NAOPlanningChallenge.py

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NAO PLANNING CHALLENGE 2021
TEAM WALL E = [
   'Samuele Marino',
   ALMA MATER STUDIORUM
   UNIVERSITÀ DI BOLOGNA
```



```
1 # Used Library:
  import aima
  algorithm = depth first graph search()
  programming languages = 'Python'
  MODELING = {
      State: ('CurrentPosition', 'NumberPosition', 'ActualTime',
              'PreviousPosition')
     Action: 'Movement from a position P1 to another position P2'
      Goal: ('FinalPosition', 'X>=5', 'time<=20', 'PreviousPosition')
```

Fundamentals of Artificial Intelligence and Knowledge Representation

constraints.py

algorithm.pv

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algorithm.py
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constraints.py

```
CONSTRAINTS = [
    'Mandatory intermediate positions',
    'Iterate over mandatory positions and generate
   intermediate independent sequence and then unify all the
    sequence in a single choreography',
    'At least five positions'
Time = 'Choose sequence of positions in order to create
        three minutes time choreography'
```

```
MANDATORY POSITION = {
       'StandInit': 1.45948129653931,
       'Hello': 4.639948129653931,
       'Stand': 2.02,
       'Sit': 11.704515933990479,
       'Wipe Forehead': 5.119374990463257,
       'StandZero': 1.4620330333709717,
       'SitRelax': 14.200019121170044,
       'Crouch': 1.6594460010528564
14 SONG = 'Mille.wav'
```

```
POSITION = {
    'Arms opening': 7.761928081512451,
    'Diagonal left': 3.4190828800201416,
    'Diagonal right': 3.4149229526519775,
    'Stand from sit': 7.957381010055542,
    'Move backward': 3.8621809482574463,
    'Move forward': 3.838757038116455,
    'Right arm': 9.083323955535889,
    'Rotation foot LLeg': 9.015203952789307,
    'Rotation foot RLeg': 8.62186598777771,
```

regardments.py

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THANKS FOR LISTENING
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