Embedded Software

Resource Handling - Improving our programs



Challenge - Resource Handling

- Brainstorm What do you consider a Resource Handling challenge?
 - ▶ What is a resource in sw "terms"?
 - ▶ In which situations do you foresee challenges?
- Team up 2 & 2 for 5 minutes



The Challenge

- Design and implement a system that
 - That there is a garbage collection such that a resource is released when no one uses it (multi parties may share a resource)
 - It must be thread-safe
 - ▶ The resource itself is *NOT* protected, but its destruction must be



- Following usage scenario must work
 - Allocate resource in Thread A
 - Pass it to Thread B while keeping it in A
 - Relinquish usage in Thread B followed by Thread A
 - Resource is hereafter relinquished
- Could be ported to our Message Queues



The exercises for this lecture

RAII and SmartPointer

Counted Smart Pointer

Templated Counted Smart Pointer (OPTIONAL)

boost::shared_ptr<>

Increased feature set



Resource Handling



RAII for short repetition



RAII



RAII

- Managing memory is often a problem or challenge,
 - ensuring correctness forgetting to deallocate (message etc.)
 - dealing with exceptions



RAII

- Managing memory is often a problem or challenge,
 - ensuring correctness forgetting to deallocate (message etc.)
 - dealing with exceptions
- · Idiom : Resource Acquisition Is Initialization
 - Wrap up all resources in their own object that handles their lifetime and put object on stack



Simple RAII class which also is a SmartPointer

```
template<typename T>
class RAII
{
public:
    explicit RAII( T* p = 0 ) : p_(p) {}
    ~RAII() { delete p_; }

    T& operator*() const { return *p_; }
    T* operator->() const { return p_; }
private:
    T* p_;
};
```

```
{
    RAII<std::vector<int> > r( new std::vector<int>() );
    std::cout << r->size() << std::endl;
} // The std::vector<int> is automatically deallocated
```



Simple RAII class which also is a SmartPointer

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Simple RAII class which also is a SmartPointer

```
RAII in effect
 template<typename T>
 class RAII
 public:
     explicit RAII( T*p = 0 ) : p_(p) {}
                                                    Resource is
                                                    deallocated
     ~RAII() { delete p_; }
     T& operator*() const { return *p : }
     T* operator->() const { return p_;
 private:
      T* p_;
                                 Accessing handled
Usage example
                                     resource
     RAII<std::vector<int> > r( new std::vector<int>() );
     std::cout << (r->size()) << std::endl;</pre>
   // The std::vector<int> is automatically deallocated
```



boost::shared_ptr<T>



Classic problem

What is the problem here?

```
void f()
{
    Client* c = new Client;
    Data* d = acquireData(c);
    if(...)
       return;

    delete d;
    delete c;
}
```



Classic problem

What is the problem here?

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void f()
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Classic problem

What is the problem here?

```
void f()
{
    Client* c = new Client;
    Data* d = acquireData(c);
    if(...)
    return;
    delete d;
    delete c;
}
Bad, where is the deallocation?
```



Simple example

- std::string is automatically deallocated
 - Where exception is thrown
 - End of scope

```
void f()
{
    boost::shared_ptr<std::string> stringPtr(new std::string("Hello"));
    if (...) throw std::some_error("Bad number");
    std::cout << *stringPtr << std::endl*
}</pre>
```

Exit points

AARHUS UNIVERSITY

```
Stdout readout:
                                                   Pointer
                                                                        Value
                                                                               Use Count
                                                1) 003756D0
                                                                         42
                                                2) 003756D0
                                                                         43
                                                3) 003756D0
                                                                         43
  boost::shared_ptr<int> ee;
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                                                                         43
  boost::shared_ptr<int> aa(new int(42));
                                                5) 00000000
                                                                         XX
 |std::cout << aa << "\t" << *aa << "\t" << aa.use_count() << std::endl;
      boost::shared_ptr<int> bb(aa);
      ++(*bb);
      std::cout << bb << "\t" << *bb << "\t" <<bb.use_count()<<std::endl;</pre>
      ee = bb;
3)
      std::cout << ee << "\t" << *ee.use_count()<<std::endl;</pre>
  lee.reset();
4) | std::cout << aa << "\t" << *aa << "\t" <<aa.use_count()<<std::endl;
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boost::shared_ptr<T> - Properties

- A wrapping created with new T
- Reference counted
- delete is guaranteed called when the last reference to the object dies or when the member function reset() is called
- The same thread safety as build-in types
- It is possible to supply an alternative functor that handles the "deallocation"
- May be used in a container
- Implements the comparison operators
- Allows conversion from shared_ptr<T> to shared_ptr<U> if T* implicit can be converted to U* or if T is a specialization of U or U is void



boost::weak_ptr<T> - Cyclic dependencies



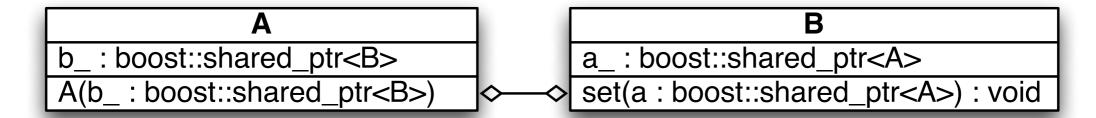
Cyclic dependency - What?

ABb_ : boost::shared_ptra_ : boost::shared_ptr<A>A(b_ : boost::shared_ptr)⇒ set(a : boost::shared_ptr<A>) : void



Cyclic dependency - What?

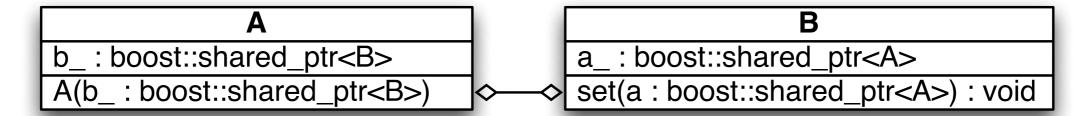
Problem simple



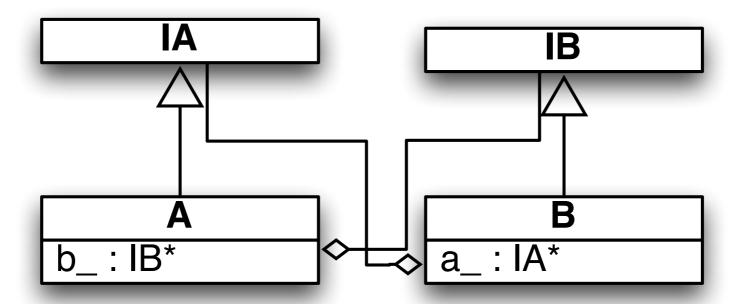


Cyclic dependency - What?

Problem simple



More complex





Usage – boost::weak_ptr

Breaking cyclic dependencies

```
struct A {
    A(boost::shared_ptr<B> b)
    : b_(b) {}
    boost::shared_ptr<B> b_;
};
```

```
struct B {
    void set(boost::shared_ptr<A> a)
    { a_ = a; }

    boost::shared_ptr<A> a_;
};
```



Usage – boost::weak_ptr

Breaking cyclic dependencies

```
struct A {
    A(boost::shared_ptr<B> b)
    : b_(b) {}
    boost::shared_ptr<B> b_;
};
```

```
Test harnish
boost::shared_ptr<B> tmpB(new B);
boost::shared_ptr<A> tmpA(new A(tmpB));
tmpB->set(tmpA); // Cyclic dependency introduced
```



Properties – boost::weak_ptr

- Typical usage is breaking cyclic dependencies
- Must call .lock() to determine whether the object pointed to still lives before trying to access it
- Must be converted to a shared_ptr when access the object again
- Implements a "a less important" shared_ptr
- A shared_ptr without reference counting.
- Can be used in containers



scoped_ptr<T>



Usage

boost::scoped_ptr

- Simpel usage
 - std::string is automatically deallocated
 - Where exception is thrown
 - End of scope

```
void f()
{
    boost::scoped_ptr<std::string>
    stringPtr(new std::string("Hello"));

    if (...) throw std::some_error("Bad number");

    std::cout << *stringPtr << std::endl;
}</pre>
```



Usage

boost::scoped_ptr

- Simpel usage
 - std::string is automatically deallocated
 - Where exception is thrown
 - End of scope

```
void f()
{
   boost::scoped_ptr<std::string>
    stringPtr(new std::string("Hello"));

   if (...) throw std::some_error("Bad number");

   std::cout << *stringPtr << std::endl;
}</pre>
Exit points
```



Properties

boost::scoped_ptr

- Holds a pointer to an element allocated with new
- Guarantees that delete is called at destruction time
- Calls delete via a call to the member function reset()
- Cannot be used in a container, not copyable
- Alternative
 - std::auto_ptr const but it cannot be reset



Boost::SmartPointer - Summary



Boost SmartPointer summary

boost::scoped_ptr & boost::scoped_array

- Objects with short lifespan confined to function/object
- Single object or an array of objects
- Non-copyable (whole point)

boost::shared_ptr & boost::shared_array

- ▶ A more general wrapping used in containers
- Single object or an array of objects
- You want it all and you are willing to pay for it

boost::weak_ptr

Typically used to break circular references

boost::intrusive_ptr

Where OS or framework implement reference counting

