HOUSE RULES

- Free Wi-Fi
- Phones and laptops on silent
- Coffee, drinks, and snacks in the Learning Hub
- If you're stuck, ask for help :)
- Online? Drop your question in the chat, we've got helpers watching.

WI-FI

SSID: ***"Entelect Guest"***

BUILD-A-BOT WORKSHOP

2025

ENTELECT CHALLENGE 2025

ZOOSCAPE

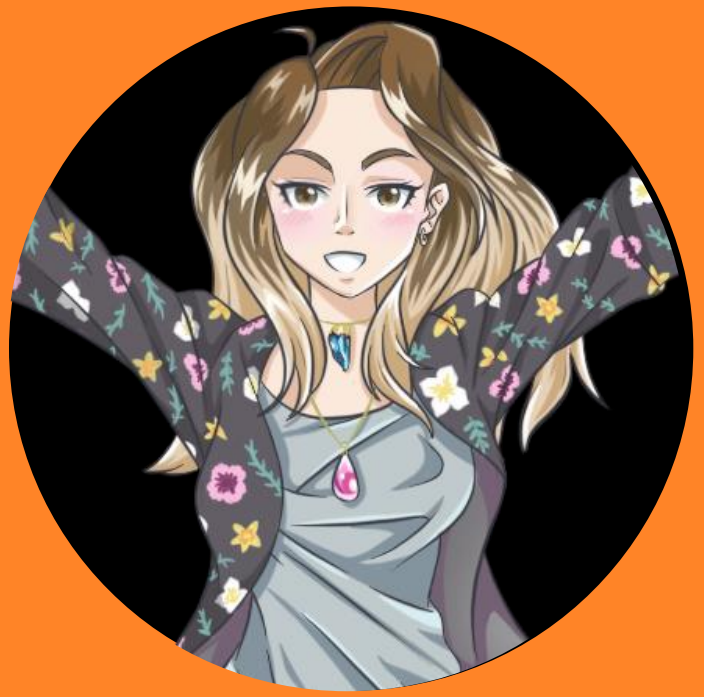
Welcome to the chaos of pellets, cages, and zookeepers

Code along, learn, and maybe… escape.

Build-A-Bot - 21 June 2025

https://l.ead.me/build-a-bot-2025

About me



- Jessica-Bianca Cordier
- Software Engineer
- Website Squad
- Lover of rogue-like, Pokémon, and life sim games
- Steam backlog longer than a novel
- Built a bot to farm an idle game… and then got banned
- https://github.com/JessicaBCordier

Agenda

01

Intro Presentation

You are here! Introduction and some theory

02

Coding Setup

Get your laptops out and setup those environments!

03

Quick Break

Grab a coffee and get those fingers warmed up!

https://l.ead.me/build-a-bot-2025

Agenda

04

Let's Build-A-Bot!

Step-by-step coding walkthrough

05

Short Break

Bathroom break and time to catch up and get help

06

More Code!

Carrying on with the bot implementation

07

Pizza & Networking

Grab some food and drink, chat with others and the team!

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The Team

Meet the Entelect Challenge Team

We're here to help.

No question is too small, too weird, or too broken.

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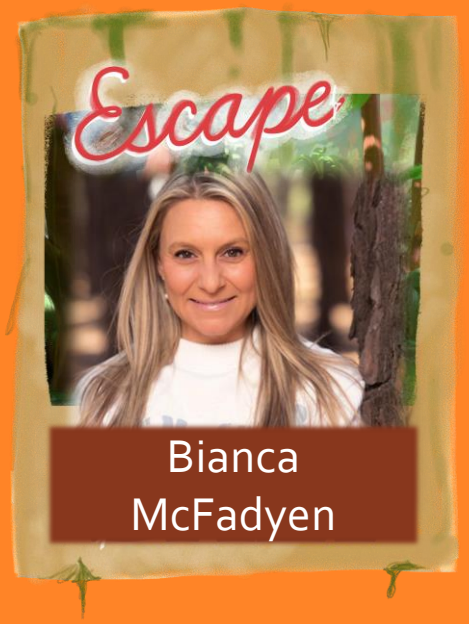
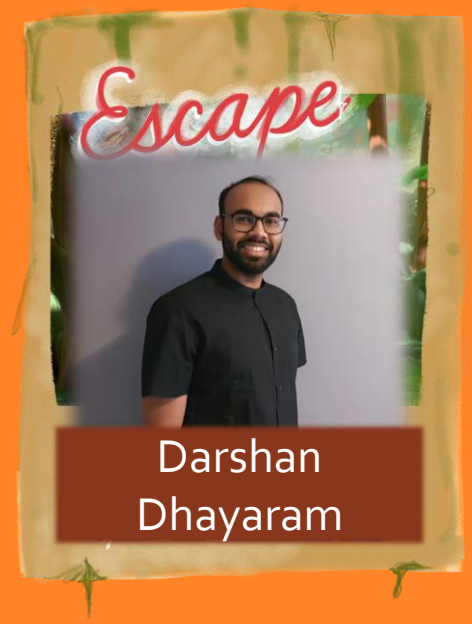
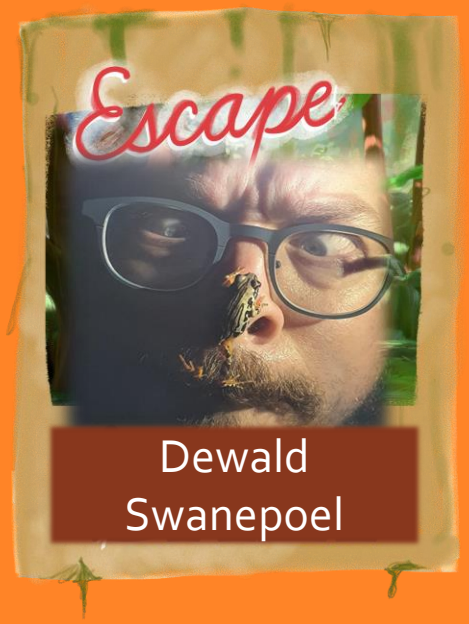
The Johannesburg Squad



Bianca McFadyen

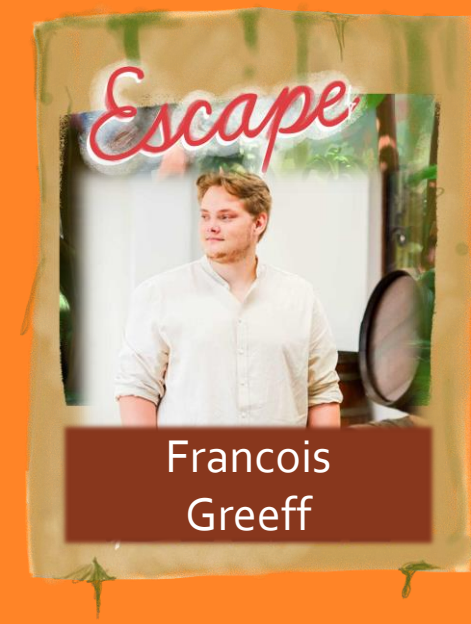


Darshan Dhayaram



Dewald Swanepoel

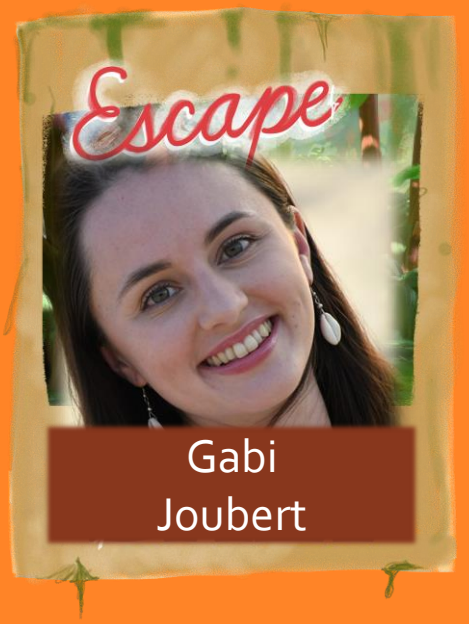
Douglas van Reeuwyk



Francois Greeff

The Johannesburg Squad

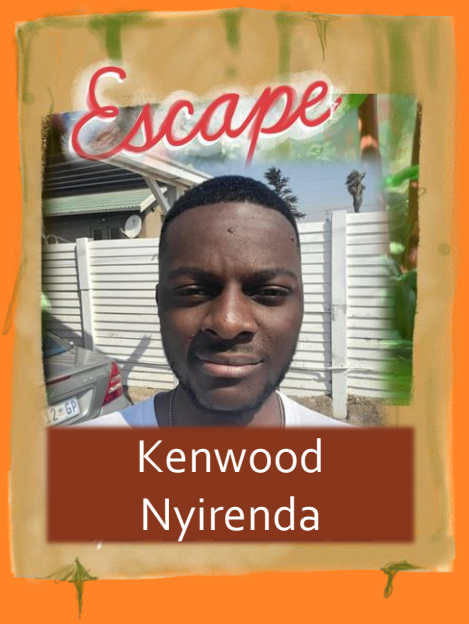
Francois Volschenk



Gabi Joubert

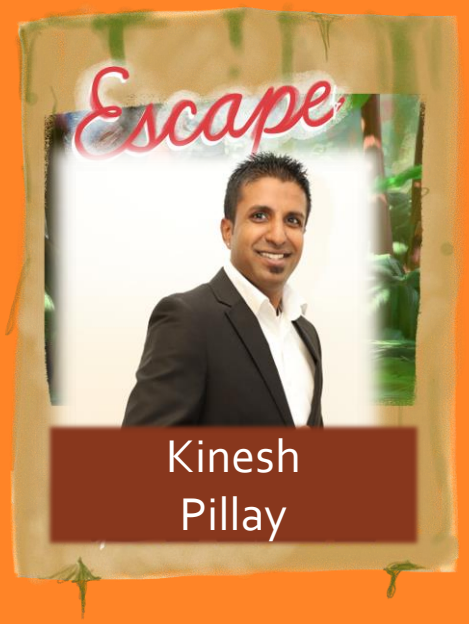
Husnaa Molvi

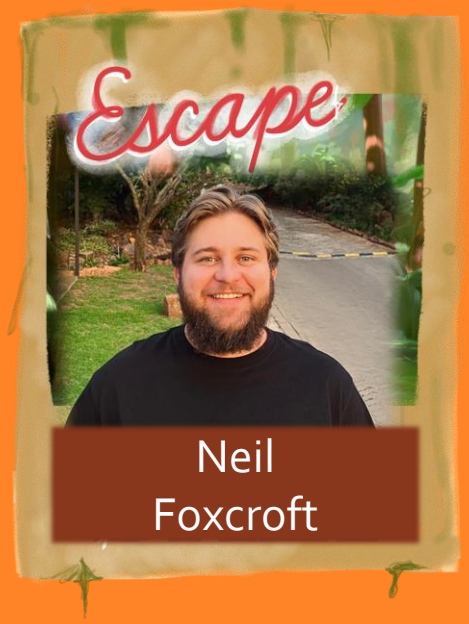
IB van Schalkwyk



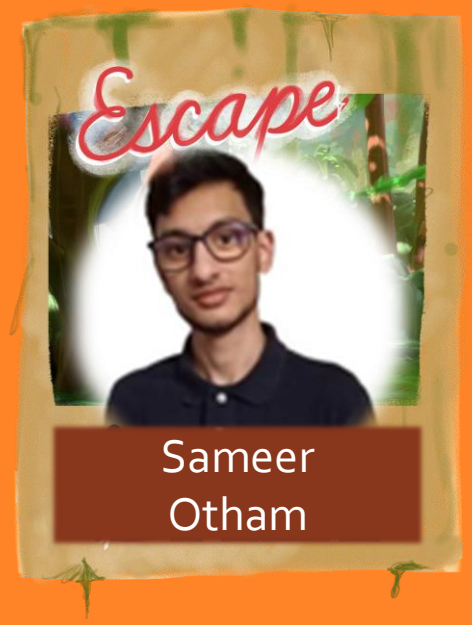
Kenwood Nyirenda

The Johannesburg Squad





The Johannesburg Squad



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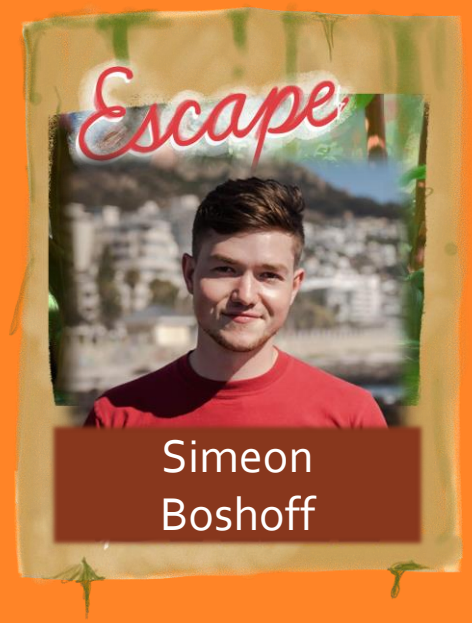
The Cape Town Squad



https://l.ead.me/build-a-bot-2025

How do I join Entelect?

- Graduate programme for final-year students
- Roles include:
  - Software Engineer
  - User Experience Engineer
  - Business Analyst
- Find out more from:
  - https://culture.entelect.co.za
  - Our team in the office

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Theoretical Intro

How does this thing even work?!

It’s not magic, unfortunately.

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Game Rules

- Your bot is an animal
  - Move: UP, DOWN, LEFT, RIGHT (1 per tick)
  - No diagonals, no collisions with other animals
  - Queue actions, processed in order
- Collect Pellets
  - Scattered across all walkable tiles
  - Earn points by picking them up
  - Ties go to whoever sent the action first

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Game Rules

- Avoid the Zookeeper
  - Now up to 4 zookeepers per game
  - Targets the closest viable animal
  - Catches you = score penalty + back to cage (respawn point)
  - Can’t use tunnels

- Use the World
  - Tunnels wrap the map
  - Symmetrical maps with walls

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Game Rules

- New Mechanics (2025.2.0)
  - Power-Ups:
    - Power Pellet (x10 points)
    - Chameleon Cloak (invisible to zookeepers for 20 ticks)
    - Scavenger (slurp all pellets in 11x11 for 5 ticks)
    - Big Moose Juice (3x pellet score for 5 ticks)
  - Score Streaks: Each consecutive pellet increases score multiplier, up to x4, resets after 3 empty ticks
  - Pellet Respawn

- Win by…
  - Most points when pellets run out or time is up

Technologies Used

- C# and .NET 8
- SignalR for real-time communication
- Git for version control

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SignalR Basics

- Asynchronous event-driven messaging system
- Client opens a connection to a “hub” (server)
  - In our case, that’s the game engine’s “/bothub”
- Message consists of a name and optional payload
  - E.g. GameState, BotCommand, Registered, Disconnect

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Game Engine Setup

- GitHub: https://github.com/EntelectChallenge/2025-Zooscape
- Docker Desktop required
- Works on Windows, macOS, and Linux
- README file on Repo with instructions
- Run scripts:
  - Windows: .\run.bat
  - macOS/Linux: ./run.sh

Coding Setup

Ready, Set, Code!

Let’s get your environment ready so your bot can join the chaos.

Build-A-Bot - 21 June 2025

https://l.ead.me/build-a-bot-2025

GitHub Repository

- GitHub: https://github.com/EntelectChallenge/Build-a-Bot-2025
- Branches for each step:
  - step-1, step-2, step-3 etc.
- The repo is a guide, try not to copy and paste!
- If you are stuck with Git, ask a helper for assistance.
- 2023: https://forum.entelect.co.za/t/build-a-bot-workshop-1-july/1605/7
- 2024: https://forum.entelect.co.za/t/build-a-bot-workshop-1-july/1605/7

No git? No problem!

- Zip file: https://github.com/EntelectChallenge/Build-a-Bot-2025/archive/refs/heads/step-3.zip
- Download the file directly and extract it
- Will not have access to the branches and individual steps

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Prerequisites

- We will be using Visual Studio Code for the presentation
  - You may use whichever IDE you wish to
- .NET SDK 8 is required

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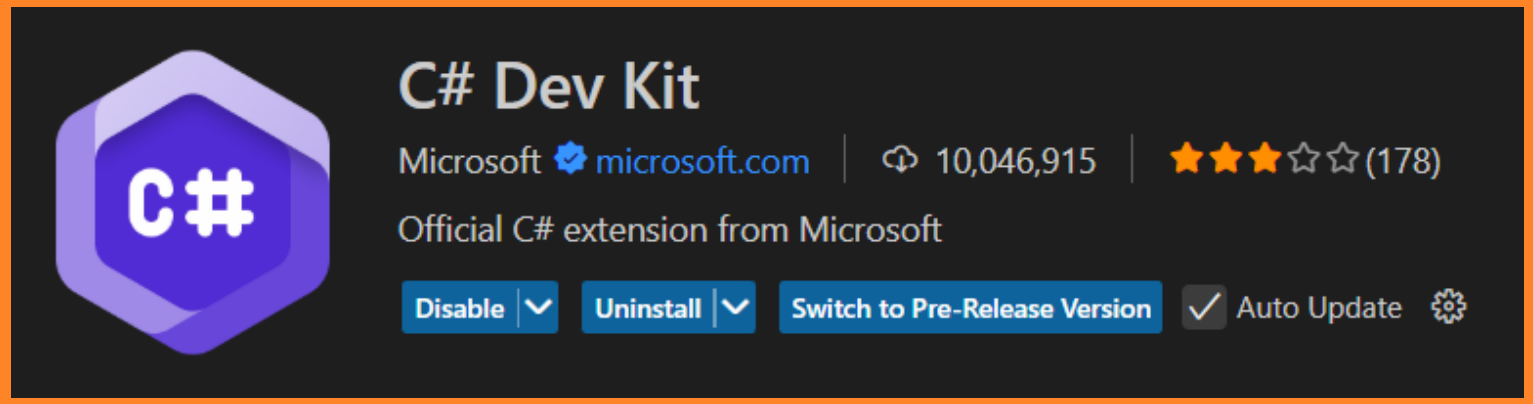
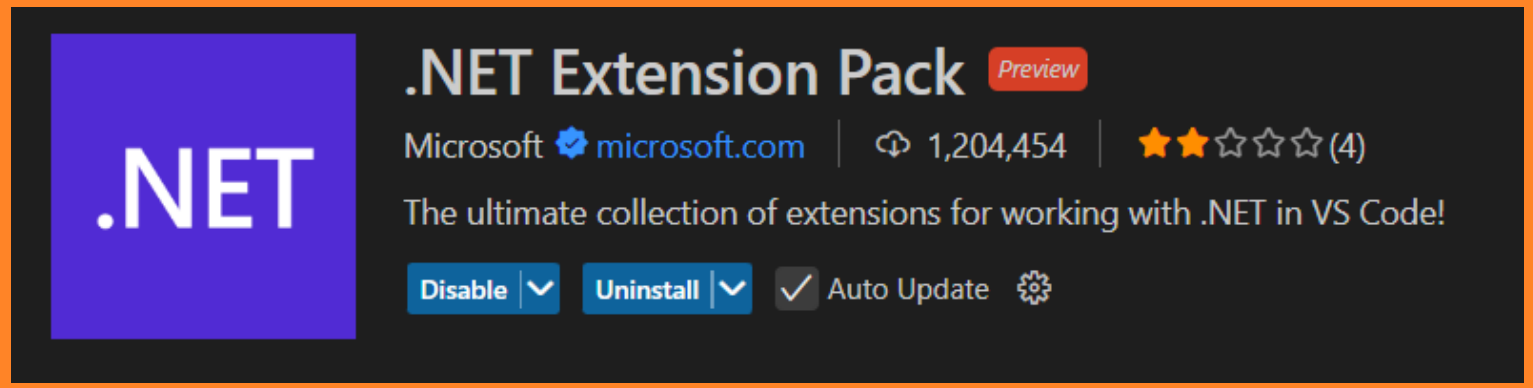
Visual Studio Code Extensions





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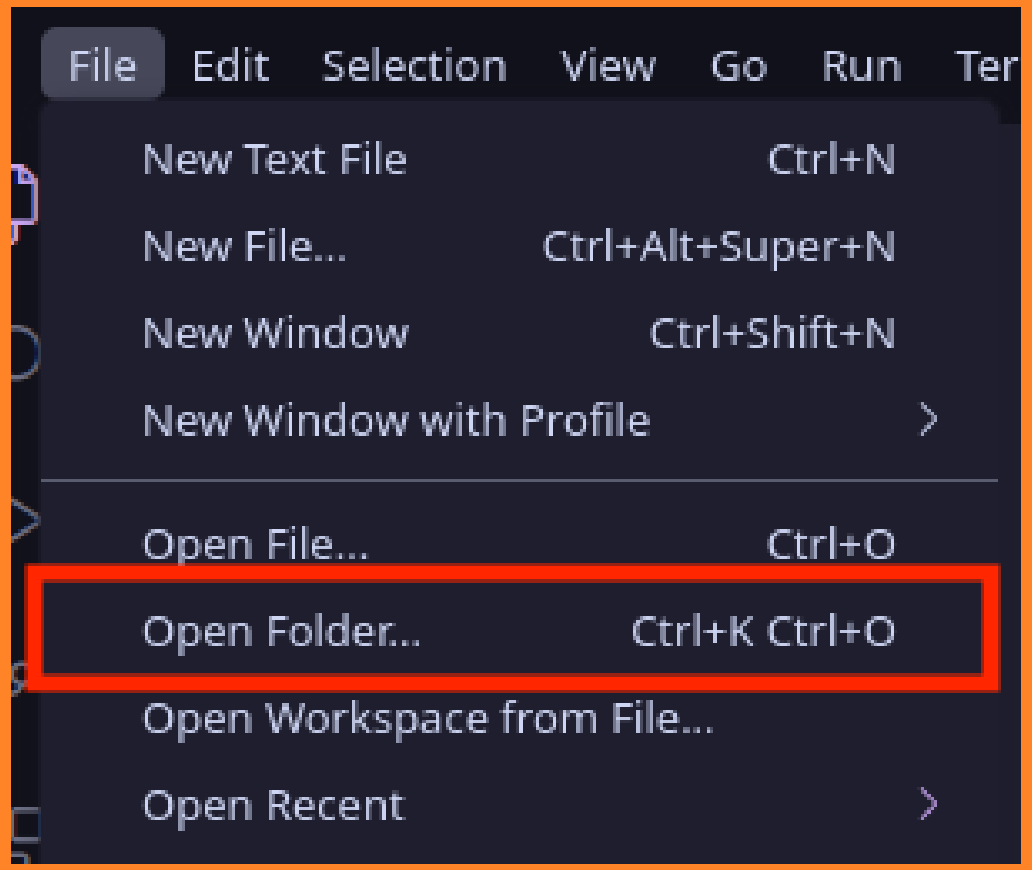
Creating the project



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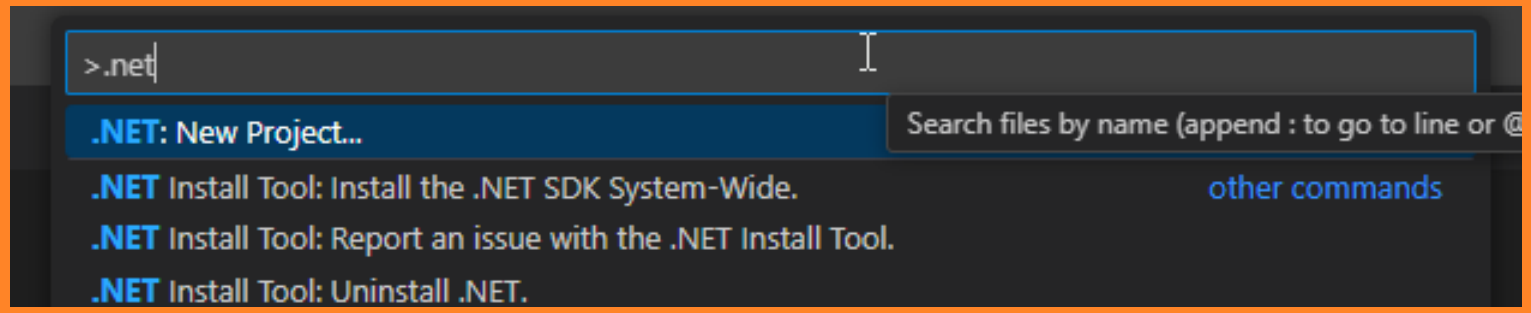
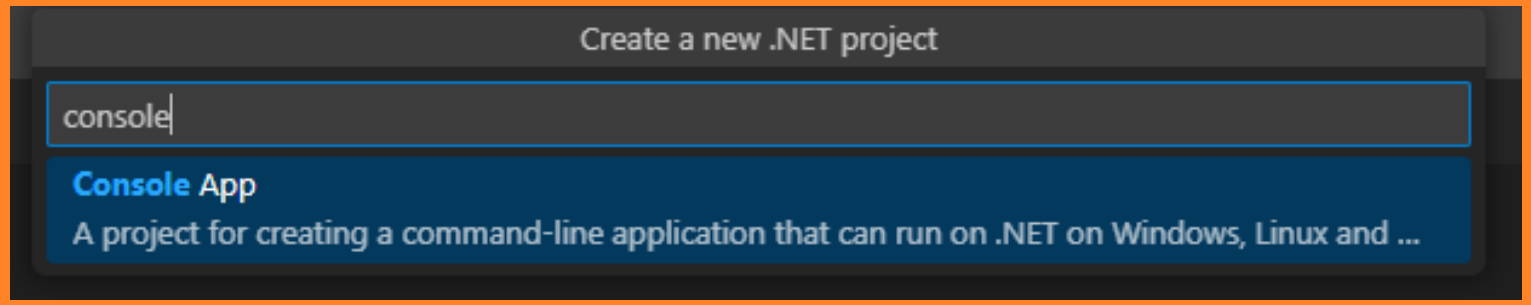
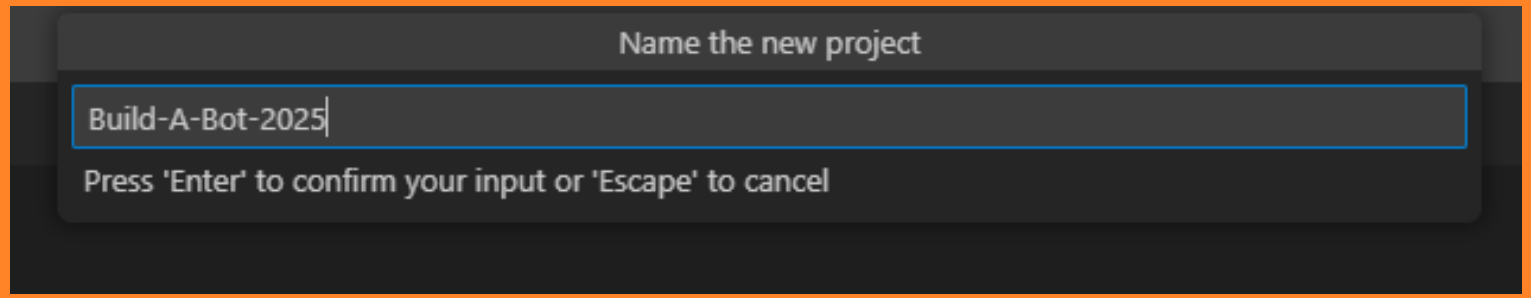
Creating the project







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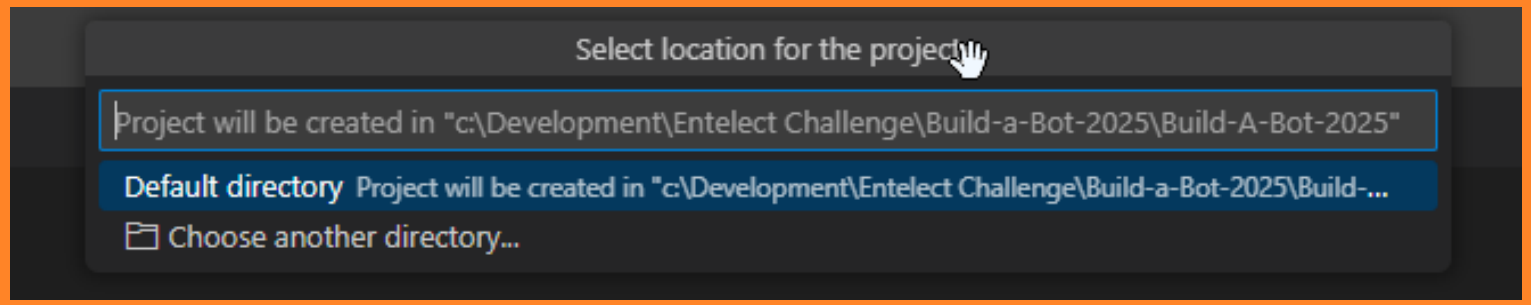

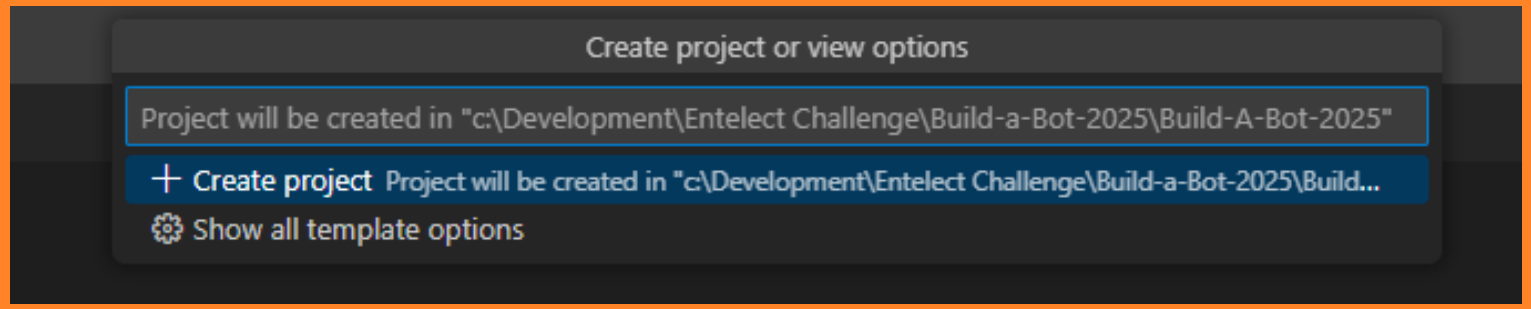

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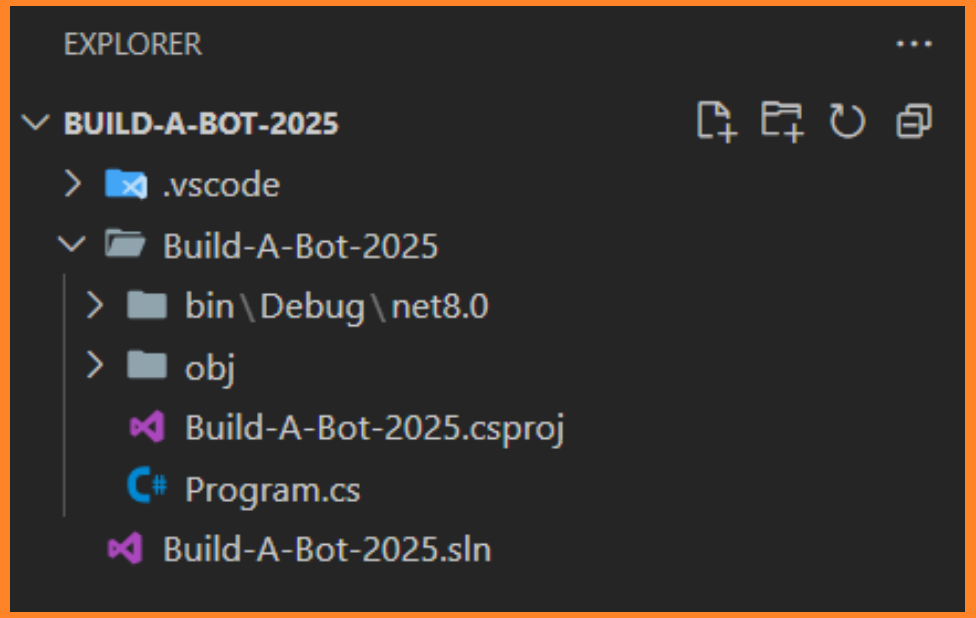
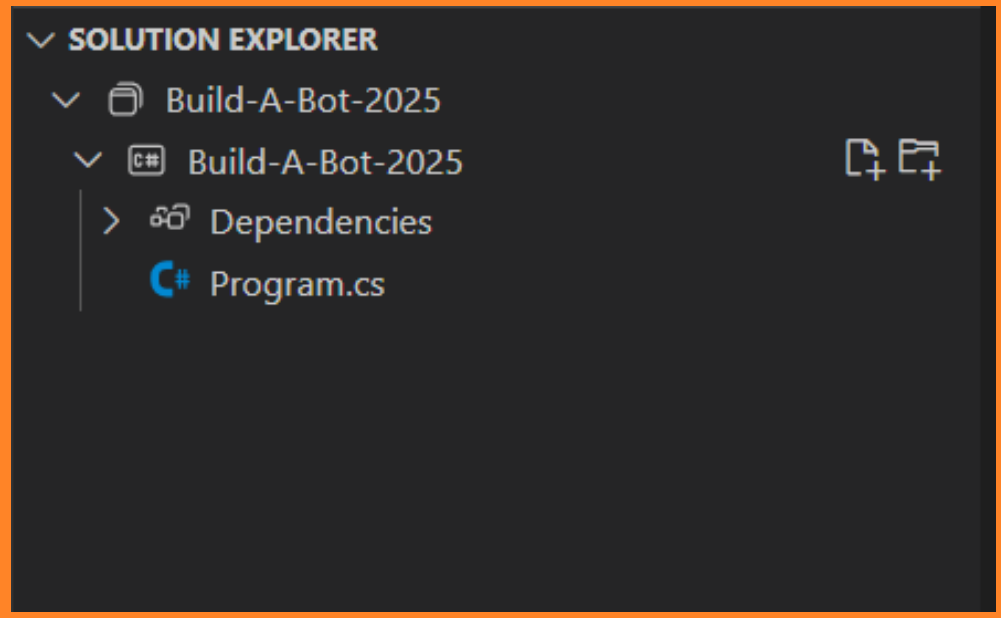
Creating the project





https://l.ead.me/build-a-bot-2025

Coffee Time!

Catch-up, questions, and caffeine

Helpers will be available to assist you with project setup.

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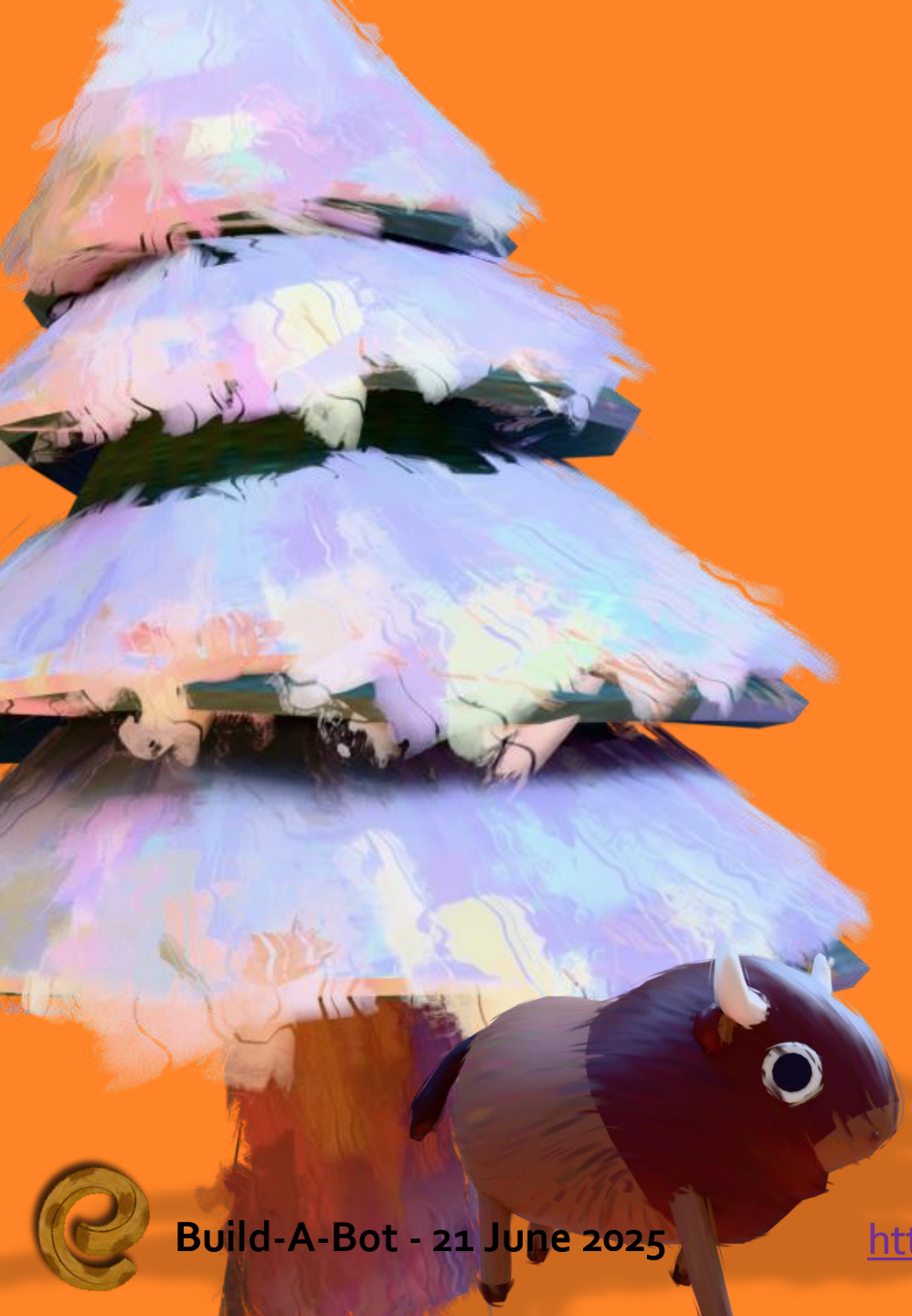

ENTELECT CHALLENGE 2025

Ready, set, code!

Or just listen, completely up to you.

We'll go step by step and there will be time to catch up between parts

https://l.ead.me/build-a-bot-2025

Workshop Structure

- Each step = one Github branch
- I'll explain what changed, and why
- You can code along, or just follow visually
- Helpers will be around after each step for help/advice
- Then we will proceed to the next step

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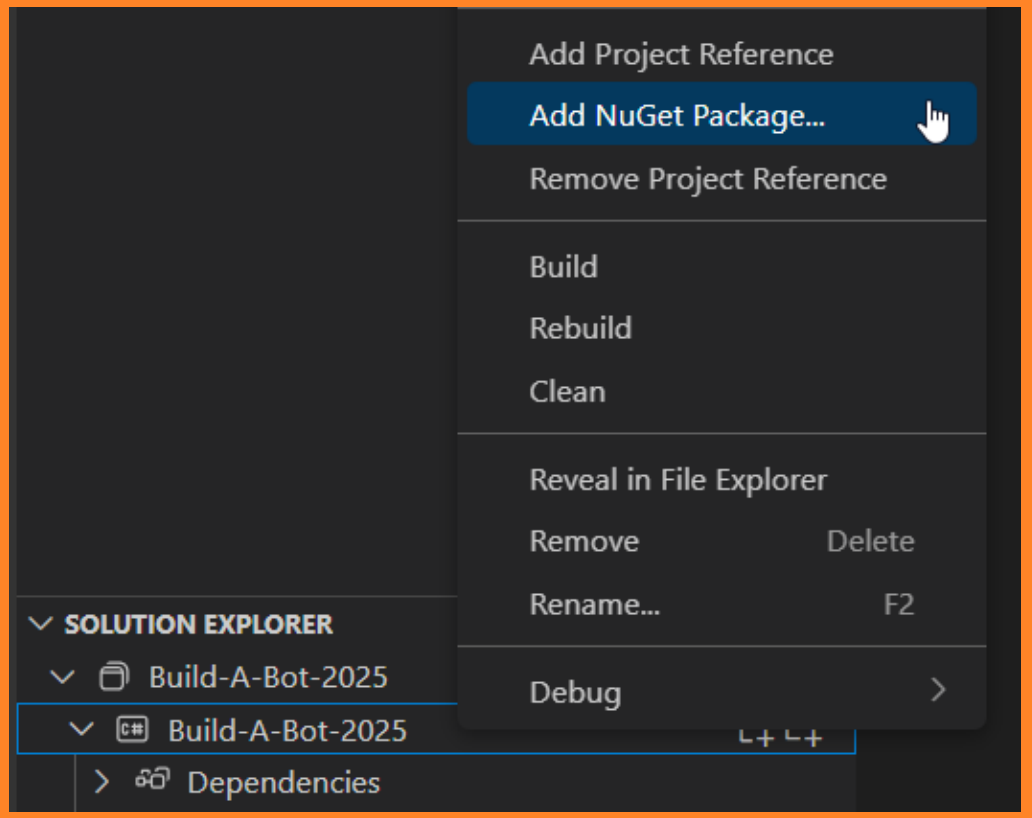
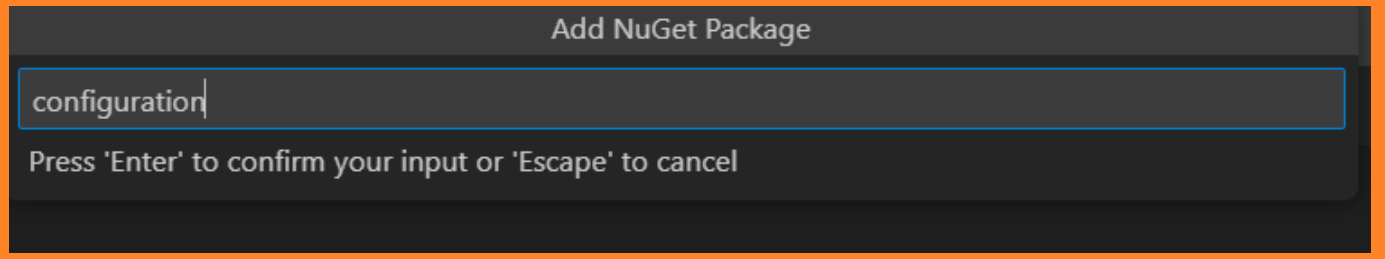
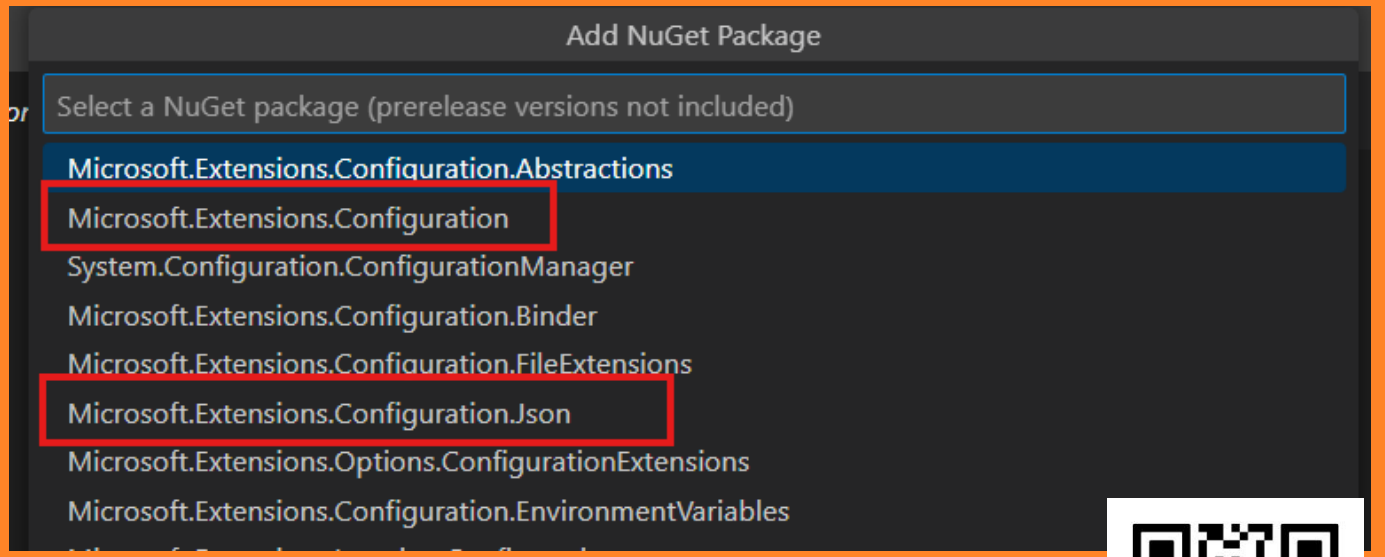
Step 1: Adding Packages







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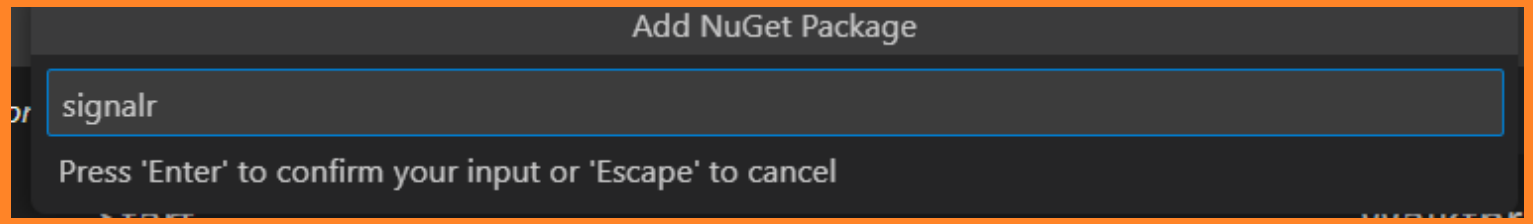
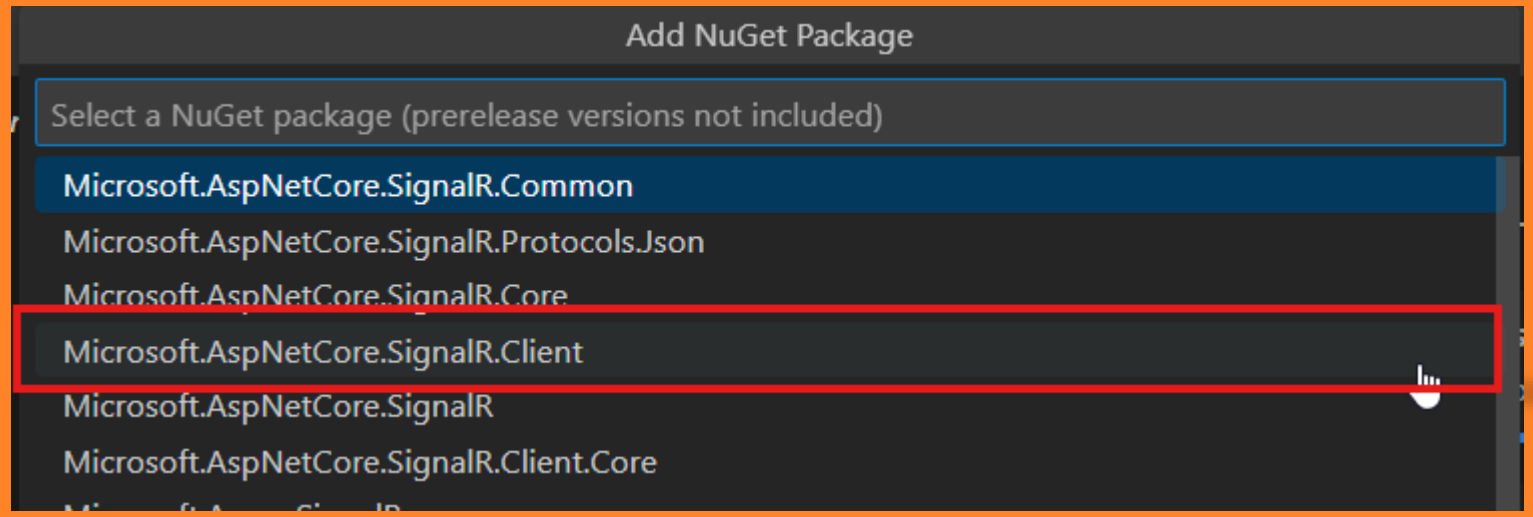
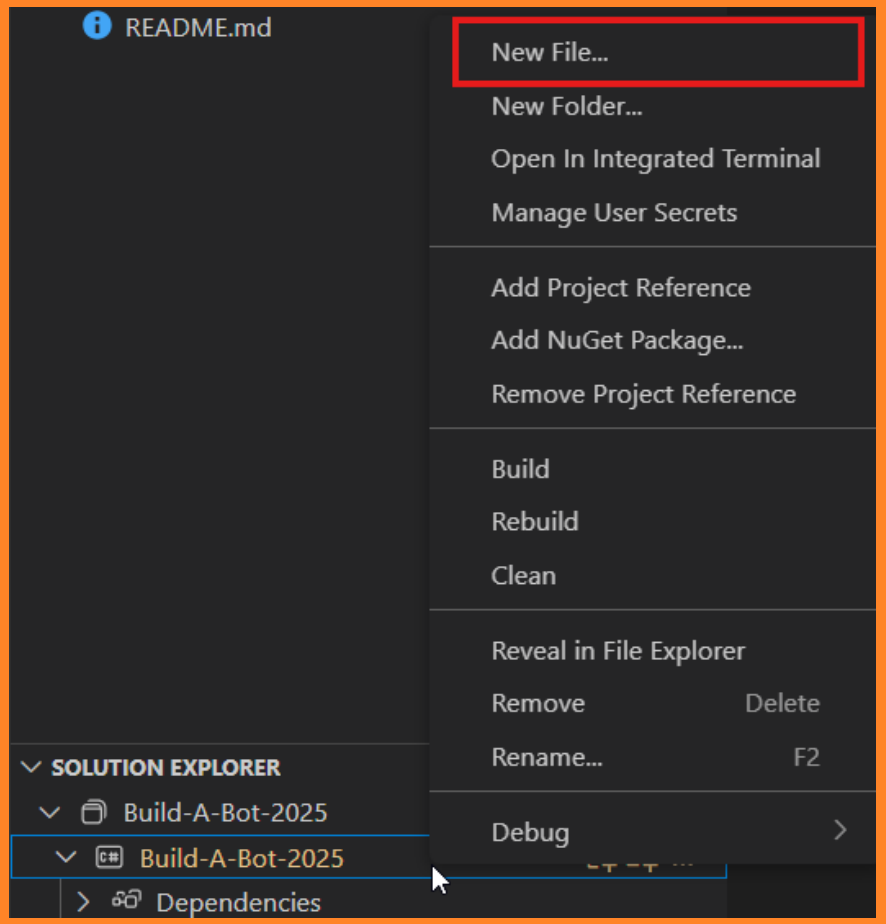
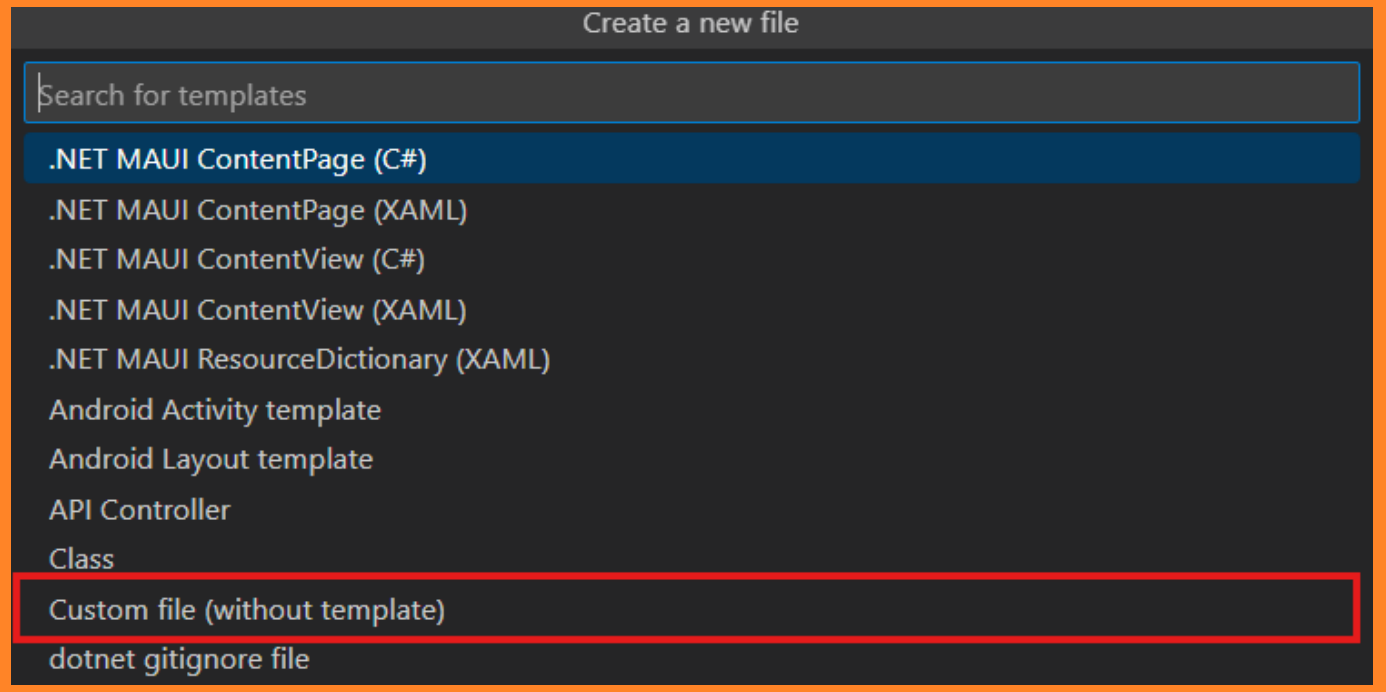


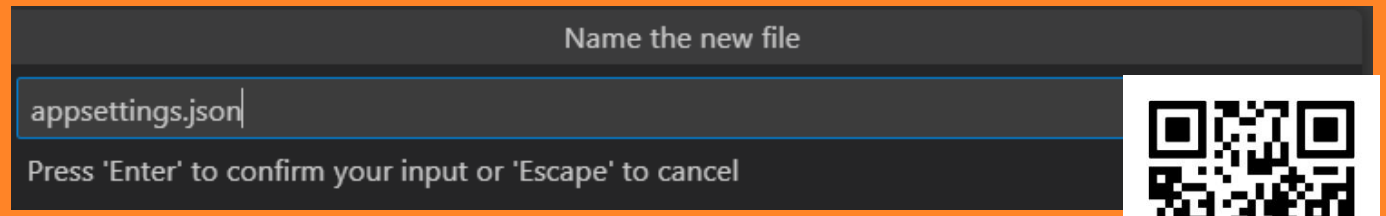


https://l.ead.me/build-a-bot-2025

Step 1: Adding Config







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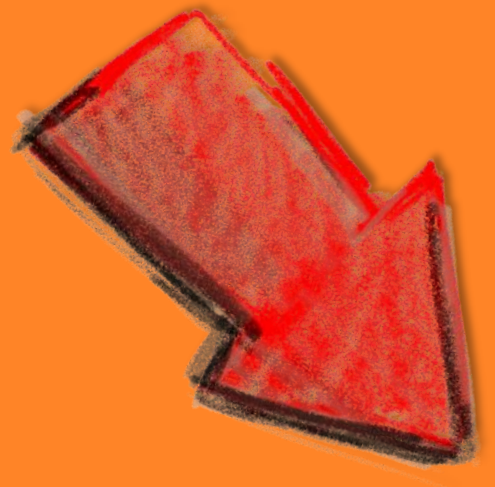
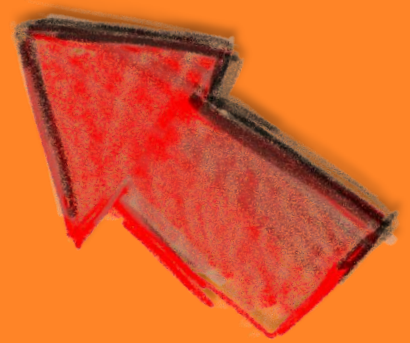


Step 1: Adding Config

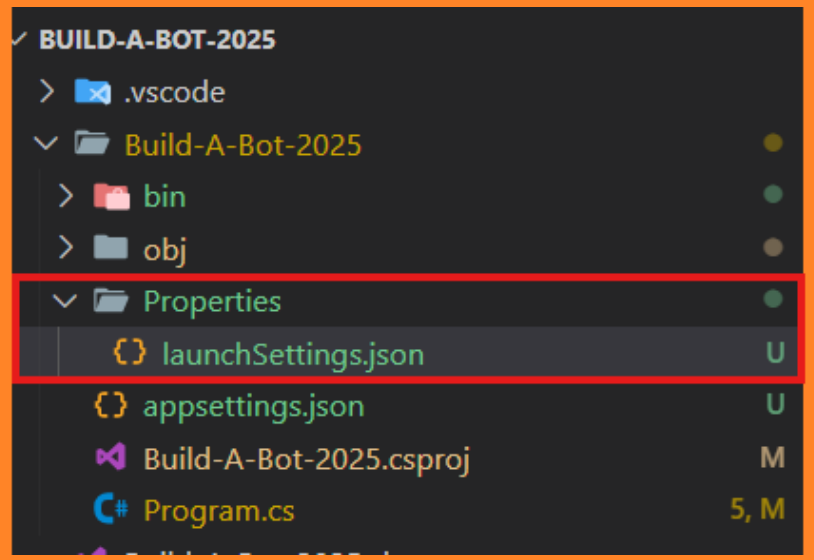
```
{
    "RunnerIP": "http://localhost",
    "RunnerPort": "5000",
    "BotNickname": "R2D2"
}
```

Step 1: Manually Adding to Output

```
<ItemGroup>
  <None Update="appsettings.json">
    <CopyToOutputDirectory>PreserveNewest
     </CopyToOutputDirectory>
  </None>
</ItemGroup>
```



Step 1: Adding Config




```
{
  "profiles": {
    "Build-A-Bot": {
      "commandName": "Project",
      "environmentVariables": {
        "Token": "8bdf0905-1fbf-48b6-b38d-5594f20e52f1"
      }
    }
  }
}
```

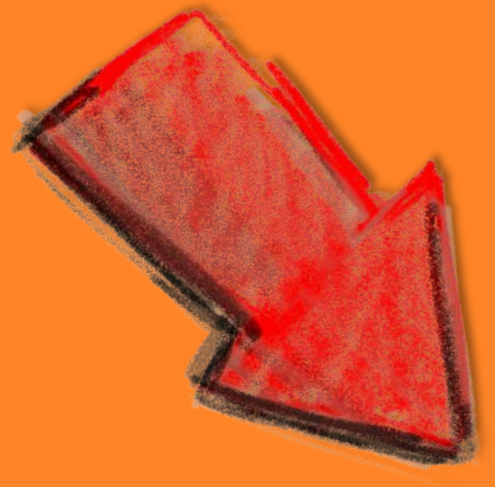
https://www.uuidgenerator.net/version4

https://l.ead.me/build-a-bot-2025

Step 1: Reading Config

```
using Microsoft.AspNetCore.SignalR.Client;
using Microsoft.Extensions.Configuration;
using Microsoft.Extensions.Logging;

public class Program
{
    public static async Task Main(string[] args)
    {
        // We'll set everything up in here
    }
}
```

https://l.ead.me/build-a-bot-2025



ENTELECT CHALLENGE 2025

Step 1: Reading Config

```
// Load configuration from appsettings.json
var builder = new ConfigurationBuilder().AddJsonFile("appsettings.json",
optional: false);
var configuration = builder.Build();
```

https://l.ead.me/build-a-bot-2025

Step 1: Reading Environment Variables

```
// Read values from config or environment
var ip = Environment.GetEnvironmentVariable("RUNNER_IPV4") ??
configuration["RunnerIP"];
if (!ip.StartsWith("http://")) ip = $"http://{ip}";

var port = configuration["RunnerPort"];
var nickname = Environment.GetEnvironmentVariable("BOT_NICKNAME") ??
configuration["BotNickname"];
var token = Environment.GetEnvironmentVariable("Token") ??
Environment.GetEnvironmentVariable("REGISTRATION_TOKEN");
```

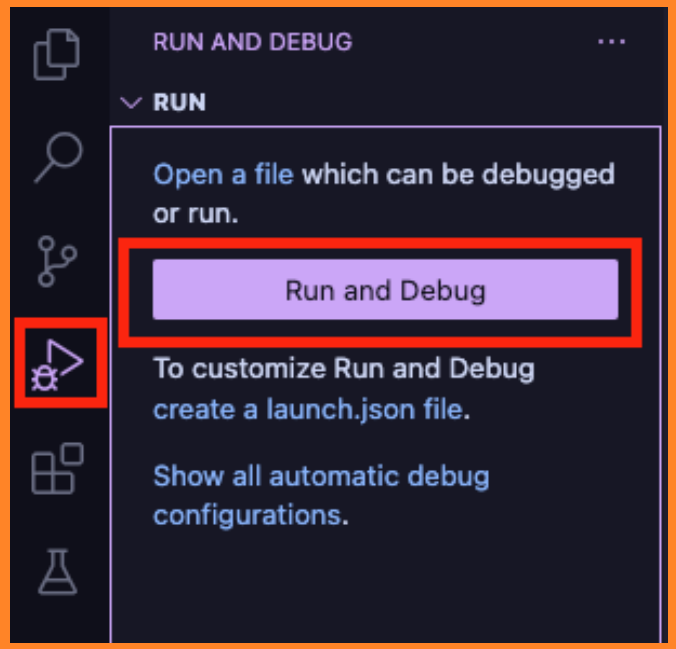
https://l.ead.me/build-a-bot-2025

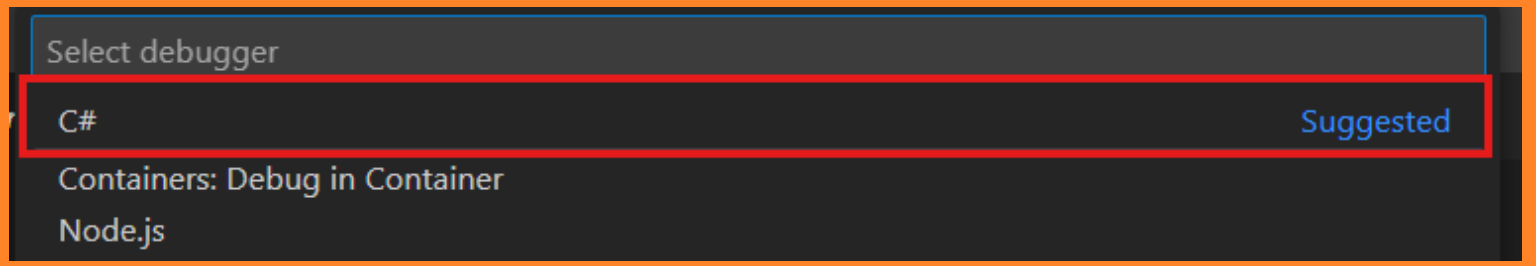
Step 1: Creating the Connection

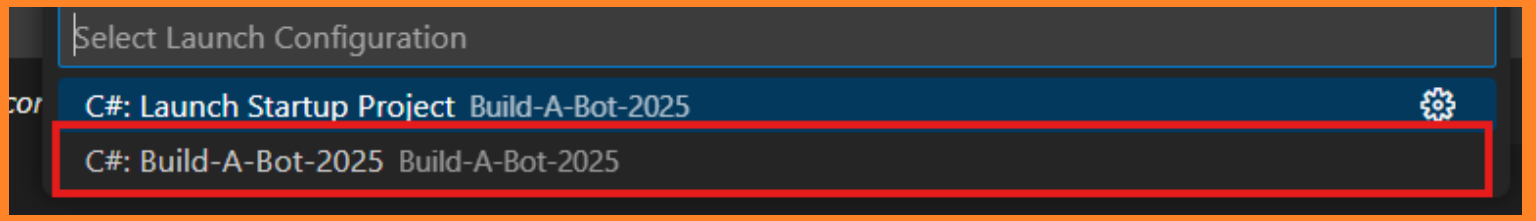
```
var url = $"{ip}:{port}/bothub";

// Create SignalR connection
var connection = new HubConnectionBuilder()
    .WithUrl(url)
    .ConfigureLogging(logging => logging.SetMinimumLevel(LogLevel.Debug))
    .WithAutomaticReconnect()
    .Build();

// Connect!
await connection.StartAsync();
Console.WriteLine("Connected to Runner");
```

https://l.ead.me/build-a-bot-2025

Step 1: Running the bot







https://l.ead.me/build-a-bot-2025

Step 1: Results!

```
---------------------------------------------------------------------------
You may only use the Microsoft Visual Studio .NET/C/C++ Debugger (vsdbg) with
Visual Studio Code, Visual Studio or Visual Studio for Mac software to help you
develop and test your applications.
---------------------------------------------------------------------------
Connected to Runner
The program '[136068] Build-A-Bot-2025.exe' has exited with code 0 (0x0).
```

https://l.ead.me/build-a-bot-2025

Coffee Time!

Catch-up, questions, and caffeine

Helpers will be available to assist you with project setup.

https://l.ead.me/build-a-bot-2025

Step 2: Enums

```
namespace BuildABot2025.Enums;

public enum BotAction
{
    Up = 1,
    Down = 2,
    Left = 3,
    Right = 4,
    UseItem = 5,
}
```

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Step 2: Enums

```
namespace BuildABot2025.Enums;

public enum CellContent
{
    Empty = 0,
    Wall = 1,
    Pellet = 2,
    ZookeeperSpawn = 3,
    AnimalSpawn = 4,
    PowerPellet = 5,
    ChameleonCloak = 6,
    Scavenger = 7,
    BigMooseJuice = 8,
}
```

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Step 2: Enums

```
namespace BuildABot2025.Enums;

public enum PowerUpType
{
    PowerPellet = 0,
    ChameleonCloak = 1,
    Scavenger = 2,
    BigMooseJuice = 3,
}
```

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Step 2: Models

```
using BuildABot2025.Enums;

namespace BuildABot2025.Models;

public class ActivePowerUp
{
    public double Value { get; set; }
    public int TicksRemaining { get; set; }
    public PowerUpType Type { get; set; }
}
```

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Step 2: Models

```
using BuildABot2025.Enums;

namespace BuildABot2025.Models;

public class Animal
{
    public Guid Id { get; set; }
    public int X { get; set; }
    public int Y { get; set; }
    public int SpawnX { get; set; }
    public int SpawnY { get; set; }
    public int Score { get; set; }
    public int CapturedCounter { get; set; }
    public int DistanceCovered { get; set; }
    public bool IsViable { get; set; }
    public PowerUpType? HeldPowerUp { get; set; }
    public ActivePowerUp? ActivePowerUp { get; set; }
}
```

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Step 2: Models

```
using BuildABot2025.Enums;

namespace BuildABot2025.Models;

public class BotCommand
{
    public BotAction Action { get; set; }
}
```

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Step 2: Models

```
using BuildABot2025.Enums;

namespace BuildABot2025.Models;

public class Cell
{
    public int X { get; set; }
    public int Y { get; set; }
    public CellContent Content { get; set; }
}
```

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Step 2: Models

```
namespace BuildABot2025.Models;

public class GameState
{
    public DateTime TimeStamp { get; set; }
    public int Tick { get; set; }
    public List<Cell> Cells { get; set; }
    public List<Animal> Animals { get; set; }
    public List<Zookeeper> Zookeepers { get; set; }
}
```

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Step 2: Models

```
namespace BuildABot2025.Models;

public class Zookeeper
{
    public Guid Id { get; set; }
    public int X { get; set; }
    public int Y { get; set; }
    public int SpawnX { get; set; }
    public int SpawnY { get; set; }
}
```

Step 2: Create Bot Service

```
using BuildABot2025.Enums;
using BuildABot2025.Models;

namespace BuildABot2025.Services;

public class BotService
{
    private Guid _botId;
    public void SetBotId(Guid botId)
    {
        _botId = botId;
    }
    public Guid GetBotId()
    {
        return _botId;
    }
}
```

Step 2: Command Handling & Printing

```
public BotCommand ProcessState(GameState gameState)
{
    var bot = gameState.Animals.FirstOrDefault(a => a.Id == _botId);
    var command = new BotCommand
    {
        Action = BotAction.Right // placeholder logic
    };

    if (bot != null)
    {
        Console.WriteLine($"Tick: {gameState.Tick}");
        Console.WriteLine($"Bot Position: ({bot.X}, {bot.Y})");
        Console.WriteLine($"Planned Action: {command.Action}");
    }

    return command;
}
```

Step 2: Setup BotService & Event Handlers

```
var botService = new BotService();
BotCommand? botCommand = new BotCommand();

// Register event handlers
connection.On<Guid>("Registered", id => botService.SetBotId(id));

connection.On<string>("Disconnect", async reason =>
{
    Console.WriteLine($"Server sent disconnect: {reason}");
    await connection.StopAsync();
});
```

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Step 2: Setup BotService & Event Handlers

```
connection.On<GameState>("GameState", gamestate =>
{
    botCommand = botService.ProcessState(gamestate);
});

// Handle disconnection
connection.Closed += (error) =>
{
    Console.WriteLine($"Connection closed: {error?.Message}");
    return Task.CompletedTask;
};
```

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Step 2: Register & Send Commands

```
// Start connection
await connection.StartAsync();
Console.WriteLine("Connected to Runner");

// Register the bot
await connection.InvokeAsync("Register", token, nickname);

// Main game loop
while (connection.State == HubConnectionState.Connected)
{
    if (botCommand == null || (int)botCommand.Action is < 1 or > 5)
        continue;

    await connection.SendAsync("BotCommand", botCommand);
    botCommand = null;
}
```

Step 2: More Results!

```
Connected to Runner
Tick: 1
Bot Position: (48, 48)
Planned Action: Right
Tick: 2
Bot Position: (48, 48)
Planned Action: Right
Tick: 3
Bot Position: (49, 48)
Planned Action: Right
Tick: 4
Bot Position: (49, 48)
Planned Action: Right
Tick: 5
Bot Position: (49, 48)
Planned Action: Right
Tick: 6
Bot Position: (49, 48)
Planned Action: Right
Tick: 7
```

```
engine-1  | [19:14:05 INF] Command (Right) enqueued for bot (304
gth: 1
engine-1  | [19:14:05 INF] Command (Down) enqueued for bot (b53e
th: 1
engine-1  | [19:14:05 INF] Game tick 999, Duration = 1.93 / 200,
engine-1  | [19:14:05 INF] Command (Left) enqueued for bot (c200
th: 1
engine-1  | [19:14:05 INF] Command (Right) enqueued for bot (304
gth: 1
engine-1  | [19:14:05 INF] Command (Right) enqueued for bot (8bd
gth: 1
engine-1  | [19:14:05 INF] Command (Right) enqueued for bot (b53
gth: 1
engine-1  | [19:14:05 INF] Game end conditions met. Game Over. Th
engine-1  | [19:14:05 INF] 1: RefBot, Score: 17011, Captured: 3
engine-1  | [19:14:05 INF] 2: RefBot, Score: 14375, Captured: 5
engine-1  | [19:14:05 INF] 3: RefBot, Score: 12434, Captured: 7
engine-1  | [19:14:05 INF] 4: R2D2, Score: 0, Captured: 86
```

Coffee Time!

Catch-up, questions, and caffeine

Helpers will be available to assist you with any questions.

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Understanding the Game State

- What are we working with?
- GameState: Snapshot of the game each tick
  - Tick: The current turn count
  - Animals: List of all bots (including yours)
  - Cells: The map grid, what is in each tile
  - Zookeepers: Moving threats on the map
- Each cell has:
  - X, Y: Position
  - Content: Can be Empty, Pellet, Wall etc.

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Step 3: Start Simple – Find the Closest Pellet

- Let's replace our placeholder logic with basic goal seeking
- Still moves right for now
- But is aware of where the nearest pellet is
- Adds foundation for smarter decisions
- Filter all cells that contain pellets
- Sort them by Manhattan distance from the bot
- Choose the nearest one as the target

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Step 3: Start Simple
Find the Closest Pellet


```
public BotCommand ProcessState(GameState gameState)
{
    var bot = gameState.Animals.FirstOrDefault(a => a.Id == _botId);
    var command = new BotCommand { Action = BotAction.Right }; // fallback
    if (bot == null)
        return command;

    var pellets = gameState.Cells
        .Where(c => c.Content == CellContent.Pellet)
        .OrderBy(c => Math.Abs(c.X - bot.X) + Math.Abs(c.Y - bot.Y))
        .ToList();

    if (!pellets.Any())
        return command;

    var target = pellets.First();

    Console.WriteLine($"Planned Action: {command.Action}");
    return command;
}
```

Step 3: Move Closer to the Pellet

- Chooses the best direction to get closer
- Moves toward target pellet if possible
- Try all directions (Up, Down, Left, Right)
- Skip walls and null tiles
- Compare current vs new distance to target
- Pick the direction that gets us closer

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Step 3: Move Closer to the Pellet

```
var directions = new List<(BotAction action, int dx, int dy)>
{
    (BotAction.Up, 0, -1),
    (BotAction.Down, 0, 1),
    (BotAction.Left, -1, 0),
    (BotAction.Right, 1, 0)
};

BotCommand? fallbackCommand = null;
```

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Step 3: Move Closer to the Pellet

```
foreach (var (action, dx, dy) in directions)
{
    int newX = bot.X + dx;
    int newY = bot.Y + dy;

    var cell = gameState.Cells.FirstOrDefault(c => c.X == newX && c.Y == newY);
    if (cell != null && cell.Content != CellContent.Wall)
    {
        int currentDistance = Math.Abs(bot.X - target.X) + Math.Abs(bot.Y - target.Y);
        int newDistance = Math.Abs(newX - target.X) + Math.Abs(newY - target.Y);

        if (newDistance < currentDistance)
        {
            command.Action = action;
            Console.WriteLine($"Planned Action: {command.Action} (toward pellet)");
            return command;
        }

        fallbackCommand ??= new BotCommand { Action = action };
    }
}
```

Step 3: Move Closer to the Pellet

```
if (fallbackCommand != null)
{
    command = fallbackCommand;
    Console.WriteLine($"Planned Action: {command.Action} (fallback)");
}
```

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Step 3: Move Towards Power-Ups

- Power-ups can be game-changers
- We scan for all visible power-ups
- If there's a power-up within 5 Manhattan distance, the bot will prioritise it
- Otherwise, we weigh the closest power-up against the closest pellet and target the closer one

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Step 3: Move Towards Power-Ups


```
var allPowerUps = gameState.Cells
    .Where(c =>
        c.Content == CellContent.PowerPellet ||
        c.Content == CellContent.ChameleonCloak ||
        c.Content == CellContent.Scavenger ||
        c.Content == CellContent.BigMooseJuice)
    .ToList();

var nearbyPowerUps = allPowerUps
    .Where(c => Math.Abs(c.X - bot.X) + Math.Abs(c.Y - bot.Y) <= 5)
    .OrderBy(c => Math.Abs(c.X - bot.X) + Math.Abs(c.Y - bot.Y))
    .ToList();

var pellets = gameState.Cells
    .Where(c => c.Content == CellContent.Pellet)
    .OrderBy(c => Math.Abs(c.X - bot.X) + Math.Abs(c.Y - bot.Y))
    .ToList();

Cell? target = null;
```

Step 3: Move Towards Power-Ups

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```
if (nearbyPowerUps.Any())
{
    target = nearbyPowerUps.First();
}
else
{
    var closestPowerUp = allPowerUps.OrderBy(c => Math.Abs(c.X - bot.X) + Math.Abs(c.Y -
bot.Y)).FirstOrDefault();
    var closestPellet = pellets.FirstOrDefault();

    if (closestPowerUp != null && closestPellet != null)
    {
        var distPowerUp = Math.Abs(closestPowerUp.X - bot.X) + Math.Abs(closestPowerUp.Y - bot.Y);
        var distPellet = Math.Abs(closestPellet.X - bot.X) + Math.Abs(closestPellet.Y - bot.Y);
        target = distPowerUp <= distPellet ? closestPowerUp : closestPellet;
    }
    else
    {
        target = closestPowerUp ?? closestPellet;
    }
}

if (target == null)
    return command;
```

Step 3: Prioritise Power-Ups

```
Console.WriteLine($"Planned Action: {command.Action} (toward {(target.Content ==
CellContent.Pellet ? "pellet" : "power-up")})");
```

Step 3: Use Picked Up Power-Ups

- New game engine version introduces collectible power-ups
- Power-ups can give big scoring or survival advantages
- We'll activate a held power-up automatically
- Added before we do any movement logic

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Step 3: Use Picked Up Power-Ups

```
if (bot.HeldPowerUp != null)
{
    Console.WriteLine("Planned Action: UseItem (activating power-up)");
    return new BotCommand { Action = BotAction.UseItem };
}
```

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Step 3: Results

```
engine-1  | [23:50:11 INF] 1: RefBot, Score: 88339, Captured: 8, Power Ups Used: 1
engine-1  | [23:50:11 INF] 2: RefBot, Score: 85837, Captured: 9, Power Ups Used: 6
engine-1  | [23:50:11 INF] 3: RefBot, Score: 67235, Captured: 20, Power Ups Used: 5
engine-1  | [23:50:11 INF] 4: R2D2, Score: 49884, Captured: 43, Power Ups Used: 0
```

```
engine-1  | [23:54:34 INF] 1: R2D2, Score: 55803, Captured: 37, Power Ups Used: 1
engine-1  | [23:54:34 INF] 2: RefBot, Score: 55703, Captured: 16, Power Ups Used: 3
engine-1  | [23:54:34 INF] 3: RefBot, Score: 47566, Captured: 18, Power Ups Used: 5
engine-1  | [23:54:34 INF] 4: RefBot, Score: 31888, Captured: 17, Power Ups Used: 1
```

Step 3: Avoid Danger Zones

- Adds a danger zone map from zookeeper positions
- Avoids zookeeper tiles and adjacent tiles
- Each zookeeper creates a diamond-shaped zone of tiles within Manhattan distance 3
- Avoid any direction that moves into a danger tile
- If no safe option moves us closer, fallback to the first safe direction

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Step 3: Avoid Danger Zones

```
int maxX = gameState.Cells.Max(c => c.X);
int maxY = gameState.Cells.Max(c => c.Y);

var dangerZones = new HashSet<(int X, int Y)>();
int dangerRadius = 3;

foreach (var zk in gameState.Zookeepers)
{
    for (int dx = -dangerRadius; dx <= dangerRadius; dx++)
    {
        for (int dy = -dangerRadius; dy <= dangerRadius; dy++)
        {
            if (Math.Abs(dx) + Math.Abs(dy) > dangerRadius)
                continue;

            int zx = (zk.X + dx + maxX + 1) % (maxX + 1);
            int zy = (zk.Y + dy + maxY + 1) % (maxY + 1);
            dangerZones.Add((zx, zy));
        }
    }
}
```

Step 3: Avoid Danger Zones

```
if (dangerZones.Contains((newX, newY)))
    Console.WriteLine($"Skipped {action} (danger zone)");

if (cell != null && cell.Content != CellContent.Wall && !dangerZones.Contains((newX, newY)))
```

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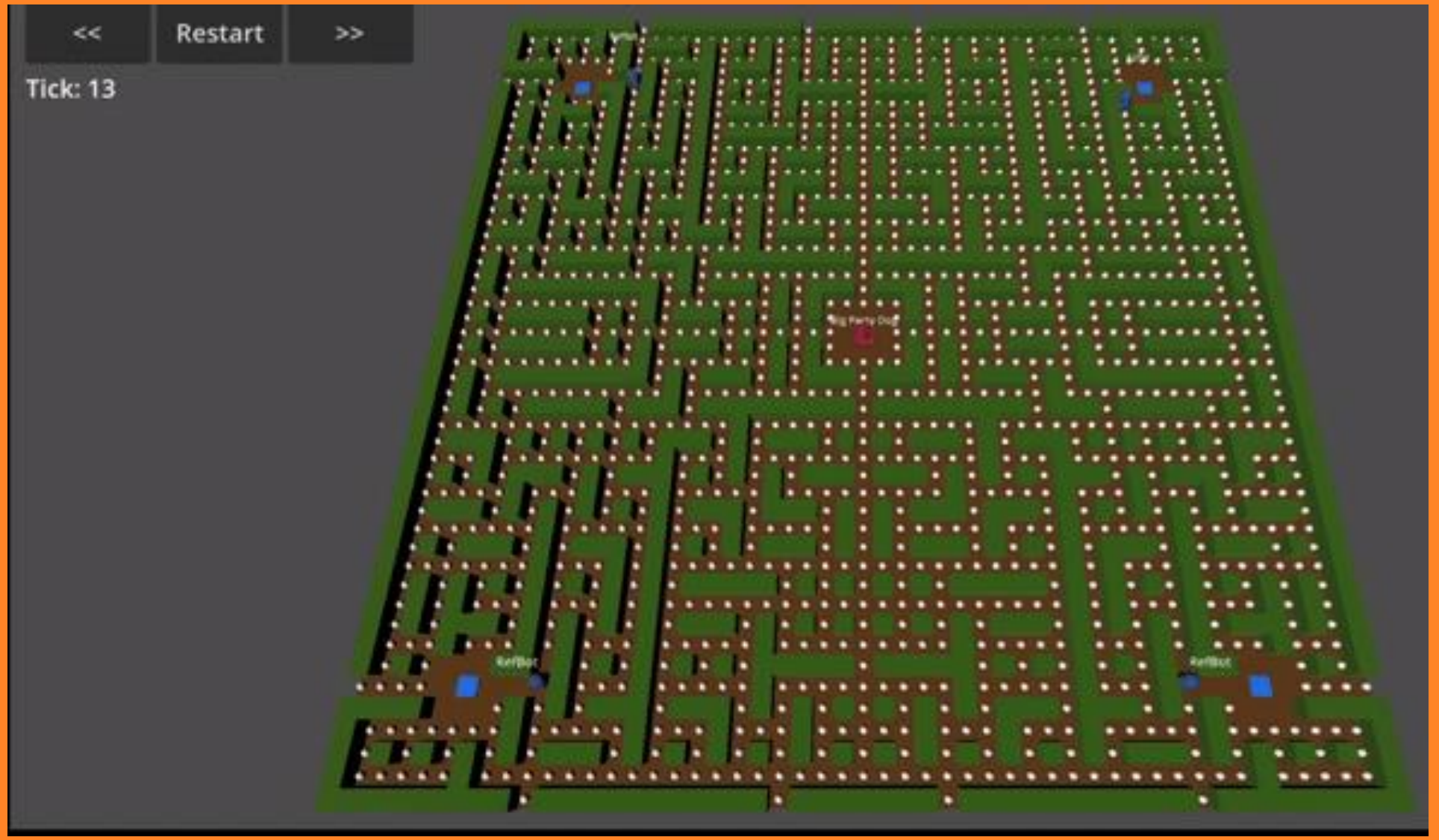
Step 3: Results



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Step 3: Results

```
engine-1  | [03:16:10 INF] 1: R2D2, Score: 91117, Captured: 7, Power Ups Used: 0
engine-1  | [03:16:10 INF] 2: RefBot, Score: 68879, Captured: 29, Power Ups Used: 6
engine-1  | [03:16:10 INF] 3: RefBot, Score: 55499, Captured: 26, Power Ups Used: 3
engine-1  | [03:16:10 INF] 4: RefBot, Score: 12286, Captured: 33, Power Ups Used: 3
```

```
engine-1  | [00:19:43 INF] 1: R2D2, Score: 83476, Captured: 6, Power Ups Used: 0
engine-1  | [00:19:43 INF] 2: RefBot, Score: 75370, Captured: 29, Power Ups Used: 9
engine-1  | [00:19:43 INF] 3: RefBot, Score: 59360, Captured: 20, Power Ups Used: 3
engine-1  | [00:19:43 INF] 4: RefBot, Score: 38644, Captured: 52, Power Ups Used: 1
```

```
engine-1  | [02:07:48 INF] 1: R2D2, Score: 147046, Captured: 8, Power Ups Used: 1
engine-1  | [02:07:48 INF] 2: RefBot, Score: 74490, Captured: 48, Power Ups Used: 2
engine-1  | [02:07:48 INF] 3: RefBot, Score: 61501, Captured: 14, Power Ups Used: 3
engine-1  | [02:07:48 INF] 4: RefBot, Score: 45094, Captured: 9, Power Ups Used: 1
```

What's Next?

- We built something simple, a starting point
- We added:
  - Pellet targeting
  - Wall avoidance
  - Danger zone detection
- But we're just getting started
- Challenge is on you to build something better than this
- Remember: Every improvement teaches you something new!

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Pizza Time!

Catch-up, questions, and pizza

Enjoy the rest of your time with us!

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2025
THANK YOU
You made it this far!
Good luck for the rest!