

ECE 351-51

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# Lab 11

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*Submitted By :*  
Kennedy Beach

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## 1 Introduction

The purpose of this lab was to use Python functions and Christopher Felton's function to analyze a discrete system.

## 2 Equations

The following causal function was provided:

$$y[k] = 2x[k] - 40x[k-1] + 10y[k-1] - 16y[k-2]$$

The steps to find the transfer function are described below:

$$\begin{aligned} y[k] - 10y[k-1] + 16y[k-2] &= 2x[k] - 40x[k-1] \\ Y(z) - 10z^{-1}Y(z) + 16z^{-2}Y(z) &= 2X(z) - 40z^{-1}X(z) \\ Y(z)(1 - 10z^{-1} + 16z^{-2}) &= X(z)(2 - 40z^{-1}) \\ \frac{Y(z)}{X(z)} &= \frac{2 - 40z^{-1}}{(1 - 10z^{-1} + 16z^{-2})} \\ H(z) &= \frac{2z(z - 20)}{z^2 - 10z + 16} \end{aligned}$$

The impulse response was found by using partial fraction expansion on the derived transfer function:

$$\begin{aligned} \frac{H(z)}{z} &= \frac{2(z - 2)}{z^2 - 10z + 16} \\ \frac{H(z)}{z} &= \frac{A}{z - 8} + \frac{B}{z - 2} \\ A &= \frac{2(z - 20)}{z - 8} \Big|_{z=2} = 6 \\ B &= \frac{2(z - 20)}{z - 2} \Big|_{z=8} = -4 \\ \frac{H(z)}{z} &= \frac{6}{z - 8} - \frac{4}{z - 2} \\ Z^{-1}\left\{\frac{H(z)}{z}\right\} &= h[k] = [6(-8)^k - 4(-2)^k]u[k] \end{aligned}$$

### 3 Methodology

The first part was to verify the partial fraction results using `scipy.signal.residuez()`. This is seen below and the output is seen in the Results section.

```

1 import numpy as np
2 import matplotlib.pyplot as plt
3 import scipy.signal as sig
4 import control
5 import control as con
6
7 num = [2, -40]
8 den = [1, -10, 16]
9
10 r, p, k = sig.residuez(num, den)
11
12 print("Task 3 Residue Results:\n r = {}\n p={}\n k = {}\n".format(r
    ,p,k))

```

Listing 1: `scipy.signal.residuez()`

The Z-plane function provided by Felton was used to create the pole-zero plot for the transfer function.

```

1 def zplane(b,a,filename=None):
2     """Plot the complex z-plane given a transfer function.
3     """
4     import numpy as np
5     import matplotlib.pyplot as plt
6     from matplotlib import patches
7
8     # get a figure/plot
9     ax = plt.subplot(111)
10    # create the unit circle
11    uc = patches.Circle((0,0), radius=1, fill=False,
12                        color='black', ls='dashed')
13    ax.add_patch(uc)
14    # The coefficients are less than 1, normalize the coefficients
15    if np.max(b) > 1:
16        kn = np.max(b)
17        b = np.array(b)/float(kn)
18    else:
19        kn = 1
20    if np.max(a) > 1:
21        kd = np.max(a)
22        a = np.array(a)/float(kd)
23    else:
24        kd = 1
25

```

```

26     # Get the poles and zeros
27     p = np.roots(a)
28     z = np.roots(b)
29     k = kn/float(kd)
30
31     # Plot the zeros and set marker properties
32     t1 = plt.plot(z.real, z.imag, 'o', ms=10, label='Zeros')
33     plt.setp( t1, markersize=10.0, markeredgewidth=1.0)
34     # Plot the poles and set marker properties
35     t2 = plt.plot(p.real, p.imag, 'x', ms=10, label='Poles')
36     plt.setp( t2, markersize=12.0, markeredgewidth=3.0)
37     ax.spines['left'].set_position('center')
38     ax.spines['bottom'].set_position('center')
39     ax.spines['right'].set_visible(False)
40     ax.spines['top'].set_visible(False)
41
42     plt.legend()
43     # set the ticks
44     # r = 1.5; plt.axis('scaled'); plt.axis([-r, r, -r, r])
45     # ticks = [-1, -.5, .5, 1]; plt.xticks(ticks); plt.yticks(ticks
46     )
47     if filename is None:
48         plt.show()
49     else:
50         plt.savefig(filename)
51
52     return z, p, k
53
54 z, p, k = zplane(num, den)
55 print('Zeros = ', z, '\nPoles = ', p)

```

Listing 2: Z-plane function

The last part involved plotting the magnitude and phase responses of the transfer function using `scipy.signal.freqz()`. Since the output of `scipy.signal.freqz()` was in Hertz, I converted the magnitude of the output to decibels.

```

1 w, h = sig.freqz(num, den, whole=True)
2
3 plt.figure(figsize = (10, 7))
4 plt.subplot(2, 1, 1)
5 plt.ylabel(' |HU+FFD| (dB) ')
6 plt.semilogx(w, 20*np.log10(np.abs(h)))
7 plt.grid()
8 plt.subtitle('Task 5 - Bode Plot of H(z) via sig.freqz() function')
9 plt.subplot(2, 1, 2)
10 plt.ylabel(' /_HU+FFD ')
11 plt.semilogx(w, np.angle(h))

```

```
12 plt.grid()
```

Listing 3: Magnitude and Phase Responses

## 4 Results

```
Task 3 Residue Results:  
r = [ 6. -4.]  
p=[2. 8.]  
k = []
```

Figure 1: Residue Output

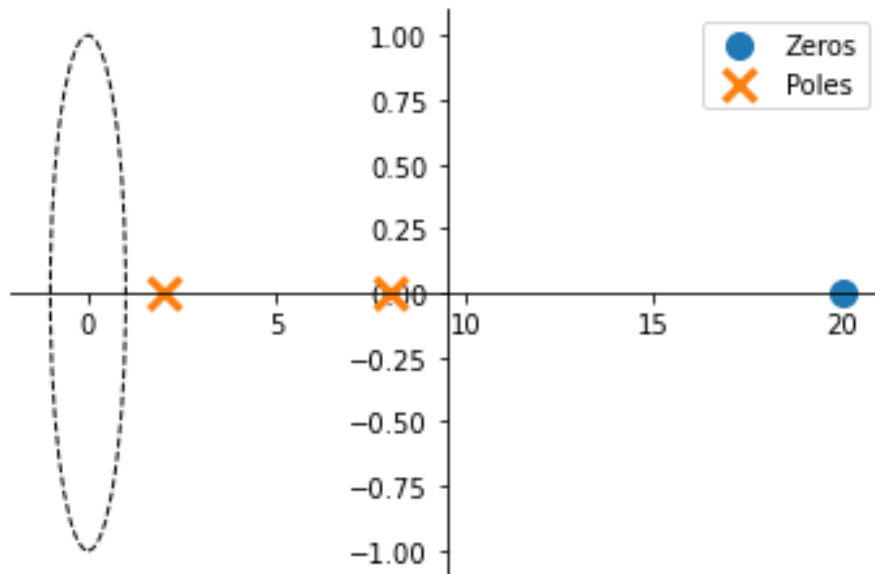


Figure 2: Z-plane Function Output

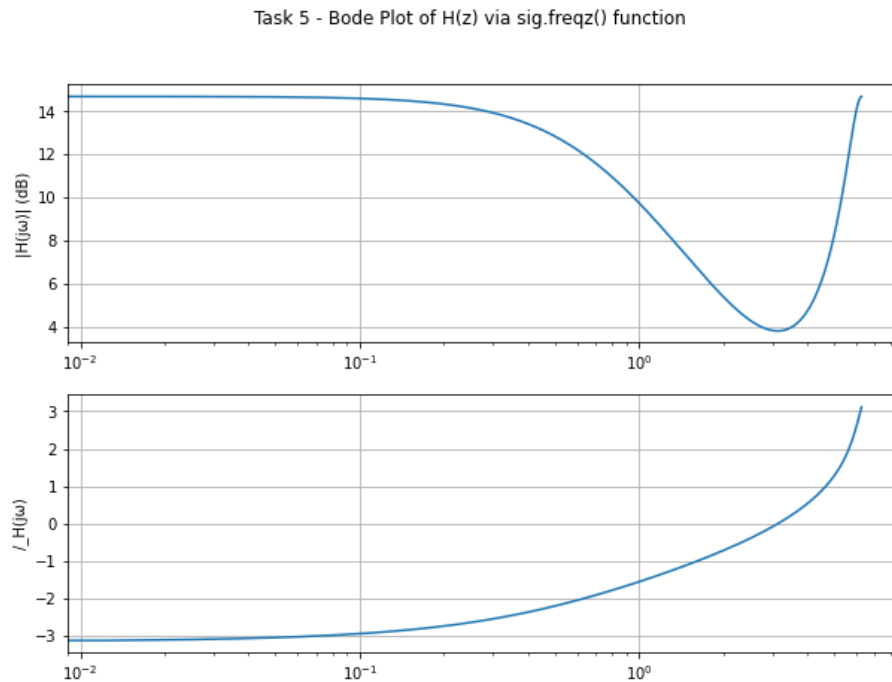


Figure 3: Bode Plot using `scipy.signal.freqz()`

## 5 Error Analysis

There may be some potential errors with the bode plot since it is was not checked to make sure it is correct.

## 6 Questions

1. Looking at the plot generated in Task 4, is  $H(z)$  stable? Explain why or why not.

$H(z)$  is not stable since the poles and zeros are not within the unit circle.

2. Leave any feedback on the clarity of the expectations, instructions, and deliverables.

Everything was clear on what needed to be done and turned in.

## 7 Conclusion

This lab delved into analyzing systems using the Z-domain and more of Python's capabilities. The Python and L<sup>A</sup>T<sub>E</sub>X code are seen in [https://github.com/Eniac618/ECE351\\_Code](https://github.com/Eniac618/ECE351_Code) and [https://github.com/Eniac618/ECE351\\_Reports](https://github.com/Eniac618/ECE351_Reports) respectively.