

Linear Algebra Done Right

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3 Linear Map

3.A The Vector Space of Linear Maps

1.

Proof. If T is linear, then $T(0, 0, 0) = 0$ and therefore $b = 0$. Meanwhile, $T(2, 2, 2) = 2T(1, 1, 1)$ implies $12 + 8c = 12 + 2c$. Hence, $c = 0$. The proof of the converse part is trivial. \square

3.

Proof. Let e_i be the i -th vector in the standard base of \mathbb{F}^n and suppose that $Te_i = \sum_{j=1}^n A_{1,j}e_j$. Then for $x = (x_1, \dots, x_n)^T \in \mathbb{F}^n$,

$$Tx = T\left(\sum_{i=1}^n x_i e_i\right) = \sum_{i=1}^n x_i Te_i = \sum_{i=1}^n x_i \sum_{j=1}^n A_{j,i} e_j = \sum_{j=1}^n \left(\sum_{i=1}^n A_{j,i} x_i\right) e_j.$$

\square

5.

Proof. Too lengthy to write it down... \square

7.

Proof. Let $\{x_0\}$ be a basis of V and λ be a scalar such that $Tx_0 = \lambda x_0$. By the linearity of T , for every $x = kx_0$ in V , $Tx = kTx_0 = k\lambda x_0 = \lambda(kx_0) = \lambda x$. \square

9.

Solution. From the additivity condition we can derive that $\varphi(kz) = k\varphi(z)$ for any $k \in \mathbb{Q}$. Hence we can try some functions where $\varphi(iz) = i\varphi(z)$ fails. It turns out that $\varphi(z) = \text{Im}(z)$ is one of the maps required. \square

11.

Proof. Let $\{\alpha_1, \dots, \alpha_p\}$ and $\{\alpha_1, \dots, \alpha_p, \beta_1, \dots, \beta_q\}$ be bases of U and V respectively. Then the linear map which maps α_i to $T\alpha_i$ and maps β to 0. Clear that it is the desired linear map. \square

13.

Proof. Suppose that v_k is in the span of the other vectors and let $w_i = 0$ for each $i \neq k$ and $w_k \neq 0$. No $T \in \mathcal{L}(V, W)$ can map v_i to w_i since the linearity of T would force w_k to be 0, leading to a contradiction. \square

3.B Null Spaces and Ranges

2.

Proof. Since S maps every vector of V into the null space of T , the map TS is the zero map. Hence $(ST)^2 = S(TS)T = 0$. \square

4.

Proof. Suppose $S, T \in \mathcal{L}(\mathbb{R}^5, \mathbb{R}^4)$ maps and only maps e_1, e_2, e_3 and e_3, e_4, e_5 to the zero vector respectively. Then $e_1, e_2, e_4, e_5 \notin \text{null}(S + T)$, implying that $\dim \text{null}(S + T) < 2$. Hence $\{T \in \mathcal{L}(\mathbb{R}^5, \mathbb{R}^4) : \dim \text{null } T > 2\}$ is not a subspace of $\mathcal{L}(\mathbb{R}^5, \mathbb{R}^4)$. \square

6.

Proof. It follows immediately from the rank-nullity theorem and the fact that $\dim \text{null } T$ and $\dim \text{range } T$ are integers. \square

8.

Proof. Let $\{w_1, \dots, w_m\}$ be a basis of W and $S, T \in \mathcal{L}(V, W)$ be two linear maps such that $\text{range } S = \text{span}(w_1)$ and $\text{range } T = \text{span}(w_2, \dots, w_n)$. Clear that $\text{range}(S + T) = W$. Hence, the set described is not a subspace of $\mathcal{L}(V, W)$. \square

10.

Proof. For every $y \in \text{range } T$ there exists some $x = \sum x_i v_i \in V$ such that

$$y = Ty = T \left(\sum_{i=1}^n x_i v_i \right) = \sum_{i=1}^n x_i T v_i.$$

Hence, $\text{range } T = \text{span}(T v_1, \dots, T v_n)$. \square

12. For readers who familiar with the orbit-stabilizer theorem or just the (group) homomorphism, the proof should be straightforward.

Proof. For every nonzero y in $\text{range } T$, there exists some $x \in V$ such that $Tx = y$. For each $y \neq 0$, we choose one such x , put them all together and put 0 into them to get U . By the construction, clear that $T(U) = \text{range } T$ and $U \cap \text{null } T = \{0\}$. \square

14.

Proof. By the rank-nullity theorem,

$$\dim \text{null } T + \dim \text{range } T = 8 \quad \Rightarrow \quad \dim \text{range } T = 5 = \dim \mathbb{R}^5.$$

Hence, $\text{range } T = \mathbb{R}^5$ and therefore T is surjective. \square

16. Actually, the cosets of the kernel partition the whole space.

Proof. Let $\{v_1, \dots, v_n\}$ be a basis of $\text{range } T$ and $Tu_i = v_i$ for $i = 1, 2, \dots, n$. Denote $\text{span}(u_1, \dots, u_n)$ by U . We now prove that $V = U + \text{null } T$. For every $x \in V$, suppose that $Tx = y = \sum y_i v_i$ and $\tilde{x} = \sum y_i u_i$. Note that $\tilde{x} \in U$ and $T(x - \tilde{x}) = Tx - T\tilde{x} = 0$, i.e., $x - \tilde{x} \in \text{null } T$. Hence, $V = U + \text{null } T$. As both of U and $\text{null } T$ are finite-dimensional, so is V . \square

18.

Proof. By the rank-nullity theorem, clear that $\dim V \geq \dim \text{range } T = \dim W$ if there exists some surjective $T \in \mathcal{L}(V, W)$.

Assume that $\dim V \geq \dim W$ and let $\{v_1, \dots, v_n\}$ and $\{w_1, \dots, w_m\}$ be bases of V and W respectively. Then the linear map which maps v_i to w_i for each $1 \leq i \leq m$ is surjective. \square

20.

Proof. If T is injective, then for every $y \in \text{range } T$, there exists exactly one $x \in V$ such that $y = Tx$. Let S be the map which maps y to such x . It is linear since for every $y_1, y_2 \in \text{range } T$ and scalar a, b , supposing $Sy_i = x_i$,

$$T(ax_1 + bx_2) = aTx_1 + bTx_2 = ay_1 + by_2.$$

implying $S(ay_1 + by_2) = ax_1 + bx_2 = aSy_1 + bSy_2$. For every $x \in V$, $(ST)x = S(Tx) = x$.

Suppose there exists some $S \in \mathcal{L}(W, V)$ such that $ST = I$. Then

$$Tx_1 = Tx_2 \quad \Rightarrow \quad STx_1 = STx_2 \quad \Rightarrow \quad x_1 = x_2.$$

Hence, T is injective. \square

22.

Proof. Let \tilde{T} be the restriction of T to $\text{null } ST$. It is still a linear map since $\text{null } ST$ is a subspace of U . Note that $x \in \text{null } ST$ iff $(ST)x = 0$ iff $Tx \in \text{null } S$. Hence, $\text{range } \tilde{T} \subset \text{null } S$. Thus, by the rank-nullity theorem,

$$\dim \text{range } \tilde{T} \leq \dim \text{null } S \quad \Rightarrow \quad \dim \text{null } ST - \dim \text{null } \tilde{T} \leq \dim \text{null } S.$$

Since $\text{null } \tilde{T} \leq \text{null } T$, this implies $\dim \text{null } ST \leq \dim \text{null } S + \dim \text{null } T$. \square

24.

Proof. If there exists $S \in \mathcal{L}(W, W)$ such that $T_2 = ST_1$, then $\text{null } T_2 = \text{null } ST_1$. Hence for every $x \in \text{null } T_1$, as $S(T_1x) = S0 = 0$, $x \in \text{null } T_2$. Therefore, $\text{null } T_1 \subset \text{null } T_2$.

Now we suppose $\text{null } T_1 \subset \text{null } T_2$ and construct S . Note that all we concerns is its behavior on some basis of $\text{range } T_1$. Let $\{w_1, \dots, w_n\}$ be a basis of $\text{range } T_1$ and $T_1v_i = w_i$ for $i = 1, \dots, n$. For each $x \in V$, let $U_x = \{x + y : y \in \text{null } T_2\}$ and $Sw_k = T_2x$ as long as $v_k \in U_x$. It can be verified that S is well-defined and does satisfy the requirement as long as $\text{null } T_1 \subset \text{null } T_2$. \square