

# Graph visits

Programmazione Avanzata 2025-26

# Visit algorithms

- Visit
  - **Systematic exploration** of a graph
  - Starting from a “source” vertex
  - Reaching all reachable vertices
- Main strategies
  - Breadth-First Visit
  - Depth-First Visit

# Breadth-First Visit

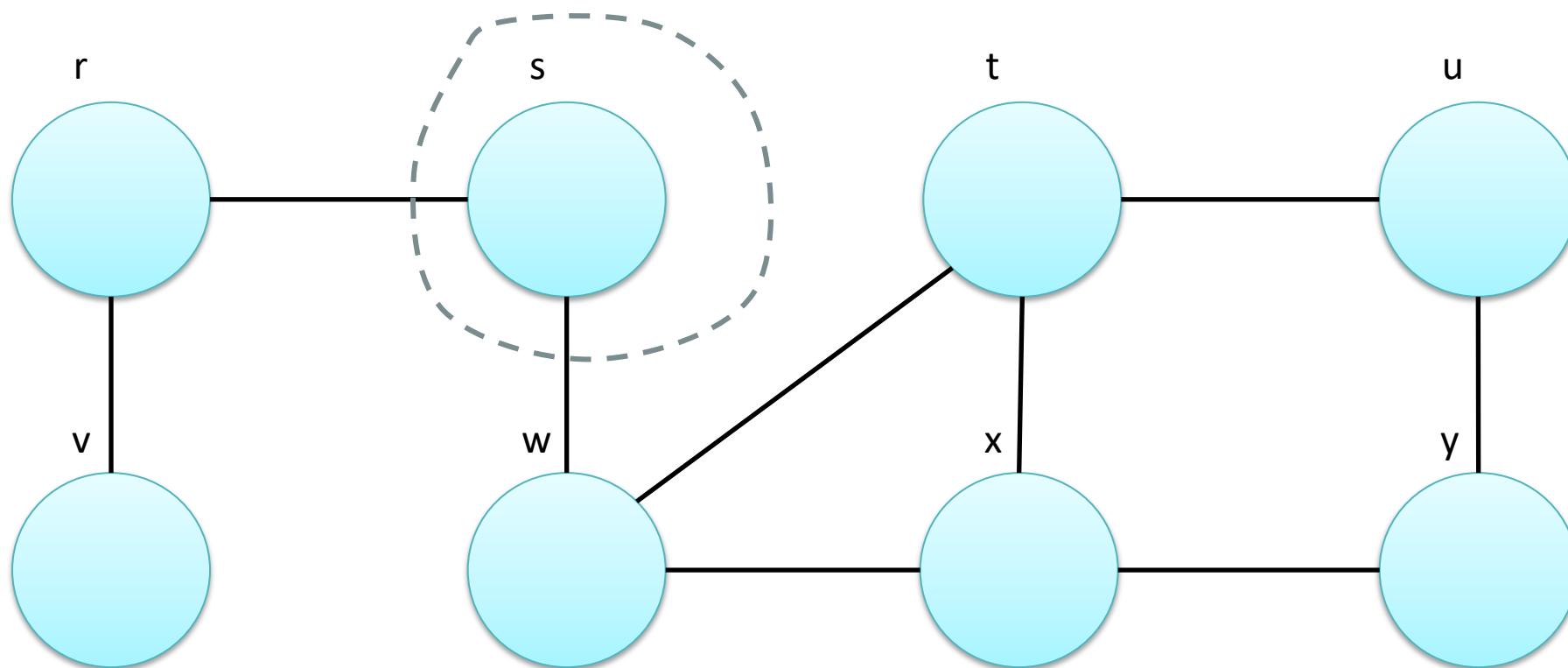
- Also called Breadth-First Search (BFV or BFS)
- All reachable vertices are visited “by levels”
  - $L$ , level of the visit
  - $S_L$ , set of vertices in level  $L$
  - $L=0$ ,  $S_0=\{v_{\text{source}}\}$

# BFS algorithm

- Repeat while  $S_L$  is not empty:
  - $S_{L+1}$ , set of all vertices:
    - Not visited yet, and
    - Adjacent to at least one vertex in  $S_L$
  - $L=L+1$

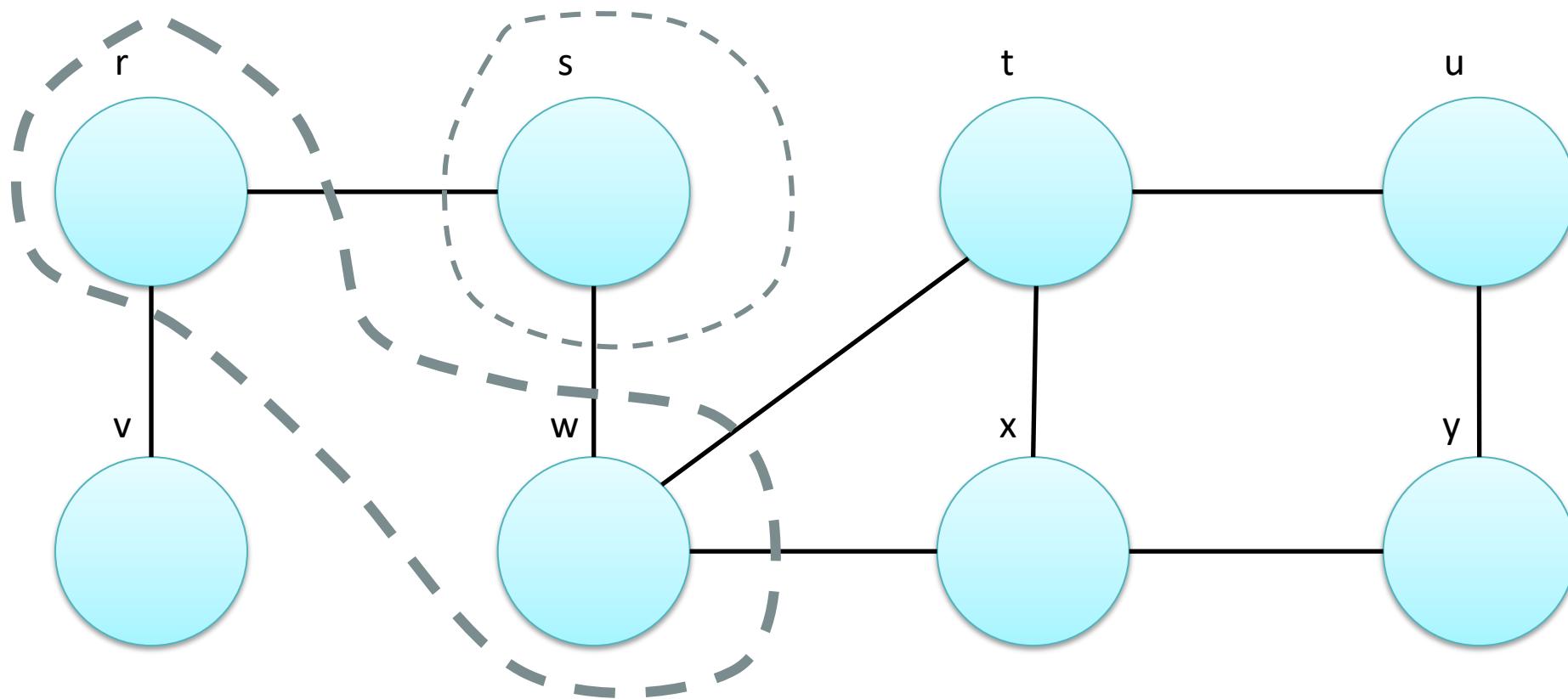
# Example

Source = s  
 $L = 0$   
 $S_0 = \{s\}$



# Example

$$\begin{aligned}L &= 1 \\S_0 &= \{s\} \\S_1 &= \{r, w\}\end{aligned}$$

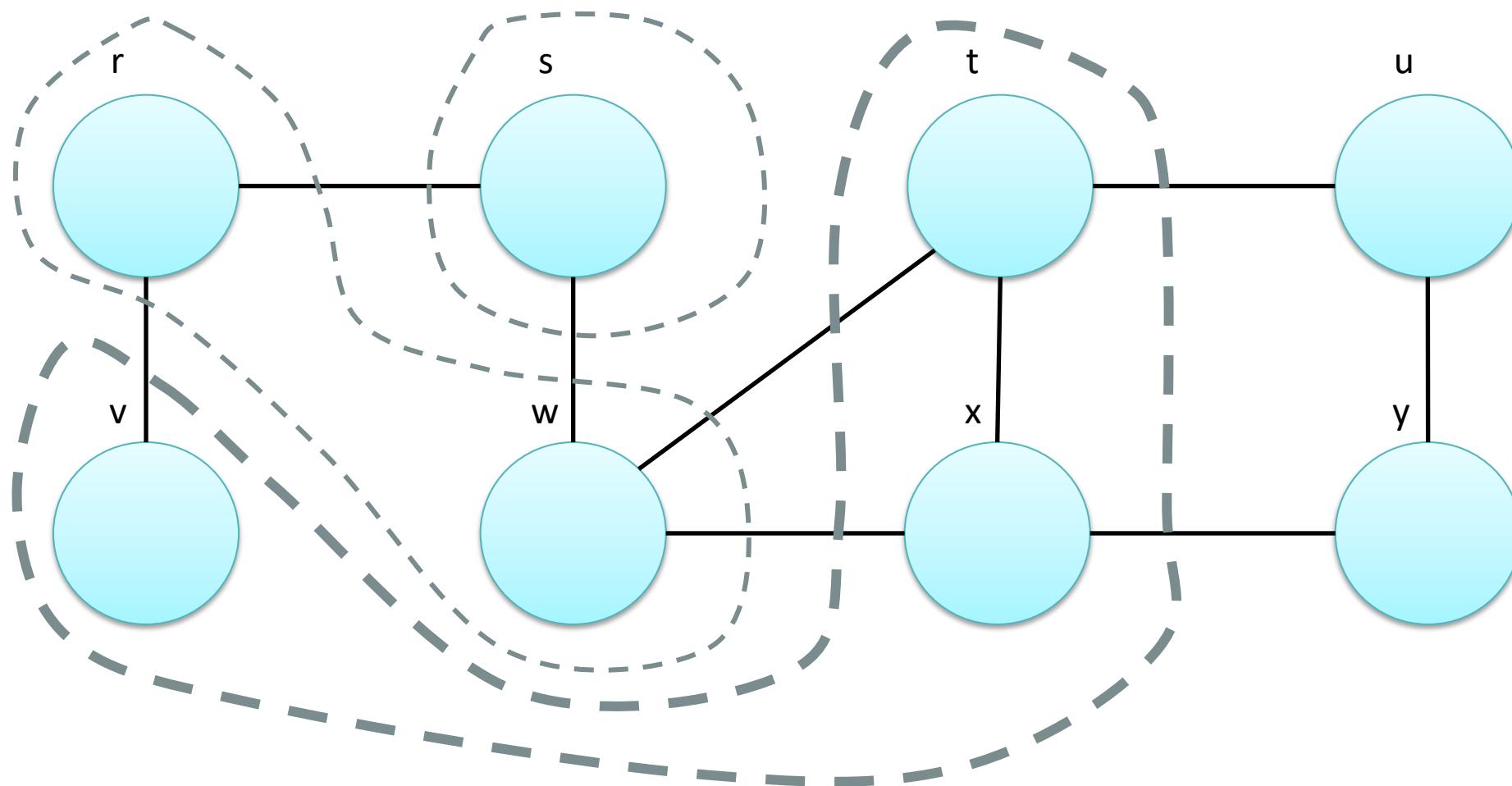


# Example

$$L = 2$$

$$S_1 = \{r, w\}$$

$$S_2 = \{v, t, x\}$$

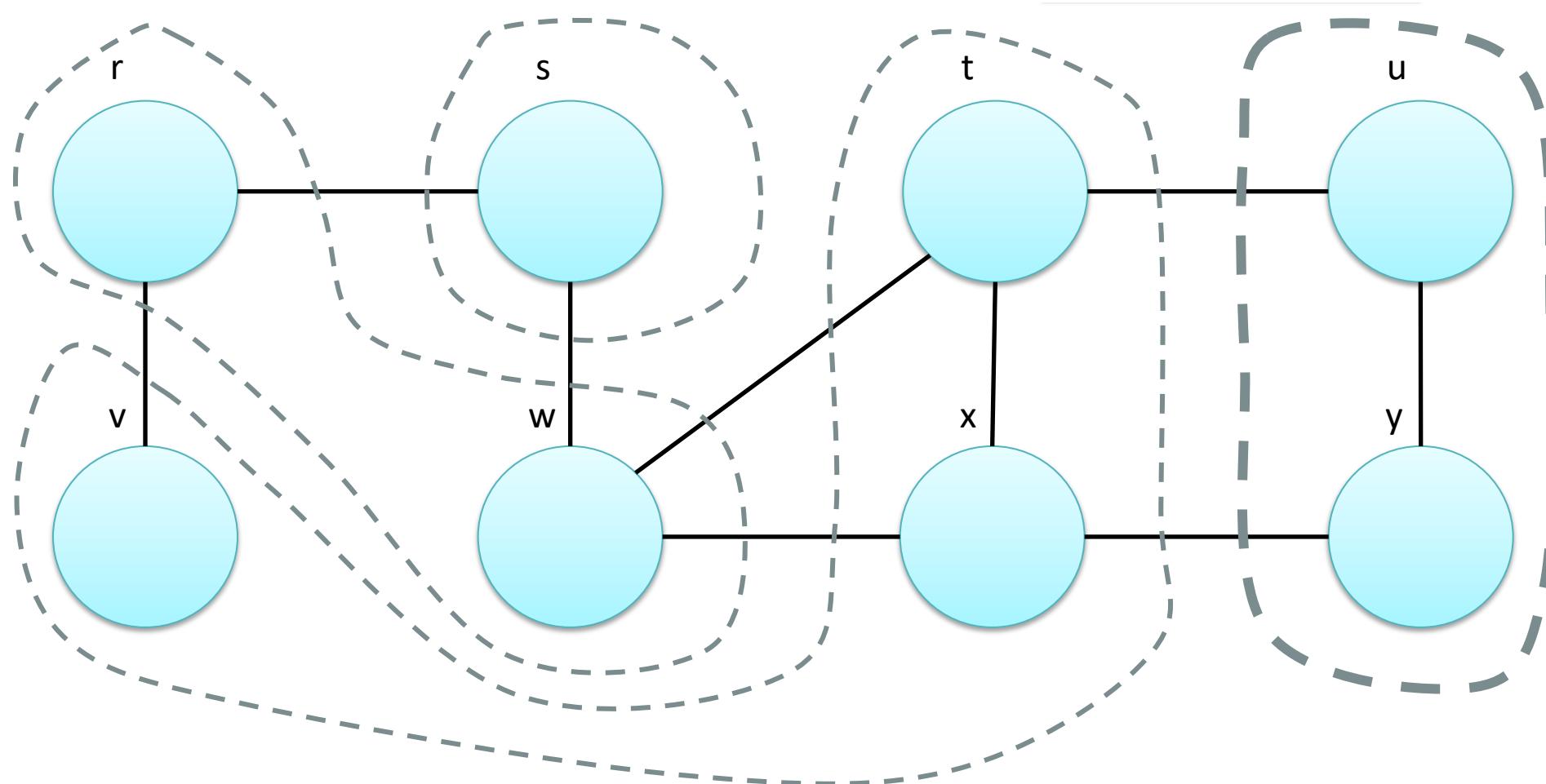


# Example

$$L = 3$$

$$S_2 = \{v, t, x\}$$

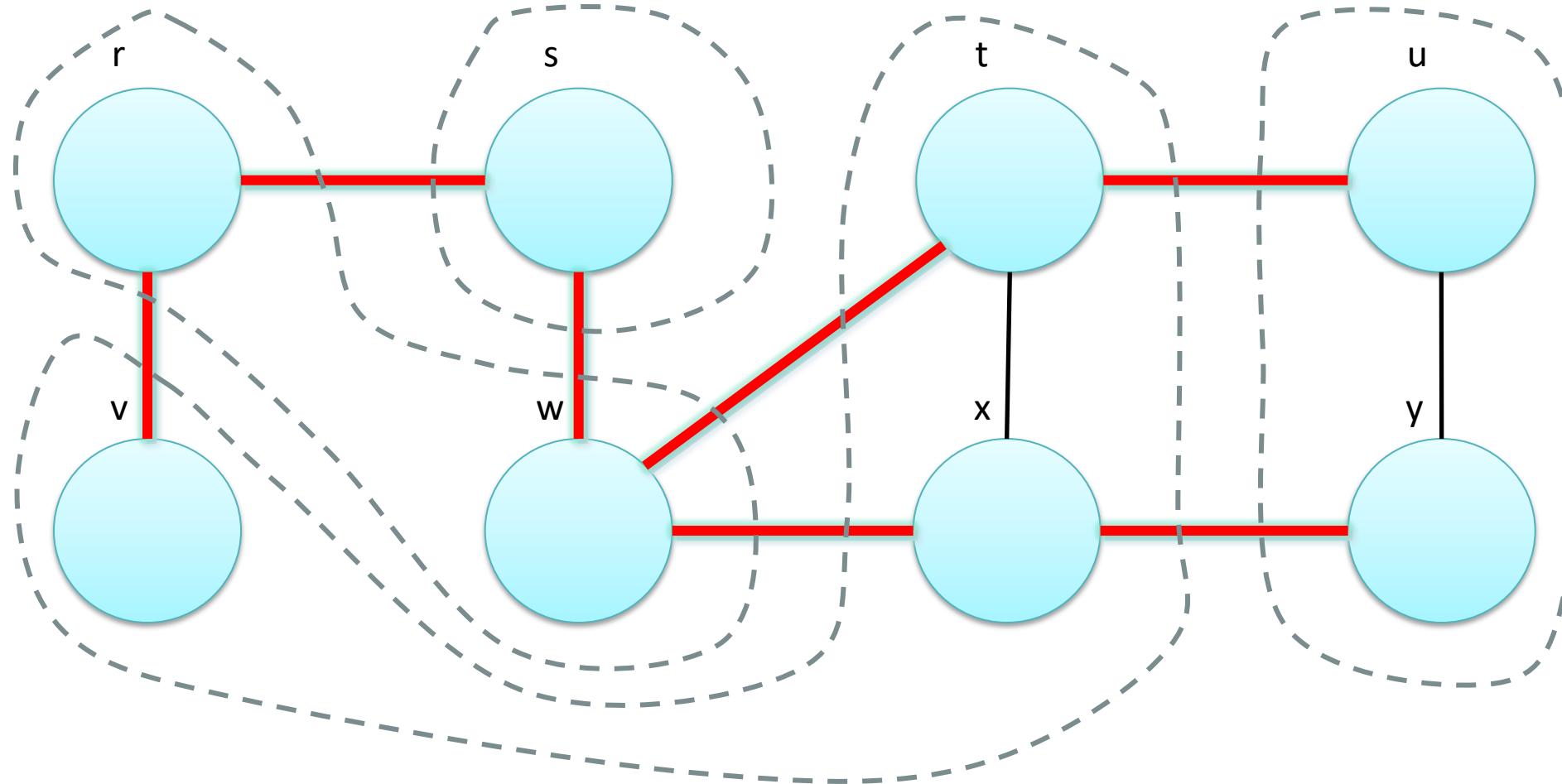
$$S_3 = \{u, y\}$$



# BFS Tree

- The result of a BFV identifies a “visit tree” in the graph:
  - The tree root is the source vertex
  - Tree nodes are all graph vertices
    - (In the same connected component of the source)
  - Tree edges are a subset of graph edges
    - Those edges that have been used to “discover” new vertices

# BFS Tree



# Minimum (shortest) paths

- Shortest path: the minimum number of edges on any path between two vertices
- The BFS algorithm computes all minimum paths for all vertices, starting from the source vertex
- Unweighted graphs: path length = number of edges

# Depth First Visit

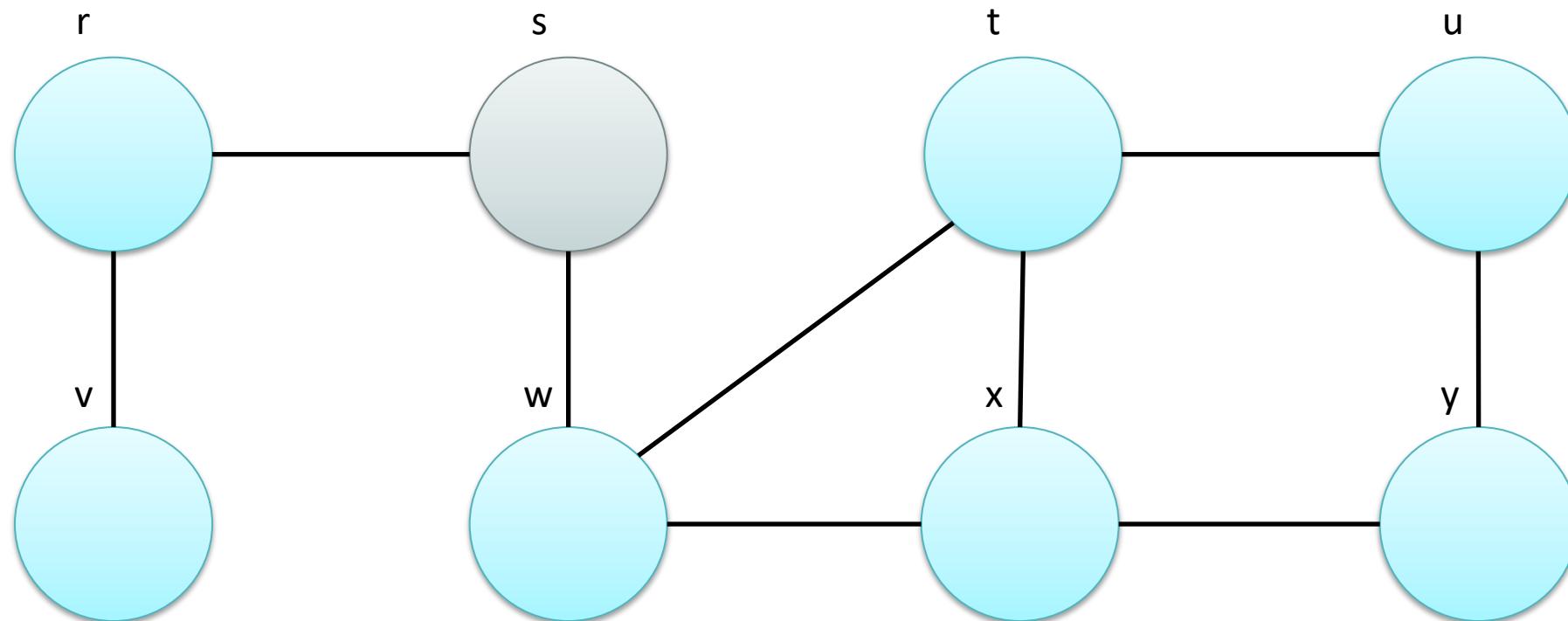
- Also called Depth-first search (DFV or DFS)
- Opposite approach to BFS
  - At every step, visit one (yet unvisited) vertex, adjacent to the last visited one
  - If no such vertex exist, go back one step to the previously visited vertex
  - Lends itself to recursive implementation
    - Similar to tree visit procedures

# DFS algorithm

- $\text{DFS}(\text{Vertex } v)$ 
  - For all (  $w : \text{adjacent\_to}(v)$  )
  - If( not visited (  $w$  ) )
    - Visit (  $w$  )
    - $\text{DFS}(w)$
- Start with:  $\text{DFS}(v_{\text{source}})$

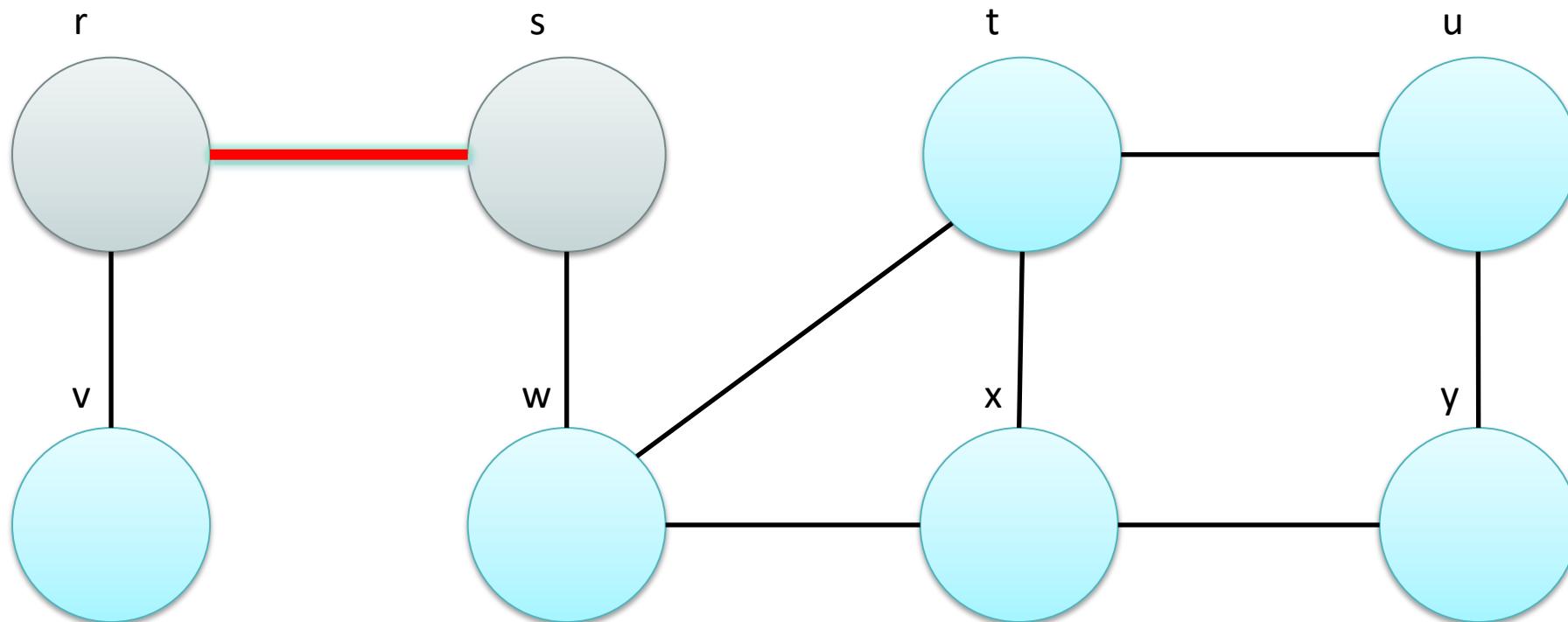
# Example

Source = s



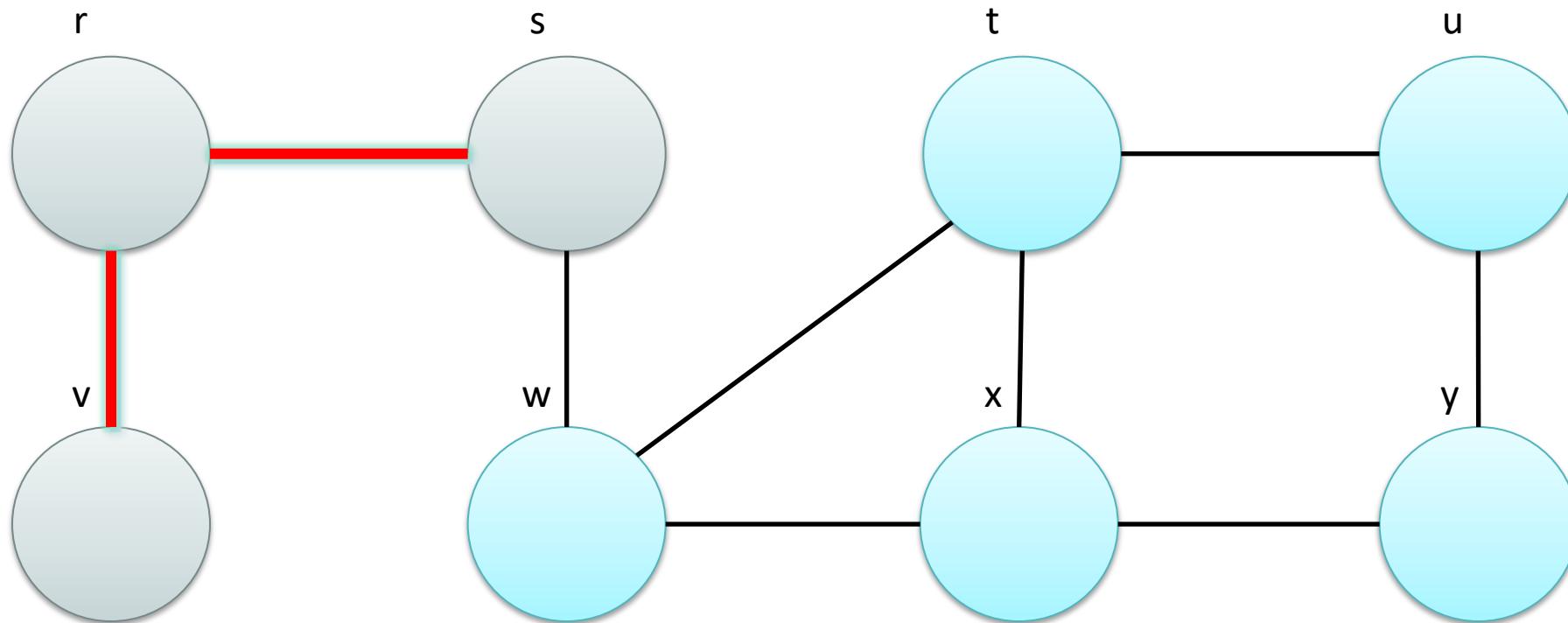
# Example

Source = s  
Visit r



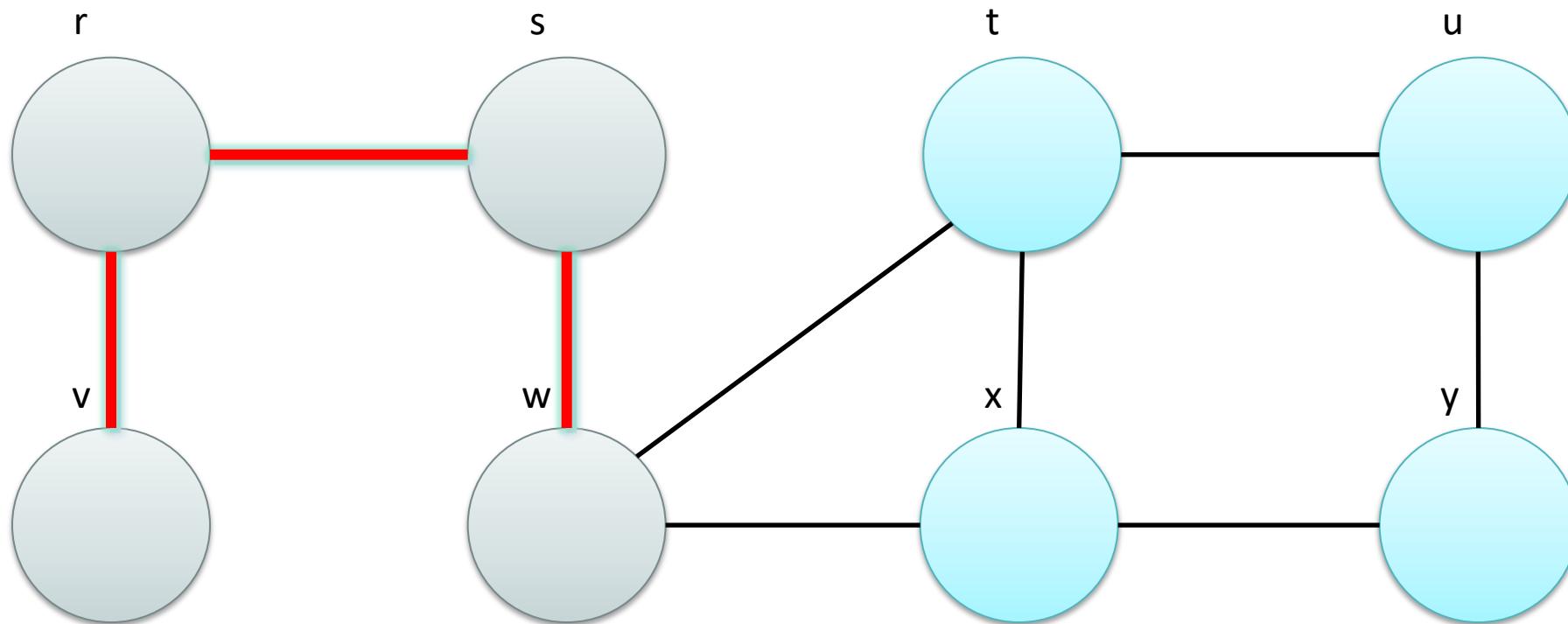
# Example

Source = s  
Visit r  
Visit v



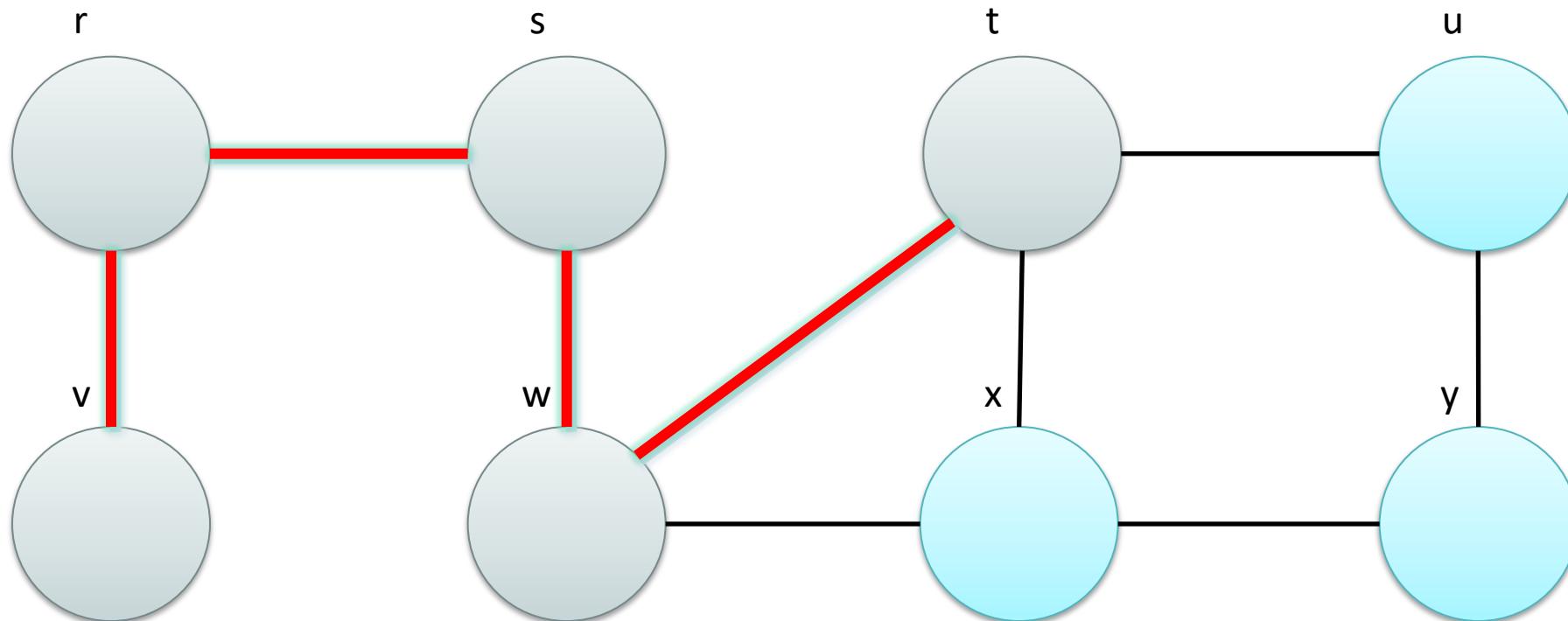
# Example

Source = s  
Visit w



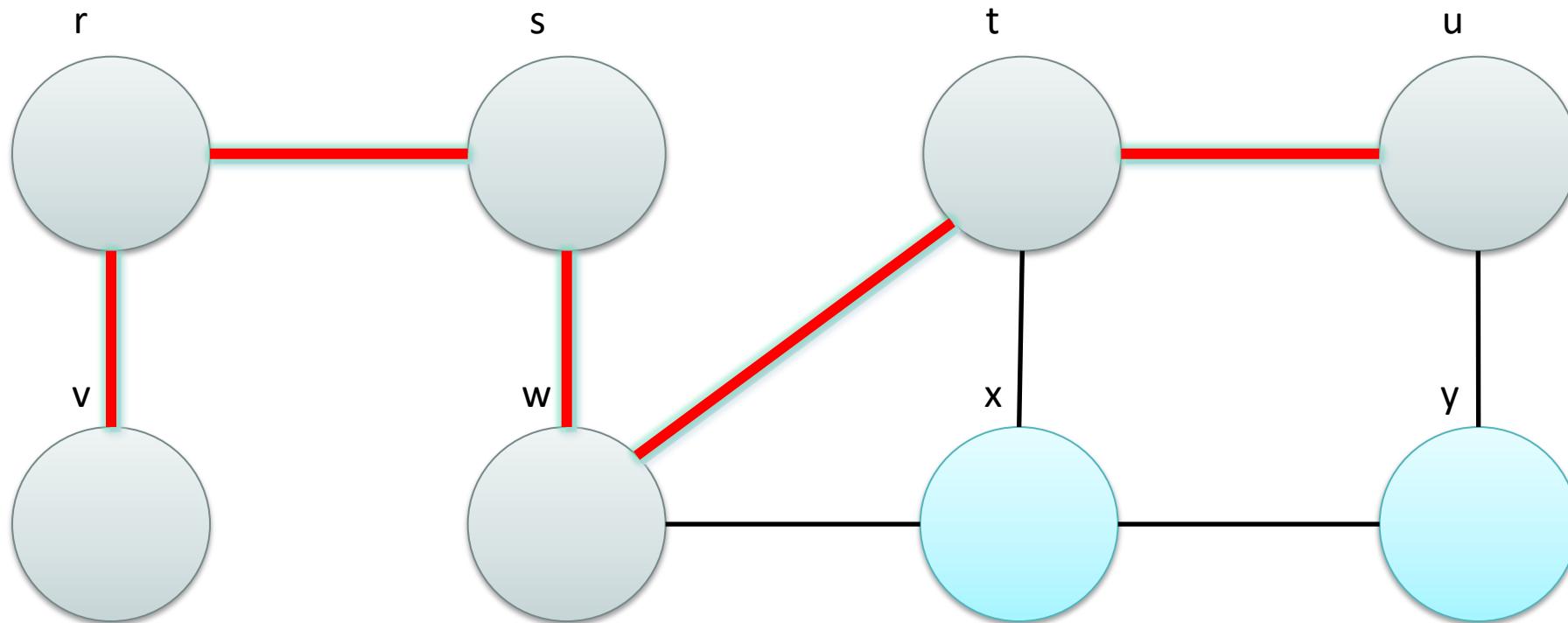
# Example

Source = s  
Visit w  
Visit t



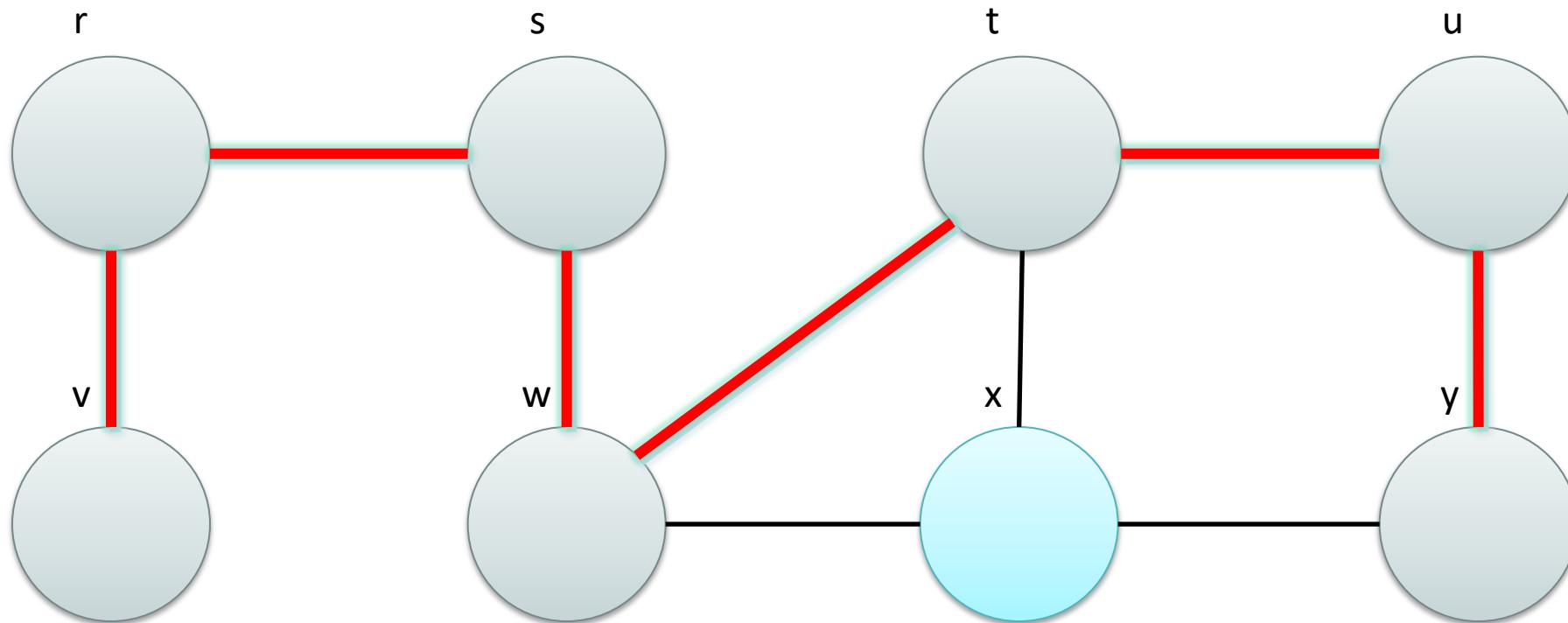
# Example

Source = s  
Visit w  
Visit t  
Visit u



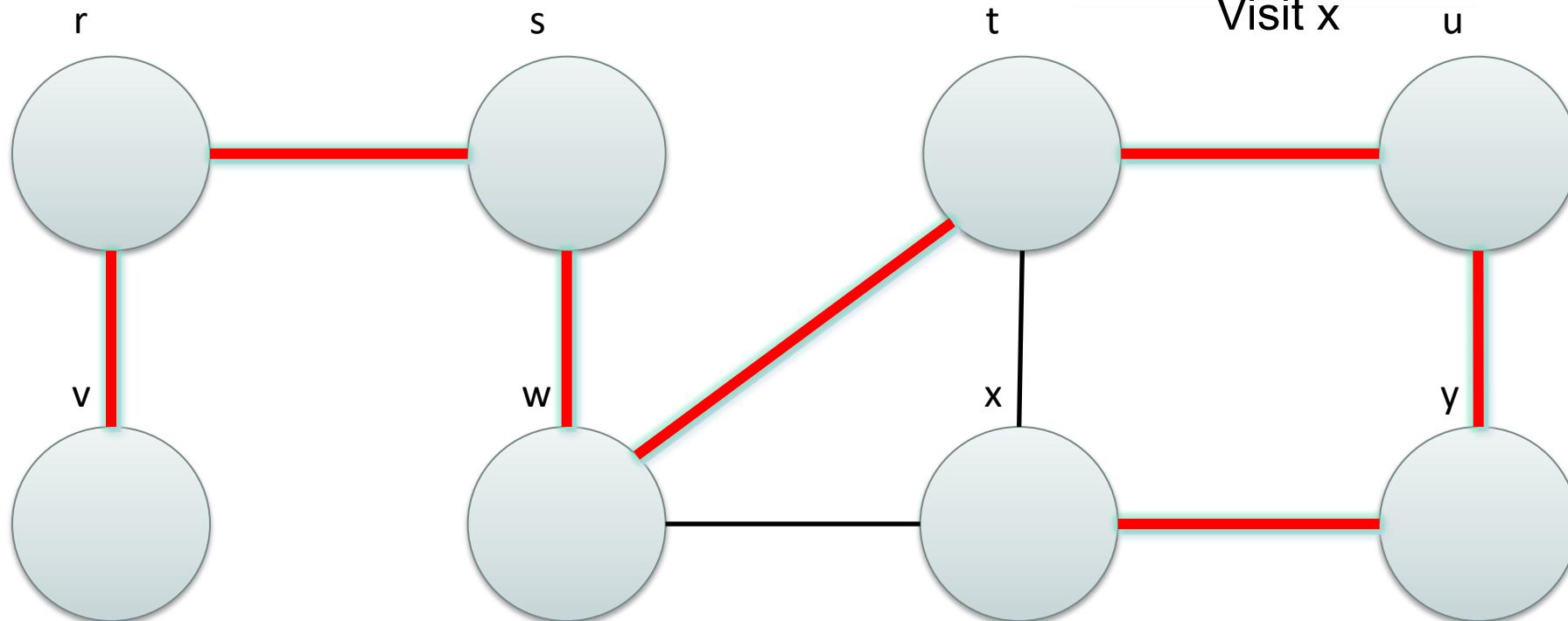
# Example

Source = s  
Visit w  
Visit t  
Visit u  
Visit y



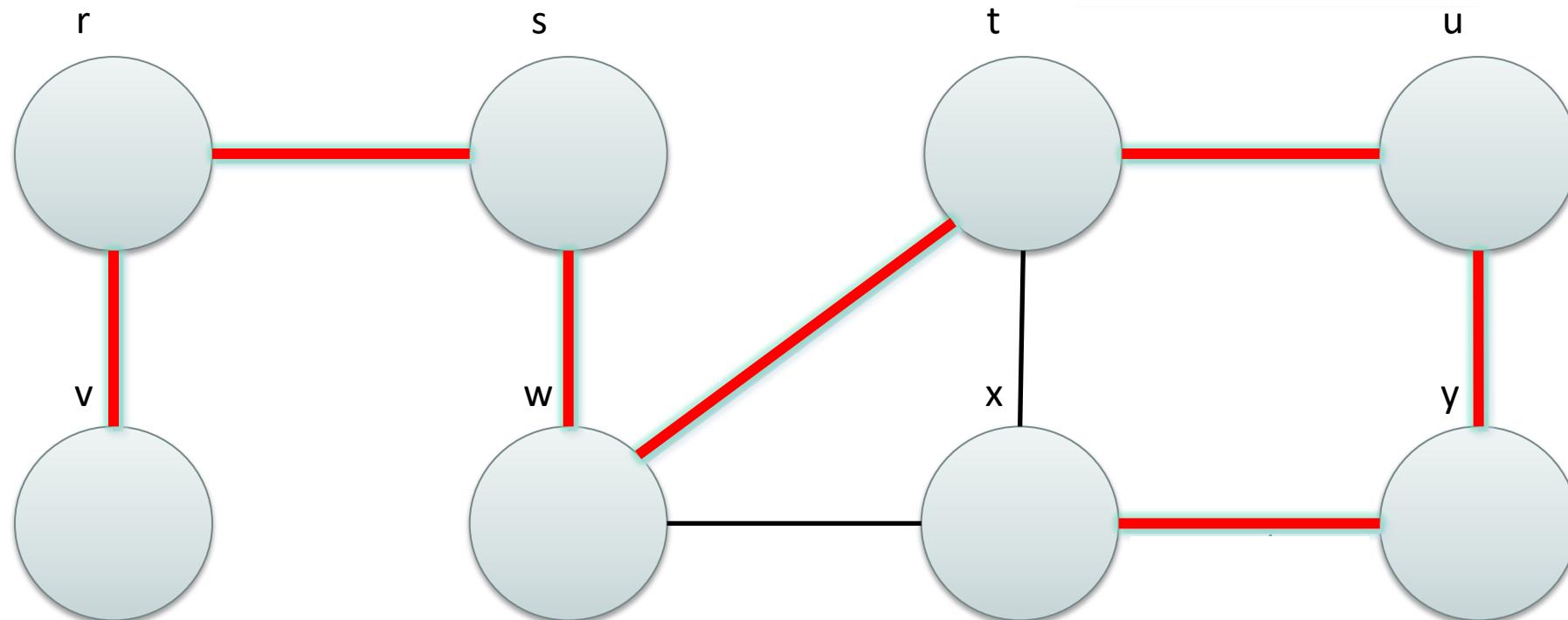
# Example

Source = s  
Visit w  
Visit t  
Visit u  
Visit y  
Visit x



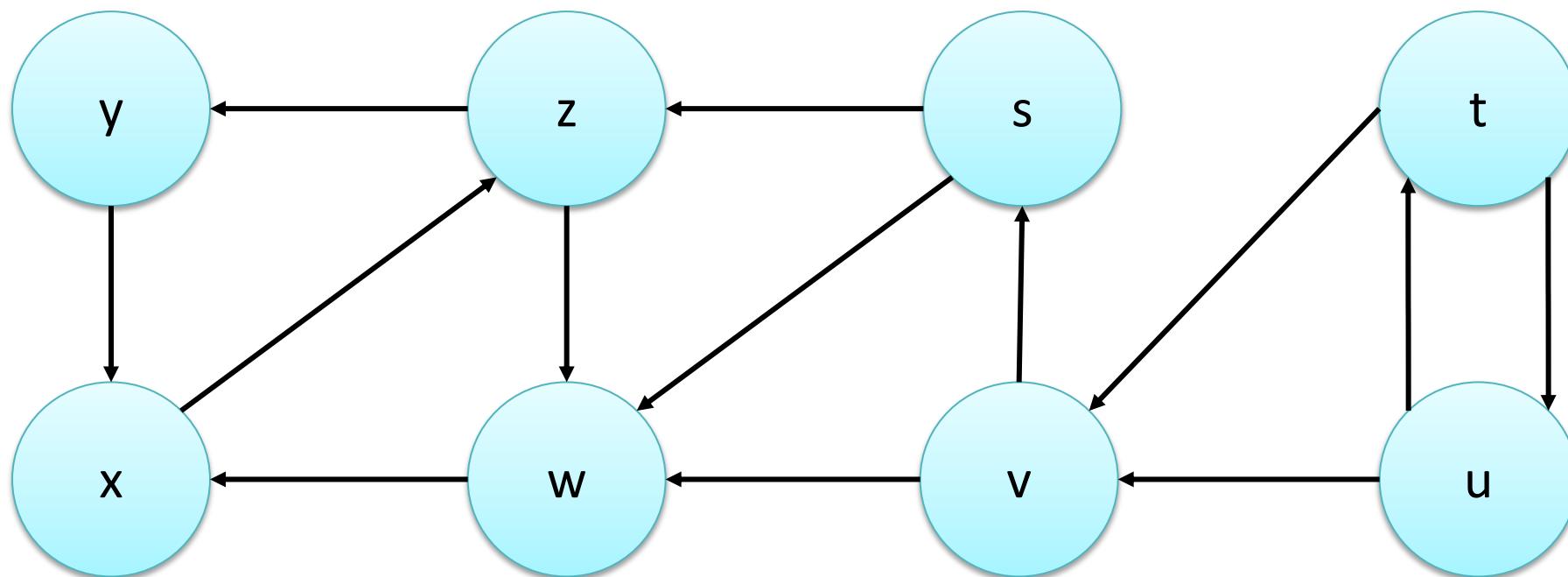
# DFS tree

Back to s and stop



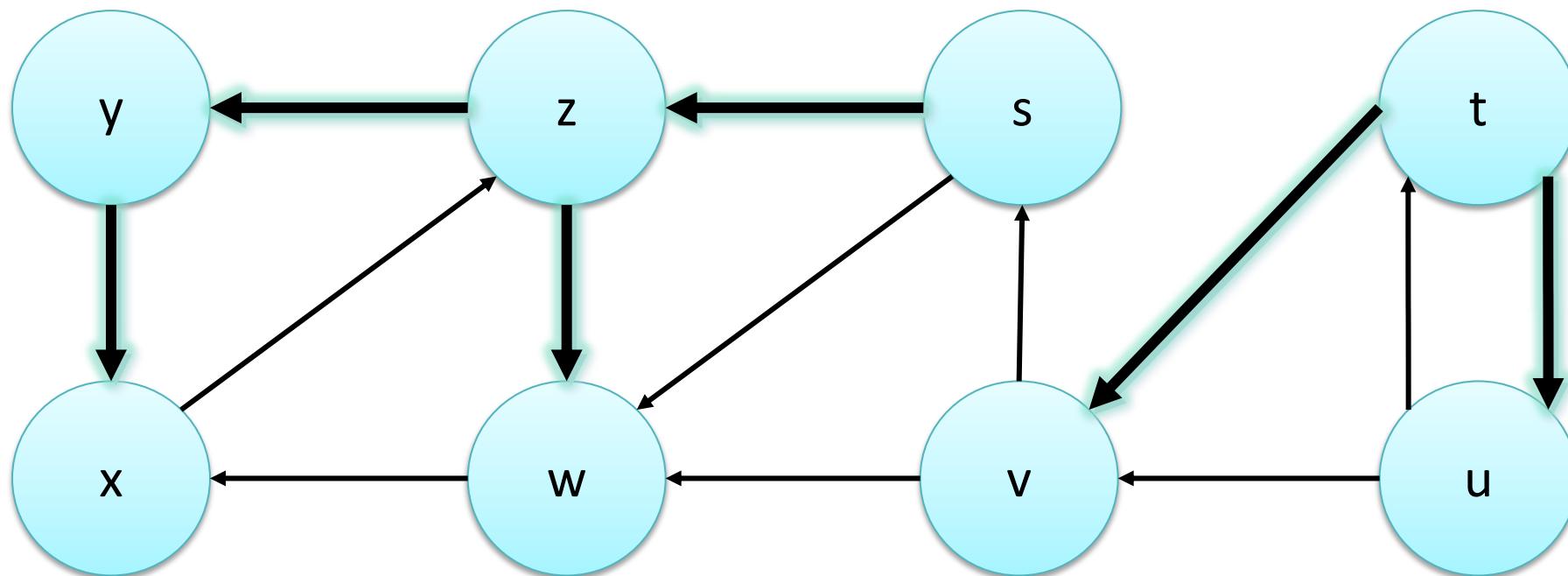
# Example

Directed graph



# Example

DFS visit  
Sources: s, t



# Complexity

- Visits have linear complexity in the graph size
  - BFS :  $O(V+E)$
  - DFS :  $Q(V+E)$
- For dense graphs,  $E = O(V^2)$

# Visits in NetworkX

- Visits are called “traversals”
- NetworkX already provides implementations for BFV and DFV, together with other visits strategies
  - <https://networkx.org/documentation/stable/reference/algorithms/traversal.html>

# Graph traversal methods

## Breadth First Search

Basic algorithms for breadth-first searching the nodes of a graph.

<a href="#"><code>bfs_edges</code></a> (G, source[, reverse, depth_limit, ...])	Iterate over edges in a breadth-first-search starting at source.
<a href="#"><code>bfs_layers</code></a> (G, sources)	Returns an iterator of all the layers in breadth-first search traversal.
<a href="#"><code>bfs_tree</code></a> (G, source[, reverse, depth_limit, ...])	Returns an oriented tree constructed from of a breadth-first-search starting at source.
<a href="#"><code>bfs_predecessors</code></a> (G, source[, depth_limit, ...])	Returns an iterator of predecessors in breadth-first-search from source.
<a href="#"><code>bfs_successors</code></a> (G, source[, depth_limit, ...])	Returns an iterator of successors in breadth-first-search from source.
<a href="#"><code>descendants_at_distance</code></a> (G, source, distance)	Returns all nodes at a fixed <code>distance</code> from <code>source</code> in <code>G</code> .
<a href="#"><code>generic_bfs_edges</code></a> (G, source[, neighbors, ...])	Iterate over edges in a breadth-first search.

## Depth First Search

Basic algorithms for depth-first searching the nodes of a graph.

<a href="#"><code>dfs_edges</code></a> (G, source, depth_limit, ...])	Iterate over edges in a depth-first-search (DFS).
<a href="#"><code>dfs_tree</code></a> (G[, source, depth_limit, ...])	Returns oriented tree constructed from a depth-first-search from source.
<a href="#"><code>dfs_predecessors</code></a> (G[, source, depth_limit, ...])	Returns dictionary of predecessors in depth-first-search from source.
<a href="#"><code>dfs_successors</code></a> (G[, source, depth_limit, ...])	Returns dictionary of successors in depth-first-search from source.
<a href="#"><code>dfs_preorder_nodes</code></a> (G[, source, depth_limit, ...])	Generate nodes in a depth-first-search pre-ordering starting at source.
<a href="#"><code>dfs_postorder_nodes</code></a> (G[, source, ...])	Generate nodes in a depth-first-search post-ordering starting at source.
<a href="#"><code>dfs_labeled_edges</code></a> (G[, source, depth_limit, ...])	Iterate over edges in a depth-first-search (DFS) labeled by type.