input.ID()}\n"
    yield ''.join(attempts)

app = App(app_ui, server)

```

# Interactive Problem Interface

To scaffold your learning in this example, we have provided a free body diagram for you and a repeat of the problem statement.

A city planner is installing a new traffic light. Light A weighs 65 lb, while lights B and C weigh 50 lb each. The post at O has a hollow circular cross-section with an outer diameter of 5 inches and a wall thickness of 0.2 inches. Please calculate the magnitude of the maximum combined stress in the post. You may ignore the weight of the post.



Figure 0.4: Figure 1: Three traffic light installation with loads

Please work through the problem step by step showing your math in the interactive interface [here](#).

```
#| standalone: true
#| viewerHeight: 600
#| components: [viewer]

#| standalone: true
#| viewerHeight: 600
#| components: [viewer]

import io
import numpy as np
```

```

import matplotlib.pyplot as plt
from shiny import App, render, ui, reactive, req
from sympy import solve, Eq, Symbol
from sympy.parsing.sympy_parser import parse_expr
from shiny.ui import h4

# load equations lists

class eqn:
    def __init__(self, name, inline_math, newline_math, working_sym, working_eqn_latex, working_eqn_solver):
        self.name = name
        self.inline_math = inline_math
        self.newline_math = newline_math
        self.working_sym = working_sym
        self.working_eqn_latex = working_eqn_latex
        self.working_eqn_solver = working_eqn_solver

StaticsSumFx = eqn(
    "Equilibrium Forces in X",
    "\\(\\Sigma F_x=0\\)",
    "$$\\Sigma F_x=0$$",
    "SigmaFx",
    "$$F_{x1}+F_{x2}+F_{x3}+F_{x4}+F_{x5}=0$$",
    "F_{x1}+F_{x2}+F_{x3}+F_{x4}+F_{x5}=0"
)

StaticsSumFy = eqn(
    "Equilibrium Forces in Y",
    "\\(\\Sigma F_y=0\\)",
    "$$\\Sigma F_y=0$$",
    "SigmaFy",
    "$$F_{y1}+F_{y2}+F_{y3}+F_{y4}+F_{y5}=0$$",
    "F_{y1}+F_{y2}+F_{y3}+F_{y4}+F_{y5}=0"
)

StaticsSumM = eqn(
    "Equilibrium Moments about O",
    "\\(\\Sigma M_O=0\\)",
    "$$\\Sigma M_O=0$$",
    "SigmaM",

```

```

    "$M_1+M_2+M_3+M_4+M_5=0$$",
    "M_1+M_2+M_3+M_4+M_5=0"
)

StressEqn = eqn(
    "Stress Equation",
    "\(\sigma=\frac{F}{A}\)",
    "$$\sigma=\frac{F}{A}$$",
    "sigma,F,A",
    "$$\sigma=\frac{(F)}{(A)}$$",
    "Eq(sigma,(F)/(A))"
)

AxialDeform = eqn(
    "Axial Deformation by Force",
    "\(\delta_l=\frac{P L}{AE}\)",
    "$$\delta_l=\frac{P \cdot L}{A \cdot E}$$",
    "delta_l,P,L,A,E",
    "$$\delta_l=\frac{(P)(L)}{(A)(E)}$$",
    "Eq(delta_l,(P)*(L)/(A)/(E))"
)

ThermalDeform = eqn(
    "Axial Deformation by Thermal",
    "\(\delta_t= \alpha \Delta T L\)",
    "$$\delta_t= \alpha \cdot \Delta T \cdot L$$",
    "delta_t,alpha,DeltaT,L",
    "$$\delta_t= \alpha \Delta T L$$",
    "delta_t= alpha*(Delta_T)*L"
)

AreaTube = eqn(
    "Area of a Tube",
    "\((A_{tube}=\pi(r_o^2-r_i^2))\)",
    "$$A_{tube}=\pi(r_o^2-r_i^2)$$",
    "A_tube,r_o,r_i",
    "$$A_{tube}=\pi(r_o^2-r_i^2)$$",
    "Eq(A_tube,pi*((r_o)**2-(r_i)**2))"
)

ITube = eqn(

```

```

    "Moment of Inertia of a Tube",
    "\(\mathcal{I}_{\text{tube}}=\frac{\pi}{4}(r_o^4-r_i^4)\)",
    "$$\mathcal{I}_{\text{tube}}=\frac{\pi}{4}(r_o^4-r_i^4)$$",
    "I_tube,r_o,r_i",
    "$$\mathcal{I}_{\text{tube}}=\frac{\pi}{4}(r_o^4-r_i^4)$$",
    "Eq(I_tube,\pi/4*((r_o)**4-(r_i)**4))"
)

BendingStress = eqn(
    "Bending Stress from a Moment",
    "\(\sigma_b=\frac{M*y}{I}\)",
    "$$\sigma_b=\frac{M*y}{I}$$",
    "sigma_b,M,y,I,",
    "$$\sigma_b=\frac{M*y}{I}$$",
    "Eq(sigma_b,M*y/I)"
)

Compatability1 = eqn(
    "Compatability Equation 1",
    "\(\mathcal{a}_1+\ldots=\mathcal{b}_1+\mathcal{b}_2+\ldots\)",
    "$$\mathcal{a}_1+\ldots=\mathcal{b}_1+\mathcal{b}_2+\ldots$$",
    "",
    "$$\mathcal{a}_1+\mathcal{a}_n=\mathcal{b}_1+\mathcal{b}_n$$",
    "Eq(a_1+a_n=b_1+b_n)"
)

Compatability2 = eqn(
    "Compatability Equation 2",
    "\(\mathcal{c}_1+\ldots=\mathcal{d}_1+\mathcal{d}_2+\ldots\)",
    "$$\mathcal{c}_1+\ldots=\mathcal{d}_1+\mathcal{d}_2+\ldots$$",
    "",
    "$$\mathcal{c}_1+\mathcal{c}_n=\mathcal{d}_1+\mathcal{d}_n$$",
    "Eq(c_1+c_n=d_1+d_n)"
)

statics_eqnbank_inline = {
    StaticsSumFx.name: StaticsSumFx.inline_math,
    StaticsSumFy.name: StaticsSumFy.inline_math,
    StaticsSumM.name: StaticsSumM.inline_math,
}

```

```

deforms_eqnbank_inline = {
    StressEqn.name: StressEqn.inline_math,
    AxialDeform.name: AxialDeform.inline_math,
    ThermalDeform.name: ThermalDeform.inline_math,
}

geom_eqnbank_inline = {
    AreaTube.name: AreaTube.inline_math,
    ITube.name: ITube.inline_math,
}

eqnbank_inline = {
    StaticsSumFx.name: StaticsSumFx.inline_math,
    StaticsSumFy.name: StaticsSumFy.inline_math,
    StaticsSumM.name: StaticsSumM.inline_math,
    StressEqn.name: StressEqn.inline_math,
    BendingStress.name: BendingStress.inline_math,
    AxialDeform.name: AxialDeform.inline_math,
    ThermalDeform.name: ThermalDeform.inline_math,
    AreaTube.name: AreaTube.inline_math,
    ITube.name: ITube.inline_math,
    Compatability1.name: Compatability1.inline_math,
    Compatability2.name: Compatability2.inline_math,
}

eqnbank_newline = {
    StaticsSumFx.name: StaticsSumFx.newline_math,
    StaticsSumFy.name: StaticsSumFy.newline_math,
    StaticsSumM.name: StaticsSumM.newline_math,
    StressEqn.name: StressEqn.newline_math,
    BendingStress.name: BendingStress.newline_math,
    AxialDeform.name: AxialDeform.newline_math,
    ThermalDeform.name: ThermalDeform.newline_math,
    AreaTube.name: AreaTube.newline_math,
    ITube.name: ITube.newline_math,
    Compatability1.name: Compatability1.newline_math,
    Compatability2.name: Compatability2.newline_math,
}

```

```

working_equations_solver=reactive.Value([])
working_equations_latex_render=reactive.Value([])
working_symbols=reactive.Value([])

feedback_equations=reactive.Value([])
feedback_solns=reactive.Value([])
feedback_syms=reactive.Value([])

working_SumFx_render=reactive.Value("")
working_SumFy_render=reactive.Value("")
working_SumM_render=reactive.Value("")
working_StressEqn_render=reactive.Value("")
working_BendingStress_render=reactive.Value("")
working_AxialDeform_render=reactive.Value("")
working_ThermalDeform_render=reactive.Value("")
working_AreaTube_render=reactive.Value("")
working_Itube_render=reactive.Value("")
working_Compatibility1_render=reactive.Value("")
working_Compatibility2_render=reactive.Value("")

working_SumFx_string=reactive.Value("")
working_SumFy_string=reactive.Value("")
working_SumM_string=reactive.Value("")
working_StressEqn_string=reactive.Value("")
working_BendingStress_string=reactive.Value("")
working_AxialDeform_string=reactive.Value("")
working_ThermalDeform_string=reactive.Value("")
working_AreaTube_string=reactive.Value("")
working_Itube_string=reactive.Value("")
working_Compatibility1_string=reactive.Value("")
working_Compatibility2_string=reactive.Value("")

NumForcesY=reactive.Value(2)
F1y=reactive.Value("")
F2y=reactive.Value("")
F3y=reactive.Value("")
F4y=reactive.Value("")
F5y=reactive.Value("")
Equil_latex=reactive.Value("")

NumForcesX=reactive.Value(2)

```

```

F1x=reactive.Value("")
F2x=reactive.Value("")
F3x=reactive.Value("")
F4x=reactive.Value("")
F5x=reactive.Value("")

NumMoments=reactive.Value(2)
M1=reactive.Value("")
M2=reactive.Value("")
M3=reactive.Value("")
M4=reactive.Value("")
M5=reactive.Value("")

axial_stress_sigma=reactive.Value("")
axial_stress_force=reactive.Value("")
axial_stress_area=reactive.Value("")

bending_stress_sigma=reactive.Value("")
bending_stress_M=reactive.Value("")
bending_stress_y=reactive.Value("")
bending_stress_I=reactive.Value("")

axial_delta_l=reactive.Value("")
axial_P=reactive.Value("")
axial_L=reactive.Value("")
axial_A=reactive.Value("")
axial_E=reactive.Value("")

thermal_delta_t=reactive.Value("")
thermal_alpha=reactive.Value("")
thermal_Delta_T=reactive.Value("")
thermal_L=reactive.Value("")

area_tube_A_tube=reactive.Value("")
area_tube_Ar_o=reactive.Value("")
area_tube_Ar_i=reactive.Value("")

I_tube_I_tube=reactive.Value("")
I_tube_Ir_o=reactive.Value("")
i_tube_Ir_i=reactive.Value("")

```



```

Compatability1_NumLHS=reactive.Value(1)
Compatability1_NumRHS=reactive.Value(2)
Compatability1_a_1=reactive.Value("")
Compatability1_a_2=reactive.Value("")
Compatability1_a_3=reactive.Value("")
Compatability1_a_4=reactive.Value("")
Compatability1_a_5=reactive.Value("")
Compatability1_b_1=reactive.Value("")
Compatability1_b_2=reactive.Value("")
Compatability1_b_3=reactive.Value("")
Compatability1_b_4=reactive.Value("")
Compatability1_b_5=reactive.Value("")

Compatability2_NumLHS=reactive.Value(1)
Compatability2_NumRHS=reactive.Value(2)
Compatability2_c_1=reactive.Value("")
Compatability2_c_2=reactive.Value("")
Compatability2_c_3=reactive.Value("")
Compatability2_c_4=reactive.Value("")
Compatability2_c_5=reactive.Value("")
Compatability2_d_1=reactive.Value("")
Compatability2_d_2=reactive.Value("")
Compatability2_d_3=reactive.Value("")
Compatability2_d_4=reactive.Value("")
Compatability2_d_5=reactive.Value("")

active_eqn_tab=reactive.Value("Instructions")

prob_statement="To scaffold your learning in this example, we have provided a free body di

app_ui = ui.page_fluid(
  ui.head_content(
    ui.tags.script(
      src="https://mathjax.rstudio.com/latest/MathJax.js?config=TeX-AMS-MML_HTMLorMML"
    ),
    ui.tags.script(
      "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
    ),
  ),
  ui.panel_title("Interactive Problem Solving Environment"),
  ui.row(

```

```

        ui.column(6,
            ui.markdown("**Problem Statement**"),
            ui.markdown(prob_statement),
        ),
        ui.column(6, ui.output_ui("dyn_ui_nav")),
    ),
    #ui.row(
    #    ui.output_ui("dyn_ui_nav"),
    #    ),
    ui.row(
        ui.markdown("**Your Equation Workspace**"),
        #ui.column(6, ui.output_ui("dyn_ui_nav")),
        ui.column(4,
            ui.navset_tab_card(
                ui.nav("Equation Bank",
                    ui.input_checkbox_group("selected_eqns", "Choose your equations:", eqns_keys)),
            ),
        ),
        ui.column(2, ui.output_ui("dyn_eqns"), style='border-right:1px solid;'),
        ui.column(4, ui.output_ui("dyn_working_eqns"), ui.output_text("txt")),
    ),
    ui.row(
        ui.output_ui("ui_equation_bookkeeping")
    ),
    #ui.row(ui.input_action_button(
    #    "solveEquations", "Solve Equations", class_="btn-success", width="240px"
    #    ),
    ui.output_ui("ui_solutions"),
)

```

```
def server(input, output, session):
```

```

    @output
    @render.ui
    def dyn_eqns():
        eqns_keys = input.selected_eqns()
        req(eqns_keys)
        lookup_eqns = [eqnbank_newline[key] for key in eqns_keys]

```

```

mystring_eqns = "".join(lookup_eqns)
feedback_equations.set(lookup_eqns)

return [
    ui.markdown(mystring_eqns),
    ui.tags.script(
        "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
    ),
]

@output
@render.ui
def dyn_working_eqns():
    eqns_keys = input.selected_eqns()
    req(eqns_keys)
    lookup_eqns = [eqnbank_newline[key] for key in eqns_keys]

# Dynamic Filling of Force equations
if StaticsSumFy.newline_math in lookup_eqns:
    StaticsSumFy_list = ["F_y1", "F_y2", "F_y3", "F_y4", "F_y5"]
    StaticsSumFy_list = StaticsSumFy_list[:input.NumForcesY()]
    StaticsSumFy.working_sym = ",".join(StaticsSumFy_list)
    StaticsSumFy.working_eqn_latex = "$$" + "+" .join(StaticsSumFy_list) + "=0$$"
    StaticsSumFy.working_eqn_solver = "+" .join(StaticsSumFy_list)

    if str(input.F1y()) != "" :
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y1",str(input.F1y()))
        StaticsSumFy.working_sym = StaticsSumFy.working_sym.replace("F_y1",str(input.F1y()))
        StaticsSumFy.working_eqn_solver = StaticsSumFy.working_eqn_solver.replace("F_y1",str(input.F1y()))
    else:
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y1",str(input.F1y()))

    if str(input.F2y()) != "" :
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y2",str(input.F2y()))
        StaticsSumFy.working_sym = StaticsSumFy.working_sym.replace("F_y2",str(input.F2y()))
        StaticsSumFy.working_eqn_solver = StaticsSumFy.working_eqn_solver.replace("F_y2",str(input.F2y()))
    else:
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y2",str(input.F2y()))

    if str(input.F3y()) != "" :

```

```

        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y3",str(input.F3y()))
        StaticsSumFy.working_sym = StaticsSumFy.working_sym.replace("F_y3",str(input.F3y()))
        StaticsSumFy.working_eqn_solver = StaticsSumFy.working_eqn_solver.replace("F_y3",str(input.F3y()))
    else:
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y3",str(input.F3y()))

    if str(input.F4y()) != "" :
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y4",str(input.F4y()))
        StaticsSumFy.working_sym = StaticsSumFy.working_sym.replace("F_y4",str(input.F4y()))
        StaticsSumFy.working_eqn_solver = StaticsSumFy.working_eqn_solver.replace("F_y4",str(input.F4y()))
    else:
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y4",str(input.F4y()))

    if str(input.F5y()) != "" :
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y5",str(input.F5y()))
        StaticsSumFy.working_sym = StaticsSumFy.working_sym.replace("F_y5",str(input.F5y()))
        StaticsSumFy.working_eqn_solver = StaticsSumFy.working_eqn_solver.replace("F_y5",str(input.F5y()))
    else:
        StaticsSumFy.working_eqn_latex = StaticsSumFy.working_eqn_latex.replace("F_y5",str(input.F5y()))

# Dynamic Filling of Force equations
if StaticsSumFx.newline_math in lookup_eqns:
    StaticsSumFx_list = ["F_x1","F_x2","F_x3","F_x4","F_x5"]
    StaticsSumFx_list = StaticsSumFx_list[:input.NumForcesX()]
    StaticsSumFx.working_sym = ",".join(StaticsSumFx_list)
    StaticsSumFx.working_eqn_latex = "$$" + "+" .join(StaticsSumFx_list) + "=0$$"
    StaticsSumFx.working_eqn_solver = "+" .join(StaticsSumFx_list)

    if str(input.F1x()) != "" :
        StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F_x1",str(input.F1x()))
        StaticsSumFx.working_sym = StaticsSumFx.working_sym.replace("F_x1",str(input.F1x()))
        StaticsSumFx.working_eqn_solver = StaticsSumFx.working_eqn_solver.replace("F_x1",str(input.F1x()))
    else:
        StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F_x1",str(input.F1x()))

    if str(input.F2x()) != "" :
        StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F_x2",str(input.F2x()))
        StaticsSumFx.working_sym = StaticsSumFx.working_sym.replace("F_x2",str(input.F2x()))
        StaticsSumFx.working_eqn_solver = StaticsSumFx.working_eqn_solver.replace("F_x2",str(input.F2x()))
    else:
        StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F_x2",str(input.F2x()))

```

```

if str(input.F3x()) != "" :
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F3")
    StaticsSumFx.working_sym = StaticsSumFx.working_sym.replace("F_x3", str(input.F3x()))
    StaticsSumFx.working_eqn_solver = StaticsSumFx.working_eqn_solver.replace("F", "F3")
else:
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F")

if str(input.F4x()) != "" :
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F4")
    StaticsSumFx.working_sym = StaticsSumFx.working_sym.replace("F_x4", str(input.F4x()))
    StaticsSumFx.working_eqn_solver = StaticsSumFx.working_eqn_solver.replace("F", "F4")
else:
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F")

if str(input.F5x()) != "" :
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F5")
    StaticsSumFx.working_sym = StaticsSumFx.working_sym.replace("F_x5", str(input.F5x()))
    StaticsSumFx.working_eqn_solver = StaticsSumFx.working_eqn_solver.replace("F", "F5")
else:
    StaticsSumFx.working_eqn_latex = StaticsSumFx.working_eqn_latex.replace("F", "F")

# Dynamic Filling of Moment equations
if StaticsSumM.newline_math in lookup_eqns:
    StaticsSumM_list = ["M_1", "M_2", "M_3", "M_4", "M_5"]
    StaticsSumM_list = StaticsSumM_list[:input.NumMoments()]
    StaticsSumM.working_sym = ",".join(StaticsSumM_list)
    StaticsSumM.working_eqn_latex = "$$" + "+" .join(StaticsSumM_list) + "=0$$"
    StaticsSumM.working_eqn_solver = "+" .join(StaticsSumM_list)

if str(input.M1()) != "" :
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_1", str(input.M1()))
    StaticsSumM.working_sym = StaticsSumM.working_sym.replace("M_1", str(input.M1()))
    StaticsSumM.working_eqn_solver = StaticsSumM.working_eqn_solver.replace("M_1", str(input.M1()))
else:
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_1", "M_1")

if str(input.M2()) != "" :
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_2", str(input.M2()))
    StaticsSumM.working_sym = StaticsSumM.working_sym.replace("M_2", str(input.M2()))
    StaticsSumM.working_eqn_solver = StaticsSumM.working_eqn_solver.replace("M_2", str(input.M2()))

```

```

else:
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_2")

if str(input.M3()) != "" :
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_3")
    StaticsSumM.working_sym = StaticsSumM.working_sym.replace("M_3",str(input.M3()))
    StaticsSumM.working_eqn_solver = StaticsSumM.working_eqn_solver.replace("M_3",str(input.M3()))
else:
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_3")

if str(input.M4()) != "" :
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_4")
    StaticsSumM.working_sym = StaticsSumM.working_sym.replace("M_4",str(input.M4()))
    StaticsSumM.working_eqn_solver = StaticsSumM.working_eqn_solver.replace("M_4",str(input.M4()))
else:
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_4")

if str(input.M5()) != "" :
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_5")
    StaticsSumM.working_sym = StaticsSumM.working_sym.replace("M_5",str(input.M5()))
    StaticsSumM.working_eqn_solver = StaticsSumM.working_eqn_solver.replace("M_5",str(input.M5()))
else:
    StaticsSumM.working_eqn_latex = StaticsSumM.working_eqn_latex.replace("M_5")

# Dynamic Filling of A equations
if AreaTube.newline_math in lookup_eqns:
    AreaTube.working_eqn_latex = AreaTube.newline_math
    AreaTube.working_eqn_solver = "Eq(A_tube,pi*((r_o)**2-(r_i)**2))"
    AreaTube.working_sym = "A_tube,r_o,r_i"

if str(input.A_tube()) != "" :
    AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("A_{tube}",str(input.A_tube()))
    AreaTube.working_sym = AreaTube.working_sym.replace("A_tube",str(input.A_tube()))
    AreaTube.working_eqn_solver = AreaTube.working_eqn_solver.replace("A_tube",str(input.A_tube()))
else:
    AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("A_{tube}",str(input.A_tube()))

if str(input.Ar_o()) != "" :
    AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("r_o",str(input.Ar_o()))
    AreaTube.working_sym = AreaTube.working_sym.replace("r_o",str(input.Ar_o()))
    AreaTube.working_eqn_solver = AreaTube.working_eqn_solver.replace("r_o",str(input.Ar_o()))
else:

```

```

        AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("r_o", "\\boxed{r_o}")
    if str(input.Ar_i()) != "" :
        AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("r_i", str(input.Ar_i()))
        AreaTube.working_sym = AreaTube.working_sym.replace("r_i", str(input.Ar_i()))
        AreaTube.working_eqn_solver = AreaTube.working_eqn_solver.replace("r_i", str(input.Ar_i()))
    else:
        AreaTube.working_eqn_latex = AreaTube.working_eqn_latex.replace("r_i", "\\boxed{r_i}")

# Dynamic Filling of I equations
if ITube.newline_math in lookup_eqns:
    ITube.working_eqn_latex = ITube.newline_math
    ITube.working_eqn_solver = "Eq(I_tube, pi/4*((r_o)**4-(r_i)**4))"
    ITube.working_sym = "I_tube, r_o, r_i"
    if str(input.I_tube()) != "" :
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("I_{tube}", str(input.I_tube()))
        ITube.working_sym = ITube.working_sym.replace("I_tube", str(input.I_tube()))
        ITube.working_eqn_solver = ITube.working_eqn_solver.replace("I_tube", str(input.I_tube()))
    else:
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("I_{tube}", "\\boxed{I_tube}")
    if str(input.Ir_o()) != "" :
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("r_o", str(input.Ir_o()))
        ITube.working_sym = ITube.working_sym.replace("r_o", str(input.Ir_o()))
        ITube.working_eqn_solver = ITube.working_eqn_solver.replace("r_o", str(input.Ir_o()))
    else:
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("r_o", "\\boxed{r_o}")
    if str(input.Ir_i()) != "" :
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("r_i", str(input.Ir_i()))
        ITube.working_sym = ITube.working_sym.replace("r_i", str(input.Ir_i()))
        ITube.working_eqn_solver = ITube.working_eqn_solver.replace("r_i", str(input.Ir_i()))
    else:
        ITube.working_eqn_latex = ITube.working_eqn_latex.replace("r_i", "\\boxed{r_i}")

# Dynamic Filling of Stress equation
if StressEqn.newline_math in lookup_eqns:
    StressEqn.working_eqn_latex = StressEqn.newline_math
    StressEqn.working_eqn_solver = "Eq(sigma, (F)/(A))"
    StressEqn.working_sym = "sigma, F, A"
    if str(input.sigma()) != "" :
        StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("\\sigma", str(input.sigma()))
        StressEqn.working_eqn_solver = StressEqn.working_eqn_solver.replace("sigma", str(input.sigma()))
        StressEqn.working_sym = StressEqn.working_sym.replace("sigma", str(input.sigma()))

```

```

else:
    StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("\sigma"
if str(input.force()) != "" :
    StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("F",str(
    StressEqn.working_eqn_solver = StressEqn.working_eqn_solver.replace("F",st
    StressEqn.working_sym = StressEqn.working_sym.replace("F",str(input.force(
else:
    StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("F","\b
if str(input.area()) != "" :
    StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("A",str(
    StressEqn.working_eqn_solver = StressEqn.working_eqn_solver.replace("A",st
    StressEqn.working_sym = StressEqn.working_sym.replace("A",str(input.area(
else:
    StressEqn.working_eqn_latex = StressEqn.working_eqn_latex.replace("A","\b

# Dynamic Filling of Bending Stress equation
if BendingStress.newline_math in lookup_eqns:
    BendingStress.working_eqn_latex = BendingStress.newline_math
    BendingStress.working_eqn_solver = "Eq(sigma_b,M*y/I)"
    BendingStress.working_sym = "sigma_b,M,y,I"
    if str(input.bendingstress_sigma_b()) != "" :
        BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
        BendingStress.working_eqn_solver = BendingStress.working_eqn_solver.replac
        BendingStress.working_sym = BendingStress.working_sym.replace("sigma_b",st
    else:
        BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
if str(input.bendingstress_M()) != "" :
    BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
    BendingStress.working_eqn_solver = BendingStress.working_eqn_solver.replac
    BendingStress.working_sym = BendingStress.working_sym.replace("M",str(inpu
else:
    BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
if str(input.bendingstress_y()) != "" :
    BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
    BendingStress.working_eqn_solver = BendingStress.working_eqn_solver.replac
    BendingStress.working_sym = BendingStress.working_sym.replace("y",str(inpu
else:
    BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(
if str(input.bendingstress_I()) != "" :
    BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace(

```



```

        BendingStress.working_eqn_solver = BendingStress.working_eqn_solver.replace("I",str(input.I))
        BendingStress.working_sym = BendingStress.working_sym.replace("I",str(input.I))
    else:
        BendingStress.working_eqn_latex = BendingStress.working_eqn_latex.replace("I",str(input.I))

```

```

# Dynamic Filling of Axial Deform equation

```

```

if AxialDeform.newline_math in lookup_eqns:

```

```

    AxialDeform.working_eqn_latex = AxialDeform.newline_math

```

```

    AxialDeform.working_eqn_solver = "Eq(delta_l,P*L/A/E)"

```

```

    AxialDeform.working_sym = "delta_l,P,L,A,E"

```

```

    if str(input.axial_delta_l()) != "" :

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("\delta_l",str(input.axial_delta_l()))

```

```

        AxialDeform.working_eqn_solver = AxialDeform.working_eqn_solver.replace("d",str(input.axial_delta_l()))

```

```

        AxialDeform.working_sym = AxialDeform.working_sym.replace("delta_l",str(input.axial_delta_l()))

```

```

    else:

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("\delta_l",str(input.axial_delta_l()))

```

```

    if str(input.axial_P()) != "" :

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("P",str(input.axial_P()))

```

```

        AxialDeform.working_eqn_solver = AxialDeform.working_eqn_solver.replace("P",str(input.axial_P()))

```

```

        AxialDeform.working_sym = AxialDeform.working_sym.replace("P",str(input.axial_P()))

```

```

    else:

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("P",str(input.axial_P()))

```

```

    if str(input.axial_L()) != "" :

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("L",str(input.axial_L()))

```

```

        AxialDeform.working_eqn_solver = AxialDeform.working_eqn_solver.replace("L",str(input.axial_L()))

```

```

        AxialDeform.working_sym = AxialDeform.working_sym.replace("L",str(input.axial_L()))

```

```

    else:

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("L",str(input.axial_L()))

```

```

    if str(input.axial_A()) != "" :

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("A",str(input.axial_A()))

```

```

        AxialDeform.working_eqn_solver = AxialDeform.working_eqn_solver.replace("A",str(input.axial_A()))

```

```

        AxialDeform.working_sym = AxialDeform.working_sym.replace("A",str(input.axial_A()))

```

```

    else:

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("A",str(input.axial_A()))

```

```

    if str(input.axial_E()) != "" :

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("E",str(input.axial_E()))

```

```

        AxialDeform.working_eqn_solver = AxialDeform.working_eqn_solver.replace("E",str(input.axial_E()))

```

```

        AxialDeform.working_sym = AxialDeform.working_sym.replace("E",str(input.axial_E()))

```

```

    else:

```

```

        AxialDeform.working_eqn_latex = AxialDeform.working_eqn_latex.replace("E",str(input.axial_E()))

```

```

# Dynamic Filling of Thermal Deform equation
if ThermalDeform.newline_math in lookup_eqns:
    ThermalDeform.working_eqn_latex = ThermalDeform.newline_math
    ThermalDeform.working_eqn_solver = "Eq(delta_t,alpha*Delta_T*L)"
    ThermalDeform.working_sym = "delta_t,Delta_T,alpha,L"
    if str(input.thermal_delta_t()) != "" :
        ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
            ThermalDeform.working_eqn_solver = ThermalDeform.working_eqn_solver.replac
            ThermalDeform.working_sym = ThermalDeform.working_sym.replace("delta_t",st
    else:
        ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
if str(input.thermal_alpha()) != "" :
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
    ThermalDeform.working_eqn_solver = ThermalDeform.working_eqn_solver.replac
    ThermalDeform.working_sym = ThermalDeform.working_sym.replace("alpha",str(
else:
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
if str(input.thermal_Delta_T()) != "" :
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
    ThermalDeform.working_eqn_solver = ThermalDeform.working_eqn_solver.replac
    ThermalDeform.working_sym = ThermalDeform.working_sym.replace("Delta_T",st
else:
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
if str(input.thermal_L()) != "" :
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(
    ThermalDeform.working_eqn_solver = ThermalDeform.working_eqn_solver.replac
    ThermalDeform.working_sym = ThermalDeform.working_sym.replace("L",str(inp
else:
    ThermalDeform.working_eqn_latex = ThermalDeform.working_eqn_latex.replace(

# Dynamic Filling of Compatability equation 1
if Compatability1.newline_math in lookup_eqns:
    Compatability1_list__LHS = ["a_1","a_2","a_3","a_4","a_5"]
    Compatability1_list__RHS = ["b_1","b_2","b_3","b_4","b_5"]
    Compatability1_list_LHS = Compatability1_list__LHS[:input.Compatability1_NumLH
    Compatability1_list_RHS = Compatability1_list__RHS[:input.Compatability1_NumRH
    Compatability1_list = Compatability1_list_LHS + Compatability1_list_RHS
    Compatability1.working_sym = ",".join(Compatability1_list)
    Compatability1.working_eqn_latex = "$$" + "+".join(Compatability1_list_LHS) +
    Compatability1.working_eqn_solver = "Eq("+ "+".join(Compatability1_list_LHS) +

```

```

if str(input.a_1()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_1",str(input.a_1()))
    Compatability1.working_sym = Compatability1.working_sym.replace("a_1",str(input.a_1()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("a_1",str(input.a_1()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_1",str(input.a_1()))

if str(input.a_2()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_2",str(input.a_2()))
    Compatability1.working_sym = Compatability1.working_sym.replace("a_2",str(input.a_2()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("a_2",str(input.a_2()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_2",str(input.a_2()))

if str(input.a_3()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_3",str(input.a_3()))
    Compatability1.working_sym = Compatability1.working_sym.replace("a_3",str(input.a_3()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("a_3",str(input.a_3()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_3",str(input.a_3()))

if str(input.a_4()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_4",str(input.a_4()))
    Compatability1.working_sym = Compatability1.working_sym.replace("a_4",str(input.a_4()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("a_4",str(input.a_4()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_4",str(input.a_4()))

if str(input.a_5()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_5",str(input.a_5()))
    Compatability1.working_sym = Compatability1.working_sym.replace("a_5",str(input.a_5()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("a_5",str(input.a_5()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("a_5",str(input.a_5()))

if str(input.b_1()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_1",str(input.b_1()))
    Compatability1.working_sym = Compatability1.working_sym.replace("b_1",str(input.b_1()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("b_1",str(input.b_1()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_1",str(input.b_1()))

```

```

if str(input.b_2()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_2",str(input.b_2()))
    Compatability1.working_sym = Compatability1.working_sym.replace("b_2",str(input.b_2()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("b_2",str(input.b_2()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_2",str(input.b_2()))

if str(input.b_3()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_3",str(input.b_3()))
    Compatability1.working_sym = Compatability1.working_sym.replace("b_3",str(input.b_3()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("b_3",str(input.b_3()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_3",str(input.b_3()))

if str(input.b_4()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_4",str(input.b_4()))
    Compatability1.working_sym = Compatability1.working_sym.replace("b_4",str(input.b_4()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("b_4",str(input.b_4()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_4",str(input.b_4()))

if str(input.b_5()) != "" :
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_5",str(input.b_5()))
    Compatability1.working_sym = Compatability1.working_sym.replace("b_5",str(input.b_5()))
    Compatability1.working_eqn_solver = Compatability1.working_eqn_solver.replace("b_5",str(input.b_5()))
else:
    Compatability1.working_eqn_latex = Compatability1.working_eqn_latex.replace("b_5",str(input.b_5()))

# Dynamic Filling of Compatability equation 2
if Compatability2.newline_math in lookup_eqns:
    Compatability2_list__LHS = ["c_1","c_2","c_3","c_4","c_5"]
    Compatability2_list__RHS = ["d_1","d_2","d_3","d_4","d_5"]
    Compatability2_list_LHS = Compatability2_list__LHS[:input.Compatability2_NumLHS]
    Compatability2_list_RHS = Compatability2_list__RHS[:input.Compatability2_NumRHS]
    Compatability2_list = Compatability2_list_LHS + Compatability2_list_RHS
    Compatability2.working_sym = ",".join(Compatability2_list)
    Compatability2.working_eqn_latex = "$$" + "+" .join(Compatability2_list_LHS) + "+" .join(Compatability2_list_RHS)
    Compatability2.working_eqn_solver = "Eq(" + "+" .join(Compatability2_list_LHS) + "+" .join(Compatability2_list_RHS)

if str(input.c_1()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replace("c_1",str(input.c_1()))

```

```

        Compatability2.working_sym = Compatability2.working_sym.replace("c_1",str(
        Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
    else:
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.c_2()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
    Compatability2.working_sym = Compatability2.working_sym.replace("c_2",str(
    Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
else:
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.c_3()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
    Compatability2.working_sym = Compatability2.working_sym.replace("c_3",str(
    Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
else:
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.c_4()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
    Compatability2.working_sym = Compatability2.working_sym.replace("c_4",str(
    Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
else:
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.c_5()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
    Compatability2.working_sym = Compatability2.working_sym.replace("c_5",str(
    Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
else:
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.d_1()) != "" :
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
    Compatability2.working_sym = Compatability2.working_sym.replace("d_1",str(
    Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
else:
    Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

if str(input.d_2()) != "" :

```

```

        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
        Compatability2.working_sym = Compatability2.working_sym.replace("d_2",str(
        Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
    else:
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

    if str(input.d_3()) != "" :
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
        Compatability2.working_sym = Compatability2.working_sym.replace("d_3",str(
        Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
    else:
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

    if str(input.d_4()) != "" :
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
        Compatability2.working_sym = Compatability2.working_sym.replace("d_4",str(
        Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
    else:
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

    if str(input.d_5()) != "" :
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac
        Compatability2.working_sym = Compatability2.working_sym.replace("d_5",str(
        Compatability2.working_eqn_solver = Compatability2.working_eqn_solver.repl
    else:
        Compatability2.working_eqn_latex = Compatability2.working_eqn_latex.replac

eqnbank_working_latex = {
StaticsSumFx.name: StaticsSumFx.working_eqn_latex,
StaticsSumFy.name: StaticsSumFy.working_eqn_latex,
StaticsSumM.name: StaticsSumM.working_eqn_latex,
StressEqn.name: StressEqn.working_eqn_latex,
BendingStress.name: BendingStress.working_eqn_latex,
AxialDeform.name: AxialDeform.working_eqn_latex,
ThermalDeform.name: ThermalDeform.working_eqn_latex,
AreaTube.name: AreaTube.working_eqn_latex,
ITube.name: ITube.working_eqn_latex,
Compatability1.name: Compatability1.working_eqn_latex,
Compatability2.name: Compatability2.working_eqn_latex
}

```

```

eqnbank_working_solver = {
StaticsSumFx.name: StaticsSumFx.working_eqn_solver,
StaticsSumFy.name: StaticsSumFy.working_eqn_solver,
StaticsSumM.name: StaticsSumM.working_eqn_solver,
StressEqn.name: StressEqn.working_eqn_solver,
BendingStress.name: BendingStress.working_eqn_solver,
AxialDeform.name: AxialDeform.working_eqn_solver,
ThermalDeform.name: ThermalDeform.working_eqn_solver,
AreaTube.name: AreaTube.working_eqn_solver,
ITube.name: ITube.working_eqn_solver,
Compatability1.name: Compatability1.working_eqn_solver,
Compatability2.name: Compatability2.working_eqn_solver
}

```

```

symbank_working = {
StaticsSumFx.name: StaticsSumFx.working_sym,
StaticsSumFy.name: StaticsSumFy.working_sym,
StaticsSumM.name: StaticsSumM.working_sym,
StressEqn.name: StressEqn.working_sym,
BendingStress.name: BendingStress.working_sym,
AxialDeform.name: AxialDeform.working_sym,
ThermalDeform.name: ThermalDeform.working_sym,
AreaTube.name: AreaTube.working_sym,
ITube.name: ITube.working_sym,
Compatability1.name: Compatability1.working_sym,
Compatability2.name: Compatability2.working_sym
}

```

```

working_eqns_latex = [eqnbank_working_latex[key] for key in eqns_keys]
working_SumFx_render.set(eqnbank_working_latex["Equilibrium Forces in X"])
working_SumFy_render.set(eqnbank_working_latex["Equilibrium Forces in Y"])
working_SumM_render.set(eqnbank_working_latex["Equilibrium Moments about 0"])
working_StressEqn_render.set(eqnbank_working_latex["Stress Equation"])
working_BendingStress_render.set(eqnbank_working_latex["Bending Stress from a Mome
working_AxialDeform_render.set(eqnbank_working_latex["Axial Deformation by Force"])
working_ThermalDeform_render.set(eqnbank_working_latex["Axial Deformation by Therm
working_AreaTube_render.set(eqnbank_working_latex["Area of a Tube"])
working_Itube_render.set(eqnbank_working_latex["Moment of Inertia of a Tube"])
working_Compatability1_render.set(eqnbank_working_latex["Compatability Equation 1"])
working_Compatability2_render.set(eqnbank_working_latex["Compatability Equation 2"])
working_eqns_solver = [eqnbank_working_solver[key] for key in eqns_keys]

```

```

temp_working_equations_solver = "#".join(working_eqns_solver)
temp_working_equations_solver = temp_working_equations_solver.replace("Eq", "Wrap_c
temp_working_equations_solver = temp_working_equations_solver.replace("E", "E_clash
temp_working_equations_solver = temp_working_equations_solver.replace("I", "I_clash
temp_working_equations_solver = temp_working_equations_solver.replace("N", "N_clash
temp_working_equations_solver = temp_working_equations_solver.replace("Wrap_clash"
working_eqns_solver = temp_working_equations_solver.split("#")

#working_eqns_solver=[]
#for j in working_eqns_solver_pre:
#    temp=j.split(",")
#    temp2=temp.replace("I", "I_clash")
#    temp3=temp2.replace("E", "E_clash")
#    working_eqns_solver.append(temp3)

working_syms = [symbank_working[key] for key in eqns_keys]
mystring_working_eqns = "#".join(working_eqns_latex)
mystring_working_eqns = mystring_working_eqns.replace("*", "\\times")
feedback_syms.set(working_syms)
working_equations_solver.set(working_eqns_solver)

working_syms_only=[]
for j in working_syms:
    temp=j.split(",")
    for k in temp:
        try:
            float(eval(k))
        except:
            temp2=k.replace("I", "I_clash")
            temp3=temp2.replace("E", "E_clash")
            temp4=temp3.replace("N", "N_clash")
            working_syms_only.append(temp4)
working_syms_only=list(dict.fromkeys(working_syms_only))
working_symbols.set(working_syms_only)

return [
    ui.markdown(mystring_working_eqns),
    ui.tags.script(
        "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
    )
]

```



```

@output
@render.ui
def dyn_ui_nav():

    tab_Instructions = ui.nav(
        "Instructions",ui.markdown("Please choose the equations you would like to use
    )

    tab_StaticsSumFy = ui.nav(
        str(StaticsSumFy.inline_math),
        #ui.markdown(working_SumFy_string()),
        ui.input_numeric("NumForcesY","How many terms do you want?",value=NumForce
        ui.input_text("F1y","\ (F_{y_1}=\)", value=F1y(),placeholder="Please type i
        ui.input_text("F2y","\ (F_{y_2}=\)", value=F2y(),placeholder="Please type i
        ui.panel_conditional("input.NumForcesY>=3", ui.input_text("F3y","\ (F_{y_3}
        ui.panel_conditional("input.NumForcesY>=4", ui.input_text("F4y","\ (F_{y_4}
        ui.panel_conditional("input.NumForcesY>=5", ui.input_text("F5y","\ (F_{y_5}
    )

    tab_StaticsSumFx = ui.nav(
        str(StaticsSumFx.inline_math),
        #ui.markdown(working_SumFx_string()),
        ui.input_numeric("NumForcesX","How many terms do you want?",value=NumForce
        ui.input_text("F1x","\ (F_{x_1}=\)", value=F1x(),placeholder="Please type i
        ui.input_text("F2x","\ (F_{x_2}=\)", value=F2x(),placeholder="Please type i
        ui.panel_conditional("input.NumForcesX>=3", ui.input_text("F3x","\ (F_{x_3}
        ui.panel_conditional("input.NumForcesX>=4", ui.input_text("F4x","\ (F_{x_4}
        ui.panel_conditional("input.NumForcesX>=5", ui.input_text("F5x","\ (F_{x_5}
    )

    tab_StaticsSumM = ui.nav(
        str(StaticsSumM.inline_math),
        #ui.markdown(working_SumM_string()),
        ui.input_numeric("NumMoments","How many terms do you want?",value=NumMomen
        ui.input_text("M1","\ (M_1=\)", value=M1(),placeholder="Please type in vari
        ui.input_text("M2","\ (M_2=\)", value=M2(),placeholder="Please type in vari
        ui.panel_conditional("input.NumMoments>=3", ui.input_text("M3","\ (M_3=\)",
        ui.panel_conditional("input.NumMoments>=4", ui.input_text("M4","\ (M_4=\)",
        ui.panel_conditional("input.NumMoments>=5", ui.input_text("M5","\ (M_5=\)",
    )

```

```

tab_StressEqn = ui.nav(
    str(StressEqn.inline_math),
    #ui.markdown(working_StressEqn_string()),
    ui.input_text("sigma","\(\sigma\)", value=axial_stress_sigma(),placeholder="Please type"),
    ui.input_text("force","\(F\)", value=axial_stress_force(),placeholder="Please type"),
    ui.input_text("area","\(A\)", value=axial_stress_area(),placeholder="Please type")
)

tab_BendingStress = ui.nav(
    str(BendingStress.inline_math),
    #ui.markdown(working_BendingStress_string()),
    ui.input_text("bendingstress_sigma_b","\(\sigma_b\)", value=bending_stress_sigma_b(),placeholder="Please type"),
    ui.input_text("bendingstress_M","\(M\)", value=bending_stress_M(), placeholder="Please type"),
    ui.input_text("bendingstress_y","\(y\)", value=bending_stress_y(), placeholder="Please type"),
    ui.input_text("bendingstress_I","\(I\)", value= bending_stress_I(), placeholder="Please type")
)

tab_AxialDeform = ui.nav(
    str(AxialDeform.inline_math),
    #ui.markdown(working_AxialDeform_string()),
    ui.input_text("axial_delta_l","\(\delta_l\)", value=axial_delta_l(), placeholder="Please type"),
    ui.input_text("axial_P","\(P\)", value=axial_P(), placeholder="Please type"),
    ui.input_text("axial_L","\(L\)", value=axial_L(), placeholder="Please type"),
    ui.input_text("axial_A","\(A\)", value=axial_A(), placeholder="Please type"),
    ui.input_text("axial_E","\(E\)", value=axial_E(), placeholder="Please type")
)

tab_ThermalDeform = ui.nav(
    str(ThermalDeform.inline_math),
    #ui.markdown(working_ThermalDeform_string()),
    ui.input_text("thermal_delta_t","\(\delta_t\)", value=thermal_delta_t(), placeholder="Please type"),
    ui.input_text("thermal_alpha","\(\alpha\)", value=thermal_alpha(), placeholder="Please type"),
    ui.input_text("thermal_Delta_T","\(\Delta T\)", value=thermal_Delta_T(), placeholder="Please type"),
    ui.input_text("thermal_L","\(L\)", value=thermal_L(), placeholder="Please type")
)

tab_AreaTube = ui.nav(
    str(AreaTube.inline_math),
    #ui.markdown(working_AreaTube_string()),
    ui.input_text("A_tube","\(A_{tube}=\)", value=area_tube_A_tube(), placeholder="Please type"),
    ui.input_text("Ar_o","\(r_o=\)", value=area_tube_Ar_o(), placeholder="Please type")
)

```

```

        ui.input_text("Ar_i","\r_i\)", value=area_tube_Ar_i(), placeholder="Please
    )

tab_ITube = ui.nav(
    str(ITube.inline_math),
    #ui.markdown(working_Itube_string()),
    ui.input_text("I_tube","\(I_{tube}=\)", value=I_tube_I_tube(), placeholder=
    ui.input_text("Ir_o","\r_o=\)", value=I_tube_Ir_o(), placeholder="Please
    ui.input_text("Ir_i","\r_i\)", value=i_tube_Ir_i(), placeholder="Please t
    )

tab_Compatability1 = ui.nav(
    str(Compatability1.inline_math),
    #ui.markdown(working_Compatability1_string()),
    ui.input_numeric("Compatability1_NumLHS","How many 'a' terms do you want?"
    ui.input_numeric("Compatability1_NumRHS","How many 'b' terms do you want?"
    ui.input_text("a_1","\(a_1=\)", value=Compatability1_a_1(),placeholder="Pl
    ui.panel_conditional("input.Compatability1_NumLHS>=2",ui.input_text("a_2",
    ui.panel_conditional("input.Compatability1_NumLHS>=3", ui.input_text("a_3"
    ui.panel_conditional("input.Compatability1_NumLHS>=4", ui.input_text("a_4"
    ui.panel_conditional("input.Compatability1_NumLHS>=5", ui.input_text("a_5"
    ui.input_text("b_1","\(b_1=\)", value=Compatability1_b_1(),placeholder="Pl
    ui.panel_conditional("input.Compatability1_NumRHS>=2",ui.input_text("b_2",
    ui.panel_conditional("input.Compatability1_NumRHS>=3",ui.input_text("b_3",
    ui.panel_conditional("input.Compatability1_NumRHS>=4",ui.input_text("b_4",
    ui.panel_conditional("input.Compatability1_NumRHS>=5",ui.input_text("b_5",
    )

tab_Compatability2 = ui.nav(
    str(Compatability2.inline_math),
    #ui.markdown(working_Compatability2_string()),
    ui.input_numeric("Compatability2_NumLHS","How many 'c' terms do you want?"
    ui.input_numeric("Compatability2_NumRHS","How many 'd' terms do you want?"
    ui.input_text("c_1","\(c_1=\)", value=Compatability2_c_1(),placeholder="Pl
    ui.panel_conditional("input.Compatability2_NumLHS>=2",ui.input_text("c_2",
    ui.panel_conditional("input.Compatability2_NumLHS>=3", ui.input_text("c_3"
    ui.panel_conditional("input.Compatability2_NumLHS>=4", ui.input_text("c_4"
    ui.panel_conditional("input.Compatability2_NumLHS>=5", ui.input_text("c_5"
    ui.input_text("d_1","\(d_1=\)", value=Compatability2_d_1(),placeholder="Pl
    ui.panel_conditional("input.Compatability2_NumRHS>=2",ui.input_text("d_2",
    ui.panel_conditional("input.Compatability2_NumRHS>=3",ui.input_text("d_3",

```

```

        ui.panel_conditional("input.Compatability2_NumRHS>=4",ui.input_text("d_4",
        ui.panel_conditional("input.Compatability2_NumRHS>=5",ui.input_text("d_5",
        )

tab_bank = {
    StaticsSumFx.name: tab_StaticsSumFx,
    StaticsSumFy.name: tab_StaticsSumFy,
    StaticsSumM.name: tab_StaticsSumM,
    StressEqn.name: tab_StressEqn,
    BendingStress.name: tab_BendingStress,
    AxialDeform.name: tab_AxialDeform,
    ThermalDeform.name: tab_ThermalDeform,
    AreaTube.name: tab_AreaTube,
    ITube.name: tab_ITube,
    Compatability1.name: tab_Compatability1,
    Compatability2.name: tab_Compatability2,
}

eqns_keys = input.selected_eqns()
tabs = [tab_bank[key] for key in eqns_keys]
tabs.insert(0,tab_Instructions)
equations = ui.navset_tab_card(*tabs,id="mytab",selected=active_eqn_tab())

return [equations,
        ui.tags.script(
            "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
        ),]

@output
@render.ui
def ui_equation_bookkeeping():
    req(working_equations_solver())
    num_working_equations=len(working_equations_solver())
    num_working_symbols=len(working_symbols())
    string_working_symbols= "\\(\\("+ "\\),\\(\\("".join(working_symbols())+"\\)\\)"
    string_working_symbols=string_working_symbols.replace("N_clash","N")
    string_working_symbols=string_working_symbols.replace("I_clash","I")
    string_working_symbols=string_working_symbols.replace("E_clash","E")
    string_working_symbols=string_working_symbols.replace("delta","\\delta")
    string_working_symbols=string_working_symbols.replace("Delta","\\Delta")
    string_working_symbols=string_working_symbols.replace("sigma","\\sigma")
    return [ui.markdown(f"Your equation-solver set up currently has **{num_working_equations} equations")]
```

```

        ui.input_action_button(
            "solveEquations", "Solve Equations", class_="btn-success", width="240p
        ui.tags.script(
            "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
        ])

@output
@render.ui
@reactive.event(input.solveEquations)
def ui_solutions():
    for j in working_symbols():
        j=Symbol(j)
    print(working_equations_solver())
    print(working_symbols())
    my_solver_equations=[]
    for m in working_equations_solver():
        m=parse_expr(m)
    solve_eqns = solve(working_equations_solver(),working_symbols(),dict=True)
    answers=[]
    for k in working_symbols():
        try:
            temp=solve_eqns[0][parse_expr(k)]
            temp2="$$"+k+"="+f'{temp:.2f}'+ "$$"
            answers.append(temp2)
        except:
            pass
    mystring_answers="".join(answers)
    mystring_answers=mystring_answers.replace("pi","\pi")
    mystring_answers=mystring_answers.replace("delta","\delta")
    mystring_answers=mystring_answers.replace("Delta","\Delta")
    mystring_answers=mystring_answers.replace("sigma","\sigma")
    mystring_answers=mystring_answers.replace("E_clash","E")
    mystring_answers=mystring_answers.replace("I_clash","I")
    mystring_answers=mystring_answers.replace("N_clash","N")
    #feedback_solns.set(mystring_answers)
    return [ui.markdown(f"Your solution is {mystring_answers}"),
            ui.input_text("answer","Answer:",placeholder="Please type in your answer"),
            ui.input_action_button("feedback", "Check answer and show feedback"),
            ui.tags.script(
                "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
            )]

```

```

#@reactive.Effect
#def _():

#    active_eqn_tab.set(input.mytab())

@reactive.Effect
def _():

    input.selected_eqns()
    active_eqn_tab.set(input.mytab())

    #working_SumFx_render():
    #working_SumFy_render()
    #working_SumM_render()
    #working_StressEqn_render()
    #working_BendingStress_render()
    #working_AxialDeform_render()
    #working_ThermalDeform_render()
    #working_AreaTube_render()
    #working_Itube_render()
    #working_Compatability1_render()
    #working_Compatability2_render()

    with reactive.isolate():
        if "Equilibrium Forces in Y" in input.selected_eqns():
            NumForcesY.set(input.NumForcesY())
            F1y.set(input.F1y())
            F2y.set(input.F2y())
            F3y.set(input.F3y())
            F4y.set(input.F4y())
            F5y.set(input.F5y())
            working_SumFy_string.set(str(working_SumFy_render()))
        else:
            pass

        if "Equilibrium Forces in X" in input.selected_eqns():
            NumForcesX.set(input.NumForcesX())
            F1x.set(input.F1x())
            F2x.set(input.F2x())

```

```

        F3x.set(input.F3x())
        F4x.set(input.F4x())
        F5x.set(input.F5x())
        working_SumFx_string.set(str(working_SumFx_render()))
    else:
        pass

    if "Equilibrium Moments about 0" in input.selected_eqns():
        NumMoments.set(input.NumMoments())
        M1.set(input.M1())
        M2.set(input.M2())
        M3.set(input.M3())
        M4.set(input.M4())
        M5.set(input.M5())
        working_SumM_string.set(str(working_SumM_render()))
    else:
        pass

    if "Stress Equation" in input.selected_eqns():
        axial_stress_sigma.set(input.sigma())
        axial_stress_force.set(input.force())
        axial_stress_area.set(input.area())
        working_StressEqn_string.set(str(working_StressEqn_render()))
    else:
        pass

    if "Axial Deformation by Force" in input.selected_eqns():
        axial_delta_l.set(input.axial_delta_l())
        axial_P.set(input.axial_P())
        axial_L.set(input.axial_L())
        axial_A.set(input.axial_A())
        axial_E.set(input.axial_E())
        working_AxialDeform_string.set(str(working_AxialDeform_render()))
    else:
        pass

    if "Axial Deformation by Thermal" in input.selected_eqns():
        thermal_delta_t.set(input.thermal_delta_t())
        thermal_alpha.set(input.thermal_alpha())
        thermal_Delta_T.set(input.thermal_Delta_T())
        thermal_L.set(input.thermal_L())

```

```

        working_ThermalDeform_string.set(str(working_ThermalDeform_render()))
    else:
        pass

    if "Area of a Tube" in input.selected_eqns():
        area_tube_A_tube.set(input.A_tube())
        area_tube_Ar_o.set(input.Ar_o())
        area_tube_Ar_i.set(input.Ar_i())
        working_AreaTube_string.set(str(working_AreaTube_render()))
    else:
        pass

    if "Moment of Inertia of a Tube" in input.selected_eqns():
        I_tube_I_tube.set(input.I_tube())
        I_tube_Ir_o.set(input.Ir_o())
        I_tube_Ir_i.set(input.Ir_i())
        working_Itube_string.set(str(working_Itube_render()))
    else:
        pass

    if "Bending Stress from a Moment" in input.selected_eqns():
        bending_stress_sigma.set(input.bendingstress_sigma_b())
        bending_stress_M.set(input.bendingstress_M())
        bending_stress_y.set(input.bendingstress_y())
        bending_stress_I.set(input.bendingstress_I())
        working_BendingStress_string.set(str(working_BendingStress_render()))
    else:
        pass

    if "Compatability Equation 1" in input.selected_eqns():
        Compatability1_NumLHS.set(input.Compatability1_NumLHS())
        Compatability1_NumRHS.set(input.Compatability1_NumRHS())
        Compatability1_a_1.set(input.a_1())
        Compatability1_a_2.set(input.a_2())
        Compatability1_a_3.set(input.a_3())
        Compatability1_a_4.set(input.a_4())
        Compatability1_a_5.set(input.a_5())
        Compatability1_b_1.set(input.b_1())
        Compatability1_b_2.set(input.b_2())
        Compatability1_b_3.set(input.b_3())
        Compatability1_b_4.set(input.b_4())

```





```
feedback_message, ui.tags.script(
    "if (window.MathJax) MathJax.Hub.Queue(['Typeset', MathJax.Hub]);"
),
title="Feedback on your solution",
easy_close=True,
footer=None,
)
ui.modal_show(m)

app = App(app_ui, server)
```

# 1 Summary

In summary, this book has no content whatsoever.

## References