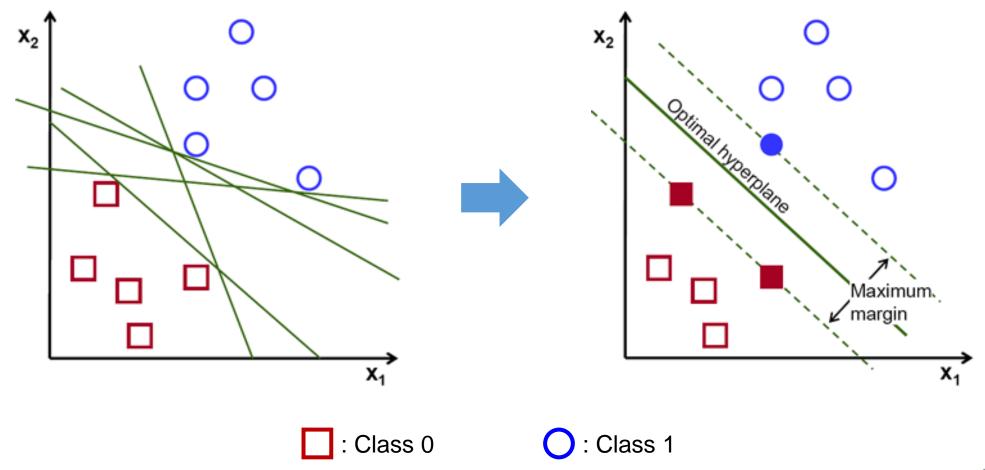
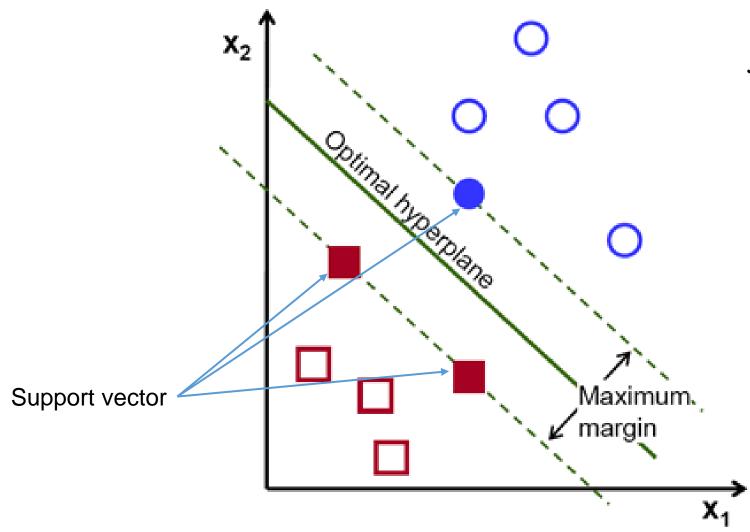


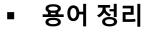
■ 목적: Margin을 최대화하는 optimal separating hyperplane (decision boundary) 구하기

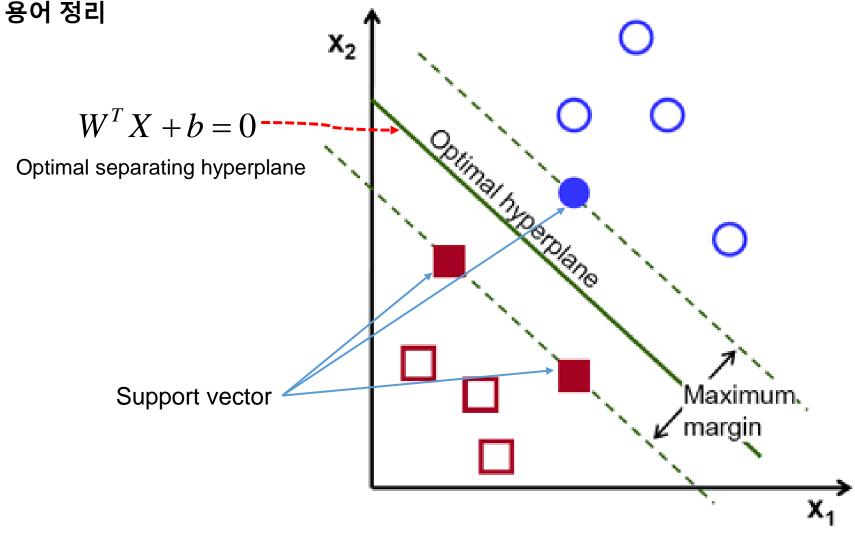


■ 용어 정리

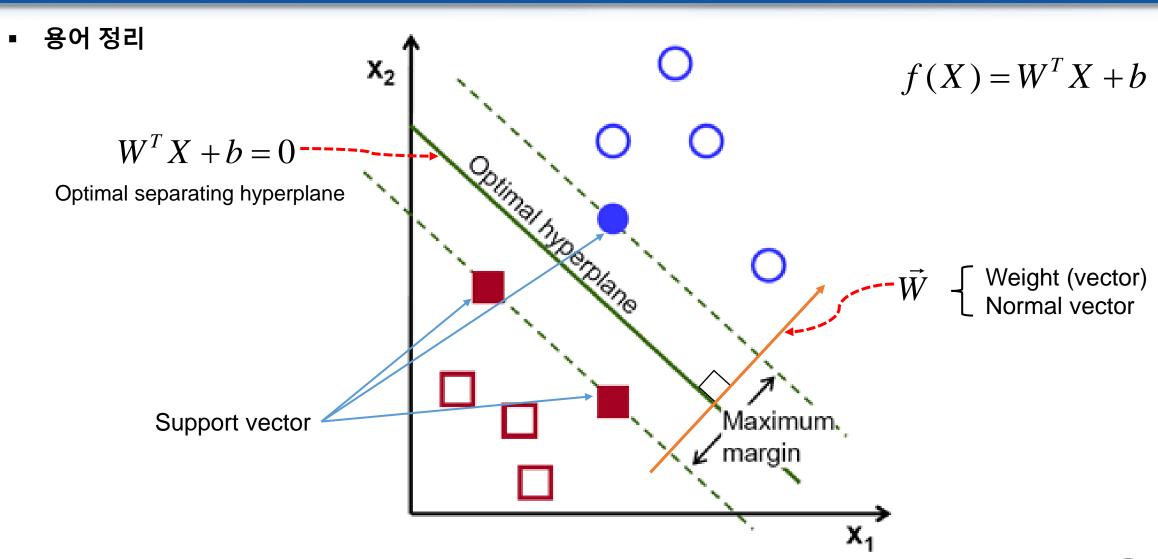


$$f(X) = W^T X + b$$

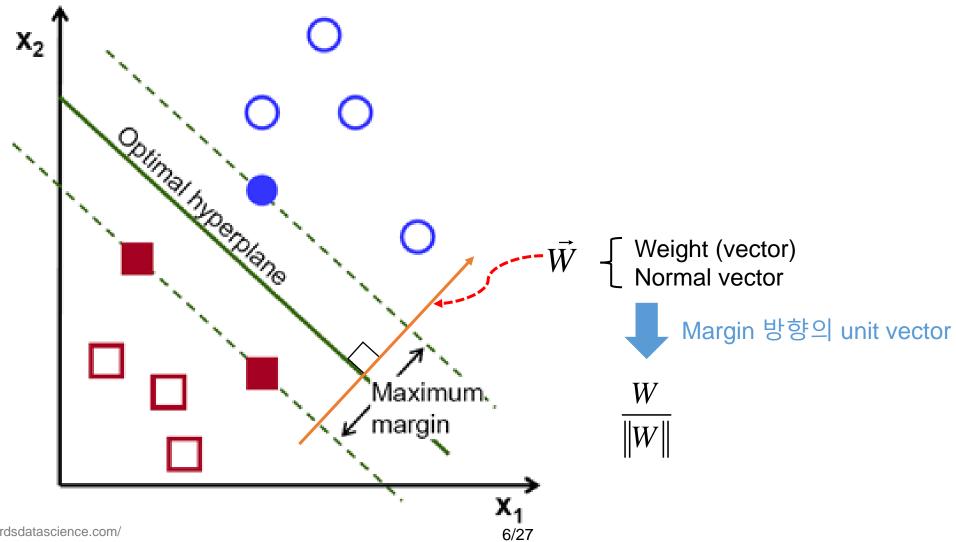




$$f(X) = W^T X + b$$

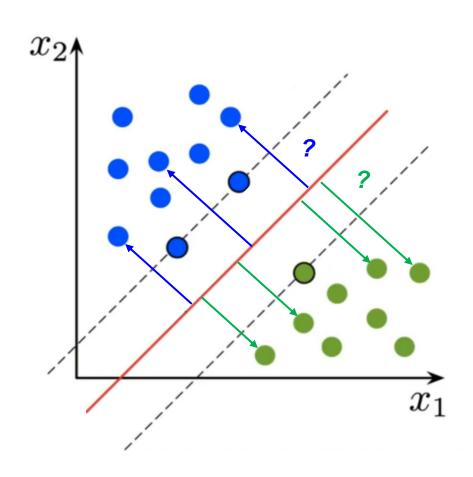


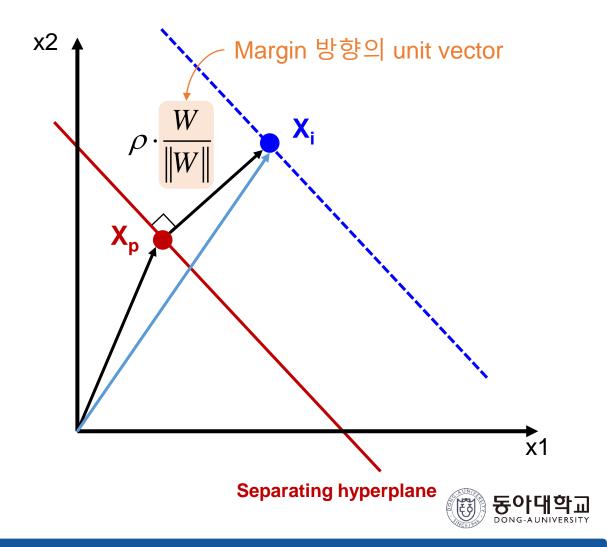
용어 정리



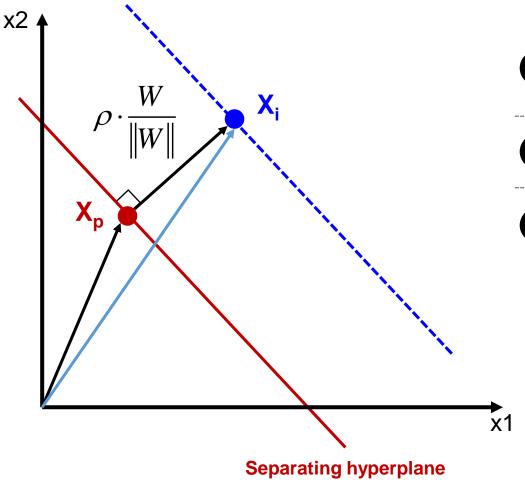


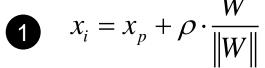
임의의 데이터 x_i 에 대해 separating hyperplane과의 거리: ρ

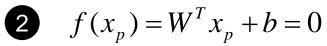


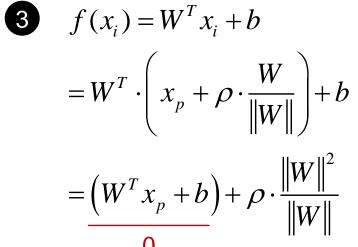


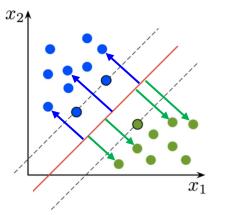
임의의 데이터 x_i 에 대해 separating hyperplane과의 거리: ρ











$$4 : \rho = \frac{f(x)}{\|W\|}$$



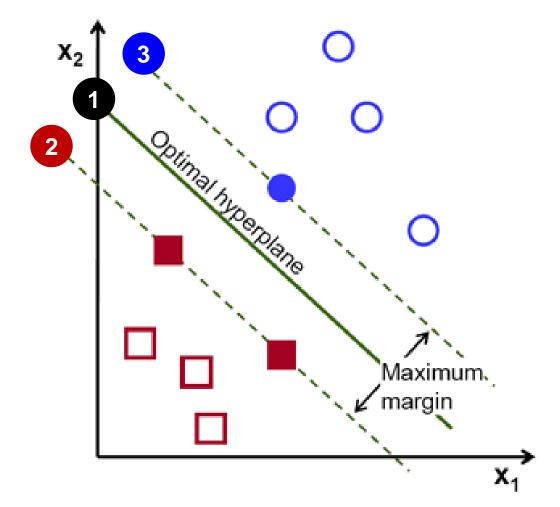
Binary classification

1 : Optimal separating hyperplane $f(X) = W^T X + b = 0$

2 : Support vector (negative)

$$f(X) = W^T X + b = -1$$

$$f(X) = W^T X + b = +1$$





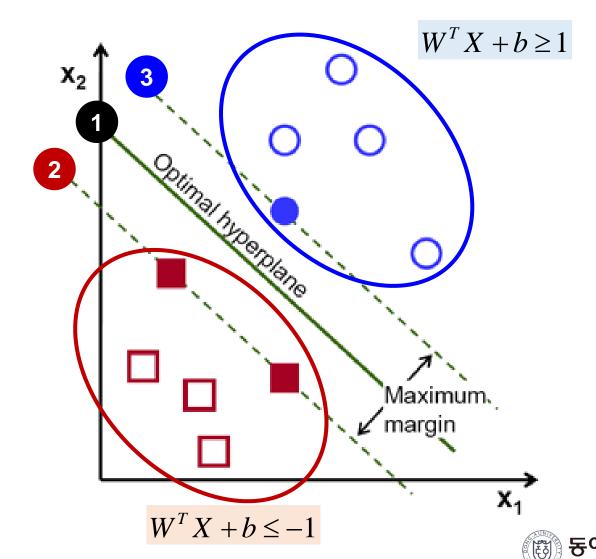
Binary classification

1 : Optimal separating hyperplane $f(X) = W^{T}X + b = 0$

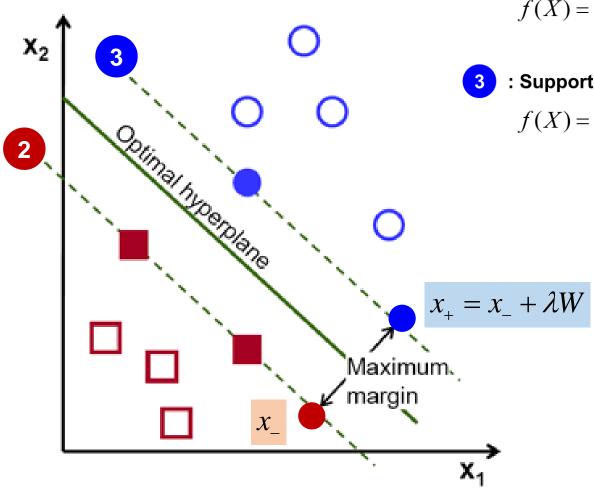
2 : Support vector (negative)

$$f(X) = W^T X + b = -1$$

$$f(X) = W^T X + b = +1$$



■ Margin 계산



2 : Support vector (negative)

$$f(X) = W^T X + b = -1$$

$$f(X) = W^{T}X + b = +1$$

$$W^T x_+ + b = 1$$

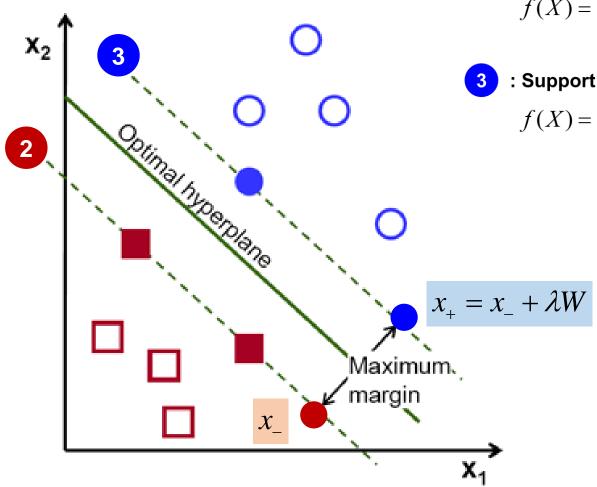
$$W^T(x_- + \lambda W) + b = 1$$

$$\frac{W^T x_- + b + W^T \lambda W = 1}{-1}$$

$$\therefore \lambda = \frac{2}{W^T W}$$



■ Margin 계산



2 : Support vector (negative)

$$f(X) = W^T X + b = -1$$

$$f(X) = W^T X + b = +1$$

$$W^{T}x_{+} + b = 1$$

$$W^{T}(x_{-} + \lambda W) + b = 1$$

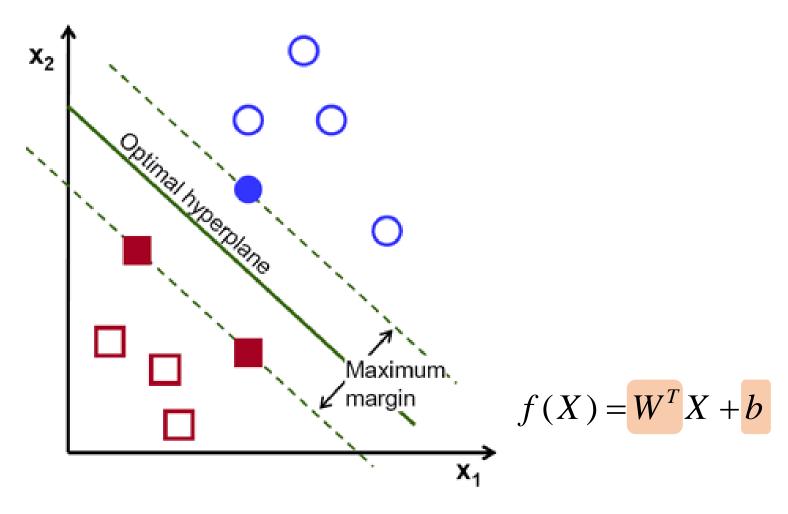
$$W^{T}x_{-} + b + W^{T}\lambda W = 1$$

$$\therefore \lambda = \frac{2}{W^{T}W}$$

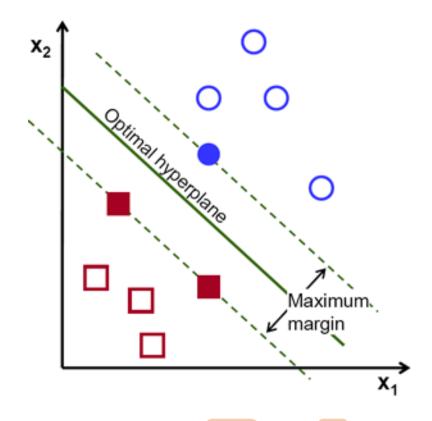
Margin = distance(
$$x_{+}, x_{-}$$
)
= $||x_{+} - x_{-}||_{2} = ||\lambda W||_{2}$
= $\frac{2}{W^{T}W} \cdot \sqrt{W^{T}W} = \frac{2}{||W||_{2}}$



■ 목적: Margin을 최대화하는 optimal separating hyperplane (decision boundary) 구하기



- 목적: Margin을 최대화하는 optimal separating hyperplane (decision boundary) 구하기
- Solution
 - Quadratic Programming (2차 계획법)
 - Gradient Decent Method (GD) → Optimal W, b

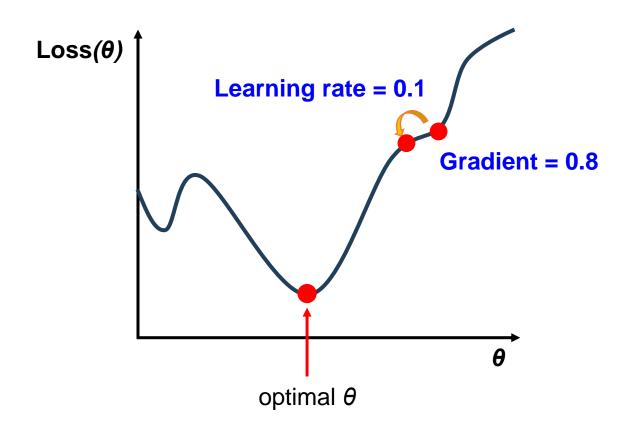


$$f(X) = W^T X + b$$



Solution

- Quadratic Programming (2차 계획법)
- Gradient Decent Method (GD) → Optimal W, b



Gradient decent algorithm

- ① 현재 지점에서 미분을 이용해 gradient 계산
- ② Gradient에 learning rate를 곱하고 반대 방향으로 weight update

$$egin{aligned} heta_{t+1} &= heta_t - lpha \, rac{\partial L}{\partial heta_t} \ &= heta_t - 0.08 \end{aligned}$$



Loss function (Cost function): Hinge loss

Prediction

Label

$$W^T X_i + b \ge 1 \qquad \Rightarrow \qquad y_i = +1$$

$$\rightarrow$$

$$y_i = +1$$

$$W^T X_i + b \le -1 \qquad \Rightarrow \qquad y_i = -1$$

$$\rightarrow$$

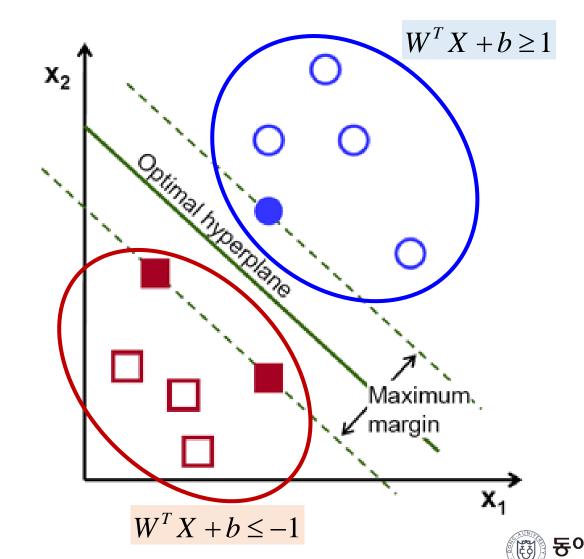
$$y_i = -1$$

$$y_i(W^T x_i + b) \ge 0$$

Label

Prediction

이 조건을 만족하는 경우 정상적으로 분류 성공



Loss function (Cost function): Hinge loss

Prediction

Label

$$W^T X_i + b \ge 1 \qquad \rightarrow \qquad y_i = +1$$

$$\rightarrow$$

$$y_i = +1$$

$$W^T X_i + b \le -1 \qquad \Rightarrow \qquad y_i = -1$$

$$\rightarrow$$

$$y_i = -1$$

$|y_i(W^Tx_i+b)| \ge 0$

Label

Prediction

이 조건을 만족하는 경우 정상적으로 분류 성공

Hinge loss

$$Loss = \max(0, 1 - y_i(W^T x_i + b))$$



Loss function (Cost function): Hinge loss

Prediction

Label

$$W^T X_i + b \ge 1 \qquad \rightarrow \qquad y_i = +1$$

$$\rightarrow$$

$$y_i = +1$$

$$W^T X_i + b \le -1 \qquad \Rightarrow \qquad y_i = -1$$



$$y_i = -1$$

$$|y_i(W^Tx_i+b)| \ge 0$$

Label **Prediction**

이 조건을 만족하는 경우 정상적으로 분류 성공

Hinge loss

$$Loss = \max(0, 1 - y_i(W^T x_i + b))$$

$$y_i(W^Tx_i+b)=-1 \rightarrow Loss=+2$$

$$y_i(W^Tx_i + b) = 0$$
 \rightarrow Loss = +1

$$y_i(W^T x_i + b) = +0.5 \rightarrow Loss = +0.5$$

$$y_i(W^Tx_i + b) = +1 \rightarrow Loss = 0$$



■ Loss function (Cost function): Hinge loss → Gradient

Hinge loss

$$Loss = \max(0, 1 - y_i(W^T x_i + b))$$

 $1 \quad y_i(W^T x_i + b) \ge 1 \quad \longrightarrow \quad Loss = 0$

2 otherwise \longrightarrow Loss = $1 - y_i(W^T x_i + b)$



■ Loss function (Cost function): Hinge loss → Gradient

Hinge loss

$$Loss = \max(0, 1 - y_i(W^T x_i + b))$$

1 $y_i(W^Tx_i + b) \ge 1$ \longrightarrow Loss = 0

2 otherwise \longrightarrow Loss = $1 - y_i(W^T x_i + b)$

 $y_i(W^T x_i + b) \ge 1$

$$\frac{\delta L}{\delta W} = 0 \qquad \frac{\delta L}{\delta b} = 0$$

Update 수행 X

2 otherwise

$$\frac{\delta L}{\delta W} = -y_i x_i \qquad \frac{\delta L}{\delta b} = y_i$$



■ Basecode 다운로드: LMS 강의 콘텐츠 13주차

Support Vector Machine (GD Method)

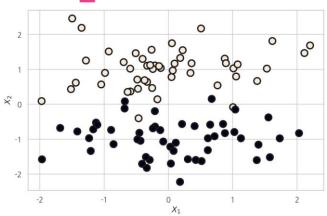
```
[ ] import pandas as pd
  import numpy as np
  import matplotlib.pyplot as plt

from sklearn.datasets import make_blobs
```

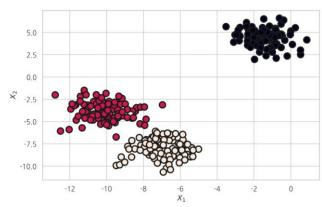


▪ 데이터셋 생성: sklearn.datasets

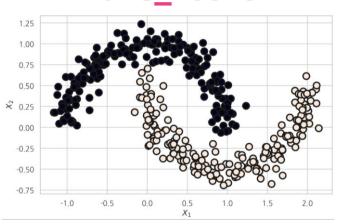




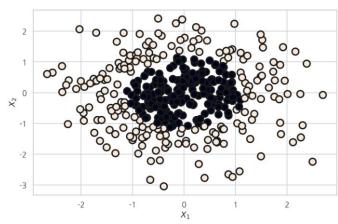
make_blobs



make_moons



make_gaussian_quantiles

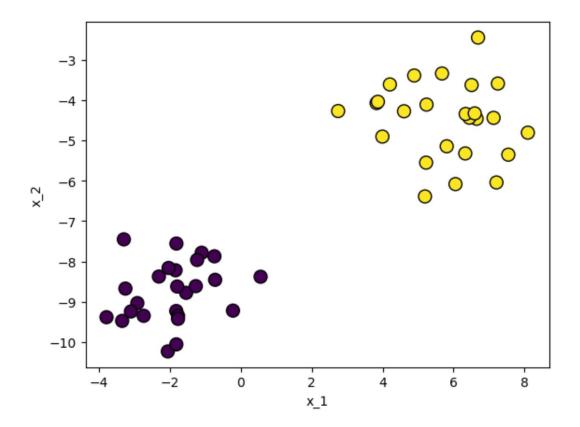




■ 데이터셋 생성: sklearn.datasets

▼ Dataset

```
[] X, y = make_blobs(n_samples=50, n_features=2, centers=2, cluster_std=1.05, random_state=40)
plt.scatter(X[:, 0], X[:, 1], marker='o', c=y, s=100, edgecolor="k", linewidth=1)
plt.xlabel("x_1")
plt.ylabel("x_2")
plt.show()
```





■ SVM 모델 작성 및 gradient decent 코드 작성

Model

```
class SVM:
    def __init__(self, learning_rate=0.001, n_iters=1000):
        # initialization
    def fit(self, X, y):
        # Update parameters
    def predict(self, X):
        # Prediction
```

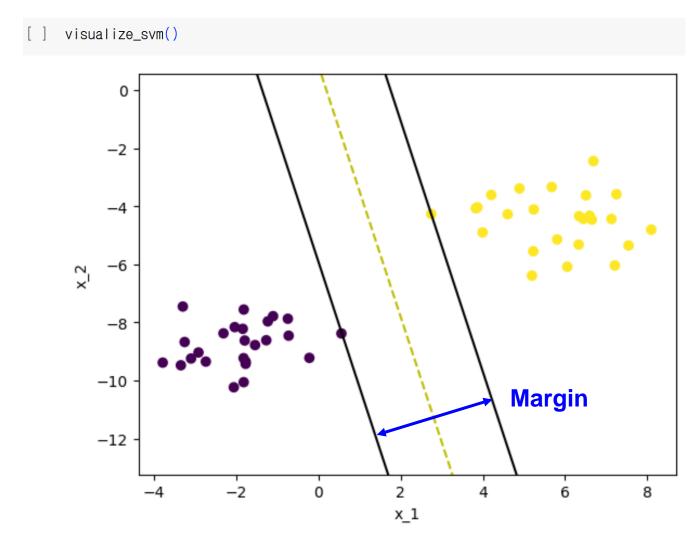
■ SVM 모델 training 및 도출된 W, b값 확인

Prediction

```
model = SVM()
margin_log = model.fit(X, y)
print(model.w, model.b)
[0.64070956 0.14828428] -0.12500000000000008
margin = 2 / np.sqrt(np.dot(model.w.T, model.w))
print(margin)
3.0411543613656318
```

Margin = distance (x_{+}, x_{-}) = $||x_{+} - x_{-}||_{2} = ||\lambda W||_{2}$ = $\frac{2}{W^{T}W} \cdot \sqrt{W^{T}W} = \frac{2}{||W||_{2}}$

Visualization





Questions & Answers

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