# **ASEN 5044 HW 8 Main Script**

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## Housekeeping

### **Problem 1**

Helper functions

Qb =

$$F\_a = \begin{bmatrix} 1.0000 & 0.5000 & 0 & -0.0056 \\ 0 & 0.9997 & 0 & -0.0225 \\ 0 & 0.0056 & 1.0000 & 0.5000 \\ 0 & 0.0225 & 0 & 0.9997 \end{bmatrix}$$

$$Q\_a = \begin{bmatrix} 0.8329 & 2.4983 & 0.0261 & 0.0953 \\ 2.4983 & 9.9931 & 0.0719 & 0.3343 \\ 0.0261 & 0.0719 & 0.2087 & 0.6266 \\ 0.0953 & 0.3343 & 0.6266 & 2.5069 \end{bmatrix}$$

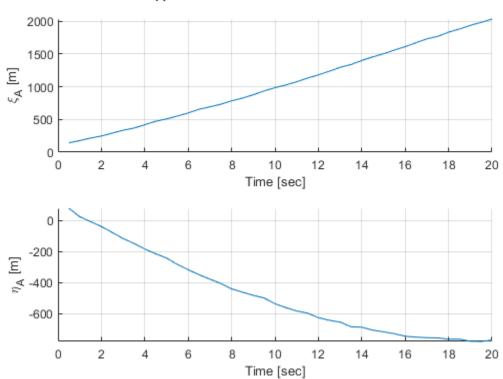
$$F\_b = \begin{bmatrix} 1.0000 & 0.5000 & 0 & 0.0056 \\ 0 & 0.9997 & 0 & 0.0225 \\ 0 & -0.0056 & 1.0000 & 0.5000 \\ 0 & -0.0225 & 0 & 0.9997 \end{bmatrix}$$

0.8336	2.5011	0.0156	0.0297
2.5011	10.0044	0.0531	0.1656
0.0156	0.0531	0.2080	0.6238
0.0297	0.1656	0.6238	2.4956

## **Problem 2 setup**

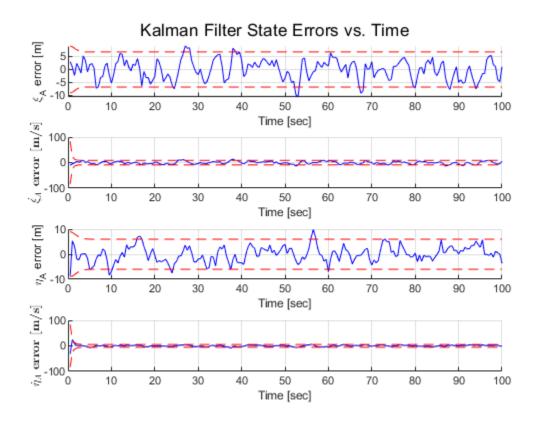
## Problem 2a

 $\boldsymbol{y}_{\boldsymbol{A}}(\boldsymbol{k})$  vs. time, first 20 seconds

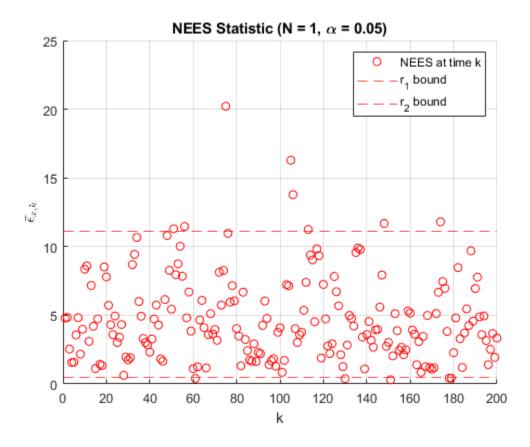


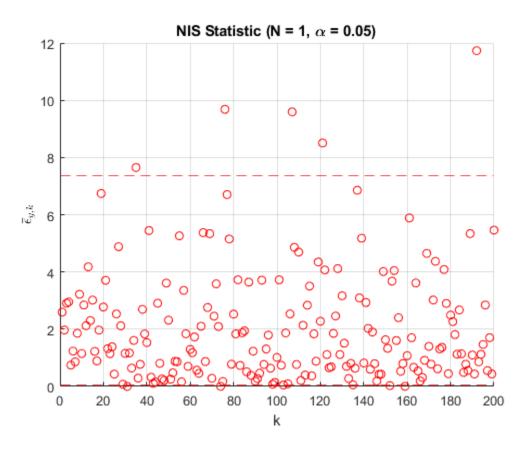
### **Problem 2b**

Setup



## **Problem 2 NEES/NIS tests**

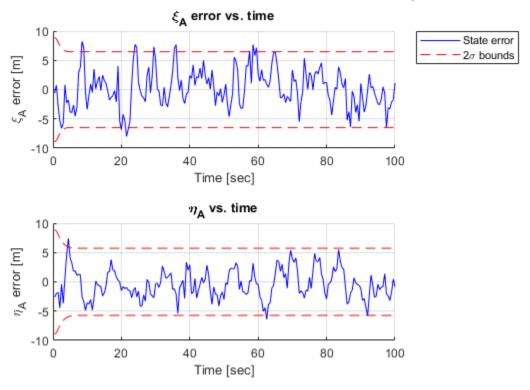




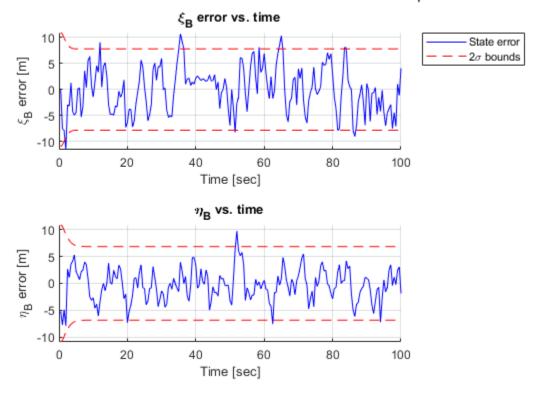
# Test function Problem 3a

Setup

#### Position Errors for Aircraft A - Ground Station and Transponder



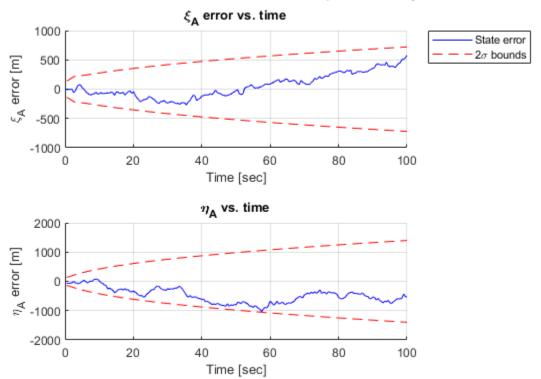
### Position Errors for Aircraft B - Ground Station and Transponder



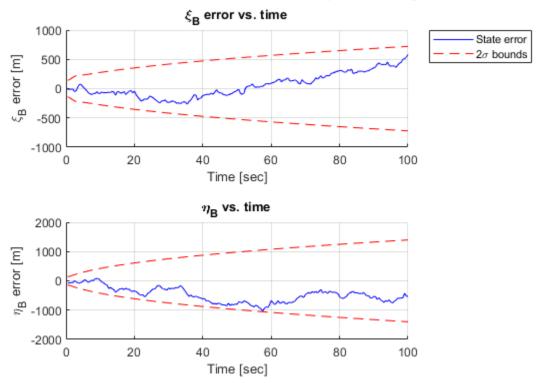
## **Problem 3b**

New matrices





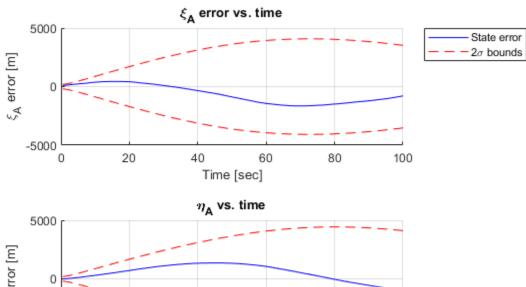




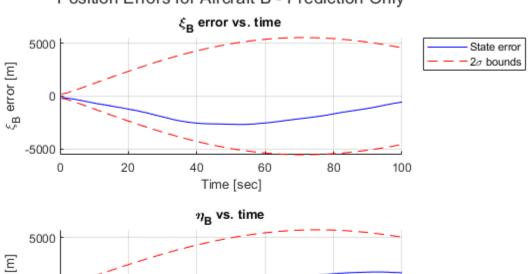
## **Problem 3c**

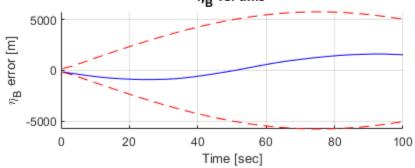
Measurement steps shouldn't matter, are ignored in this problem New matrices

### Position Errors for Aircraft A - Prediction only



### Position Errors for Aircraft B - Prediction Only





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