

Supporting Information for “Dir-GLM: A Bayesian GLM with data-driven reference distribution” by Entejar Alam, Peter Müller, and Paul J. Rathouz

Appendix A: Results, Proofs and additional Figures

In this section, we first provide the proofs of all the results stated in “Dir-GLM: A Bayesian GLM with data-driven reference distribution” [AMR, 2024].

Result 1. *The exponentially tilted Dirichlet distribution, $tDir(c, \mu, s)$ with $c = \{\alpha H(s_\ell); \ell = 1, \dots, k\}$, $s = \{s_\ell; \ell = 1, \dots, k\}$, is outside the Dirichlet parametric family; however, it remains a valid probability distribution defined over the $(k - 1)$ dimensional simplex. In the context of Eq. (1) in [AMR, 2024], exponential tilting transforms $f_0(s_\ell)$ to $f(s_\ell | x) \propto \exp(\theta s_\ell) f_0(s_\ell)$.*

Proof. As per Eq. (4) in [AMR, 2024], $[f_0(s_1), \dots, f_0(s_k)] \sim \text{Dir}[\alpha H(s_1), \dots, \alpha H(s_k)]$. Let $a_\ell = \alpha H(s_\ell) > 0$ and $f_{0,\ell} = f_0(s_\ell)$, $\ell = 1, \dots, k$. Upon exponential tilting $f_{0,\ell}$ as per Eq. (1) in [AMR, 2024], it transforms to $f(s_\ell | x) \propto \exp(\theta_x s_\ell) f_{0,\ell}$. We use $f_0^{(x)}$ to represent the tilted random vector $[f(s_1 | x), \dots, f(s_k | x)]$.

We proof the result using contradiction. We then assume that $f_0^{(x)}$ follows a Dirichlet distribution. So, its marginal should be a beta distribution. For simplicity, we first take $k = 2$, and denote $Z_\ell = f_{0,\ell}$, for $\ell = 1, 2$. Thus, Z_1 follows a beta distribution with shape parameters (a_1, a_2) , and $Z_2 = 1 - Z_1$. Writing $Z_\ell^x = f_{0,\ell}^x$, we have

$$Z_1^x = \frac{\exp(\theta_x s_1) Z_1}{\exp(\theta_x s_1) Z_1 + \exp(\theta_x s_2) Z_2} = \frac{\exp(\theta_x s_1) Z_1}{\exp(\theta_x s_2) + [\exp(\theta_x s_1) - \exp(\theta_x s_2)] Z_1} = h(Z_1).$$

For notational simplicity, let $u = \exp(\theta_x s_1)$ and $v = \exp(\theta_x s_2)$. Then Z_1^x can be expressed as $Z_1^x = \frac{u Z_1}{v + (u-v) Z_1}$, and $Z_1 = h^{-1}(Z_1^x) = \frac{v Z_1^x}{u - Z_1^x(u-v)}$. The density of Z_1 is $f_{Z_1}(z) = \frac{1}{B(a_1, a_2)} z^{a_1-1} (1-z)^{a_2-1}$, $0 < z < 1$, where $B(a_1, a_2)$ is the beta function. The Jacobian of the transformation is $J = \left| \frac{dz_1}{dz_1^x} \right| = \frac{uv}{[u - z_1^x(u-v)]^2}$. Applying the change of variables formula, we get

$$\begin{aligned} f_{Z_1^x}(z) &= f_{Z_1}(h^{-1}(z)) \cdot |J| \\ &= \frac{1}{B(a_1, a_2)} \cdot \left[\frac{vz}{A - z(u-v)} \right]^{a_1-1} \cdot \left[1 - \frac{vz}{u - z(u-v)} \right]^{a_2-1} \cdot \frac{uv}{[u - z(u-v)]^2} \end{aligned}$$

Let $w = v/u$. After simplification, the density of Z_1^x is

$$f_{Z_1^x}(z) = \frac{w^{a_1}}{B(a_1, a_2)} \cdot \frac{z^{a_1-1} \cdot (1-z)^{a_2-1}}{[1 - (1-w)z]^{a_1+a_2}}, \quad (1)$$

for $0 < z < 1$, where $w = \exp[\theta_x(s_2 - s_1)]$. Based on the density in Eq. (1), we can say that Z_1^x does not follow a beta distribution. A similar argument can be made for $k > 2$, with h representing a multivariate mapping. This contradiction implies that the exponentially tilted Dirichlet random vector $f_0^{(x)}$ is outside the Dirichlet parametric family. Nevertheless, since $f_{0,\ell}^{(x)} \in [0, 1]$ for all s_ℓ , $\ell = 1, \dots, k$ and $\sum_{\ell=1}^k f_{0,\ell}^{(x)} = 1$, it remains a valid probability distribution defined over the standard $(k - 1)$ dimensional simplex. \square

Result 2. Under the Dir-GLM with prior model (4) in [AMR, 2024], with the additional constraint that μ is bounded away from the two endpoints s_1 and s_k , and $f_0 \in \mathcal{F}^* = \{f_0^* \in \mathcal{F} : E_{f_0^*}(y) = \mu_0\}$, if g and μ_0 are chosen such that as $\|x\|_2 \rightarrow 0$, $\mu = g^{-1}(\eta) \xrightarrow{P} \mu_0$, then the derived parameter $\theta = \theta(x; \beta, f_0)$ has the following properties

(a) $\theta \xrightarrow{P} 0$, and

(b) θ is asymptotically normal with mean zero.

Proof. The derived parameter $\theta = \theta(x; \beta, f_0)$ is a solution from Eq. (3) in [AMR, 2024]. If possible let, $\theta \xrightarrow{P} \theta_0 (\neq 0)$ as $\|x\|_2 \rightarrow 0$. Using continuous mapping theorem, we have

$$b'(\theta) \xrightarrow{P} b'(\theta_0) \text{ [as } b' \text{ is a continuous function]} \quad (2)$$

From Eq. (3) in [AMR, 2024], we have

$$b'(\theta) = \frac{\int_{\mathcal{Y}} y \exp(\theta y) f_0(y) dy}{\int_{\mathcal{Y}} \exp(\theta y) f_0(y) dy} = g^{-1}(\eta) \xrightarrow{P} \mu_0 \text{ [as } \mu = g^{-1}(\eta) \xrightarrow{P} \mu_0, \text{ as } \|x\|_2 \rightarrow 0] \quad (3)$$

Note that b' is a one-to-one function since $b''(\theta) = \text{Var}_{\theta}(y) > 0$. Using Eqs. (2) and (3), $b'(\theta_0) = \mu_0$. A trivial solution is $\theta_0 = 0$, as $b'(0) = \frac{\int_{\mathcal{Y}} y f_0(y) dy}{\int_{\mathcal{Y}} f_0(y) dy} = \mu_0$. By assumption $\theta_0 \neq 0$. Hence, there are at least two values of θ_0 which satisfies $b'(\theta_0) = \mu_0$. This implies that b' is not a one-to-one function, which is not true. Hence, proof by contradiction and we have $\theta \xrightarrow{P} 0$ as $\|x\|_2 \rightarrow 0$. This completes part (a).

Define a function $h : \mathcal{R} \rightarrow \mathcal{R}$ such that $h = b'^{-1} \circ g^{-1}$. First consider proving the following required properties: $h(0) = 0$ and $h'(0) \neq 0$. If possible let, $h(0) = \theta_0 (\neq 0)$. We have $\lim_{\|x\|_2 \rightarrow 0} g^{-1}(\eta) = \mu_0$. Since g^{-1} is a continuous function, $g^{-1}(0) = \mu_0$. Based on Eq. (3) in [AMR, 2024], we have $b'(\theta_0) = b'(h(0)) = g^{-1}(0) = \mu_0$. Also, $b'(0) = \mu_0$. Since $\theta_0 \neq 0$, b' is not a one-to-one function, which is not true. Hence, proof by contradiction and we have $h(0) = 0$. For the next one, first note that h is differentiable by definition since composite of two differentiable functions is also differentiable. Upon differentiating $g(b'(h(\eta))) = \eta$ both sides with respect to η , we have

$$g'(b'(h(\eta))) \cdot b''(h(\eta)) \cdot h'(\eta) = 1 \quad (4)$$

Eq. (4) implies that $h'(\eta)$ can not be zero for any choices of η . Hence, $h'(0) \neq 0$. In part (b), we are to show that θ is asymptotically mean-zero normal as $\|x\|_2 \rightarrow 0$. Due to the sequential definition of limit, equivalently we can show the result for an arbitrary sequence $\{x_m\}_{m=1}^{\infty}$ with $\lim_{m \rightarrow \infty} \|x_m\|_2 \rightarrow 0$, where $x_m = \left(\frac{x_1^*}{\sqrt{m_1}}, \dots, \frac{x_p^*}{\sqrt{m_p}} \right)$ with $m = \min_j m_j \rightarrow \infty$. We consider the following two exhaustive cases.

Case 1. Take $m_j = k_j m + r_j$ for some fixed constants $k_j \neq 0$ and r_j . Define, $\tilde{x}_j = \frac{x_j^*}{\sqrt{k_j}}$ and $\frac{r_j}{k_j} = \tilde{r}_j$ for all j . Then, we can express x_m as

$$x_m = \left(\frac{x_1^*}{\sqrt{m_1}}, \dots, \frac{x_p^*}{\sqrt{m_p}} \right) = \left(\frac{\tilde{x}_1}{\sqrt{m + \tilde{r}_1}}, \dots, \frac{\tilde{x}_p}{\sqrt{m + \tilde{r}_p}} \right)$$

We have, $\eta_m = g(b'(\theta_m)) = x_m^t \beta = \sum_{j=1}^p \frac{\tilde{x}_j}{\sqrt{m + \tilde{r}_j}} \beta_j$, which implies $\sqrt{m} \eta_m = \sum_{j=1}^p \frac{\tilde{x}_j}{\sqrt{1 + \tilde{r}_j/m}} \beta_j \xrightarrow{D} N(0, \|\tilde{x}\|_2^2)$ (using Slutsky's theorem as $1 + \tilde{r}_j/m \rightarrow 1$). Using delta method,

$$\sqrt{m}(\eta_m - 0) \sim N(0, \|\tilde{x}\|_2^2) \Rightarrow \sqrt{m}\{h(\eta_m) - h(0)\} \xrightarrow{D} N(0, \{h'(0)\}^2 \|\tilde{x}\|_2^2), \quad (5)$$

since $h'(0)$ exists and is non-zero. Note that $\theta_m = b'^{-1}(g^{-1}(\eta_m)) = h(\eta_m)$. Since $h(0) = 0$, from Eq. (5) we have $\sqrt{m} \theta_m \xrightarrow{D} N(0, \{h'(0)\}^2 \|\tilde{x}\|_2^2) \equiv \text{mean-zero normal}$.

Case 2. Take $m_j = k_j m^{\alpha_j} + r_j$ for some fixed constants $k_j \neq 0$ and r_j , where $\alpha_j = 1$ for some j and $\alpha_j > 1$ for others. WOLG let's assume that $\alpha_j = 1$ for $j = 1$ and $m = \min_j m_j = m_1$. Define, $\tilde{x}_j = \frac{x_j^*}{\sqrt{k_j}}$ and $\tilde{r}_j = \frac{r_j}{k_j}$ for all j . Then, we can express x_m as

$$x_m = \left(\frac{\tilde{x}_1}{\sqrt{m}}, \frac{\tilde{x}_2}{\sqrt{m^{\alpha_2} + \tilde{r}_2}}, \dots, \frac{\tilde{x}_p}{\sqrt{m^{\alpha_p} + \tilde{r}_p}} \right)$$

We have, $\eta_m = g(b'(\theta_m)) = x_m^t \beta = \frac{\tilde{x}_1}{\sqrt{m}} \beta_1 + \sum_{j=2}^p \frac{\tilde{x}_j}{\sqrt{m^{\alpha_j} + \tilde{r}_j}} \beta_j \Rightarrow \sqrt{m} \eta_m = \tilde{x}_1 \beta_1 + \sum_{j=2}^p \frac{\tilde{x}_j}{\sqrt{m^{\alpha_j-1} + \tilde{r}_j/m}} \beta_j$.

Here, $\tilde{x}_1 \beta_1 \sim N(0, \tilde{x}_1^2)$ and $\sum_{j=2}^p \frac{\tilde{x}_j}{\sqrt{m^{\alpha_j-1} + \tilde{r}_j/m}} \beta_j \xrightarrow{P} 0$ as $\alpha_j - 1 > 0$ for $j = 2, \dots, n$. Hence, using

Slutsky's theorem, we can say that $\sqrt{m} \eta_m \xrightarrow{D} N(0, \tilde{x}_1^2) + 0 \equiv N(0, \tilde{x}_1^2)$. Using delta method and following similar steps as in case 1, we get

$$\sqrt{m} \theta_m \xrightarrow{D} N(0, \{h'(0)\}^2 \tilde{x}_1^2) \equiv \text{mean-zero normal}$$

In case 1 and 2, we have shown that for any arbitrary sequence $\{x_m\}_{m=1}^\infty$ with $\lim_{m \rightarrow \infty} \|x_m\|_2 \rightarrow 0$, $\sqrt{m} \theta_m$ converges in distribution to a mean-zero normal. Hence, as $\|x\|_2 \rightarrow 0$, the derived parameter θ is asymptotically normal with zero mean. \square

Additional Figures. See Section 3.1 in [AMR, 2024]. We here show the cdf of $f_0^* \in \mathcal{F}^*$ for two choices of $f_0 \in \mathcal{F}$ in Figure 1. As we increase μ_0 , the distribution f_0^* becomes more and more left-skewed to achieve the required mean.

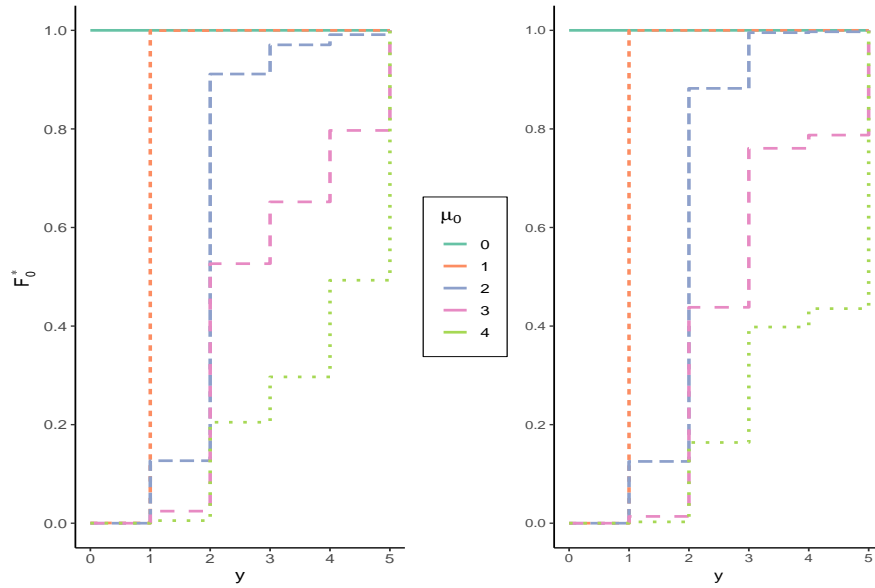


Figure 1: For two choices of f_0 (blue line, with $\mu_0 = 2$), the figure shows the equivalent (with respect to likelihood identifiability) exponentially tilted f_0^* with fixed μ_0 , with different color lines showing the cdf for f_0^* for different μ_0 .

See Section 3.2 in [AMR, 2024]. Using the same setup as in Figure 2 in [AMR, 2024], a kernel density estimate of the prior density on θ for different values of x is displayed in Figure 2.

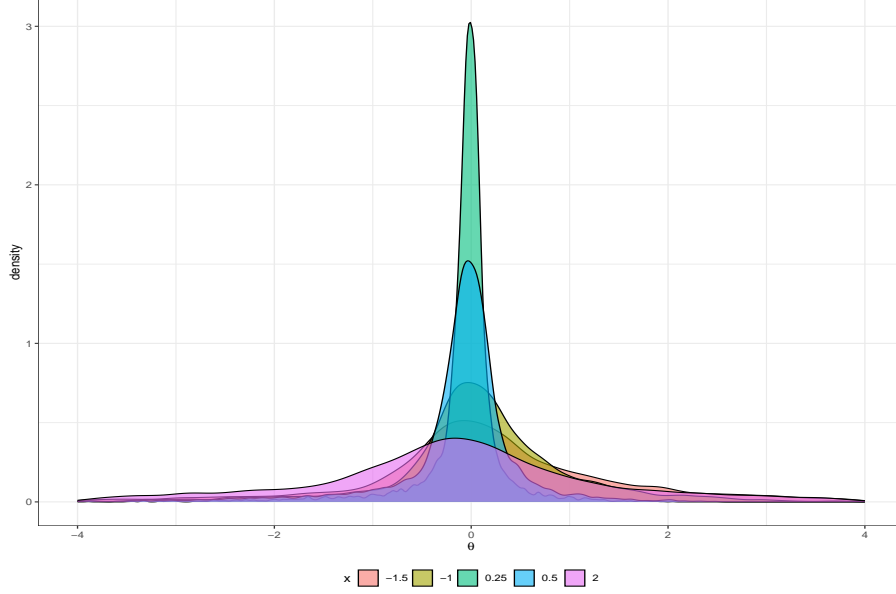


Figure 2: Kernel density estimate of the prior density on θ , for various values of x .

Appendix B: Simulation results

This section provides some additional plots for the regression parameters. Figure 3 represents the Rao–Blackwellized marginal posterior density estimate and its uncertainty quantification, in terms of 95% quantile-based credible intervals, for the regression parameters. The estimates and credible intervals are averaged across 10 replicates based on the first simulation scenario.

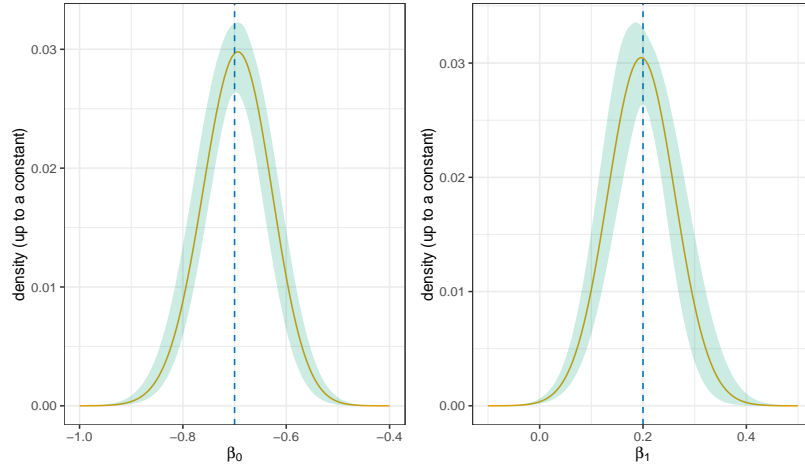


Figure 3: Simulation study. The solid brown curve represents the Rao–Blackwellized marginal posterior density estimate and the shaded area (in light green) surrounding it indicates the corresponding 95% credible band for the regression parameters. The blue dotted line represents the true value.

Figure 4 shows the box-plots of Dir-GLM estimates as a function of sample size (n), for the regression parameters. With the increase in sample size, the estimate converges to the truth — ensures consistency. This figure is based on 1,000 replicates using the first simulation scenario.

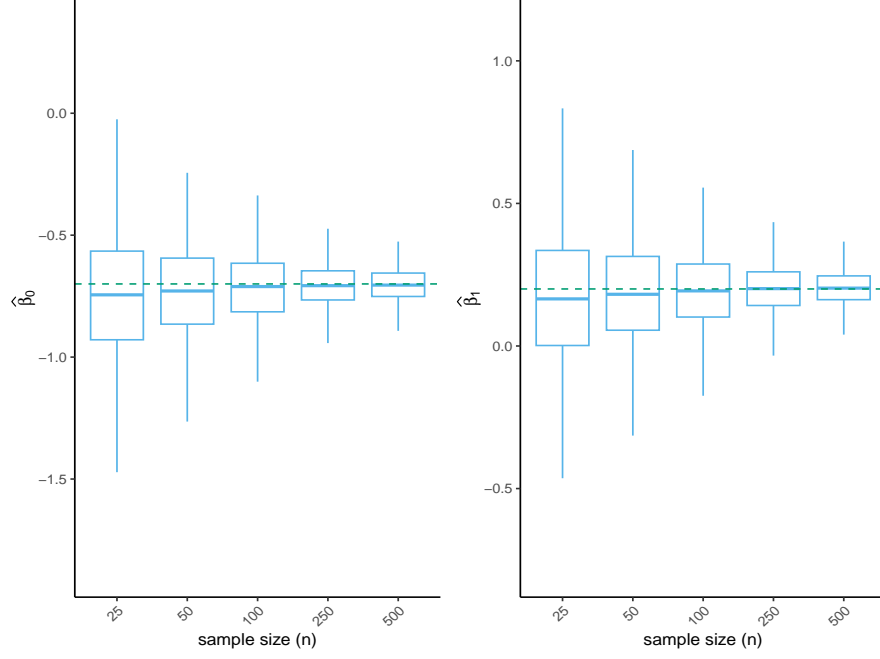


Figure 4: Simulation study. Box-plots of Dir-GLM estimates as a function of sample size, for the regression parameters. The green dotted line represents the true value.

In Figures 5 and 6, we compare estimation of the selected exceedance probabilities, $p(y \geq y_0 \mid x)$ with $y_0 = 2$ and 4, under GLDRM and Dir-GLM models.

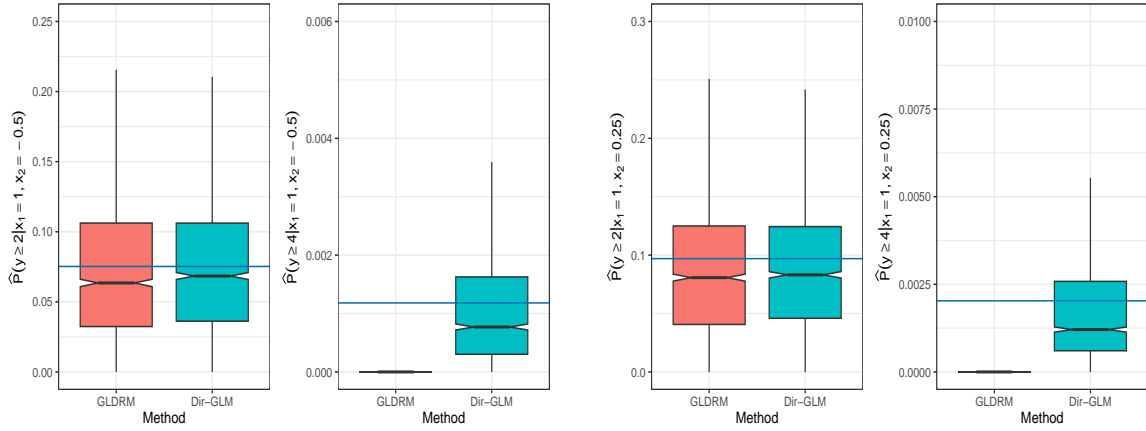


Figure 5: Simulation study. Exceedance probability estimates for GLDRM and Dir-GLM models replicating over 2,000 simulated data sets. Blue horizontal line denotes the true value. This figure is based on the first simulation scenario.

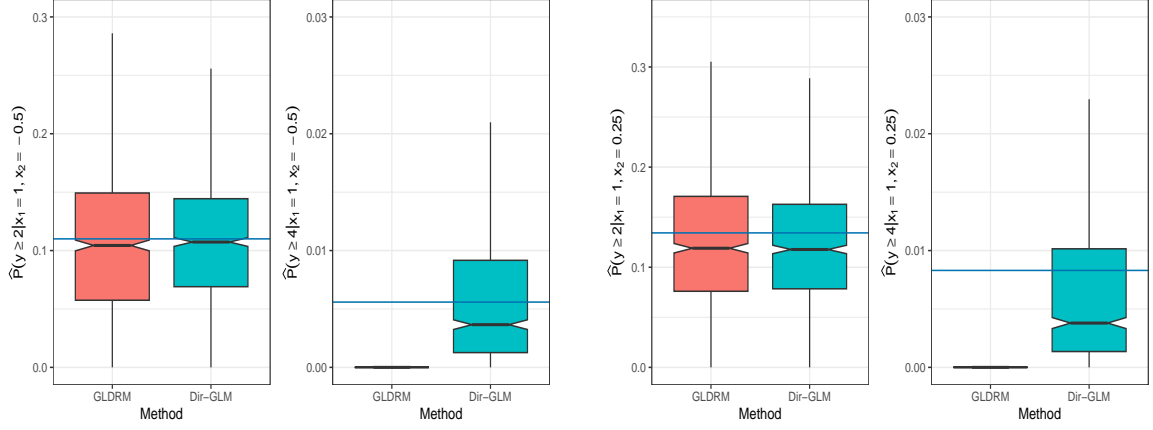


Figure 6: Simulation study. Exceedance probability estimates for GLDRM and Dir-GLM models replicating over 2,000 simulated data sets. Blue horizontal line denotes the true value. This figure is based on the second simulation scenario.

Appendix C: Large sample simulation results for f_0

Table 1: Simulation study. Same as Table 2 in [AMR, 2024], for $n = 250$.

n	DGM	Parm	Method	True value	Est _a	RRMSE _a	Est _m	RRMSE _m	CP
250	1	$f_0(0)$	GLDRM	0.367	0.359	1.00	0.359	1.00	N/A
			Dir-GLM		0.370	0.92	0.370	0.93	0.95
		$f_0(1)$	GLDRM	0.368	0.373	1.00	0.372	1.00	N/A
			Dir-GLM		0.369	0.97	0.368	0.99	0.95
		$f_0(2)$	GLDRM	0.185	0.191	1.00	0.188	1.00	N/A
			Dir-GLM		0.183	0.91	0.181	0.94	0.93
		$f_0(3)$	GLDRM	0.062	0.062	1.00	0.062	1.00	N/A
			Dir-GLM		0.056	0.92	0.056	0.93	0.93
		$f_0(4)$	GLDRM	0.015	0.014	1.00	0.000	1.00	N/A
			Dir-GLM		0.016	0.63	0.014	0.45	0.97
		$f_0(5)$	GLDRM	0.003	0.000	1.00	0.000	1.00	N/A
			Dir-GLM		0.006	1.70	0.004	0.48	0.97
	2	$f_0(0)$	GLDRM	0.471	0.465	1.00	0.466	1.00	N/A
			Dir-GLM		0.471	0.91	0.472	0.93	0.94
		$f_0(1)$	GLDRM	0.232	0.235	1.00	0.234	1.00	N/A
			Dir-GLM		0.233	0.99	0.232	1.00	0.95
		$f_0(2)$	GLDRM	0.172	0.177	1.00	0.174	1.00	N/A
			Dir-GLM		0.173	0.95	0.172	0.97	0.94
		$f_0(3)$	GLDRM	0.085	0.087	1.00	0.087	1.00	N/A
			Dir-GLM		0.082	0.93	0.084	0.94	0.94
		$f_0(4)$	GLDRM	0.031	0.030	1.00	0.029	1.00	N/A
			Dir-GLM		0.028	0.86	0.026	0.99	0.91
		$f_0(5)$	GLDRM	0.009	0.006	1.00	0.000	1.00	N/A
			Dir-GLM		0.012	0.87	0.008	0.54	0.95

Appendix D: Predictive inference for the AHEAD data

We perform a small sample study on the AHEAD data in Section 6.2 in [AMR, 2024]. The competing models GLDRM and Dir-GLM are fitted based on a small training data set of size $n = 100$, randomly sampled from the complete AHEAD data of size 6,441. We then assess prediction accuracy on the held-out test data set of size 6,341. For comparison, we focus on estimating probabilities of exceedance events at moderate and severe difficulty in daily activities, i.e. $p(y \geq y_0 | x)$ with $y_0 = 2$ and 4, respectively. The comparison is summarized in Figure 7.

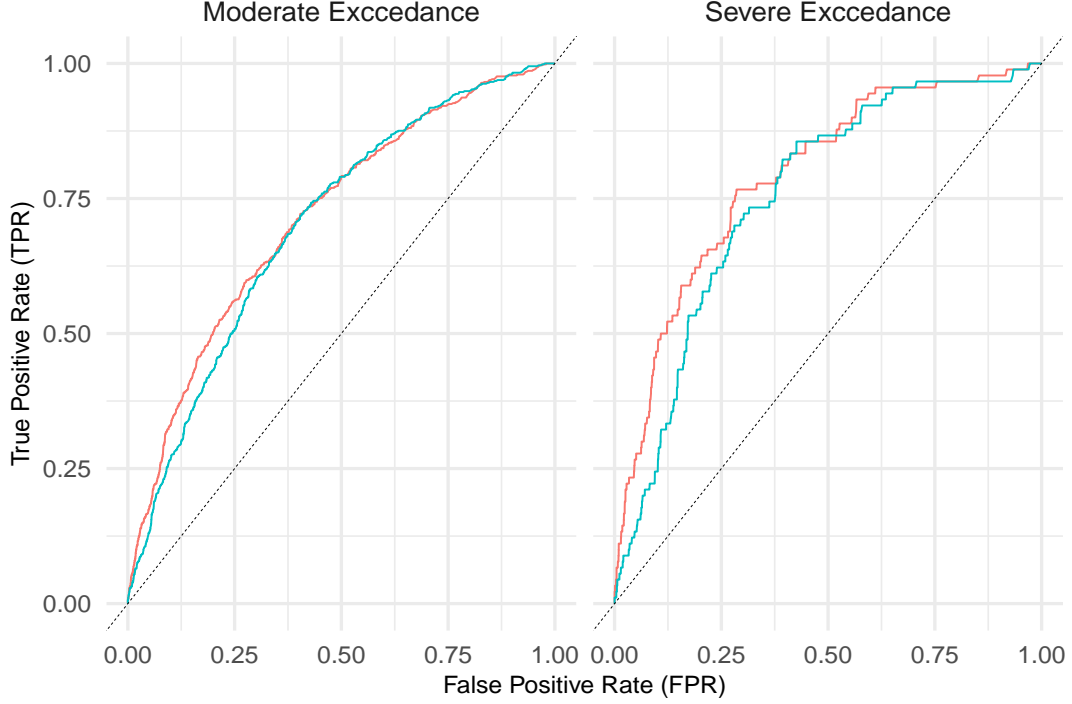


Figure 7: AHEAD study. ROC plot for comparing GLDRM (cyan) and Dir-GLM (coral) model accuracy in predicting moderate exceedance events (left) and severe exceedance events (right) on the held-out test data set.

Figure 8 presents some additional analysis plots. The competing models GLDRM and Dir-GLM are again fitted based on a small training data set of size $n = 100$, randomly sampled from the complete AHEAD data of size 6,441. However here we assess the prediction accuracy in estimating exceedance probabilities based on five test data sets, of size 1,000, randomly sampled from the held aside test data set of size 6,341.

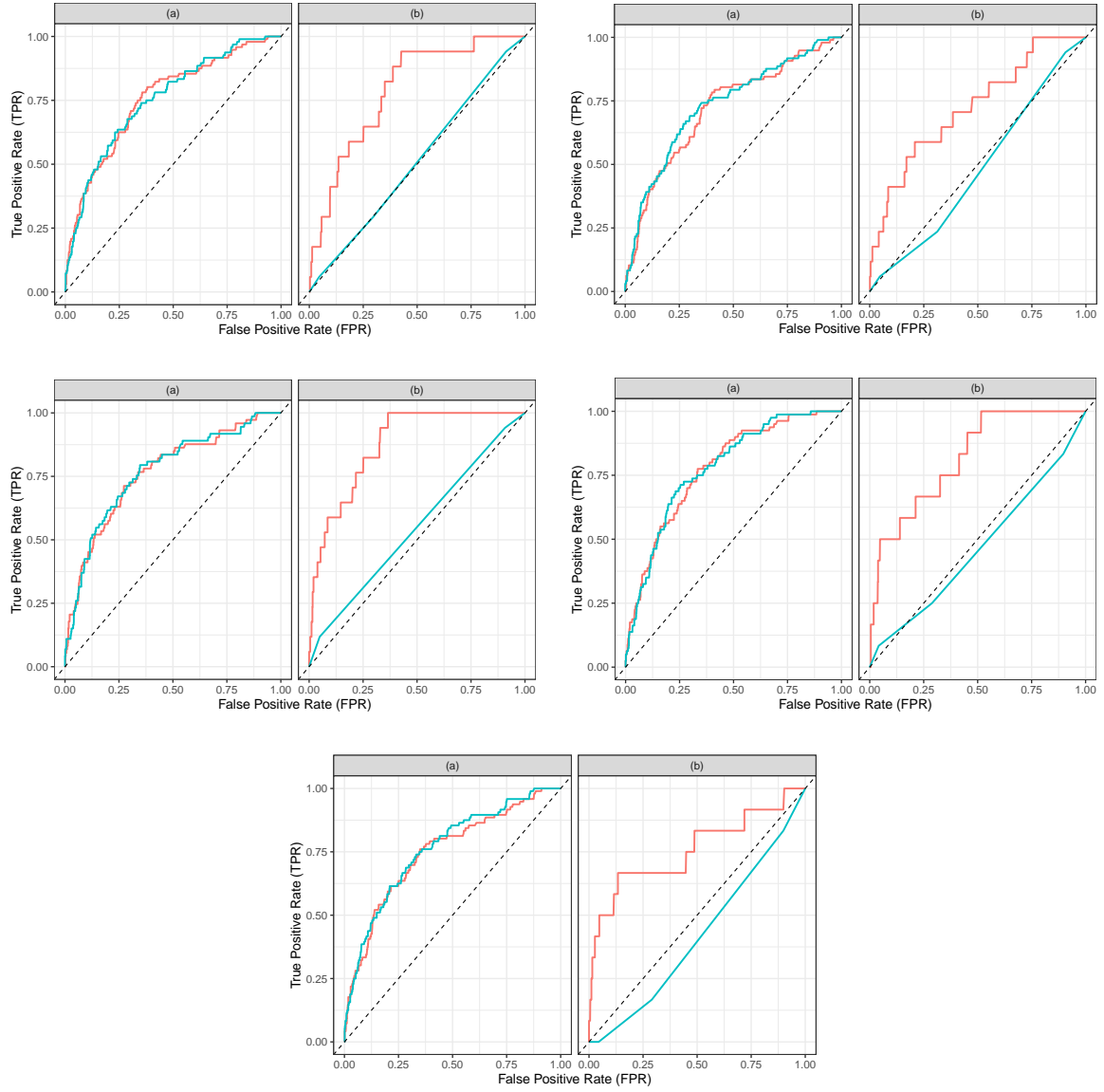


Figure 8: AHEAD study. ROC plot for comparing GLDRM (cyan) and Dir-GLM (coral) model accuracy in exceedance probabilities, $p(y \geq y_0 | x)$, estimation with $y_0 = 2$ (a) and $y_0 = 4$ (b).

The above figures in 8 highlight the limitation of maximum likelihood based inference in sparse or small data scenarios. We have a sparse-data situation for $y_0 = 4$ and hence, only a limited number of observations are available for estimating $p(y \geq y_0 | x)$, which is not the case for $y_0 = 2$.

Appendix E: AHEAD study results for the model parameters

Table 2: AHEAD study. Small and large training sample results for regression parameters. Abbreviations: TSS – Training sample size; Par – Parameter; Est – Estimate; CI – 95% credible or confidence intervals.

TSS	Par	Method	Est	CI	CI length
Small	β_0	GLDRM	-0.10	[-1.37, 1.17]	2.54
		Dir-GLM	-0.69	[-1.53, 0.09]	1.62
	β_1	GLDRM	0.14	[-0.29, 0.58]	0.87
		Dir-GLM	0.20	[-0.20, 0.62]	0.82
	β_2	GLDRM	-0.29	[-1.12, 0.54]	1.66
		Dir-GLM	-0.24	[-0.97, 0.57]	1.54
	β_3	GLDRM	-0.19	[-0.72, 0.34]	1.06
		Dir-GLM	-0.22	[-0.70, 0.28]	0.98
	β_4	GLDRM	-0.72	[-2.00, 0.55]	2.55
		Dir-GLM	-0.24	[-1.22, 0.78]	2.00
	β_5	GLDRM	-1.82	[-3.65, 0.00]	3.65
		Dir-GLM	-0.94	[-2.09, 0.22]	2.31
	β_6	GLDRM	-1.11	[-2.41, 0.19]	2.60
		Dir-GLM	-0.55	[-1.53, 0.38]	1.91
	β_7	GLDRM	-1.16	[-2.76, 0.43]	3.19
		Dir-GLM	-0.53	[-1.61, 0.57]	2.18
Large	β_0	GLDRM	-0.70	[-0.86, -0.55]	0.31
		Dir-GLM	-0.71	[-0.87, -0.57]	0.30
	β_1	GLDRM	0.28	[0.23, 0.32]	0.09
		Dir-GLM	0.28	[0.23, 0.32]	0.09
	β_2	GLDRM	0.16	[0.06, 0.26]	0.20
		Dir-GLM	0.15	[0.05, 0.26]	0.21
	β_3	GLDRM	-0.39	[-0.44, -0.34]	0.10
		Dir-GLM	-0.39	[-0.44, -0.34]	0.10
	β_4	GLDRM	-0.26	[-0.41, -0.10]	0.31
		Dir-GLM	-0.25	[-0.40, -0.09]	0.31
	β_5	GLDRM	-0.45	[-0.61, -0.29]	0.32
		Dir-GLM	-0.44	[-0.59, -0.28]	0.31
	β_6	GLDRM	-0.69	[-0.85, -0.53]	0.32
		Dir-GLM	-0.69	[-0.83, -0.51]	0.32
	β_7	GLDRM	-0.76	[-0.94, -0.59]	0.35
		Dir-GLM	-0.76	[-0.91, -0.57]	0.34

Table 3: AHEAD study. Small and large training sample results for baseline distribution f_0 . Abbreviations: TSS – Training sample size; Par – Parameter; Est – Estimate; CI – 95% credible or confidence intervals; N/A – Not available.

TSS	Par	Method	Est	CI
Small	$f_0(0)$	GLDRM	0.805	N/A
		Dir-GLM	0.815	[0.764, 0.859]
	$f_0(1)$	GLDRM	0.136	N/A
		Dir-GLM	0.126	[0.069, 0.198]
	$f_0(2)$	GLDRM	0.023	N/A
		Dir-GLM	0.021	[0.004, 0.057]
	$f_0(3)$	GLDRM	0.021	N/A
		Dir-GLM	0.020	[0.003, 0.044]
	$f_0(4)$	GLDRM	0.009	N/A
		Dir-GLM	0.010	[0.001, 0.028]
	$f_0(5)$	GLDRM	0.006	N/A
		Dir-GLM	0.009	[0.001, 0.026]
Large	$f_0(0)$	GLDRM	0.725	N/A
		Dir-GLM	0.725	[0.719, 0.731]
	$f_0(1)$	GLDRM	0.187	N/A
		Dir-GLM	0.186	[0.176, 0.196]
	$f_0(2)$	GLDRM	0.059	N/A
		Dir-GLM	0.059	[0.054, 0.064]
	$f_0(3)$	GLDRM	0.022	N/A
		Dir-GLM	0.022	[0.019, 0.025]
	$f_0(4)$	GLDRM	0.006	N/A
		Dir-GLM	0.006	[0.005, 0.008]
	$f_0(5)$	GLDRM	0.002	N/A
		Dir-GLM	0.002	[0.001, 0.002]

Appendix F: Uncertainty in exceedance probability estimates for the AHEAD data

See Section 6.3 in [AMR, 2024].

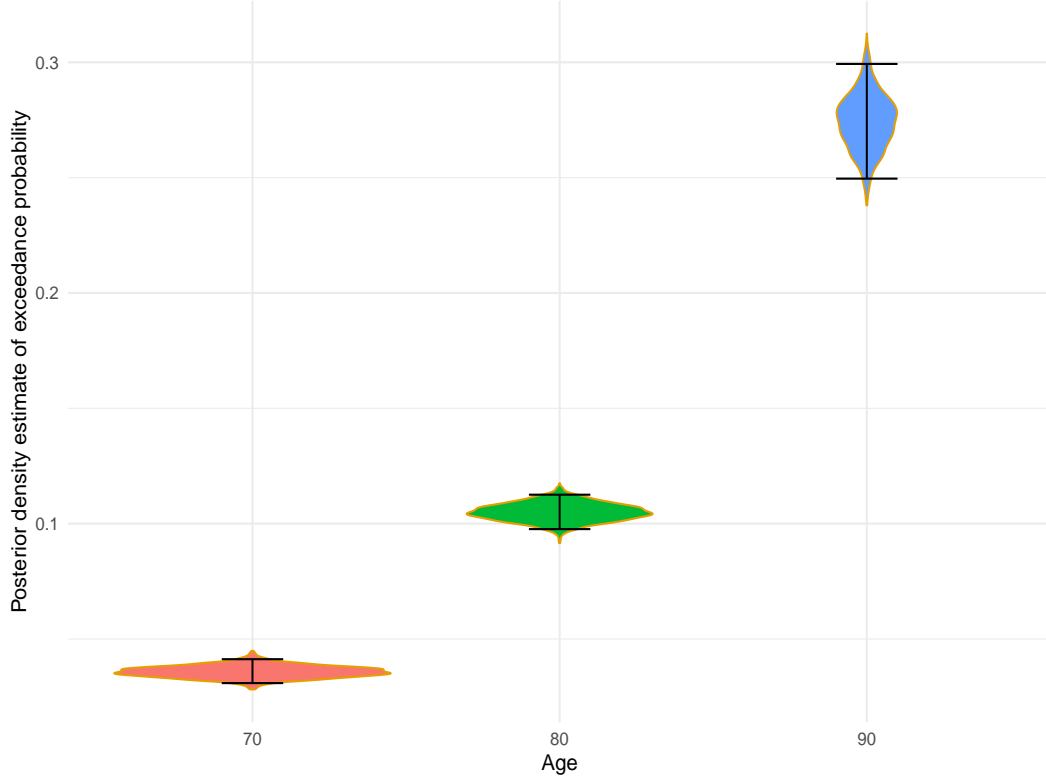


Figure 9: AHEAD study. Moderate exceedance probabilities $\pi = p(y \geq 2 \mid x_{age}, \mathcal{D}_n)$ for $x_{age} = 70, 80$, and 90. The vertically plotted density summarizes uncertainty about the probability of the exceedance event as a function of model parameters $\phi = (\beta, f_0)$. That is, let $\pi_\phi = p(y \geq 2 \mid x_{age}, \phi)$ (with $\pi = \int \pi_\phi dp(\phi \mid \mathcal{D}_n)$). The violin plots show posterior distribution of π_ϕ ; a peaked density indicates less posterior uncertainty about π_ϕ .

Appendix G: Computation time

We carried out a simulation experiment for assessing scalability of the proposed methodology, in terms of number of covariates (P), and also the same for number of observations (N). Figures 10 and 11 illustrate that the methodology scales linearly with N and P over a range of reasonable values.

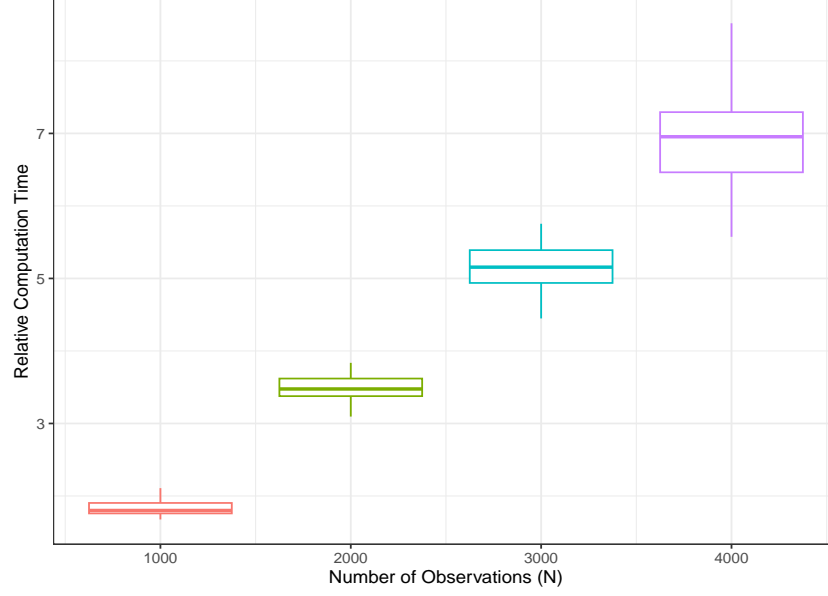


Figure 10: Relative computation time as a function of the number of observations (N) for 25 data replicates. We take $N = 500, 1000, 2000, 3000, 4000$ and $P = 10$. Relative computation time is calculated relative to $N = 500$. The absolute computation time with $N = 500$ is approx 1 second per iteration.

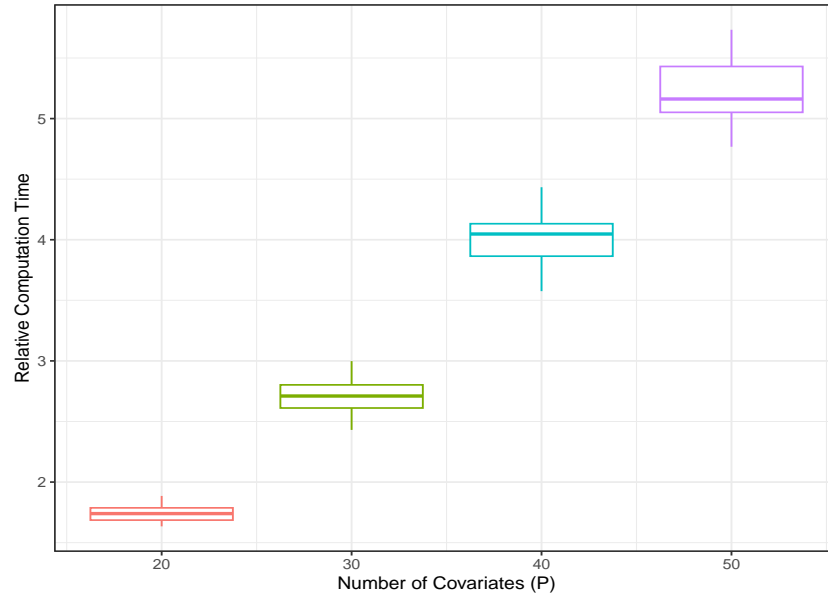


Figure 11: Relative computation time as a function of the number of covariates (P) for 25 data replicates. We take $N = 500$ and $P = 10, 20, 30, 40, 50$. Relative computation time is calculated relative to $P = 10$. The absolute computation time with $P = 10$ is approx 1 second per iteration.

Appendix H: θ_i solving algorithm

We summarize the discussion on solving θ_i from Wurm and Rathouz (2018). We use the following notations:

- n : sample size
- $S = \{s_1, \dots, s_K\}$: observed support, with respective frequencies $\{f_1, \dots, f_K\}$;
- $m = \min(S)$; $M = \max(S)$
- $\mu_i = E(y_i | x_i)$
- ε : convergence threshold, typically 10^{-10}

We solve for θ_i such that $b'(\theta_i) = \mu_i = g^{-1}(\eta_{x_i})$, where g is a user-chosen link function and e.g., $\eta_{x_i} = x_i^T \beta$. Equivalently, $g_l\{b'(\theta_i)\} = g_l(\mu_i)$, where $g_l(u) = \text{logit}\left(\frac{u-m}{M-m}\right) = \log\left(\frac{u-m}{M-u}\right)$. The transformation g_l stabilizes the solution. Define $t(\theta_i) = g_l\{b'(\theta_i)\} - g_l(\mu_i)$, which implies $t'(\theta_i) = \frac{M-m}{\{b'(\theta_i)-m\}\{M-b'(\theta_i)\}} b''(\theta_i)$, with $b''(\theta_i) = \sum_{k=1}^K \{s_k - b'(\theta_i)\}^2 f_k \exp\{\theta_i s_k - b(\theta_i)\}$. We use Newton-Raphson iterative procedure for finding the root θ_i of the equation $t(\theta_i) = g_l\{b'(\theta_i)\} - g_l(\mu_i)$, see Algorithm 1. Note that as $\mu_i \rightarrow M$ from the left, $\theta_i \rightarrow +\infty$. Likewise, as $\mu_i \rightarrow m$ from the right, $\theta_i \rightarrow -\infty$. To prevent the numerical instability when μ_i is at or near these boundaries (m, M), we cap $|\theta_i|$ at a maximum value (we use 500 by default).

Algorithm 1: Newton-Raphson Procedure for Solving θ_i

Initialization: $(\theta_i^{(0)} = 0, \text{ for } i = 1, \dots, n)$
 $r \leftarrow 0$;
repeat
 $\theta_i^{(r+1)} \leftarrow \theta_i^{(r)} - \{t'(\theta_i^{(r)})\}^{-1} t(\theta_i^{(r)})$;
 $r \leftarrow r + 1$;
until $|t(\theta_i^{(r)})| < \varepsilon$;
 $\theta_i \leftarrow \theta_i^{(r)}$;
return θ_i

References

- Entejar Alam, Peter Müller, and Paul J. Rathouz. Dir-GLM: A Bayesian GLM with data-driven reference distribution. 2024.
- Michael J Wurm and Paul J Rathouz. Semiparametric generalized linear models with the gldrm package. *The R journal*, 10(1):288, 2018.