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GEOL 6670 Geophysical Inverse Theory

Tutorial on Python

Shane Zhang*

University of Colorado Boulder

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*shane.zhang@colorado.edu (mailto:shane.zhang@colorado.edu)

Why Python?

- Versatile
 - A personal story: My old workflow is to use C/Fortran for computing, then use Shell/Perl for I/O, and Matlab/GMT for plotting.
- Easy to read

```
def add(a, b):
    # Return the sum of two numbers.
    return a + b
```

- "Efficient"
 - I believe human time is more precious than machine time, and thus appreciate the fast feedback from Python in the development stage.
- Open-source
- Popular

Fig: Trends of programming languages in [StackOverflow] (https://insights.stackoverflow.com/trends? tags=java%2Cc%2Cc%2B%2B%2Cpython%2Cc%23%2Cvb.net%2Cjavascript%2Casse c).

A google search of python tutorial yields ~1 billion results, thus I would not try to provide a list of useful resources. In addition, the tutorial aims to be useful for a diverse audience but will become more biased in the later part.

Some examples are provided only as counterparts to Menke's introdution to Matlab.

Python syntax

Variables and formats

```
In [1]: # Single line comment
        Multiple
        line
        comments.
        # Integer division
        5 // 3
        -5 // 3
        # Exponentiation
        2**3
        # Boolean
        True
        not True
        True or False
        True and False
        # Comparison
        1 == 1
        1 != 2
        1 < 2
        2 <= 2
        1 < 2 < 3
        x = 0
        print('temperature data from {} to {}'.format(1.1, 2))
        print('{0} and {1}'.format('spam', 'eggs'))
        print('{1} and {0}'.format('spam', 'eggs'))
        print('x = ' + str(x))
        print(f'x = \{x\}')
        print(f'x = \{x:.3f\}')
        temperature data from 1.1 to 2
        spam and eggs
        eggs and spam
        x = 0
        x = 0
        x = 0.000
```

Data structures

```
In []: # List
         li = []
         li.append(1)
         li.append(2)
         li.append(3)
         li[1]
         li[1:2]
         len(li)
         a, b, c = li
         2 in li
         # Tuple
         tup = (1, 2, 3)
         # tup[0] = 2 # Tuples are immutable!
         # Dictionary
         di = {'one': 1, 'two': 2, 'three': 3}
         di['one']
         list(di.keys())
         list(di.values())
         'one' in di
         di.get('one')
         di.update({'four': 4})
         # Set
         se = set({1, 1, 2, 2, 3})
         se.add(4)
         other_set = \{3, 4\}
         se & other_set # intersection
se | other_set # union
se - other_set # difference
```

Control flows

```
In []: x = 5
        if x > 1:
            print('x > 1')
        elif x < 1:
            print('x < 1')
        else:
            print('x == 1')
        s = 0
        for i in range(1, 10, 1):
            s += i
        S
        x = 0
        while x < 2:
            print(x)
            x += 1
        # try:
              open('a/b')
        # except FileNotFoundError as e:
              raise e
        # else:
              pass
        # finally:
              pass
```

I/O (cf. using <u>numpy</u>, <u>pandas</u>)

```
In [ ]: fpath = '/Volumes/GoogleDrive/My Drive/6670/gda/data/global_temp.txt'
        with open(fpath, 'r') as f:
              d = f_read()
              d = f.readline()
              d = f.readlines()
            d = list(f)
              for i, line in enumerate(f):
        #
                  print(i, line)
        d
        year, temperature = [], []
        with open(fpath, 'r') as f:
            for line in f:
                y, t = line.split()
                year.append(int(y))
                temperature.append(float(t))
        # year, temperature
```

Functions

```
In []: def function_name(arg1, *args, **kwargs):
    print(arg1)
    print(args)
    print(kwargs)

    return

arg1 = 1
    args = (1, 2)
    kwargs = {'a': 1}
    # function_name(arg1)
    function_name(arg1, *args, **kwargs)
```

Modules

```
In []: import math
In []: a = 6
b = 8
c = math.sqrt(a**2 + b**2)
c
```

Classes

```
In [ ]: class Human(object):
            def __init__(self, name, skills=[]):
                self.name = name
                self.skills = skills
            def solve_problems(self):
                return True
        class Geologist(Human):
            def __init__(self, name, skills=['geology']):
                super().__init__(name=name, skills=skills)
                  super(Human, self).__init__(name=name, skills=skills)
        #
            def solve_geological_problems(self):
                return True
        class Physicist(Human):
            def __init__(self, name, skills=['physics']):
                super().__init__(name=name, skills=skills)
            def solve_physcis_problems(self):
                return True
        class Geophysicist(Human):
            def init (self, name, skills=['qeophysics']):
                super().__init__(name=name, skills=skills)
            def solve_geophysical_problems(self):
                return True
        class GeoPhysicist(Geologist, Physicist):
            def __init__(self, name, skills=['geology, physics']):
                Geologist.__init__(self, name=name, skills=skills)
                Physicist.__init__(self, name=name, skills=skills)
        p1 = GeoPhysicist(name='anonymous')
        p1.name
        p1.skills
        p1.solve_problems()
        # p1.solve_geological_problems()
        # p1.solve_geophysical_problems()
```

Command line

```
In [ ]: pwd
```

```
In [ ]: cd /Volumes/GoogleDrive/My\ Drive/6670
In [ ]: # dir()
In [ ]: ls -lh
```

Essential packages

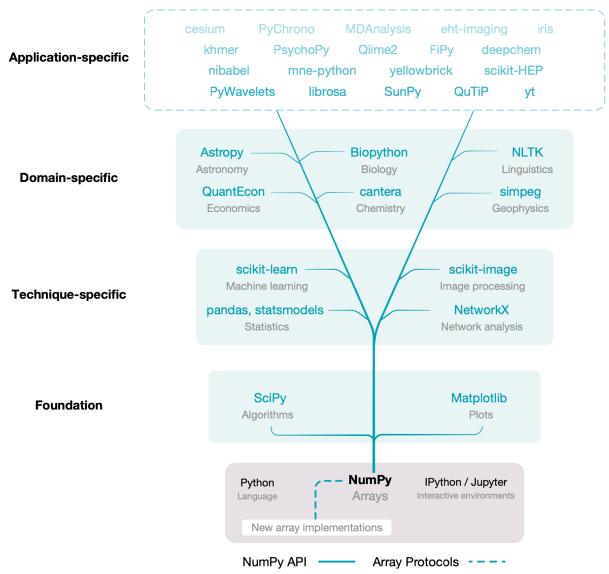
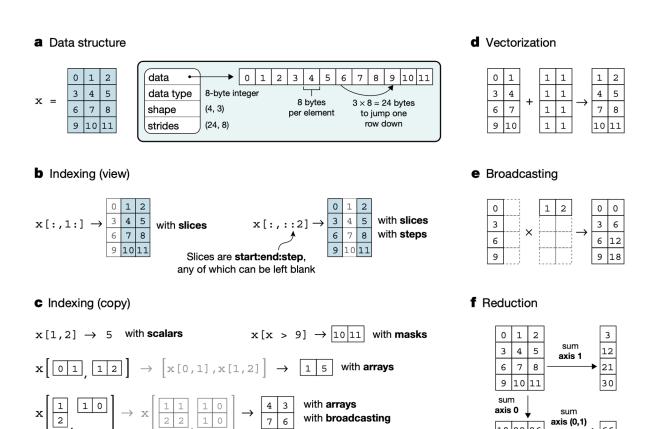


Fig: [Harris et al., 2020](https://doi.org/10.1038/s41586-020-2649-2).

Array programming with NumPy



axis (0,1)

18 22 26

Fig: [Harris et al., 2020](https://doi.org/10.1038/s41586-020-2649-2).

In []: import numpy as np

```
In [ ]: # Data structure
        x = np.arange(12).reshape(4, 3)
        x.dtype
        x.shape
        x.strides
        # Indexing (view)
        x[:, 1:]
        x[:, ::2]
        # Indexing (copy)
        x[1, 2]
        x[x > 9]
        x[[0, 1], [1, 2]]
        x[[[1], [2]], [1, 0]]
        # Vectorization
        a = np.column_stack([np.linspace(0, 9, 4), np.linspace(1, 10, 4)])
        b = np.ones((4, 2))
        a + b
        # Broadcasting
        a[:, 0].reshape(4, 1) * np.array([1, 2]).reshape(1, 2)
        # Reduction
        x.sum(axis=0)
        x.sum(axis=1)
        x.sum()
In []: r = np.array([2, 4, 6]).reshape(1, 3)
        c = np.array([1, 3, 5]).reshape(3, 1)
        r, c
In []: a = r[0, 1]
        b = c[2, 0]
        a, b
In []: M = np.arange(1, 10, 1).reshape(3, 3)
In []: c = M[0, 2]
        С
```

```
1, 0, 2,
            0, 1, 0,
            2, 0, 1,
        ]).reshape(3, 3)
        N = np.array([
            1, 0, -1,
            0, 2, 0,
            -1, 0, 3,
        ]).reshape(3, 3)
        S = M + N
In [ ]: D = M - N
In []: a = np.array([1, 3, 5]).reshape(3, 1)
        b = np.array([2, 4, 6]).reshape(3, 1)
        print(a.T @ b)
        print(np.dot(a.T, b))
        print(a.T.dot(b))
        print(a @ b.T)
        print(M @ a)
        print(M @ N)
        print(a * b)
```

· Loading data from a file

In []: |M = np.array([

Scientific computing with SciPy

```
In [ ]: import scipy as sp
from scipy import linalg # Linear algebra
```

```
In [ ]: # Matrix inverse
        \# A = np.array([
              [1, 5, 13],
              [2, 7, 17],
              [3, 11, 19],
        # ])
        \# b = np.array([1, 2, 3]).reshape(3, 1)
        # print(A)
        #B = linalg.inv(A)
        # print(B)
        # print(A @ B)
        # print(B @ A)
        \# c, error, rank, s = linalg.lstsq(A, b)
        # print(c, error)
        \# B = np.array([
              [1, 3, 4],
              [2, 3, 2],
              [0, 0, 4],
        # 1)
        \# D = B @ linalg.inv(A)
        # print(D)
        # Eigenvalues and eigenvectors
        M = np.array([
             [1, 2, 0],
             [2, 2, 0],
             [0, 0, 4],
        ])
        print(M)
        LAMBDA, V = linalg.eig(M)
        print(LAMBDA, '\n', V)
        print(V.T @ V)
```

• SVD (Singular Value Decomposition)

```
M = USV^H where UU^H = U^HU = I, VV^H = V^HV = I, and S is rectangular diagonal.
```

Visualization with Matplotlib

```
In []: import matplotlib.pyplot as plt

plt.rcParams.update({
    'figure.dpi': 300,
})

In []: fig, ax = plt.subplots()
ax.plot(
    d['year'], d['temperature'], 'r-', linewidth=2,
    marker='o', markerfacecolor='none', markeredgecolor='k',
)
ax.set_xlim(1965, 2020)
ax.set_ylim(-0.5, 1)
ax.set_xlabel(r'Calendar year, $t_i$ (years)')
ax.set_ylabel(r'Temperature anomaly, $T_i$ ($^\circ$C)')
ax.set_title('Global temperature data', fontsize=14)
# fig.savefig('test.pdf')
```

Specific packages

Analysis of tabular data with Pandas

```
In [ ]: import pandas as pd
```

Load data

Plot data

```
In [ ]: ax = df.plot('year', 'temperature', kind='line', c='r')
df.plot.scatter('year', 'temperature', ax=ax, c='k')
ax.set_ylim(-.5, 1)
```

· Data analysis

Machine learning with scikit-learn

Lasso (l_1) regression

```
\arg \min_{m} ||d - Gm||_{2}^{2} + \alpha ||m||_{1}
```

```
In [ ]: from sklearn.linear_model import Lasso
```

```
In [ ]: |np.random.seed(42)
        n_samples, n_features = 50, 100
        X = np.random.randn(n samples, n features)
        idx = np.arange(n features)
        coef = -1**idx * np.exp(-idx/10)
        coef[10:] = 0
        y = np.dot(X, coef)
        y += 0.01 * np.random.normal(size=n_samples)
        X_train, y_train = X[:n_samples//2], y[:n_samples//2]
        X_test, y_test = X[n_samples//2:], y[n_samples//2:]
        alpha = 0.1
        lasso = Lasso(alpha=alpha)
        model = lasso.fit(X_train, y_train)
        y_pred = model.predict(X_test)
        fig, axes = plt.subplots(1, 2, figsize=(10, 4))
        ax = axes[0]
        ax.stem(
            np.where(coef)[0], coef[coef != 0], 'b',
            linefmt='--',
            label='True coefficients',
            markerfmt='bx',
        ax.stem(
            np.where(lasso.coef_)[0], lasso.coef_[lasso.coef_ != 0],
            'k', markerfmt='kx', label='Lasso coefficients',
        ax.legend(loc='best')
        ax = axes[1]
        ax.scatter(y_train, model.predict(X_train), label='Train', alpha=.5)
        ax.scatter(y_test, y_pred, label='Test', alpha=.5)
        ax.plot([-6, 6], [-6, 6], c='k', zorder=-1)
        ax.set_xlabel('True')
        ax.set_ylabel('Prediction')
        ax.set aspect(1)
        ax.set_xlim(-6, 6)
        ax.set_ylim(ax.get_xlim())
        ax.legend(loc='best')
```

Cartography with cartopy

```
In [ ]: import cartopy.crs as ccrs
import cartopy.feature as cfeature
```

```
In []: fig, ax = plt.subplots(subplot_kw={'projection': ccrs.Mercator()})
        ax.stock_img()
        ax.gridlines(draw_labels=True, alpha=.1)
        ax.add_feature(cfeature.COASTLINE, lw=1)
        ax.add_feature(cfeature.BORDERS, lw=1)
        ax.add_feature(cfeature.STATES, lw=1)
        ax.set_extent([245, 260, 35, 43])
        \# x, y = np.meshgrid(
             np.linspace(252, 256),
              np.linspace(37, 41)
        # )
        \# z = x + y
        # im = ax.pcolormesh(
              X, y, Z,
              transform=ccrs.PlateCarree(), # required for plotting on maps
        #
        # )
        # cb = fig.colorbar(im, orientation='horizontal')
        # cb.set_label('Z (a.u.)')
```