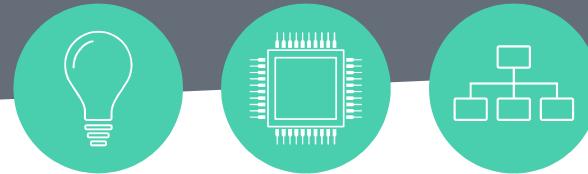


# Image recognition in java using CNN.



Made by:

Jayed Naoufal.  
Ziani Zaynab.  
Raihan Najib.

Mentored by:

Mr Bahri Abdelkhalak.

# Summary

- Introduction
- CNN
- ANN
- YOLO
- Code Explanation
- Demonstration
- Bibliography

# Introduction

Object detection and classification is a computer technology related to computer vision and image processing.

It is used in Computer Vision tasks such as: activity recognition, face detection/recognition, tracking moving objects...

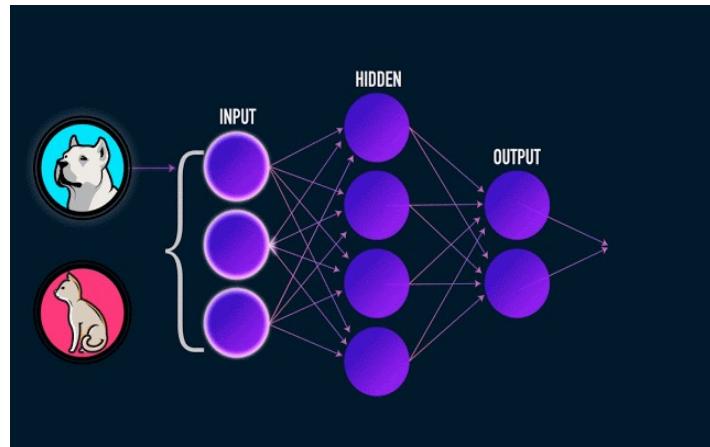
Methods for object detection fall in deep-learning-based approaches.

# What are Convolutional Neural Networks(CNNs)?

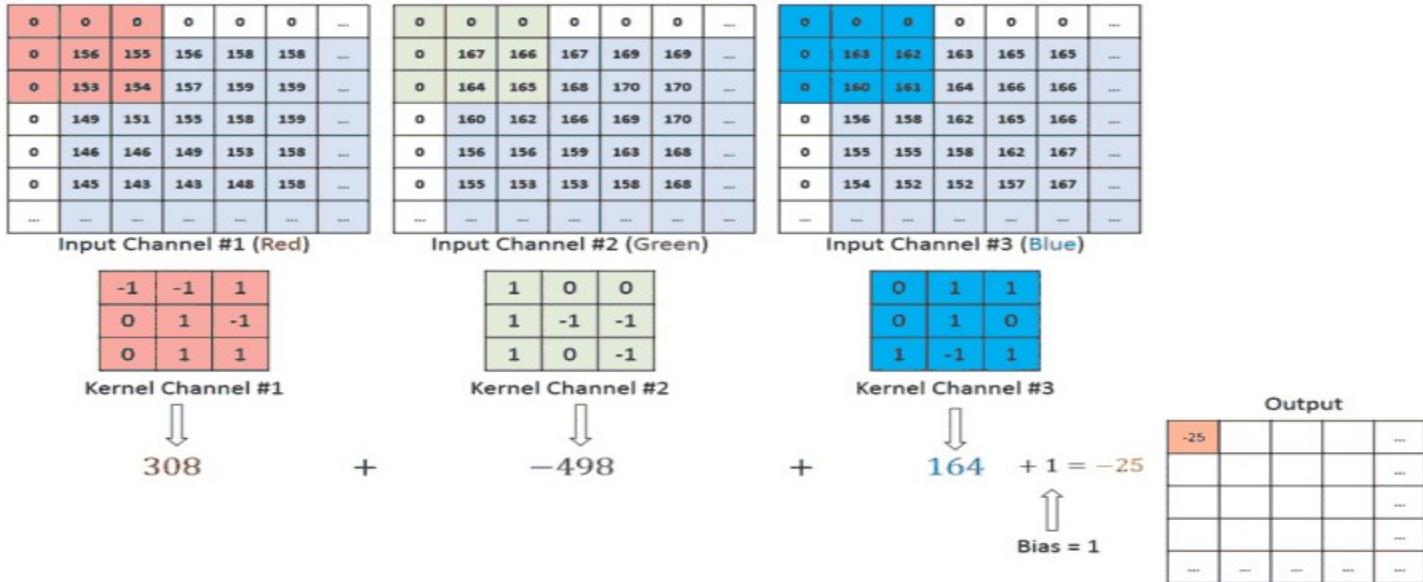
CNN is a class of deep neural network that is mostly used to do image recognition/classification, object detection... etc.

Steps:

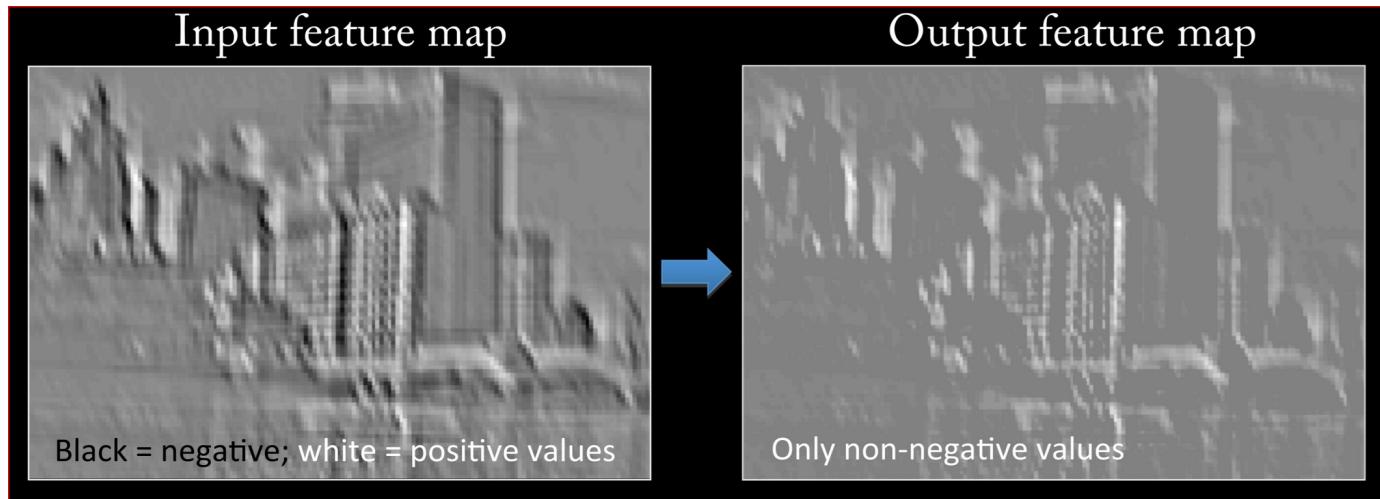
- Convolution
- ReLU (Rectified Linear-Unit)
- Pooling
- Flattening
- Full Connection



# Step1: Convolutions



## Step2: ReLU (Rectified Linear-Unit)



# Step3: Pooling

3.0	3.0	3.0
3.0	3.0	3.0
3.0	2.0	3.0

3	3	2	1	0
0	0	1	3	1
3	1	2	2	3
2	0	0	2	2
2	0	0	0	1

# Step4: Flattening

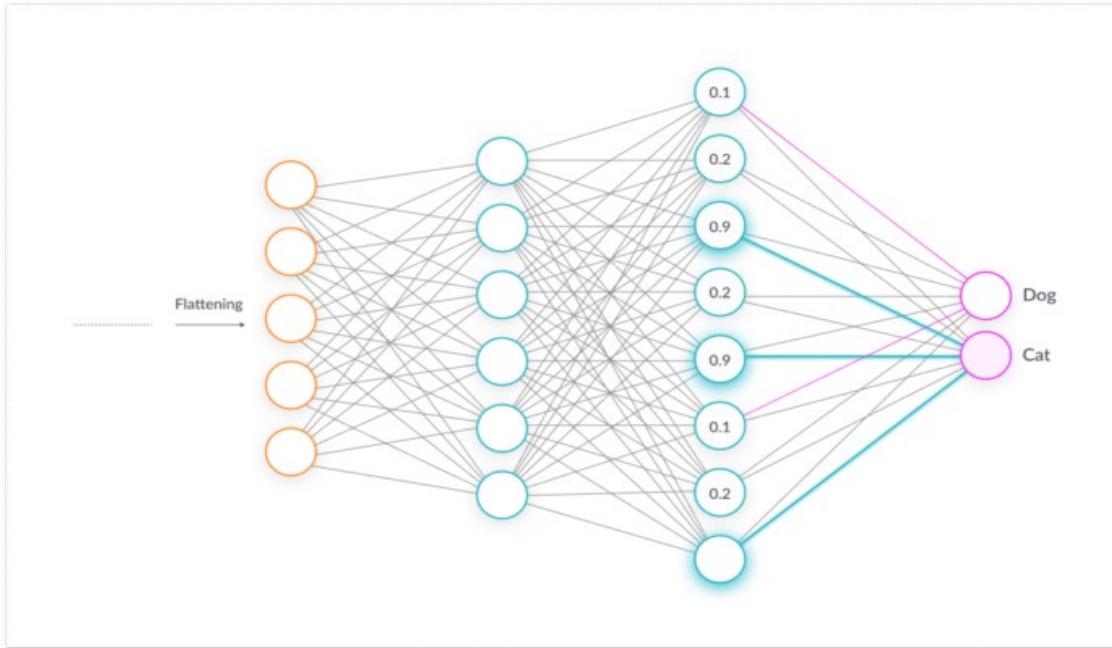
1	1	0
4	2	1
0	2	1

Pooled Feature Map

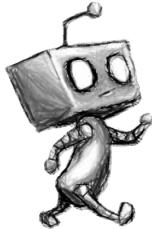
Flattening

1
1
0
4
2
1
0
2
1

# Step5: Full Connection



# What are Artificial Neural Networks(ANNs)?



ANN is an information processing paradigm that is inspired by the way the biological nervous system such as the brain processes information. It's composed of a large number of highly interconnected processing elements (neurons) working in union to solve a specific problem.

# Activation functions

- Introduces non-linearity to a NN.
- Decides whether a neuron should be activated or not.
- Many activation functions exist, each one has its advantages and drawbacks, we mention: Threshold function, sigmoid function, hyperbolic function ( $\tanh$ ), ReLU.

# How do NN learn?

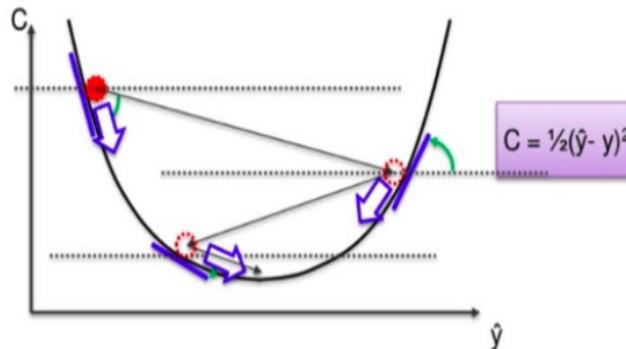
-Neural Networks use the back propagation concept for training.

The Output value is compared to the Actual value, by calculating a loss function :  $C = \frac{1}{2}(Y_{\text{output\_value}} - Y_{\text{actual\_value}})^2$  .

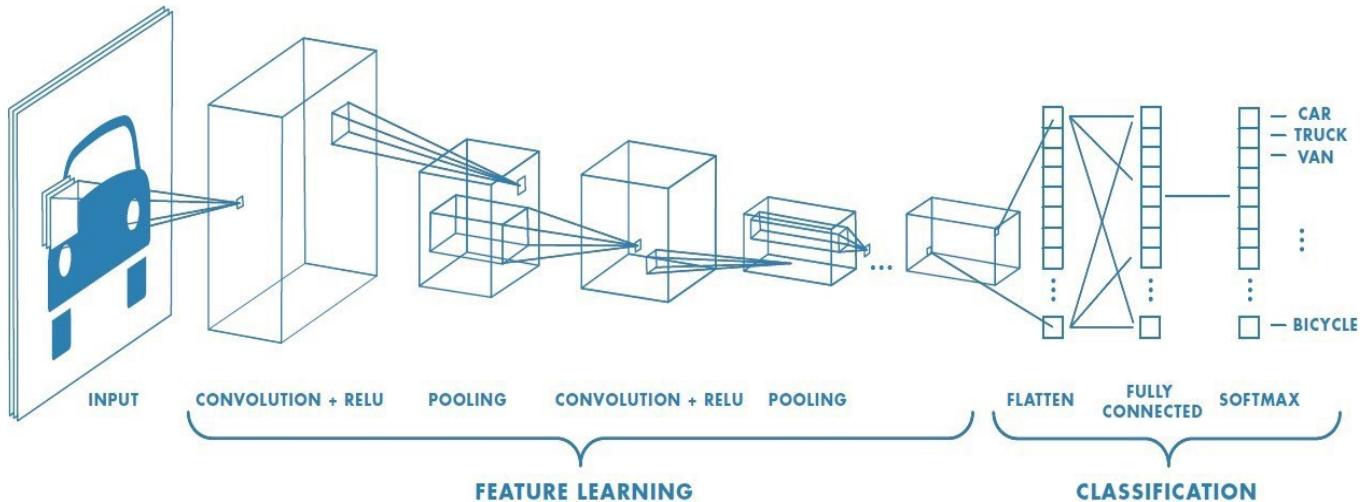
Then information are fed back to the network and weights are being update in the aim of minimizing the loss function.

# Gradient descent

-optimization algorithm responsible for finding the minimum cost value, instead of going through each weight at a time we consider the slope in the loss function.



# General architecture of CNN



# What did we use to recognize images in our project?

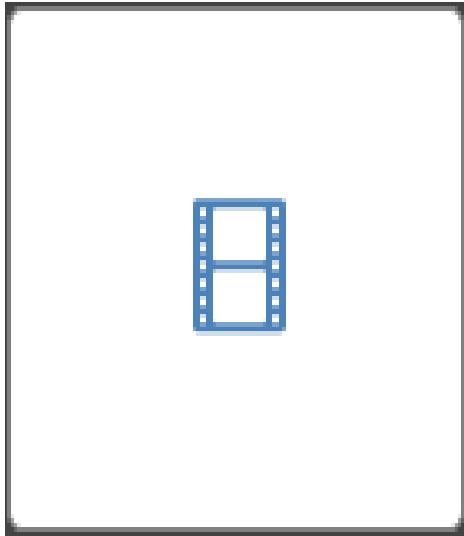


## Yolo (You Only Look Once)

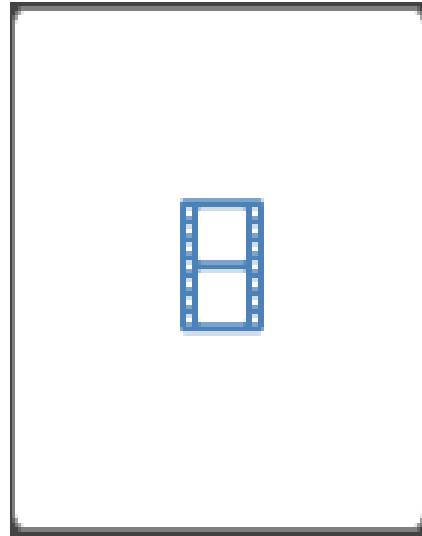
You Only Look Once is an algorithm that utilizes a single convolutional network for object detection.



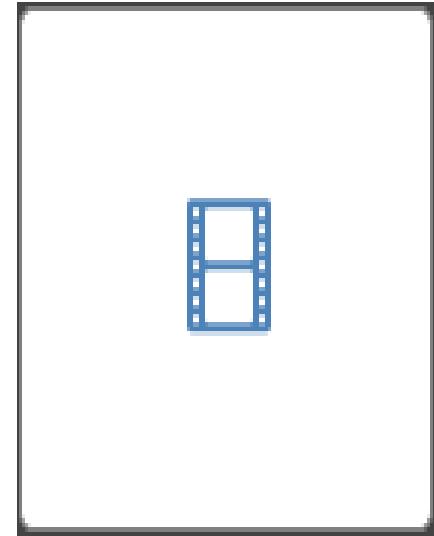
# Why exactly YOLO?



Fast RCCNs

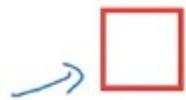


Faster RCCNs



YOLO

# Why are fast RCNNs Slower?



# How does YOLO work? What makes it faster?

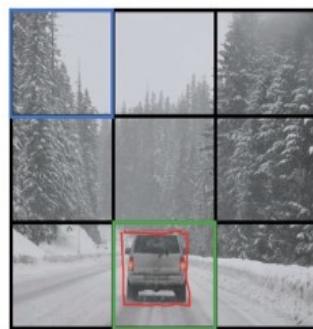
## Training



- 1 - pedestrian
- 2 - car
- 3 - motorcycle

$y$  is  $3 \times 3 \times 2 \times 8$

## Training



$y$  is  $\underbrace{3 \times 3 \times 16}_{\text{anchors}}$   
 $\uparrow$   $\overbrace{S + \# \text{classes}}$

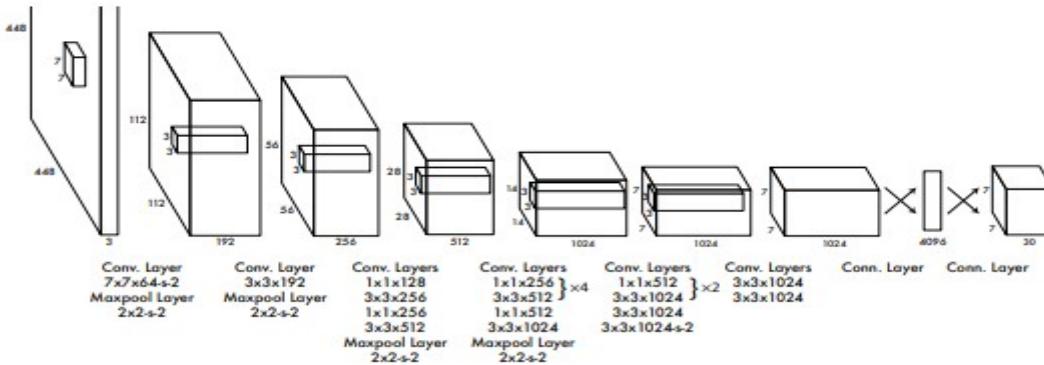
- 1 - pedestrian
- 2 - car
- 3 - motorcycle

$y =$

$$\begin{bmatrix} p_c \\ b_x \\ b_y \\ b_h \\ b_w \\ c_1 \\ c_2 \\ c_3 \\ p_c \\ b_x \\ b_y \\ b_h \\ b_w \\ c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 0 \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ 0 \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ ? \\ 1 \\ b_x \\ b_y \\ b_h \\ b_w \\ 0 \\ 1 \\ 0 \end{bmatrix}$$



=>



=>

What happens after  
generating the  
boxes and getting  
the output?

# Final Steps

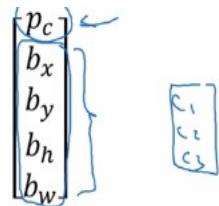
Removing boxes with a confidence $<0.6$



Non-Max Suppression



Each output prediction is:

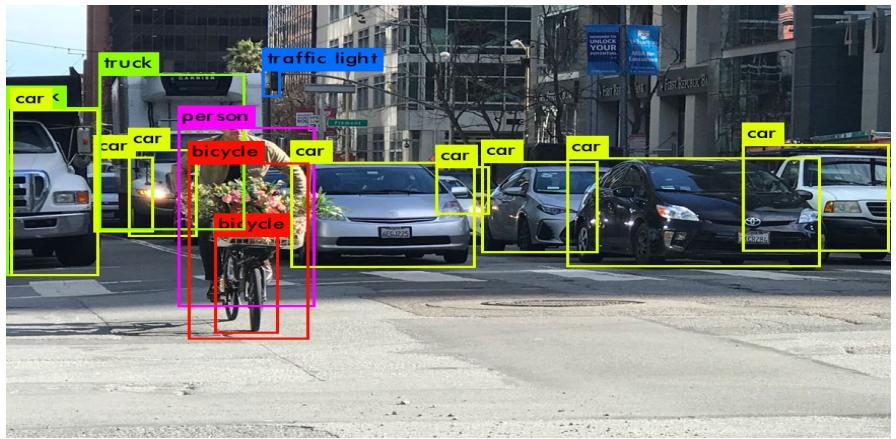


Discard all boxes with  $p_c \leq 0.6$

While there are any remaining boxes:

- Pick the box with the largest  $p_c$  Output that as a prediction.
- Discard any remaining box with  $\text{IoU} \geq 0.5$  with the box output in the previous step

# Some final results



# What do we need to run this algorithm?

- OpenCV v3.0 or newer version.
- YOLO v3 object detector model with 3 necessary files:
  - YOLOv3.weights
  - YOLOv3.cfg
  - ObjectsNames.names

# Code Explanation

- Loading weights and configuration files.

```
String modelWeights = "C:/yolo/yolov3.weights";      // weights of objects  
String modelConfiguration = "C:/yolo/yolov3.cfg";    //Convolutional layers  
  
Net net = Dnn.readNetFromDarknet(modelConfiguration, modelWeights);  
Mat image = Imgcodecs.imread(imagepath);  
Size sz = new Size( width: 416, height: 416);
```

- Reading ObjectsNames.names file

```
//////////  
  
String modelNames = "C:/yolo/coco.names";           //Objects names  
ArrayList<String> classes = new ArrayList<>();  
  
try {  
    FileReader file1 = new FileReader(modelNames);  
    BufferedReader bufferedReader = new BufferedReader(file1);  
    String Line;  
    while ((Line = bufferedReader.readLine()) != null) {  
        classes.add(Line);  
    }  
    bufferedReader.close();  
} catch (Exception error) {  
    System.out.println(error);  
}
```

- Creating a method for extracting the image's layers and their names



```
Test.java × darknet.java ×
package com.company;

import org.opencv.dnn.Net;
import java.util.ArrayList;
import java.util.List;

public class darknet {

    static List<String> names;
    static List<Integer> outLayers;
    static List<String> layersNames;

    @
    public darknet(Net net){
        names = new ArrayList<>();
        outLayers = net.getUnconnectedOutLayers().toList();
        layersNames = net.getLayerNames();
    }

    public static List<String> getOutputNames() {
        outLayers.forEach((item) -> names.add(layersNames.get(item - 1)));
        return names;
    }
}
```

## • Constructing the Blobs

```
Mat blob = Dnn.blobFromImage(image, scalefactor: 0.00392, sz, new Scalar( v0: 0), swapRB: true, crop: false);
net.setInput(blob);

///////////////////////
darknet Layers = new darknet(net);
List<String> outBlobNames = darknet.getOutputNames();
//outBlobNames.forEach(System.out::println);

///////////////////////
// backforward in Boxes

List<Mat> result = new ArrayList<>();
net.forward(result, outBlobNames);
//result.forEach(System.out::println);

///////////////////
```

- A blob is just a (potentially collection) of image(s) with the same spatial dimensions (i.e., width and height.

- Removing boxes with confidence<0.95f

```
float confThreshold = 0.95f;      ///// Minimum probability to filter weak detections
List<Integer> classesIds = new ArrayList<>();
List<Float> confidences = new ArrayList<>();
List<Rect> rects = new ArrayList<>();

for (int i = 0; i < result.size(); i++) {
    // [center_x, center_y, width, height]+ probabilities
    Mat level = result.get(i);                      ///// generate matrix of 4 dimensions
    for (int j = 0; j < level.rows(); j++) {
        Mat row = level.row(j);
        Mat scores = row.colRange(5, level.cols());
        Core.MinMaxLocResult mm = Core.minMaxLoc(scores); // search the row of the maximum
        float confidence = (float) mm.maxVal;
        Point classIdPoint = mm.maxLoc;           // get location for max condidance

        if (confidence > confThreshold) // filter row of weak detections
        {
            int centerX = (int) (row.get( row: 0, col: 0)[0] * image.cols()); // get
            int centerY = (int) (row.get( row: 0, col: 1)[0] * image.rows());
            int width = (int) (row.get( row: 0, col: 2)[0] * image.cols());
            int height = (int) (row.get( row: 0, col: 3)[0] * image.rows());
            int left = centerX - width / 2;          // get topleft point coordinates
            int top = centerY - height / 2;

            classesIds.add((int) classIdPoint.x);
            confidences.add((float) confidence);
            rects.add(new Rect(left, top, width, height)); // information of boxes
        }
    }
}
```

- Non Maximum suppression

```
/////////////////// Non-Maximum-Suppression
Rect[] boxesArray = rects.toArray(new Rect[0]);
MatOfRect boxes = new MatOfRect(boxesArray);
MatOfFloat confidence = new MatOfFloat(Converters.vector_float_to_Mat(confidences));
float NMSThreshold = 0.4f; // This is our non-maxima suppression threshold
MatOfInt indices = new MatOfInt();
Dnn.NMSBoxes(boxes, confidence, confThreshold, NMSThreshold, indices); // intersection over union IOU
```

- Draw the final boxes

```
int[] ind = indices.toArray();
System.out.println(ind.length);
for (int i = 0; i < ind.length; i++) {

    System.out.println(ind[i]);
    int idx = ind[i];
    Rect box = boxesArray[idx];      // get objects by index of classes
    System.out.println(box);

    String label = classes.get(classesIds.get(i)) + String.format("%.2f", confidences.get(i) * 100) + "%";
    Imgproc.rectangle(image, box.tl(), box.br(), new Scalar(0, 255, 0), thickness: 5); // object box
    Imgproc.putText(image, label, new Point( x: box.x + 10, box.y), fontFace: 5, fontScale: 5, new Scalar(0, 255, 0), thickness: 3); // object r
    //System.out.println(box);
}
```

# Demonstration



## Yolo Image detection

Now we will show you the demonstration of the previously explained java code.

# Bibliography

[https://en.wikipedia.org/wiki/Object\\_detection](https://en.wikipedia.org/wiki/Object_detection)

<https://medium.com/nybles/a-brief-guide-to-convolutional-neural-network-cnn-642f47e88ed4>

<https://medium.com/technologymadeeasy/the-best-explanation-of-convolutional-neural-networks-on-the-internet-fbb8b1ad5df8>

<https://towardsdatascience.com/introduction-to-artificial-neural-networks-ann-1aea15775ef9>