# MODELING - GAMA project Driftwood

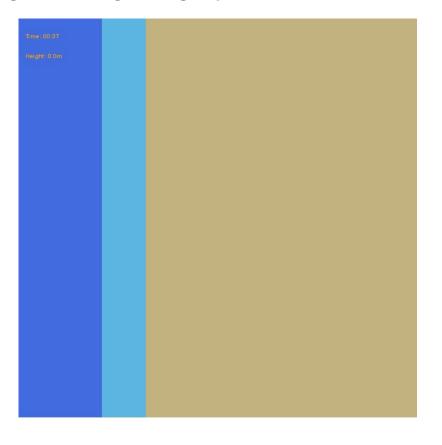
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## Overview of the Simulation

### Key questions:

- What's the impact of the stealing mechanism
- What is the impact of enforcement mechanisms
- How do group dynamics influence system stability?

## The Environment



#### **Description**:

- A dynamic beach environment modeled as a grid.
- Features include:
  - Waves and tides influencing wood movement.
  - o Zones: ocean, shoreline, and dry land.

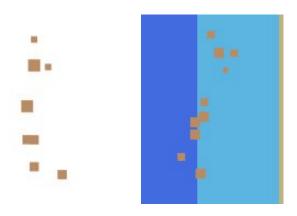
#### Visual Aids:

 Show a grid with tide zones, wave patterns, and color-coded areas.

#### **Key Metrics**:

Average height, tide levels, and wave dynamics.

## **Driftwood Species**



#### Role:

Driftwood is the core resource for collectors.

#### Behavior:

- Movement is influenced by waves, tides, and size categories.
- Sizes: Small, medium, large (affecting value and movement).

#### Visual Aids:

 Diagram showing driftwood moving across the grid with tide and wave effects.

## Collectors



#### Behavior:

 Collect driftwood, build piles, and optionally steal from others.

#### **Key Attributes:**

- Greed: Influences decision-making.
- Stealing: Managed by probabilities that adjust after successes. (extend 1)
- Grouping: Form groups for efficiency and resource sharing. (extend 3)

#### Visual Aids:

 A collector's flowchart: From identifying wood to pile creation or theft.

#### **Key Metrics**:

Active collectors, total thefts, and collection efficiency.

# WoodPile Species



#### Role:

Represents storage for driftwood collected by agents.

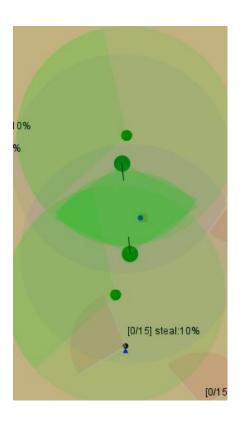
#### Behavior:

- Tracks ownership, value, and theft.
- Stability decreases with frequent thefts.

#### Visual Aids:

 Diagram showing wood being added to a pile, with theft reducing value.

# Enforcement Mechanisms (extend 2)



#### **Authority Species:**

- Mobile patrols monitor and pursue thieves.
- Dynamic behavior: Patrol paths or stationary observation.

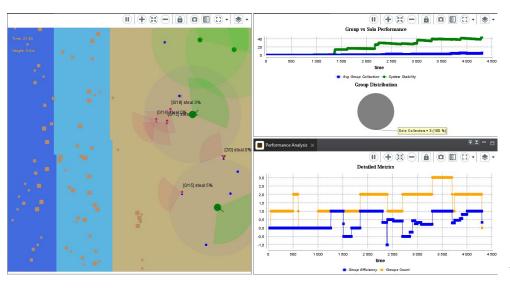
#### **Security Cameras**:

- Stationary enforcement agents with rotational FOV.
- Detect and penalize thieves within a defined radius.

#### **Key Metrics**:

Active pursuits, total catches, and thief deterrence effectiveness.

# **Experiment Design**



#### **Interactive Parameters:**

- Environmental: Waves, tides, and flow rates.
- Collector Behavior: Greed, stealing probabilities.
- Enforcement: Number of authorities/cameras, detection radius.
- Group Dynamics: Formation/breakup probabilities and cooperation bonuses.

#### Outputs:

- Graphs: Group vs. solo efficiency, theft rates, and system stability.
- Visualizations: Live beach simulation with color-coded agents.

#### Visual Aids:

Example dashboard with parameters and real-time monitors.

# Key Insights and Results

#### Findings:

- Peer pressure alone leads to moderate stability but frequent thefts.
- Adding enforcement reduces thefts significantly, especially with mobile patrols.
- Groups improve efficiency but may increase theft without enforcement.

#### Implications:

Self-regulation and enforcement must be balanced for optimal stability.

## Conclusion

#### Summary:

- The simulation highlights how resource competition can be modeled dynamically.
- Enforcement and group behavior are key to understanding resource stability.