

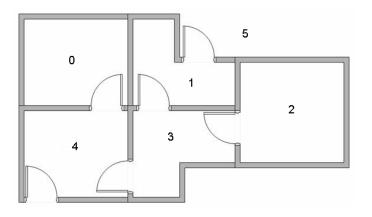
Slides adapted from John McCullock

Machine Learning

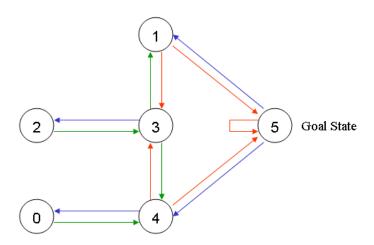
Machine Learning: Jordan Boyd-Graber University of Maryland

Content Questions

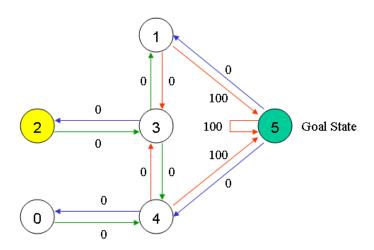
Scenario



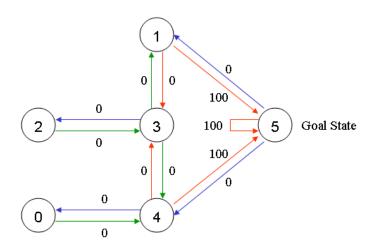
States



Scenario: Escape!



Rewards



Reward Matrix

100 Goal

- O Valid Transition
- -1 Impossible

Q-Learning Algorithm

For each s, a initialize table entry $\hat{Q}(s, a) \leftarrow 0$ Observe current state s Do forever:

- Select an action a and execute it
- Receive immediate reward r
- Observe the new state s'
- Update the table entry for $\hat{Q}(s, a)$ as follows:

$$\hat{Q}(s,a) \leftarrow r + \gamma \max_{a'} \hat{Q}(s',a')$$

 \bullet $s \leftarrow s'$

Initial Q Matrix

- Suppose we start in Room 1
- And we'll go to Room 5 afterward

In Room 5

State 0 1 2 3 4 5
$$R = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ -1 & -1 & -1 & -1 & 0 & -1 \\ 1 & -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & -1 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & -1 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$$

What is the updated Q matrix? ($\gamma = .8$)

$$\hat{Q}(s,a) \leftarrow r + \gamma \max_{a'} \hat{Q}(s',a')$$

$$\hat{Q}(1,5) = R(1,5) + \gamma \max[\hat{Q}(5,0), \dots \hat{Q}(5,5)]$$
 (1)

$$\hat{Q}(1,5) = R(1,5) + \gamma \max[\hat{Q}(5,0), \dots \hat{Q}(5,5)]$$
 (1)

$$\hat{Q}(1,5) = 100 + \gamma \cdot 0 \tag{2}$$

(3)

$$\hat{Q}(5,1) = R(5,1) + \gamma \max[\hat{Q}(1,0), \dots \hat{Q}(1,5)]$$
(3)

$$\hat{Q} = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & 0 & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{5} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{5} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$$

$$\hat{Q}(5,1) = R(5,1) + \gamma \max[\hat{Q}(1,0), \dots \hat{Q}(1,5)]$$
(3)

$$\hat{Q}(5,1) = 0 + \gamma \cdot 100 \tag{4}$$

(5)

$$\hat{Q}(1,3) = R(1,3) + \gamma \max[\hat{Q}(3,0), \dots \hat{Q}(3,5)]$$
 (5)

$$\hat{Q} = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 80 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & 0 & 0 & 0 & 100 \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{0} & 80 & 0 & 0 & 0 & 0 \\ \end{array} \right)$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \end{bmatrix}$$
 $R = \begin{array}{c} 2 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 0 & -1 \\ 0 & -1 & -1 & 0 & -1 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \\ \end{array}$

$$\hat{Q}(1,3) = R(1,3) + \gamma \max[\hat{Q}(3,0), \dots \hat{Q}(3,5)]$$
 (5)

$$\hat{Q}(1,3) = 0 + \gamma \cdot 0 \tag{6}$$

(7)

$$\hat{Q} = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 80 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & 0 & 1 & 2 & 3 & 4 & 5 \\ 0$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$$

$$\hat{Q}(3,4) = R(3,4) + \gamma \max[\hat{Q}(4,0), \dots \hat{Q}(4,5)]$$
(7)

$$\hat{Q} = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 80 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & 0 & 0 & 0 & 100 \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{0} & 0 & 0 & 0 & 0 & 0 \\ \textbf{0} & 80 & 0 & 0 & 0 & 0 \\ \end{array} \right)$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \end{bmatrix}$$
 $R = \begin{array}{c} 2 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 0 & -1 \\ 0 & -1 & -1 & 0 & -1 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \\ \end{array}$

$$\hat{Q}(3,4) = R(3,4) + \gamma \max[\hat{Q}(4,0), \dots \hat{Q}(4,5)]$$
 (7)

$$\hat{Q}(3,4) = 0 + \gamma \cdot 0 \tag{8}$$

(9)

$$\hat{Q} = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 80 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & 0 & 1 & 2 & 3 & 4 & 5 \\ 0$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$$

$$\hat{Q}(4,5) = R(4,5) + \gamma \max[\hat{Q}(5,0), \dots \hat{Q}(5,5)]$$
(9)

$$\hat{Q} = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 0 & 0 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 & 0 \\ 5 & 0 & 80 & 0 & 0 & 0 \end{pmatrix} \qquad \begin{cases} \text{Action} \\ \text{State} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{1} & \textbf{2} & \textbf{3} & \textbf{4} & \textbf{5} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \\ \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} & \textbf{0} \end{pmatrix}$$

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \end{bmatrix}$$
 $R = \begin{array}{c} 2 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 0 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$

$$\hat{Q}(4,5) = R(4,5) + \gamma \max[\hat{Q}(5,0), \dots \hat{Q}(5,5)]$$
(9)

$$\hat{Q}(4,5) = 100 + \gamma \cdot 80 \tag{10}$$

(11)

State 0 1 2 3 4 5

0
$$\begin{bmatrix} -1 & -1 & -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & 100 \\ -1 & -1 & -1 & 0 & -1 & -1 \\ 3 & -1 & 0 & 0 & -1 & 0 & -1 \\ 4 & 0 & -1 & -1 & 0 & 100 \\ 5 & -1 & 0 & -1 & -1 & 0 & 100 \end{bmatrix}$$

$$\hat{Q}(5,4) = R(5,4) + \gamma \max[\hat{Q}(4,0), \dots \hat{Q}(4,5)]$$
(11)

$$\hat{Q} = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 & 0 \\ 4 & 0 & 80 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad \begin{array}{c} \text{Action} \\ \text{State} & 0 & 1 & 2 & 3 & 4 & 5 \\ 0$$

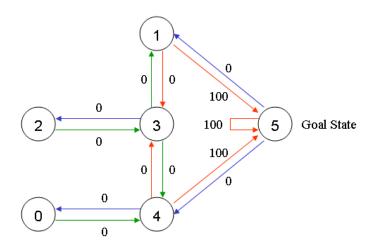
$$\hat{Q}(5,4) = R(5,4) + \gamma \max[\hat{Q}(4,0), \dots \hat{Q}(4,5)]$$
(11)

$$\hat{Q}(5,4) = 0 + \gamma \cdot 164 = 131 \tag{12}$$

If you keep going ...

$$Q = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 0 & 0 & 400 & 0 \\ 0 & 0 & 0 & 320 & 0 & 500 \\ 0 & 0 & 0 & 320 & 0 & 0 \\ 0 & 400 & 256 & 0 & 400 & 0 \\ 320 & 0 & 0 & 320 & 0 & 500 \\ 5 & 0 & 400 & 0 & 0 & 400 & 500 \end{bmatrix}$$

If you keep going ...



Is this really hard?

- Creating the state space
- Estimating rewards
- Choosing action with incomplete learning