Chapter 7 Symmetric Matrices and Quadratic Forms

Section 7.1: Diagonalization of Symmetric Matrices

Section 7.2: Quadratic Forms

• A symmetric matrix is a matrix A such that $A^T = A$.

Such a matrix is necessarily square.

 Its main diagonal entries are arbitrary, but its other entries occur in pairs—on opposite sides of the main diagonal.

• **Theorem:** If A is symmetric, then any two eigenvectors from different eigenspaces are orthogonal.

An $n \times n$ matrix A is said to be **orthogonally diagonalizable** if there are an orthogonal matrix P (with $P^{-1} = P^{T}$) and a diagonal matrix D such that

$$A = PDP^{T} = PDP^{-1} \tag{1}$$

Such a diagonalization requires *n* linearly independent and orthonormal eigenvectors.

$$A = PDP^{T} = PDP^{-1} \tag{1}$$

- When is this possible?
- If A is orthogonally diagonalizable as in (1), then

$$A^{T} = (PDP^{T})^{T} = P^{TT}D^{T}P^{T} = PDP^{T} = A$$

Thus A is symmetric.

• Theorem: An $n \times n$ matrix A is orthogonally diagonalizable if and only if A is symmetric matrix.

• Example: Orthogonally diagonalize the matrix

$$A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{bmatrix}$$
, whose characteristic equation is

$$0 = -\lambda^3 + 12\lambda^2 - 21\lambda - 98 = -(\lambda - 7)^2(\lambda + 2)$$

Solution: The usual calculations produce bases for the eigenspaces:

$$\lambda = 7 : \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix}; \lambda = -2 : \mathbf{v}_3 = \begin{bmatrix} -1 \\ -1/2 \\ 1 \end{bmatrix}$$

- Although \mathbf{v}_1 and \mathbf{v}_2 are linearly independent, they are not orthogonal.
- The projection of \mathbf{v}_2 onto \mathbf{v}_1 is $\frac{\mathbf{v}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1$.

• The component of \mathbf{v}_2 orthogonal to \mathbf{v}_1 is

$$z_2 = v_2 - \frac{v_2 \cdot v_1}{v_1 \cdot v_1} v_1 = \begin{bmatrix} -1/4 \\ 1 \\ 1/4 \end{bmatrix}$$

- Then $\{\mathbf{v}_1, \mathbf{z}_2\}$ is an orthogonal set in the eigenspace for $\lambda = 7$.
- (Note that \mathbf{z}_2 is linear combination of the eigenvectors \mathbf{v}_1 and \mathbf{v}_2 , so \mathbf{z}_2 is in the eigenspace).

• Normalize \mathbf{v}_1 and \mathbf{z}_2 to obtain the following orthonormal basis for the eigenspace for $\lambda = 7$:

$$\mathbf{u}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} -1/\sqrt{18} \\ 4/\sqrt{18} \\ 1/\sqrt{18} \end{bmatrix}$$

• An orthonormal basis for the eigenspace for $\lambda = -2$ is

$$u_3 = \frac{1}{\|2v_3\|} 2v_3 = \frac{1}{3} \begin{bmatrix} -2\\ -1\\ 2 \end{bmatrix} = \begin{bmatrix} -2/3\\ -1/3\\ 2/3 \end{bmatrix}$$

Hence $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthonormal set.

Let

$$P = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{18} & -2/3 \\ 0 & 4/\sqrt{18} & -1/3 \\ 1/\sqrt{2} & 1/\sqrt{18} & 2/3 \end{bmatrix}, D = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

• Then P orthogonally diagonalizes A, and $A = PDP^{-1}$.

The Spectral Theorem

 The set of eigenvalues of a matrix A is sometimes called the spectrum of A, and the following description of the eigenvalues is called a spectral theorem.

The Spectral Theorem

Theorem: The Spectral Theorem for Symmetric Matrices

An $n \times n$ symmetric matrix A has the following properties:

- a. A has n real eigenvalues, counting multiplicities.
- b. The dimension of the eigenspace for each eigenvalue λ equals the multiplicity of λ as a root of the characteristic equation.
- c. The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal.
- d. A is orthogonally diagonalizable.

- Suppose $A = PDP^{-1}$, where the columns of P are orthonormal eigenvectors $\mathbf{u}_1, \dots, \mathbf{u}_n$ of A and the corresponding eigenvalues $\lambda_1, \dots, \lambda_n$ are in the diagonal matrix D.
- Then, since $P^{-1} = P^T$,

$$A = PDP^{T} = \begin{bmatrix} \mathbf{u}_{1} & \cdots & \mathbf{u}_{n} \end{bmatrix} \begin{bmatrix} \lambda_{1} & & 0 \\ & \ddots & \\ 0 & & \lambda_{n} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{1}^{T} \\ \vdots \\ \mathbf{u}_{n}^{T} \end{bmatrix}$$
$$= \begin{bmatrix} \lambda_{1}\mathbf{u}_{1} & \cdots & \lambda_{n}\mathbf{u}_{n} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{1}^{T} \\ \vdots \\ \mathbf{u}_{n}^{T} \end{bmatrix}$$

Using the column-row expansion of a product, we can write

$$A = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{u}_2^T + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^T \quad (2)$$

- This representation of A is called a spectral decomposition of A because it breaks up A into pieces determined by the spectrum (eigenvalues) of A.
- Each term in (2) is an $n \times n$ matrix of rank 1.

 Example: Construct a spectral decomposition of the matrix A that has the orthogonal diagonalization

$$A = \begin{bmatrix} 7 & 2 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 8 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}$$

• Solution: Denote the columns of P by \mathbf{u}_1 and \mathbf{u}_2 .

• Then
$$A = 8\mathbf{u}_1\mathbf{u}_1^T + 3\mathbf{u}_2\mathbf{u}_2^T$$

• To verify the decomposition of A, compute

$$\mathbf{u}_{1}\mathbf{u}_{1}^{T} = \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix} \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 4/5 & 2/5 \\ 2/5 & 1/5 \end{bmatrix}$$

$$\mathbf{u}_{2}\mathbf{u}_{2}^{T} = \begin{bmatrix} -1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 1/5 & -2/5 \\ -2/5 & 4/5 \end{bmatrix}$$

and

$$8\mathbf{u}_{1}\mathbf{u}_{1}^{T} + 3\mathbf{u}_{2}\mathbf{u}_{2}^{T} = \begin{bmatrix} 32/5 & 16/5 \\ 16/5 & 8/5 \end{bmatrix} + \begin{bmatrix} 3/5 & -6/5 \\ -6/5 & 12/5 \end{bmatrix} = \begin{bmatrix} 7 & 2 \\ 2 & 4 \end{bmatrix} = A$$

Section 7.1: Diagonalization of Symmetric Matrices

Section 7.2: Quadratic Forms

• A quadratic form on \mathbb{R}^n is a function Q defined on \mathbb{R}^n whose value at a vector \mathbf{x} in \mathbb{R}^n can be computed by an expression of the form $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$, where A is an $n \times n$ symmetric matrix.

The matrix A is called the matrix of the quadratic form.

• **Example:** Let $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$. Compute $\mathbf{x}^T A \mathbf{x}$ for the

following matrices.

a.
$$A = \begin{bmatrix} 4 & 0 \\ 0 & 3 \end{bmatrix}$$

b.
$$A = \begin{bmatrix} 3 & -2 \\ -2 & 7 \end{bmatrix}$$

Solution:

a.
$$x^T A x = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 4 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 4x_1 \\ 3x_2 \end{bmatrix} = 4x_1^2 + 3x_2^2$$

b. Watch the two -2 entries from A:

$$x^{T}Ax = \begin{bmatrix} x_{1} & x_{2} \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -2 & 7 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} x_{1} & x_{2} \end{bmatrix} \begin{bmatrix} 3x_{1} - 2x_{2} \\ -2x_{1} + 7x_{2} \end{bmatrix}$$

$$= x_{1}(3x_{1} - 2x_{2}) + x_{2}(-2x_{1} + 7x_{2})$$

$$= 3x_{1}^{2} - 2x_{1}x_{2} - 2x_{2}x_{1} + 7x_{2}^{2}$$

$$= 3x_{1}^{2} - 4x_{1}x_{2} + 7x_{2}^{2}$$

• The presence of $-4x_1x_2$ in the quadratic form in Example 1(b) is due to the -2 entries off the diagonal in the matrix A.

• In contrast, the quadratic form associated with the diagonal matrix A in Example 1(a) has no x_1x_2 cross-product term.

• If x represents a variable vector in \mathbb{R}^n , then a change of variable is an equation of the form

$$\mathbf{x} = P\mathbf{y}$$
, or equivalently, $\mathbf{y} = P^{-1}\mathbf{x}$ (1)

where P is an invertible matrix and y is a new variable vector in \mathbb{R}^n .

- Here \mathbf{y} is the coordinate vector of \mathbf{x} relative to the basis of \mathbb{R}^n determined by the columns of P.
- If the change of variable (1) is made in a quadratic form $\mathbf{x}^T A \mathbf{x}$, then

$$x^{T}Ax = (Py)^{T}A(Py) = y^{T}P^{T}APy = y^{T}(P^{T}AP)y$$
 (2)

and the new matrix of the quadratic form is P^TAP .

• **Example:** Make a change of variable that transforms the quadratic form $Q(\mathbf{x}) = x_1^2 - 8x_1x_2 - 5x_2^2$ into a quadratic form with no cross-product term.

Solution: The matrix of the given quadratic form is

$$A = \begin{bmatrix} 1 & -4 \\ -4 & -5 \end{bmatrix}$$

- The first step is to orthogonally diagonalize A.
- Its eigenvalues turn out to be $\lambda = 3$ and $\lambda = -7$.
- Associated unit eigenvectors are

$$\lambda = 3: \begin{bmatrix} 2/\sqrt{5} \\ -1/\sqrt{5} \end{bmatrix}; \qquad \lambda = -7: \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$$

• These vectors are automatically orthogonal (because they correspond to distinct eigenvalues) and so provide an orthonormal basis for \mathbb{R}^2 .

Let

$$P = \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}, \qquad D = \begin{bmatrix} 3 & 0 \\ 0 & -7 \end{bmatrix}$$

- Then $A = PDP^{-1}$ and $D = P^{-1}AP = P^{T}AP$.
- A suitable change of variable is

$$\mathbf{x} = P\mathbf{y}$$
, where $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$.

Then

$$x_1^2 - 8x_1x_2 - 5x_2^2 = \mathbf{x}^T A \mathbf{x} = (P\mathbf{y})^T A (P\mathbf{y})$$
$$= \mathbf{y}^T P^T A P \mathbf{y} = \mathbf{y}^T D \mathbf{y}$$
$$= 3y_1^2 - 7y_2^2$$

• To illustrate the meaning of the equality of quadratic forms in Example, we can compute $Q(\mathbf{x})$ for $\mathbf{x} = (2, -2)$ using the new quadratic form.

• First, since x = Py,

so $\mathbf{y} = P^{-1}\mathbf{x} = P^{T}\mathbf{x}$ $\mathbf{y} = \begin{bmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 6/\sqrt{5} \\ -2/\sqrt{5} \end{bmatrix}$

Hence

$$3y_1^2 - 7y_2^2 = 3(6/\sqrt{5})^2 - 7(-2/\sqrt{5})^2 = 3(36/5) - 7(4/5)$$
$$= 80/5 = 16$$

• This is the value of $Q(\mathbf{x})$ when $\mathbf{x} = (2, -2)$.

The Principal Axis Theorem

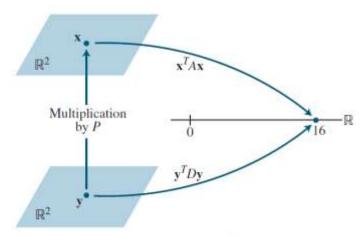


FIGURE 1 Change of variable in $\mathbf{x}^T A \mathbf{x}$.

• **Theorem:** Let A be an $n \times n$ symmetric matrix. Then there is an orthogonal change of variable, $\mathbf{x} = P\mathbf{y}$, that transforms the quadratic form $\mathbf{x}^T A \mathbf{x}$ into a quadratic form $\mathbf{y}^T D \mathbf{y}$ with no cross-product term.

The Principal Axis Theorem

• The columns of P in theorem are called the principal axes of the quadratic form $\mathbf{x}^T A \mathbf{x}$.

• The vector \mathbf{y} is the coordinate vector of \mathbf{x} relative to the orthonormal basis of \mathbb{R}^n given by these principal axes.

Classifying Quadratic Forms

- **Definition:** A quadratic form Q is:
 - a. positive definite if $Q(\mathbf{x}) > 0$ for all $\mathbf{x} \neq 0$,
 - **b.** negative definite if $Q(\mathbf{x}) < 0$ for all $\mathbf{x} \neq 0$,
 - **c. indefinite** if Q (**x**) assumes both positive and negative values.

• Also, Q is said to be positive semidefinite if $Q(\mathbf{x}) \ge 0$ for all \mathbf{x} , and negative semidefinite if $Q(\mathbf{x}) \le 0$ for all \mathbf{x} .

Quadratic Forms and Eigenvalues

- Theorem: Let A be an $n \times n$ symmetric matrix. Then a quadratic form $\mathbf{x}^T A \mathbf{x}$ is:
 - a. positive definite if and only if the eigenvalues of A are all positive,
 - b. negative definite if and only if the eigenvalues of A are all negative, or
 - c. indefinite if and only if A has both positive and negative eigenvalues.