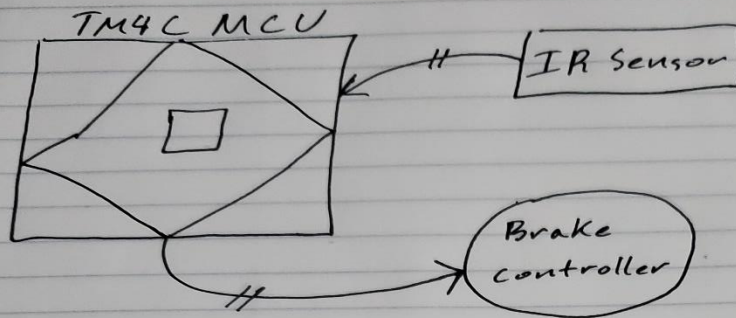


Kent Mark

Cpre 288 – Exam 3 Part B

4/16/20

while (1) {



• IR sensor sends out a ping to find vehicle
while
~~if~~ (vehicle Detect == true) {

Call method to get distance and speed
update distance variable and speed variable

decelerate until speed of vehicle in front
is matched

}
}
}