Pathfinding Algorithm Practice

A* algorithm practice: try to solve the two problems introduced in the following, example solution can be found from the Github repo: https://github.com/Enigma-li/ILP24-25 practice.

Task One - Solving the Shortest Path in a Maze

Problem Description:

Imagine you have a 2D maze represented as a grid, where some cells are walls (impassable), and others are open paths. You need to find the shortest path from a start cell to a goal cell while avoiding the walls. You'll guide your students through solving this problem using the A* algorithm.

Step-by-Step Tutorial:

1. Maze Representation:

Start by representing the maze as a 2D grid, where each cell can be either:

- Open path (denoted as '.')
- Wall (denoted as '#')
- Start point (denoted as 'S')
- Goal point (denoted as 'G')

2. A* Algorithm Implementation:

Teach your students how to implement the A* algorithm. This algorithm requires the following components:

- Priority Queue (Min Heap) for open nodes
- Closed list to track explored nodes
- Evaluation function (f-cost) for each cell

3. Pseudocode:

Provide a pseudocode for the A* algorithm. Here's a simple example:

function AStar(maze, start, goal):

```
openSet = {start}
cameFrom = {}
gScore = {cell: infinity for cell in maze}
gScore[start] = 0
fScore = {cell: infinity for cell in maze}
fScore[start] = heuristic(start, goal)
while openSet is not empty:
  current = cell in openSet with lowest fScore
  if current == goal:
    return reconstructPath(cameFrom, current)
  openSet.remove(current)
  for neighbor in getNeighbors(current):
    tentativeGScore = gScore[current] + distance(current, neighbor)
    if tentativeGScore < gScore[neighbor]:
      cameFrom[neighbor] = current
      gScore[neighbor] = tentativeGScore
      fScore[neighbor] = gScore[neighbor] + heuristic(neighbor, goal)
      if neighbor not in openSet:
         openSet.add(neighbor)
return "No path found"
```

4. Heuristic Function:

Explain what a heuristic function is and provide an example. Common heuristics include Manhattan distance, Euclidean distance, and diagonal distance.

5. Visualization:

Use a graphical tool or code to visualize the A* algorithm as it progresses through the maze. This will help students understand how the algorithm explores different paths. For Jave, just print the results maze.

6. Implementation:

Ask students to implement the A* algorithm to find the shortest path from 'S' to 'G' in a given maze. They can use the pseudocode as a guideline.

7. Testing:

Provide different maze scenarios for students to test their A* algorithm implementation. Ensure that they consider edge cases, such as mazes with no solution or mazes with multiple paths.

8. Performance Analysis:

Discuss the time and space complexity of the A* algorithm, as well as its advantages and limitations. Help students understand when to use A* and when to consider alternative algorithms.

Sample Code: download from GitHub.

- Task: implement the find shortest path function

Example Input:

Мар:

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Task Two (Extension) - Solving the 15-puzzle problem

The 15-puzzle, also known as the "Game of Fifteen," is a sliding puzzle that consists of a 4x4 grid with 15 numbered tiles and one empty space. The objective of the game is to rearrange the tiles by sliding them into the empty space to achieve a specific goal configuration, typically with the tiles arranged in ascending order, starting from the top-left corner.

The rules for the 15-puzzle are as follows:

- You can only slide a tile into the empty space, and you can't move tiles diagonally.
- The puzzle is typically solved when the tiles are arranged in ascending order from left to right, top to bottom, with the empty space in the bottom-right corner.
- The tiles can be shuffled into various configurations, making it a challenging puzzle.

The 15-puzzle is a classic example of a sliding puzzle and is often used as a recreational puzzle game and a simple problem for teaching algorithms like search and heuristic methods, such as the A* algorithm, to find an optimal solution. Solving the 15-puzzle can be done through a sequence of moves that minimize a specific cost function or heuristic.

Example:

Star	t Sta	itus:			Goal Status:									
5	1	2	4		1	2	3	4						
9	6	3	8		5	6	7	8						
13	15	10	11		9	10	11	12						
14	0	7	12		13	14	15	0						

General Tips:

You can treat the status after one movement as a grid position, from the start status, you can move tiles to achieve the goal status.

g function: calculate the moving cost from the start status to the current status

h function: calculate the number of misplaced tiles

Sample Code: download from GitHub.

- Task: implement the find shortest path function.