# **ASEN 5050 HW 8 Main Script**

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# Housekeeping

```
clc; clear; close all;
```

## **Setup**

#### **Problem 1**

```
fprintf("--- Problem 1 ---\n")
r_p = 7500; % km
r_a = 8500; % km
i_deg = 105; % deg
T = 110*60; % 110 min -> sec

aPlanet = 2.25*AU2km; % AU -> km
rPlanet = 6500; % km

aSC = 0.5*(r_a + r_p);
eSC = (r_a - r_p)/(r_a + r_p);
muPlanet = (4*pi^2*aSC^3)/(T^2);
mPlanet = muPlanet/G

RAANDot = sqrt(muSun/(aPlanet^3));

J2Planet = -(2/3)*((((1-(eSC^2))^2)*RAANDot*aSC^(7/2))/(sqrt(muPlanet)*(rPlanet^2)*cosd(i_deg)))
```

```
--- Problem 1 ---
mPlanet =
6.9538e+24

J2Planet =
2.3990e-04
```

# **Problem 2 setup**

```
R0 = [2489.63813; -3916.07418; -5679.05524];

V0 = [9.13452; -1.91212; 2.57306];

X0 = [R0; V0];
```

## **Provblem 2a**

## **Problem 2b**

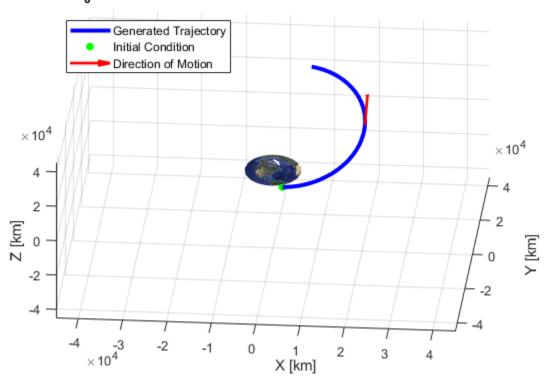
```
dTA deg = TA1 deg - TA0 deg;
    % f and g functions
f = 1 - (r1/p)*(1-cosd(dTA deg));
g = ((r1*r0)/sqrt(muEarth*p))*sind(dTA deg);
fDot = sqrt(muEarth/p)*tand(dTA deg/2)*((1-cosd(dTA deg))/p - 1/r1 - 1/r0);
gDot = 1 - (r0/p)*(1-cosd(dTA deg));
R1 = f*R0 + g*V0;
V1 = fDot*R0 + gDot*V0;
Xref = [R1; V1]
a = p/(1-e^2);
n = sqrt(muEarth/a^3);
E1 = 2*atan(sqrt((1-e)/(1+e))*tand(TA1 deg/2));
E0 = 2*atan(sqrt((1-e)/(1+e))*tand(TA0 deg/2));
t01 = (1/n)*((E1 - e*sin(E1)) - (E0 - e*sin(E0)));
t01 hr = t01/3600
--- Problem 2b ---
Xref =
   1.0e+04 *
    0.7006
    1.9504
    4.1385
   -0.0001
    0.0001
   -0.0000
t01 hr =
    5.8920
```

#### **Problem 2c**

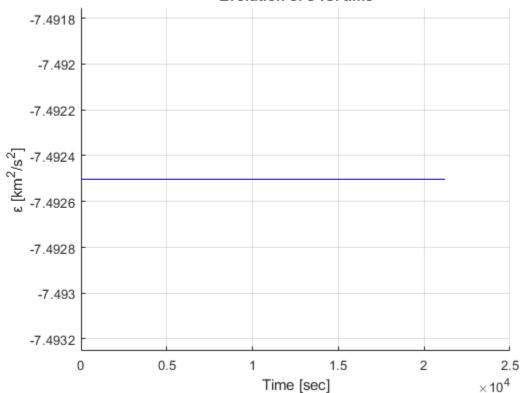
fprintf("--- Problem 2c ---\n") % Nothing output to command window, no need to separate Plotting setup

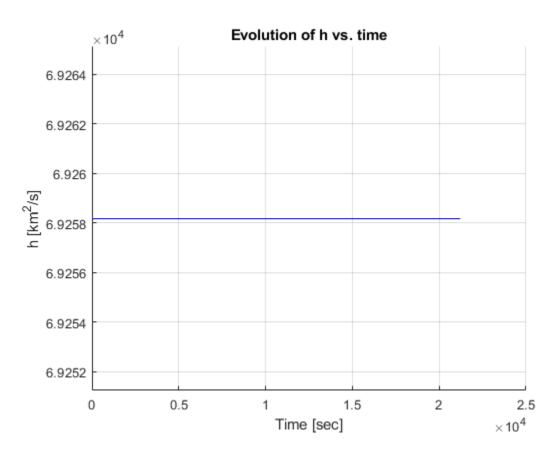
```
opt = odeset('RelTol', tol, 'AbsTol', tol);
    % Run integration
[t, X] = ode45(@(t,X)orbitEOM(t,X,muEarth), tspan, x0, opt);
X = X';
    % Compute specific energy and specific angular momentum
specEng = [];
h = [];
for k = 1:length(t)
    v = norm(X(4:6,k));
    r = norm(X(1:3,k));
    specEng = [specEng; v^2/2 - muEarth/r];
    h = [h; norm(cross(X(1:3,k),X(4:6,k)))];
end
    % Plotting config
idxArrow = find(t <= tArrow, 1, 'last');</pre>
    % Plot results
figure
hold on; grid on;
titleText = sprintf("Generated Spacecraft Trajectory, given\n X 0 = [%.3f,
%.3f, %.3f, %.3f, %.3f, %.3f]^T", x0);
title(titleText)
trajectory = plot3(X(1,:), X(2,:), X(3,:), 'b-', 'LineWidth', 3);
start = plot3(X(1,1), X(2,1), X(3,1), 'g.', 'MarkerSize', 20);
dirMotion = quiver3(X(1,idxArrow), X(2,idxArrow), X(3,idxArrow),
X(4,idxArrow), X(5,idxArrow), X(6,idxArrow), ...
                    arrowScale, 'r', 'LineWidth', 2, 'ShowArrowHead', 'on');
earth = surf(rEarth*earthX, rEarth*earthY, rEarth*earthZ);
set(earth, 'FaceColor', 'texturemap', 'cdata', earthSkin, 'edgecolor', 'none');
xlabel("X [km]"); ylabel("Y [km]"); zlabel("Z [km]")
x\lim([-45000\ 45000]); \ y\lim([-45000\ 45000]); \ z\lim([-45000\ 45000])
view([5 45]);
legend([trajectory, start, dirMotion], ["Generated Trajectory", "Initial
Condition", "Direction of Motion"], 'Location', 'northwest')
figure
hold on; grid on;
titleText = sprintf("Evolution of %s vs. time", char(949));
title(titleText);
plot(t, specEng, 'b-')
ylim([1.0001*specEng0, 0.9999*specEng0])
xlabel("Time [sec]"); ylabel(char(949) + " [km^2/s^2]")
figure
hold on; grid on;
title("Evolution of h vs. time")
plot(t, h, 'b-')
ylim([0.9999*h0, 1.0001*h0])
xlabel("Time [sec]"); ylabel("h [km^2/s]")
```

# Generated Spacecraft Trajectory, given $X_0 = [2489.638, -3916.074, -5679.055, 9.135, -1.912, 2.573]^T$



#### Evolution of $\epsilon$ vs. time





## **Problem 2d**

```
fprintf("--- Problem 2d ---\n")
    % Setup
tol = [1e-4; 1e-6; 1e-8; 1e-10; 1e-12];
compTime = zeros(size(tol));
dR = zeros(size(tol));
dV = zeros(size(tol));
dEpsilon = zeros(size(tol));
dh = zeros(size(tol));
    % Run ode45 with varying tolerances and save outputs
for k = 1:length(tol)
    opt = odeset('RelTol', tol(k), 'AbsTol', tol(k));
    tic
    [t,X] = ode45(@(t,X)orbitEOM(t,X,muEarth), tspan, x0, opt);
    compTime(k) = toc;
    X = X';
    dR(k) = norm(X(1:3,end) - Xref(1:3));
    dV(k) = norm(X(4:6,end) - Xref(4:6));
```

```
for kk = 1:length(t)
       v = norm(X(4:6,kk));
       r = norm(X(1:3,kk));
       specEng = [specEng; v^2/2 - muEarth/r];
       h = [h; norm(cross(X(1:3,kk),X(4:6,kk)))];
    end
    dEpsilon(k) = specEng(end) - specEng(1);
    dh(k) = h(end) - h(1);
end
variables = ["Absolute & Relative Tolerance", "deltaR", "deltaV",
"deltaEpsilon", "deltah", "Computational Time"];
table2d = table(tol, dR, dV, dEpsilon, dh, compTime, 'VariableNames',
variables)
--- Problem 2d ---
table2d =
  5×6 table
    Absolute & Relative Tolerance
                                                     deltaV
deltaEpsilon
                  deltah
                             Computational Time
               0.0001
                                         7.3209
                                                   0.00072883
0.0010602
                  2.8515
                               0.002784
               1e-06
                                       0.063967
                                                   6.535e-06
9.0528e-06
                0.027504
                                 0.0005487
                1e-08
                                     0.00034821
                                                  3.6509e-08
4.9494e-08
              0.00015226
                               0.0010185
               1e-10
                                      1.742e-06
                                                  1.9347e-10
                                0.0017678
2.601e-10
              9.1376e-07
               1e-12
                                     8.9443e-09
                                                   1.0707e-12
1.4406e-12
              6.5484e-09
                               0.0033238
```

### **Problem 2f**

```
fprintf("--- Problem 2f ---\n")
i_deg = 63.4;
J2Earth = 1;%1082.64*(10^-6);
argPeriDot = -(3/2)*((sqrt(muEarth)*J2Earth*rEarth^2)/(((1-e^2)^2)*a^(7/2)))*((5/2)*sind(i_deg)^2 - 2)
RAANDot = -(3/2)*((sqrt(muEarth)*J2Earth*rEarth^2)/(((1-e^2)^2)*a^(7/2)))*cosd(i_deg)
--- Problem 2f ---
argPeriDot =
```

7.4841e-08

RAANDot =

-2.7456e-05

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