

# Embedded Software

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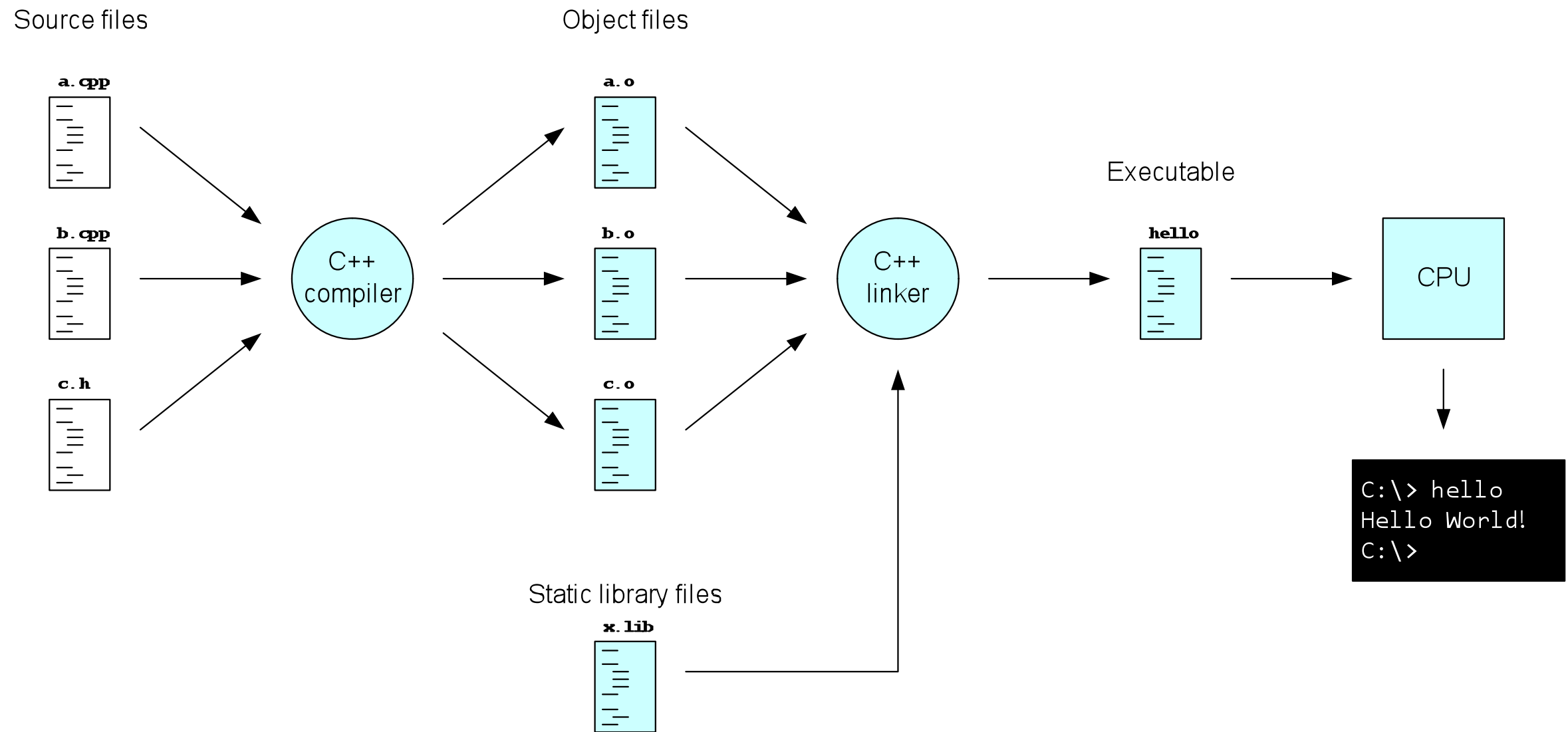
Programming in Linux

# Agenda

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- Compilation
- Host and Target
- SW Development for Embedded targets - Howto make it

# Compilation



# Host and target

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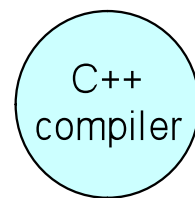
- Any executable (“binary”) is generated on a *host* for a specific *target*

```
stud@ubuntu:~/$ file hello
hello: ELF 64-bit LSB shared object, x86-64, version 1 (SYSV) ...
stud@ubuntu:~/$
```

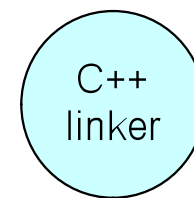
- Until now, host == target
- *What if you wish to generate programs for an **embedded** target, e.g. an ARM processor?*
  - ▶ An ARM processor does not understand an x86 binary!

# Host and target

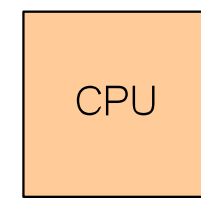
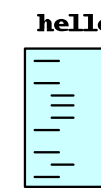
Source files



Object files



Executable



Static library files

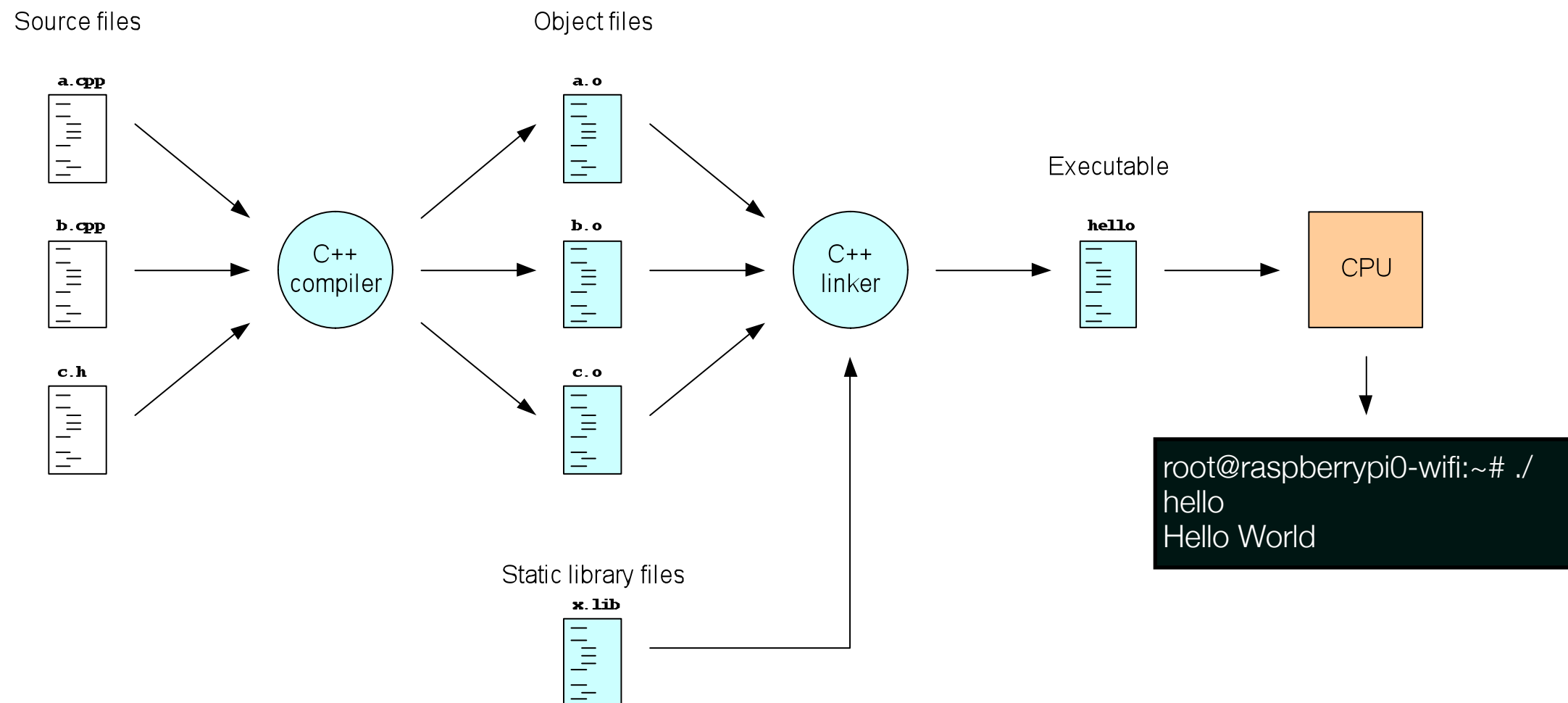


```
root@raspberrypi0-wifi:~# ./hello
Hello World
root@raspberrypi0-wifi:~#
```

# SW development for embedded targets

## - how to *make* it

- To make SW for an embedded target, you use *cross compilation*
  - You compile the program **on** the host, but **for** the target



# SW development for embedded targets

## - how to *make* it

- For the Raspberry Pi Zero Wifi (which is an ARM target) we use the Yocto (Poky) C/C++ compiler suite of tools

```
stud@ubuntu: ls /opt/poky/2.4.1/sysroot/....$  
arm-poky-linux-gnueabi-addr2line arm-poky-linux-gnueabi-gprof  
arm-poky-linux-gnueabi-ar        arm-poky-linux-gnueabi-ld  
arm-poky-linux-gnueabi-as        arm-poky-linux-gnueabi-nm  
arm-poky-linux-gnueabi-c++       arm-poky-linux-gnueabi-objcopy  
arm-poky-linux-gnueabi-c++filt  arm-poky-linux-gnueabi-objdump  
arm-poky-linux-gnueabi-cpp       arm-poky-linux-gnueabi-ranlib  
arm-poky-linux-gnueabi-g++       arm-poky-linux-gnueabi-readelf  
arm-poky-linux-gnueabi-gcc       arm-poky-linux-gnueabi-size  
arm-poky-linux-gnueabi-gcov      arm-poky-linux-gnueabi-strings  
arm-poky-linux-gnueabi-gdb       arm-poky-linux-gnueabi-strip  
arm-poky-linux-gnueabi-gdbtui
```

# SW development for embedded targets

## - how to *make* it

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- Unfortunately the correct invocation is

- **arm-poky-linux-gnueabi-g++ -march=armv6 -mfpv=vfp -mfloat-abi=hard -  
mtune=arm1176jzf-s -mfpv=vfp --sysroot=\$SDKTARGETSYSROOT .....**

- To simplify matters a simple alias has been made

- ▶ For C

**arm-rpizw-gcc .....**

- ▶ For C++

**arm-rpizw-g++ .....**



# SW development for embedded targets

## - how to *make* it

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- To invoke the compiler we specify the name of the compiler

- ▶ For host:

```
stud@ubuntu:~$ g++ -o hello_host hello.cpp
stud@ubuntu:~$ file hello_host
hello_host: ELF 64-bit LSB shared object, x86-64, version 1 (SYSV), ...
stud@ubuntu:~$ ./hello_host
Hello world!
stud@ubuntu:~$
```

- ▶ For target:

```
stud@ubuntu:~$ arm-rpizw-g++ -o hello_tgt hello.cpp
stud@ubuntu:~$ file hello_tgt
hello_tgt: ELF 32-bit LSB executable, ARM, EABI5 version 1 (GNU/Linux), ...
stud@ubuntu:~$ ./hello_tgt
bash: ./hello_tgt: cannot execute binary file
stud@ubuntu:~$
```

# Native and cross compiler - Include (&lib) handling?

---

- How does a compiler know which include to use?

```
#include <iostream>

int main(int argc, char* argv[])
{
    std::cout << "Hello World" << std::endl;
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```

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**Can be discovered by g++ -v (or cross compiler edition -v)**

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*The **sysroot** path is thus responsible for ensuring that the compilers don't miks up files*

# SW development for embedded targets

## - how to *make* it

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- Testing embedded SW can be very difficult – ***why?***
  - ▶ Very few resources (CPU, memory, keyboard, monitor, ...) for testing
- To the extent possible, you can use a simulated environment
  - ▶ If your target and host runs Linux, then it is *relatively* easy – compile and test on your host, then recompile for target
- Anything you need to think of in the simulated environment?
  - ▶ Time
  - ▶ Peripheral
  - ▶ Memory and CPU constraints
  - ▶ ...
- So...what can you test?