# MST125 TMA01

# William B. Sørensen

# December 4, 2022

# 1 Question 1

# Contents

1	Que	$\mathbf{estion}$	1																1
	1.1	a										 							2
	1.2	b										 							2
	1.3	c				•				•	•								3
2	Que	estion	2																3
3	Que	$\mathbf{estion}$	3																3
	3.1	a										 							3
		3.1.1	i									 							3
		3.1.2	ii									 							4
		3.1.3	iii									 							4
	3.2	b										 							4
		3.2.1	i									 							4
		3.2.2	ii																5
4	Que	$\mathbf{stion}$	4																5
		4.0.1										 							5
		4.0.2	ii									 							5
		4.0.3	iii									 							6
		4.0.4	iv									 							6
	4.1	b										 							6
		4.1.1	i				 					 							6
		4.1.2	ii																6
5	Que	estion	5																7
	5.1	a									_	 							7
	5.2	ъ																	7
6	c																		7

## 1.1 a

#### MST125 TMA 01 Question 1

William Bjørn Sørensen, I220215X  $\ensuremath{\mbox{\sc in}}\xspace TFX$ 

## 1.2 b

1. The distance between  $A(x_1, y_1)$  and  $B(x_2, y_2)$  is given by

AB = 
$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$
.

Hence the distance between A(-3, 1) and B(2, -2) is

$$AB = \sqrt{(2 - (-3))^2 + (-1 - 1)^2}$$
$$= \sqrt{5^2 + (-3)^2}$$
$$= \sqrt{34}.$$

2. The gradient m of the line through  $(x_1, y_1)$  and  $(x_2, y_2)$  is given by

$$m = \frac{y_2 - y_1}{x_2 - x_1}.$$

Hence the gradient of the line through (-3, 1) and (2, -2) is

$$m = \frac{-2 - 1}{2 - (-3)} = -\frac{3}{5}.$$

3. The gradient of the line is  $-\frac{3}{5}$ . Hence  $\tan \alpha = -\frac{3}{5}$ . Let  $\phi$  be the acute angle that the line makes with the nagative direction of the x-axis. Then

$$\tan \phi = \frac{3}{5},$$

so

$$\phi = \tan^{-1}\left(\frac{3}{5}\right) = 0.540\dots$$

Hence

$$\alpha = \pi - 0.540 \dots = 2.601 \dots$$

Therefore the angle  $\alpha$  is 2.60 radiants (to 2 d.p.).

## 1.3 c

I intend to typeset my TMA through the fact that I believe the programatic power of IATEXis a great advantage. Through MST125 I have even started using IATEXover Markdown (with mathjax) for school assignemts now.

Using LATEXin my daily school work leads me to a much DRYer (don't repeat yourself) documents where all my associate code can be refrenced with great accuracy without suffering from complecated compilation scripts.

I have also configured a Vim integration so I can use my primary editor for TMAs.

# 2 Question 2

(a) Find the least residue of  $64^7$  modulo 15.

$$64^7 \equiv x \mod 15$$
$$4^7 \equiv x \mod 15$$

We observe  $4^2 \equiv 1 \mod 15$ .

$$4^1 \equiv x \mod 15$$
$$64^7 \equiv 4 \mod 15$$

# 3 Question 3

## 3.1 a

#### 3.1.1 i

We find the gcd using Euler's algorithm. These variable names come from CAS tool I wrote in Rust for Unit3.

We reshape for substitution

And then conduct said substitution

$$\begin{split} a \times \textcircled{1} + b \times \textcircled{9} &= \textcircled{1} \\ &= \textcircled{5} - 2 \times \textcircled{2} \\ &= (\textcircled{9} - 5 \times \textcircled{1}) - 2 \times \textcircled{2} \\ &= (\textcircled{9} - 5 \times \textcircled{1}) - 2 \times (\textcircled{1} - 3 \times \textcircled{5}) \\ &= (\textcircled{9} - 5 \times \textcircled{1}) - 2 \times (\textcircled{1} - 3 \times (\textcircled{9} - 5 \times \textcircled{1})) \\ &= 7 \times \textcircled{9} - 37 \times \textcircled{1} \end{split}$$

Then we find the least residual of -37 and deduce that the multiplicative inverse of  $17 \mod 90$  is 53.

This means the solution to  $17x \equiv 9 \mod 90$  is  $x \equiv 53 \times 9 \equiv 477 \equiv 27 \mod 90$ .

#### 3.1.2 ii

We begin by simplifying the congruence.

As we can see here  $gcd(3,30) \neq 1$  and  $3 \nmid 4$  so the congruence is unsolvable.

### 3.1.3 iii

We begin by simplifying the congruence.

This is small enough for a brute force attack but for clarities sake I will not do this.

We can see they are coprime. Hence we can skip Euler's algo.

We find least residual and multiply with 8. So  $x \equiv -3 \times 8 \equiv 7 \times 8 \equiv 56 \equiv 6 \mod 10$ .

### 3.2 b

## 3.2.1 i

$$7\times 15\equiv 105\equiv 4\times 26+1\equiv 1\mod 26$$

## 3.2.2 ii

Using the conversion table in Figure 1 we get

A									J			
0	1	2	3	4	5	6	7	8	9	10	11	12
N	О	Р	Q	R	S	Т	U	V	W	X	Y	Z
13	14	15	16	17	18	19	20	21	22	23	24	25

Figure 1: Linear 0-indexed  $\alpha$ -numeric conversion table

$$\text{"IQZC"} \xrightarrow{\alpha-\text{numeric}} \{8,\ 16,\ 25,\ 2\} \xrightarrow{\text{affine}^{-1}} \{18,\ 8,\ 13,\ 6\} \xrightarrow{\alpha-\text{numeric}^{-1}} \text{"SING"}$$

## 4 Question 4

We rewrite the hyperbola into standard notation for standard possition.

$$9x^{2} - 4y^{2} - 100 = 0$$

$$9x^{2} - 4y^{2} = 100 = 2^{2}5^{2}$$

$$9\frac{x^{2}}{100} - \frac{y^{2}}{25} = 1$$

$$\frac{x^{2}}{100 \times 9^{-1}} - \frac{y^{2}}{25} = 1$$

$$\frac{x^{2}}{(10 \times 3^{-1})^{2}} - \frac{y^{2}}{5^{2}} = 1$$

This gives ut a few key values

$$a = \frac{10}{3}$$
  $b = 5$   $e = \sqrt{1 + \frac{25 \times 9}{100}} = \frac{\sqrt{13}}{2}$ 

#### 4.0.1 i

The asymtotes are  $y = \pm \frac{3}{2}x$ . Verticies are  $(\pm \frac{10}{3}, 0)$ .

### 4.0.2 ii

TODO

#### 4.0.3 iii

eccentricity 
$$e=\frac{\sqrt{13}}{2}$$
 foci 
$$(\pm ae,0)=(\pm\sqrt{13}\;\frac{5}{3},0)$$
 directrices 
$$y=\pm\frac{a}{e}=\pm\frac{20}{3\sqrt{13}}$$

#### 4.0.4 iv

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{10}{3} & \sec t \\ 5 & \tan t \end{pmatrix}$$

To find the bounds we need to observe when we have the signs we want. Since we want a point with a negative x-sign and a possitive y-sign we need to see when the functions satasfy this.

$$\sec x < 0 \text{ if } -3\frac{\pi}{2} < x < -\frac{\pi}{2}$$

and in the same interval we can see that

$$\tan x > 0 \text{ if } -\pi < x < -\frac{\pi}{2}$$

Hence the interval for t is  $-\pi < t < -\frac{\pi}{2}$ .

## 4.1 b

$$6x^2 - 8xy + 5y^2 - 3x - 16y - 20 = 0$$

## 4.1.1 i

$$T = B^2 - 4AC = 64 - 6 \times 5 = 34$$

Since T > 0 then the conic must be a Hyperbola.

#### 4.1.2 ii

## 5 Question 5

## 5.1 a

$$A = (4t + 2, t - 1)$$

if t=1 then we get (6,0). This means the entire line is translated up by 6. If we then plug-in t=2 then we get (10,1) which if we insert into the two point formula we get that the rise over run of this line is  $\frac{10-6}{1-0}=4$ . This means the equation for the curve A traces is y=4x+6.

## 5.2 b

$$|\vec{BA}| = \begin{vmatrix} (4t+2) - (2t+5) \\ (t-1) - (3t-1) \end{vmatrix}$$
$$= \begin{vmatrix} 2t-3 \\ -2t \end{vmatrix}$$
$$= \sqrt{(2t-3)^2 + (-2t)^2}$$
$$= \sqrt{8t^2 - 12t + 9}$$

$$d^2 = |\vec{BA}|^2 = 8t^2 - 12t + 9$$

## 6 c

$$d^2 = 8t^2 - 12t + 9 (1)$$

$$=8\left(t^2 - \frac{3}{2}t\right) + 9\tag{2}$$

$$=8\left(t-\frac{3}{4}\right)^2-\frac{9}{16}+9\tag{3}$$

$$=8\left(t-\frac{3}{4}\right)^2+\frac{135}{16}\tag{4}$$

The expression on (3) ends up evaluating to

$$8(t^2 - \frac{3}{2}t + \frac{9}{16}) - \frac{9}{16} + 9 = 8t^2 - 12t + \frac{9}{2} - \frac{9}{16} + 9$$

which obviously is not equal to (2).