robot_ws\src\assign1_650610841\assign1_650610841\hearer1_650610841.py

```python
1   import rclpy
2   from rclpy.node import Node
3
4   from std_msgs.msg import String
5
6
7   class MinimalSubscriber(Node):
8
9       def __init__(self):
10          super().__init__('hearer1_650610841')
11          self.subscription = self.create_subscription(
12              String,
13              'gossip_650610841',
14              self.listener_callback,
15              10)
16          self.subscription  # prevent unused variable warning
17
18      def listener_callback(self, msg):
19          self.get_logger().info('SUB1 get "%s"' % msg.data)
20
21
22  def main(args=None):
23      rclpy.init(args=args)
24
25      minimal_subscriber = MinimalSubscriber()
26
27      rclpy.spin(minimal_subscriber)
28
29      # Destroy the node explicitly
30      # (optional - otherwise it will be done automatically
31      # when the garbage collector destroys the node object)
32      minimal_subscriber.destroy_node()
33      rclpy.shutdown()
34
35
36  if __name__ == '__main__':
37      main()
38
```