Embedded Software

Thread synchronization II



Agenda

- Mutexes/Semaphores
 - Pitfalls
 - Priority Inversion
 - Problem
 - Solution
 - Inversion
 - ▶ Inheritance
 - Ceiling
 - Deadlocks



Mutex & Semaphore pitfalls



- It is extremely easy to get in trouble with mutexes!
- Example 1: Find and explain the problem

```
unsigned int shared;
Mutex m = MUTEX_INITIALIZER;
threadFunc()
  while(true)
   lock(m);
   shared++;
   sleep(ONE_SECOND);
   unlock(m);
main()
   shared = 0;
   createThread(threadFunc);
   createThread(threadFunc);
  for(;;) sleep(100);
```



It is extremely easy to get in trouble with mutexes!

Example 1: Find and explain the problem

m is held for a **full second**, **blocking** the other thread

```
unsigned int shared;
Mutex m = MUTEX_INITIALIZER;
threadFunc()
  while(true)
   lock(m);
   shared++;
   sleep(ONE_SECOND);
   unlock(m);
main()
  shared = 0:
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- Example 2: Find and explain the problem

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unsigned int shared;
Mutex m = MUTEX_INITIALIZER;
threadFunc()
  lock(m);
  while(true)
   shared++;
   sleep(ONE_SECOND);
  unlock(m);
main()
  shared = 0;
  createThread(threadFunc);
  createThread(threadFunc);
   for(;;) sleep(100);
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It is extremely easy to get in trouble with mutexes!

Example 2: Find and explain the problem

You're in a world of pain!

```
unsigned int shared;
Mutex m = MUTEX_INITIALIZER;
threadFunc()
  lock(m);
  while(true)
   shared++:
   sleep(ONE_SECOND);
  unlock(m);
main()
  shared = 0;
  createThread(threadFunc);
  createThread(threadFunc);
   for(;;) sleep(100);
```



- It is extremely easy to get in trouble with mutexes!
- Example 3: Find and explain the problem

```
unsigned int shared;
SEM_ID s;
threadFunc()
  while(true)
   take(s);
   shared++;
   release(s);
   sleep(ONE_SECOND);
main()
  shared = 0;
  s = createSem(0);
  createThread(threadFunc);
  createThread(threadFunc);
  for(;;) sleep(100);
```



- It is extremely easy to get in trouble with mutexes!
- Example 3: Find and explain the problem

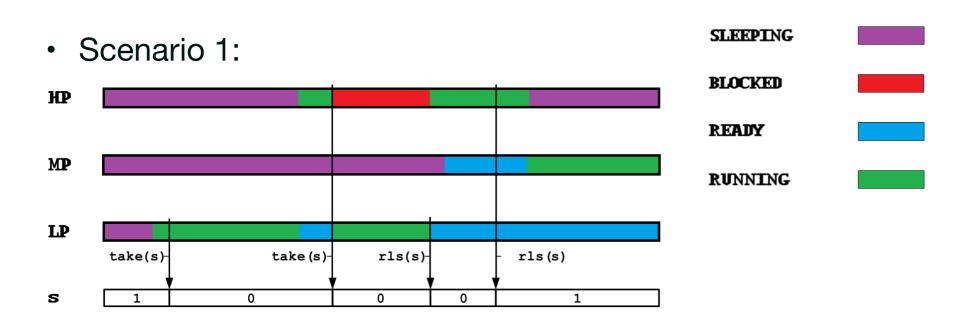
s is initialized to 0 – no one can pass **take()** before someone calls **release()**

```
unsigned int shared;
SEM_ID s;
threadFunc()
  while(true)
   take(s);
   shared++;
   release(s);
   sleep(ONE_SECOND);
main()
  shared = 0;
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  createThread(threadFunc);
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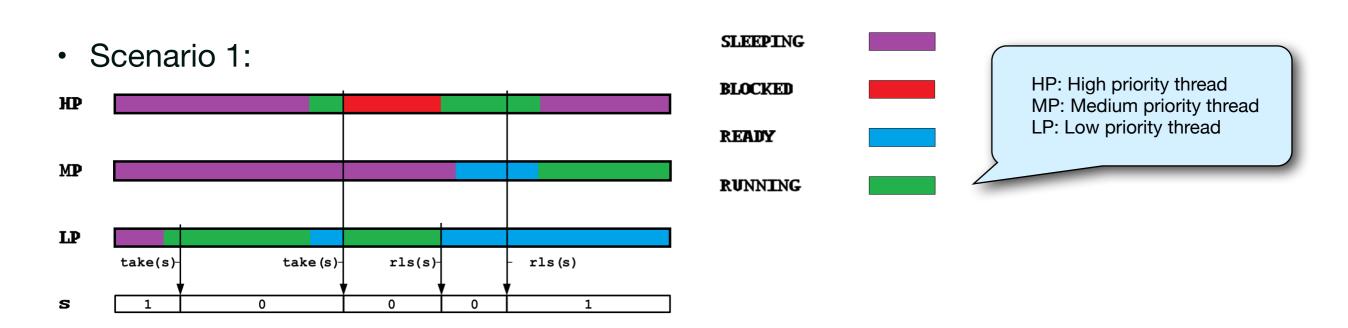


Mutex priority

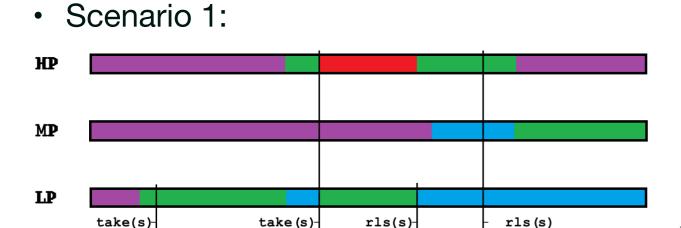


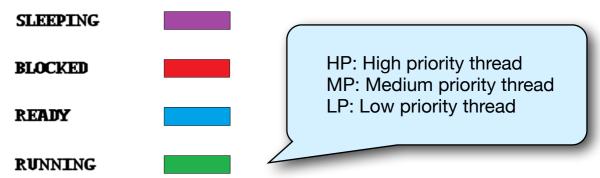












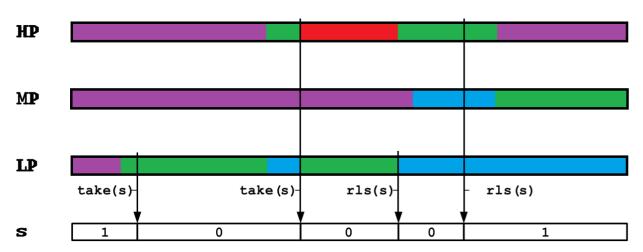
Scenario 1 - Bounded priority inversion

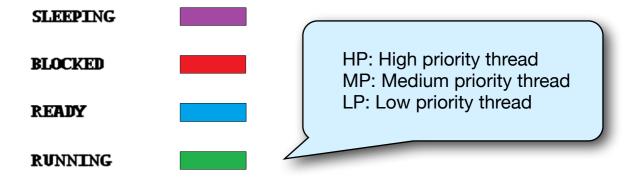
- 1. LP runs
- 2. LP acquires mutex
- 3. HP is prioritized to run, LP on waiting queue (WQ)
- 4. HP blocked due to mutex taken
- 5. LP runs until mutex release
- 6. HP runs until done, LP on WQ
- 7. MP is ready but due to lower priority -> WQ
- 8. LP waits until both HP and MP done and then run until



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Scenario 1:

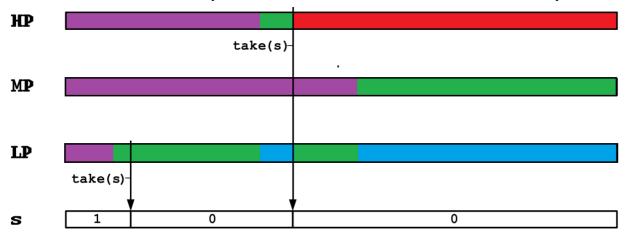




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- 5. LP runs until mutex release
- 6. HP runs until done, LP on WQ
- 7. MP is ready but due to lower priority -> WQ
- 8. LP waits until both HP and MP done and then run until

Scenario 2 (MP arrives a little earlier):



Scenario 2 - Unbounded priority inversion

- 1. LP runs
- 2. LP acquires mutex
- 3. HP is prioritized to run, LP on WQ
- 4. HP blocked due to mutex taken LP continues
- 5. MP is prioritized to run (over LP) until done MP is thus scheduled *ahead* of HP priority inversion
- 6. LP runs until mutex release, HP is blocked
- 7. HP runs until done
- 8. LP waits until HP done





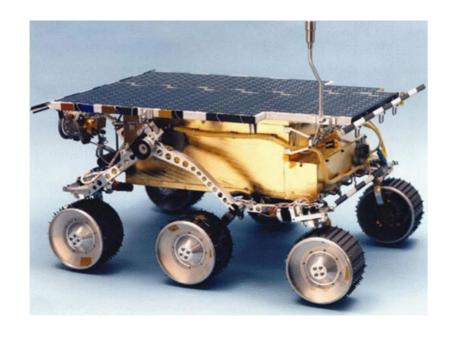
- Unbounded priority inversion is a nasty error especially in RT systems
 - System does not deadlock forever it just responds slower sometimes
 - "Slower"..."sometimes"...not words the RT system engineer likes!!!



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 - Final customer demonstration
 - Your thingy has landed on Mars



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Mars Pathfinder

<u>Problem:</u> Ground communications terminated abruptly (\$\$\$!)

Cause: HW/SW reset by watchdog

<u>Cause</u>: HP data distribution (DD) task not completed on time

<u>Cause</u>: DD-task waited for mutex held by LP ASI/MET

task, which was preempted by several MP tasks





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 - **Priority inheritance**: When a thread holds a mutex it is temporarily assigned the priority of the highest-priority thread waiting for the mutex.
 - Priority ceiling: All mutexes are assigned a (high) priority (the priority ceiling) which the owner of the mutex is assigned while it holds the mutex



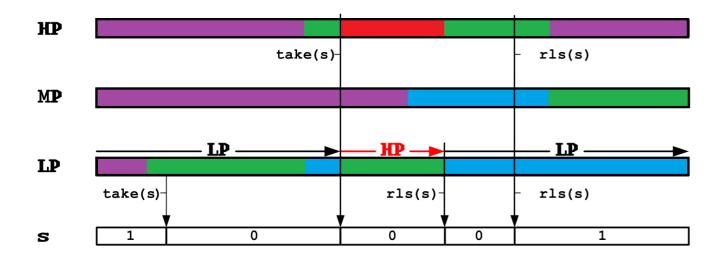
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Note semaphores do NOT support the above



Priority inheritance

- Priority inheritance:
 - When a thread holds a mutex it is temporarily assigned the priority of the highestpriority thread waiting for the mutex.

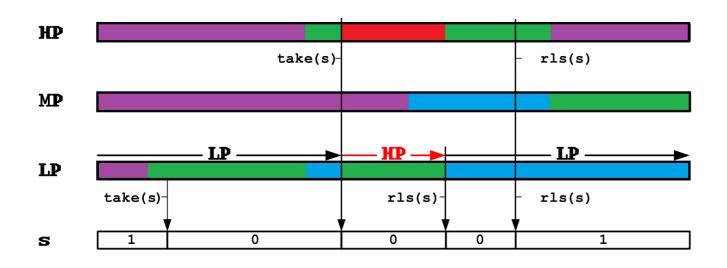


Priority inheritance can be set as a property of some mutexs on creation



Priority inheritance

- Priority inheritance:
 - When a thread holds a mutex it is temporarily assigned the priority of the highestpriority thread waiting for the mutex.



Scenario 1

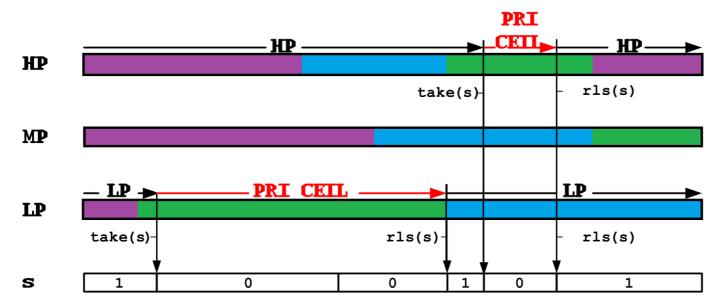
- 1. LP runs
- 2. LP acquires mutex
- 3. HP is prioritized to run, LP on waiting queue (WQ)
- 4. HP blocked due to mutex taken
- 5. LP runs until mutex release, **but with HP priority** (inheritance)
- 6. MP wants to run but due to lower priority -> WQ
- 7. HP acquires mutex and runs until done, MP & LP on WQ
- 8. MP runs until done, LP on WQ
- 9. LP runs until done

Priority inheritance can be set as a property of some mutexs on creation



Priority ceiling

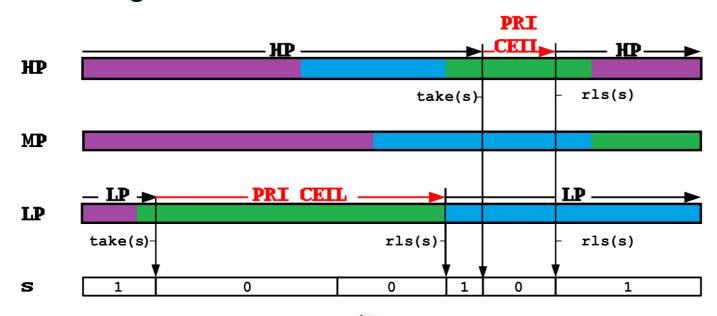
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Priority ceiling

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 - All mutexes are assigned a (high) priority (the priority ceiling) which the owner of the mutex is assigned while it holds the mutex



Scenario 1

- 1. LP runs
- 2. LP acquires mutex its priority is elevated to high priority priority ceiling
- 3. HP wants to run but has lower priority -> waiting queue (WQ)
- 4. MP wants to run but has lower priority -> WQ
- 5. LP releases mutex and changes priority to low
- 6. HP acquires mutex and runs until done, MP & LP on WQ
- 7. MP runs until done, LP on WQ
- 8. LP run until done



• ...and the fun just started! Introducing multiple mutexes:



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```
void main()
{
    createThread(printFileFunc1);
    createThread(printFileFunc2);
}
```



• ...and the fun just started! Introducing multiple mutexes:

```
void printFileFunc1()
{
   lock(fileMut);
   lock(printerMut);
   <<print file>>
   unlock(printerMut);
   unlock(fileMut);
}
```

```
void printFileFunc2()
{
   lock(printerMut);
   lock(fileMut);
   <<print file>>
   unlock(fileMut);
   unlock(printerMut);
}
```

```
void main()
{
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...and the fun just started! Introducing multiple mutexes:

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Deadlocks



Deadlocks

 A deadlock is a situation where two (or more) threads are waiting for the other to release a resource, thus neither will ever run.

The four necessary conditions for deadlocks:

1. Mutual exclusion Th	ne resource can only l	be held by one	process at a time
------------------------	------------------------	----------------	-------------------

- 2. Hold-and-wait Process already holding resources may request other resources
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Deadlocks

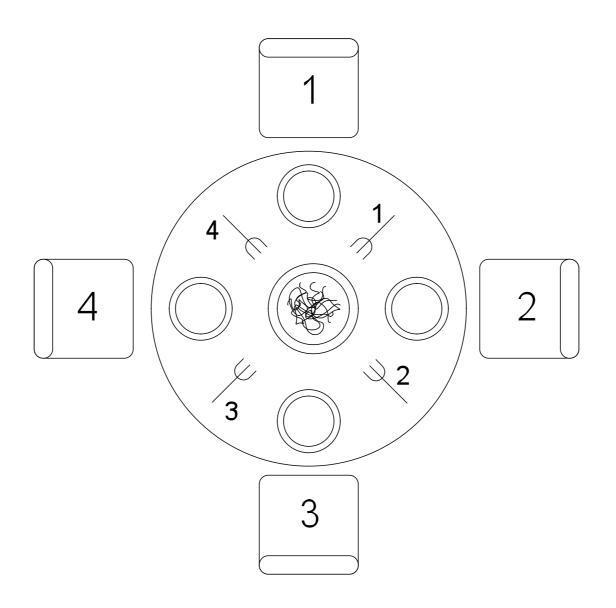
 A deadlock is a situation where two (or more) threads are waiting for the other to release a resource, thus neither will ever run.

> "When two trains approach each other at a crossing, both shall come to a full stop and neither shall start up again until the other has gone." (Kansas Legislation)

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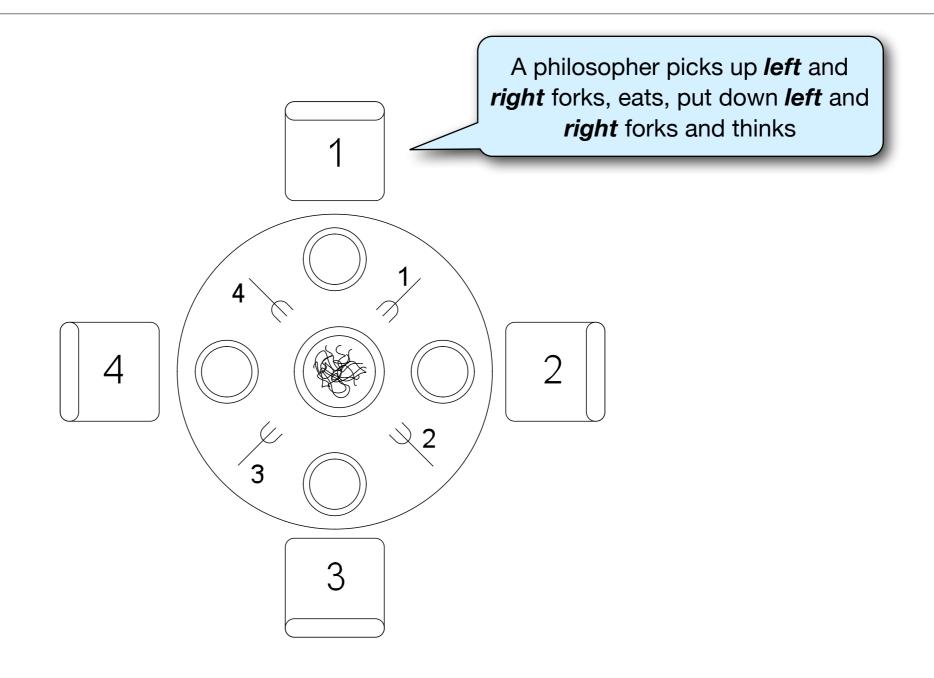


Deadlocks: Dining Philosophers

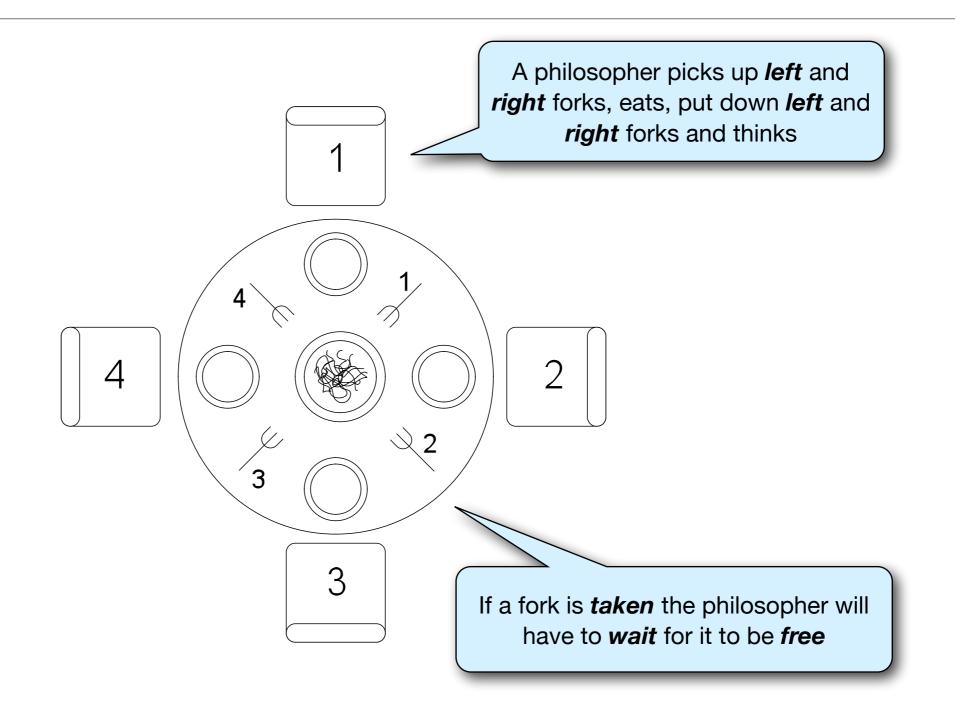




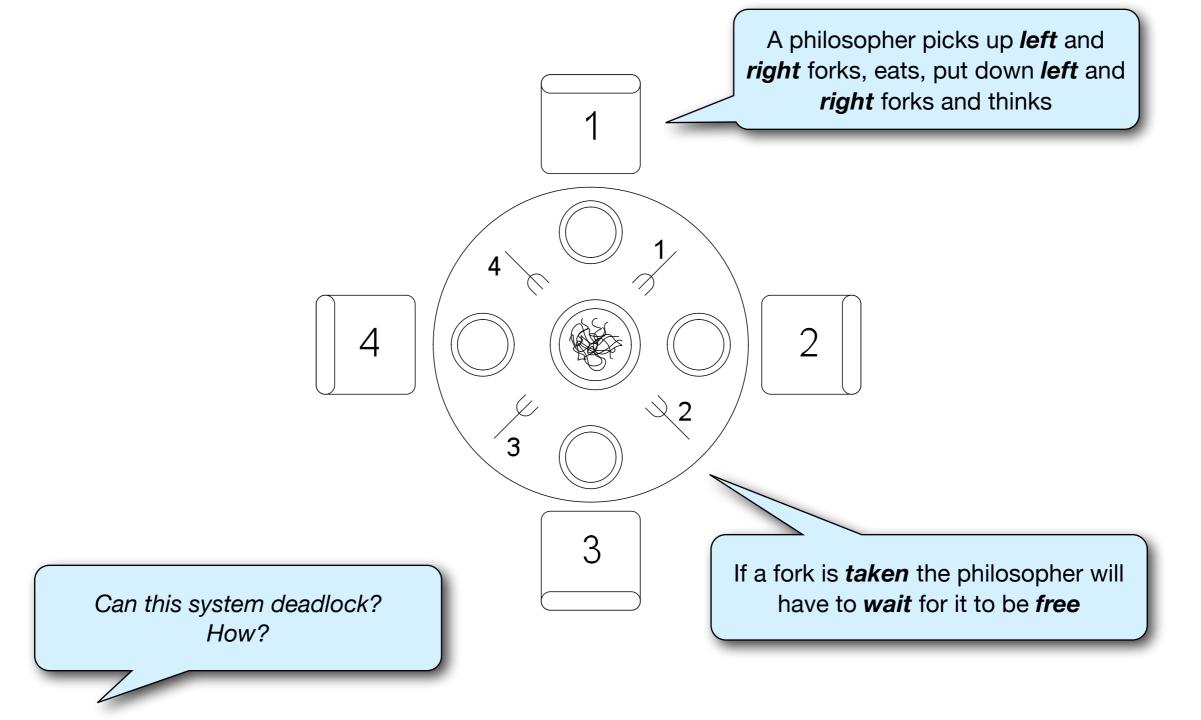
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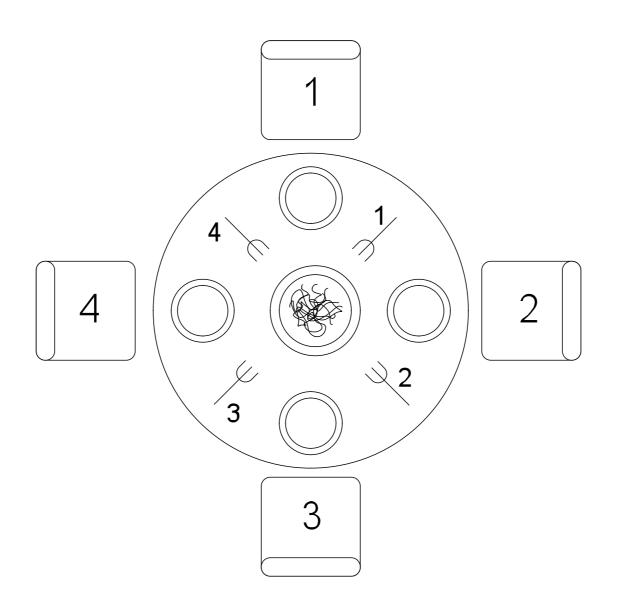




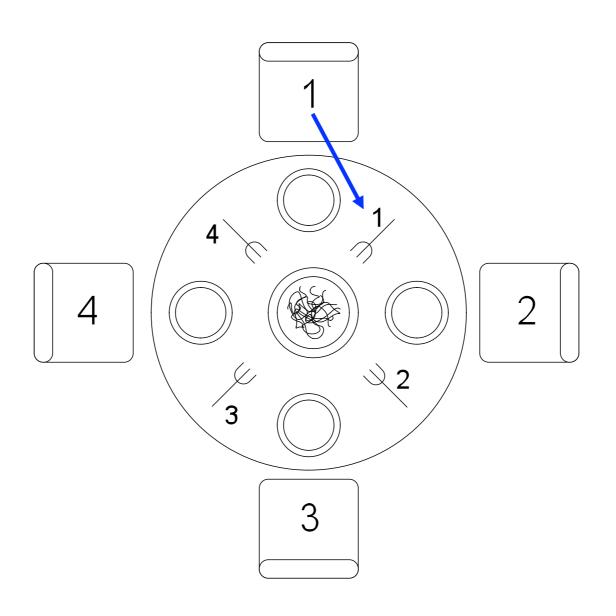




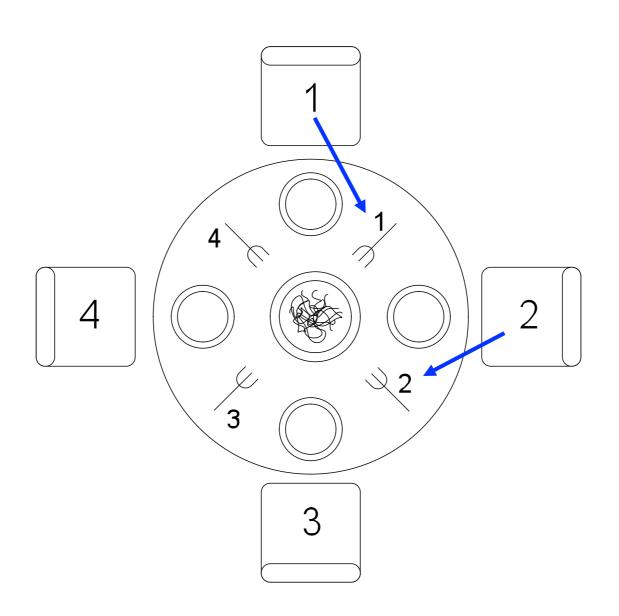




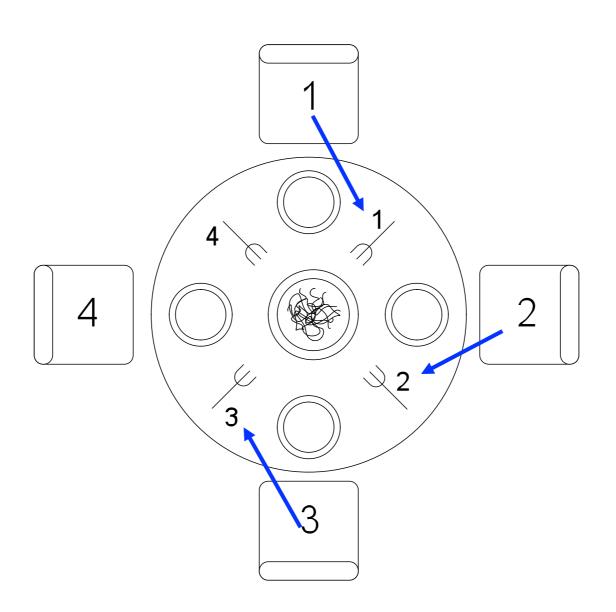




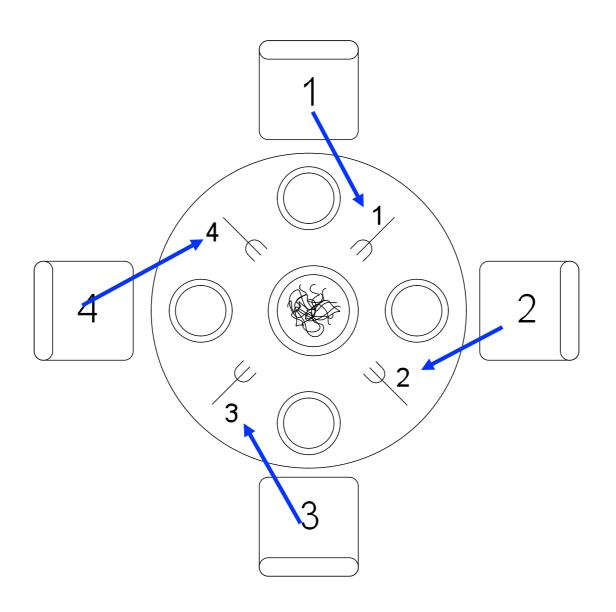




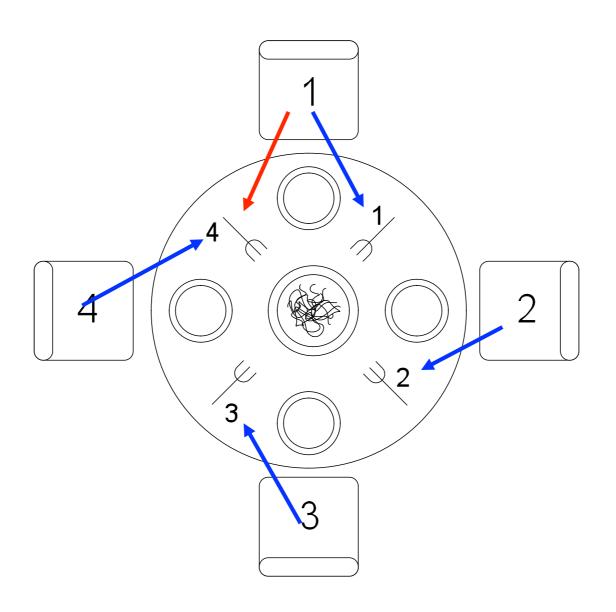




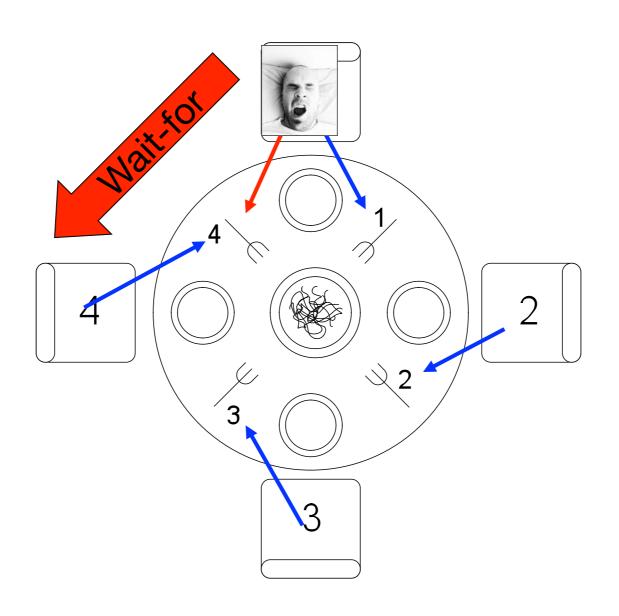




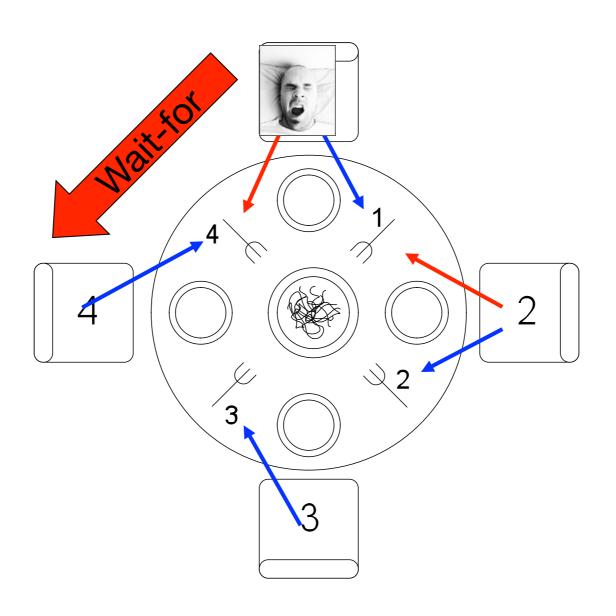




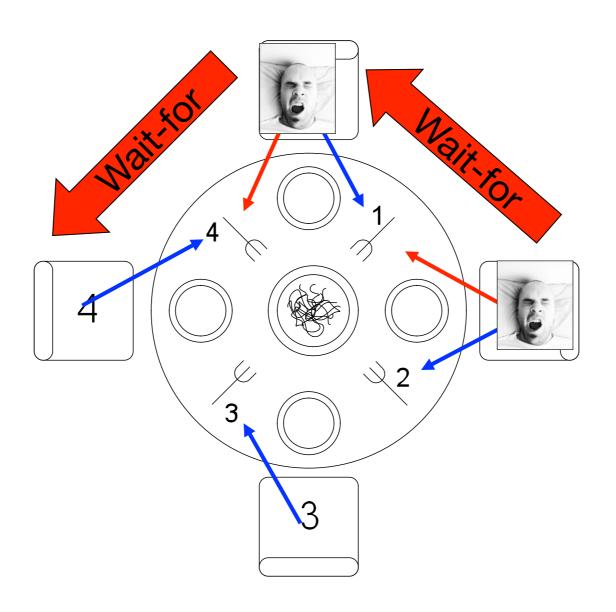




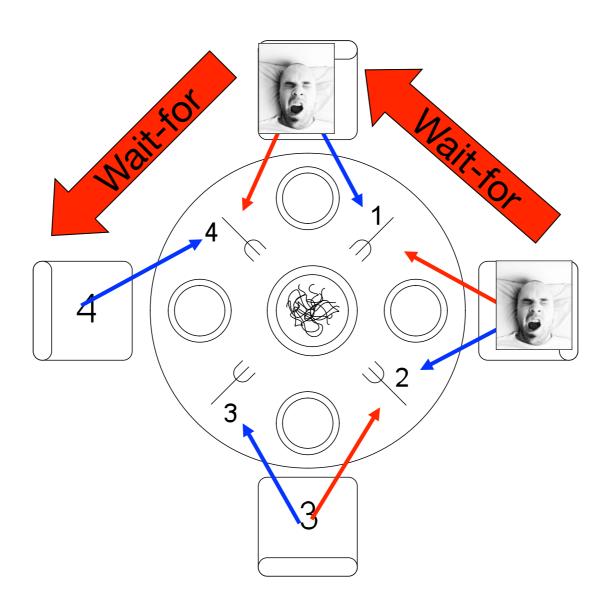




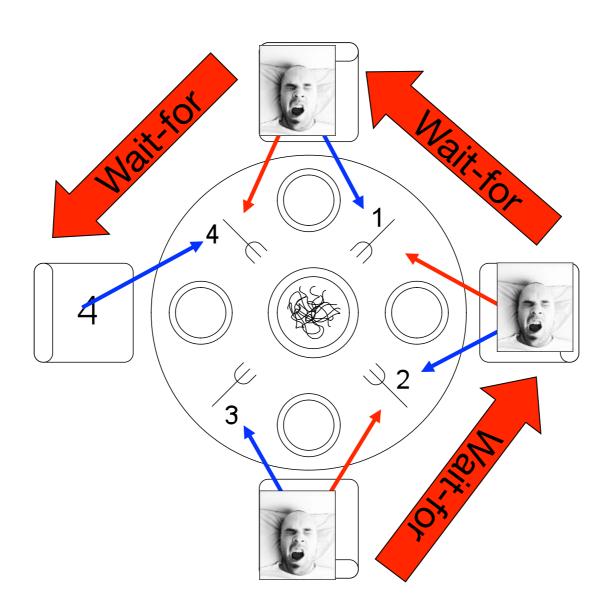




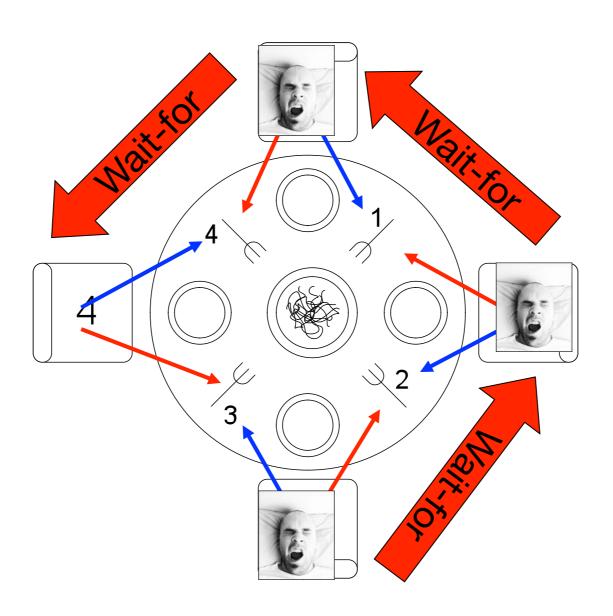




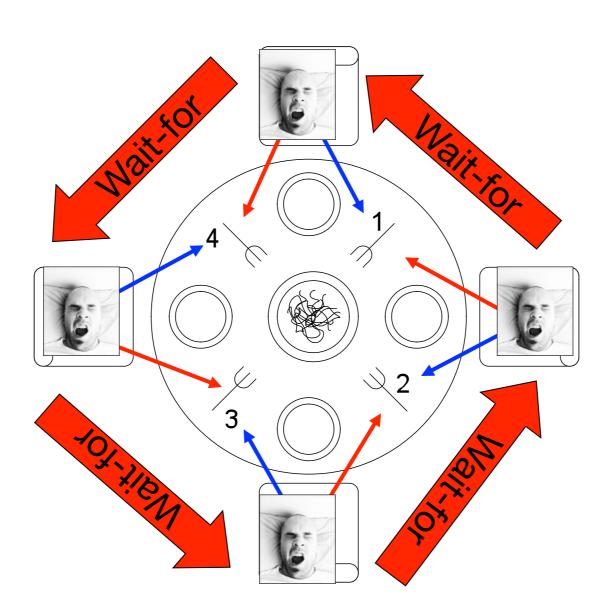




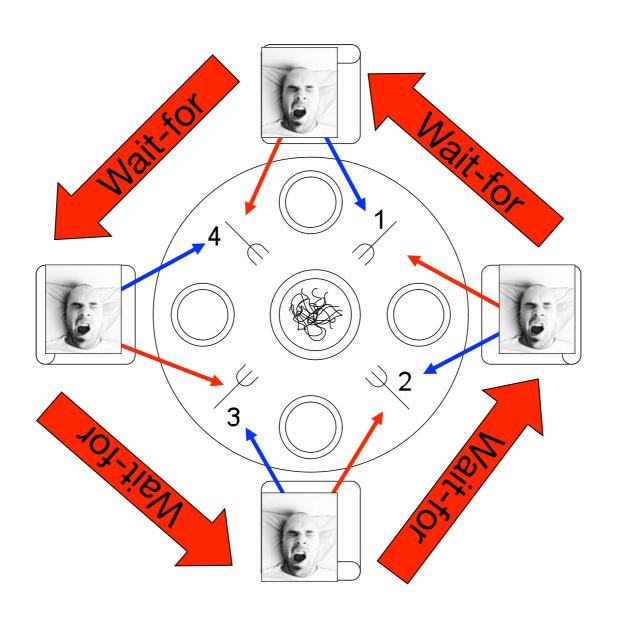
















 The solution to deadlocks in general is to remove one of the four necessary conditions:

1. Mutual exclusion	The resource can only	y be held by one	process at a time
		, ,	•

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4. Circular wait condition A cycle p0, ppi+1 holds

A cycle p0, p1,...pn, p0 exists where pi waits for a resource that



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 - 1? No, two people can't use the same fork at the same time



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4?



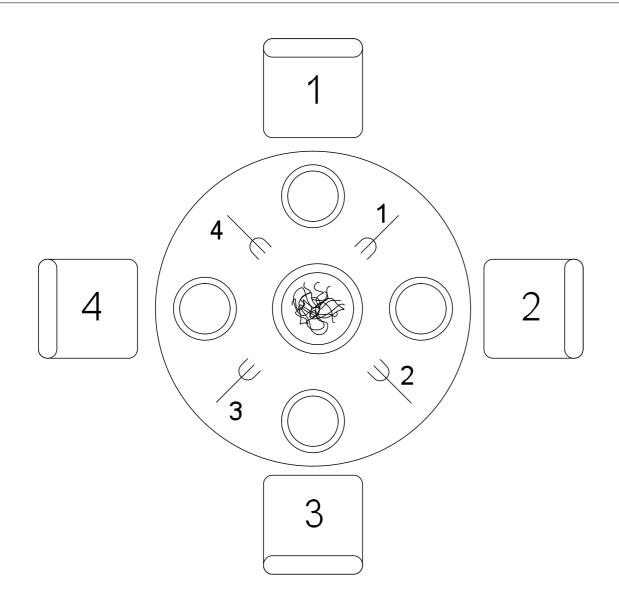
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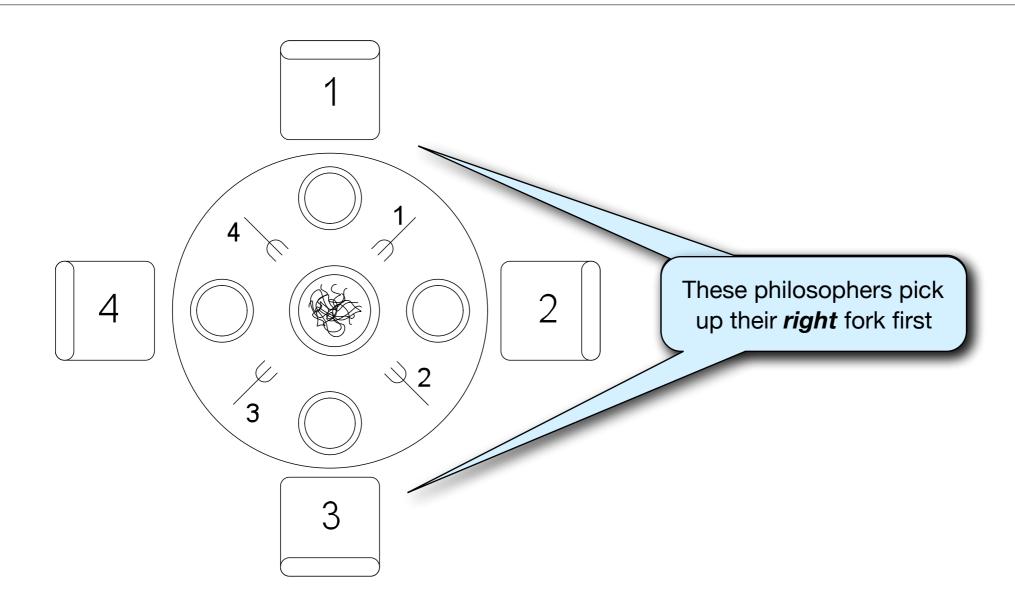


Dining Philosophers - solution





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