

Enrique Garcia Rivera

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Education

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| Washington University in St. Louis, McKelvey School of Engineering – St. Louis, MO <i>Bachelor of Science in Mechanical Engineering, Minors in Aerospace Engineering and Mechatronics</i> | <i>Expected: May 2027</i> |
| Relevant Coursework: Mechanical Vibrations, Fluid Mechanics, Solid Mechanics, Thermodynamics, Materials Science, Numerical Methods and Matrix Algebra (MATLAB), Electronic and Electrical Circuits (Arduino IDE), Machine Shop Practicum | Cumulative GPA: 3.68/4.00 |

Technical Skills

- **Design & Analysis:** CAD Modeling, Simulation, FEA (SolidWorks, Ansys), MATLAB/Simulink, Python, Sensor Fusion
- **Tools & Prototyping:** 3D Printing, CNC Machining, GD&T, Soldering, Wiring, IMU/GPS Integration, Telemetry

Experience

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| WashU Vertical Takeoff and Landing (VTOL) – Lead Avionics Engineer, St. Louis, MO | Sep 2025 – Present |
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- Founding member developing avionics and control architecture for WashU's inaugural autonomous VTOL team competing in the Vertical Flight Society's Design–Build–Vertical Flight Competition.
- Integrated Pixhawk 6C flight controller, IMU, GPS, and telemetry modules with custom power distribution to support autonomous flight operations.
- Supported hardware-in-the-loop testing, flight data collection, and troubleshooting during prototype development to improve system reliability and flight stability.
- Collaborated with electrical and mechanical teammates on instrumentation layout, EMI mitigation, and performance validation during wind-tunnel and field testing.

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| WashU Design Build Fly (DBF) – Aerodynamics & Payload Engineer, St. Louis, MO | Sep 2024 – Present |
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- Designed and optimized NACA-series wings and control surfaces using XFLR5 and CFD (ANSYS CFX) to meet payload, speed, and range competition constraints.
- Conducted structural modeling, 2.5g load analyses, and weight optimization using SolidWorks, Ansys, and analytical methods to ensure safety and efficiency.
- Assisted with fixed-wing flight testing and data logging to evaluate aerodynamic performance and control response.
- Created internal documentation and training materials for new members on aerodynamics, simulation, and test data processing in MATLAB.

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| Multiplatform Interactive Robotics Lab, UMKC – Research Intern, Kansas City, MO | May 2025 – Aug 2025 |
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- Developed a real-time sensor-fusion platform on a Teensy 4.0 using Arduino IDE to collect synchronized EMG and 9-axis IMU data at 1 kHz and visualize performance metrics in Python.
- Applied Extended Kalman Filtering in MATLAB for drift minimization and orientation accuracy; validated sensor data through controlled motion capture trials.
- Conducted instrumentation calibration, data synchronization, and troubleshooting to improve system robustness under experimental conditions.
- Presented research findings on multimodal signal integration and system reliability at the IEEE Body Sensor Networks Conference (2025).

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| Federal Express Corporation – Material Handler, Kansas City, MO | Jun 2024 – Aug 2024 |
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- Processed 100+ packages/hour with 99.8% accuracy using industrial material handling systems.
- Reduced manual errors by 15% and package defects by 20% through optimized loading patterns and damage prevention.
- Maintained perfect safety compliance while routing over 5,000 daily shipments.
- Assisted team members in workflow organization, improving efficiency and meeting tight daily shipment deadlines.

Projects

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| Adaptive Cruise Control (ACC) System – MATLAB | <i>Spring 2025</i> |
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- Simulated vehicle-following dynamics using Runge–Kutta numerical methods and PID control; tuned gains for stable response and minimal overshoot.
- Modeled sensor latency and control feedback to analyze autonomous spacing performance under variable lead-vehicle motion.

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| Autonomous Ambulance Navigation System – Arduino | <i>Fall 2024</i> |
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- Built an Arduino-based autonomous vehicle prototype with real-time path correction and obstacle detection using ultrasonic sensors.
- Implemented PWM motor control, synchronized LED strobes, and multi-tone siren signaling; validated algorithm performance in a controlled test environment.