From Three-Dimensional Electrophysiology to the Cable Model: an Asymptotic Study

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Abstract

Cellular electrophysiology is often modeled using the cable equations. The cable model can only be used when ionic concentration effects and three dimensional geometry effects are negligible. The Poisson model, in which the electrostatic potential satisfies the Poisson equation and the ionic concentrations satisfy the drift-diffusion equation, is a system of equations that can incorporate such effects. The Poisson model is unfortunately prohibitively expensive for numerical computation because of the presence of thin space charge layers at internal membrane boundaries. As a computationally efficient and biophysically natural alternative, we introduce the electroneutral model in which the Poisson equation is replaced by the electroneutrality condition and the presence of the space charge layer is incorporated in boundary conditions at the membrane interfaces. We use matched asymptotics and numerical computations to show that the electroneutral model provides an excellent approximation to the Poisson model. Further asymptotic calculations illuminate the relationship of the electroneutral or Poisson models with the cable model, and reveal the presence of a hierarchy of electrophysiology models.

1 Introduction

Electrophysiology is the study of the electrical activity of biological tissue [1, 4]. Because of its importance in many physiological processes and its quantitative nature, it has been a favorite subject in biophysics and mathematical physiology. Traditional mathematical models of cellular electrical activity are based on the famous work of Hodgkin and Huxley [5], and may be collectively termed cable models. These models are based upon an ohmic current continuity relation on a branched one dimensional electrical cable [12, 11]. The derivation of the cable model is based on several important assumptions [12]:

• A one dimensional picture, or more generally, a one dimensional tree representation of cell geometry is adequate. Geometrical details that are lost

in making this simplified description have negligible effect on electrophysiology.

- The extracellular space can be reduced to a single isopotential electrical compartment.
- Ionic concentrations are effectively constant in space and time within each cell separately and in the extracellular space. The diffusive current that may be induced by concentration gradients or the changes in equilibrium potential are negligible.

Such assumptions are justified in many instances, for example in the isolated neuronal axon [5], where the cable model has been extremely successful in explaining the physiology and in making quantitative predictions – a triumph counted among the greatest successes of mathematics in biology. There may, however, be many cases in which any or all of the above assumptions are violated especially in the central nervous system and cardiac tissue, as suggested by the complex microhistological structure they exhibit [9, 2]. One line of work that addressed this difficulty was that of Qian and Sejnowski [20]. Their work addresses the last of the above difficulties, but retains the one-dimensional character of the cable model.

In [15], we presented a three-dimensional model of cellular electrical activity which addresses all of the above limitations of the cable model. This model consists of a system of partial differential equations to be satisfied by the ionic concentrations and the electrostatic potential. In this paper, we introduce a slight modification of this model, which we call the *electroneutral model*.

The first goal of this paper is to demonstrate the validity of the electroneutral model by comparing this with the *Poisson model* [13]. In the Poisson model, the ionic concentration dynamics is governed by the drift-diffusion equations and the electrostatic potential satisfies the Poisson equation. Non-dimensionalization reveals the presence of multiple temporal scales and of a thin boundary layer at the membrane interfaces in which electric charge accumulates (Debye layer)[23]. This boundary layer necessitates the use of a fine spatiotemporal mesh in numerical simulations making such computations prohibitively expensive. We introduce the electroneutral model as an alternative to the Poisson model, in which the Poisson equation is replaced by the electroneutrality condition. The model does not resolve the dynamics within the thin boundary layers and instead incorporates the effect of these layers by modifying the boundary conditions at the membranes. The boundary layers are incorporated as charge densities of zero thickness at the membrane, a picture that is better aligned with the biophysical view of the membrane being a capacitor within a conducting medium. This obviates the necessity for high spatiotemporal resolution in computations, making the electroneutral model far more amenable to numerical simulation. Using matched asymptotics, we show that the electroneutral model provides an approximation to the Poisson model. We present computational studies in the final section to demonstrate that the electroneutral model does indeed provide an excellent approximation to the Poisson Model for biophysically realistic

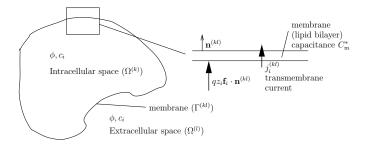


Figure 1: The variables ϕ , c_i are defined in the regions $\Omega^{(k)}$ and $\Omega^{(l)}$, which we have identified as intracellular and extracellular regions in the above. The membrane acts primarily as a capacitor, but possesses ionic channels through which transmembrane current can flow.

parameter values.

The second goal of this paper is to clarify the relationship between the Poisson and electroneutral models to cable models. If we are to claim that the Poisson or electroneutral models are a generalization of the cable model, we would like to know under what conditions these models can be reduced to the cable model. Continuing with the asymptotic calculations above, we show that the cable model can be obtained as an asymptotic limit under assumptions. We shall see that there is a hierarchy of electrophysiology models, the Poisson or electroneutral models being the most detailed, and the traditional cable model being the simplest.

2 Poisson Model

We first present the Poisson model, which is essentially equivalent to the model proposed in [13]. We consider biological tissue to be a three-dimensional space partitioned into the intracellular and extracellular spaces by the membrane. Let the biological tissue of interest be divided into subregions $\Omega^{(k)}$, indexed by k. We denote the membrane separating the regions $\Omega^{(k)}$ and $\Omega^{(l)}$ by $\Gamma^{(kl)}$ (Figure 1).

In $\Omega^{(k)}$, the equations to be satisfied by the ionic concentration c_i and the electrostatic potential ϕ are the following.

$$\frac{\partial c_i}{\partial t} = -\nabla \cdot \mathbf{f}_i \qquad \text{(ion conservation)} \tag{1}$$

$$\mathbf{f}_{i} = -D_{i} \left(\nabla c_{i} + \frac{qz_{i}c_{i}}{k_{B}T} \nabla \phi \right)$$
 (drift-diffusion flux) (2)

$$\Delta \phi = -\frac{1}{\epsilon} \left(\rho_0 + \sum_{i=1}^{N} q z_i c_i \right)$$
 (Poisson equation) (3)

Here, \mathbf{f}_i denotes the flux of the *i*-th ion. \mathbf{f}_i is expressed as a sum of two terms, the diffusion term and the drift term. D_i is the diffusion coefficient of the *i*-th ion, qz_i is the amount of charge on the *i*-th ion, where q is the elementary charge, i.e., the charge on a proton. $qz_iD_i/(k_BT)$ is the mobility of the ion species (Einstein relation) where k_B is the Boltzmann constant, and T the absolute temperature. Fixed background charge density (if any) is given by ρ_0 , and ϵ is the dielectric constant of the electrolyte solution. We note that the above system of equations has been used extensively in semiconductor device modeling [22, 8] and ionic channel modeling [18, 11, 19].

Biological membranes consists largely of a lipid bilayer that acts as a capacitor impermeable to ions. In this lipid bilayer are embedded ionic channels and transporters through which certain ionic species may pass. With this picture in mind, we write down the boundary conditions for the above system to be satisfied at both faces of the membrane.

Consider the boundary condition for the Poisson equation. The value of the electrostatic potential and the normal component of the electric displacement vector $\mathbf{D} = \epsilon \mathbf{E}$, where ϵ is the dielectric constant and \mathbf{E} is the electric field, should be continuous at the interface between the cell membrane and the electrolyte solution. Therefore, at this interface,

$$\phi^{(\text{mem})} = \phi^{(k)} \tag{4}$$

$$\epsilon_{\rm m} \frac{\partial \phi^{(\rm mem)}}{\partial \mathbf{n}^{(kl)}} = \epsilon \frac{\partial \phi^{(k)}}{\partial \mathbf{n}^{(kl)}} \tag{5}$$

where $\phi^{(\text{mem})}$ is the electrostatic potential within the membrane, ϵ_m the dielectric constant of the cell membrane, and $\mathbf{n}^{(kl)}$ the unit normal at the membrane-electrolyte interface pointing from $\Omega^{(k)}$ into the membrane.

We note that (5) is not satisfied at the mouths of ion channels. If ion channels mouths do not occupy a significant amount of membrane area, the above boundary condition may be deemed reasonable. Fortunately, ion channels are sparsely distributed even at their peak documented densities [12].

The membrane thickness $d_{\rm m}(\sim 10 {\rm nm})$ is small compared to the curvature radius of the membrane and the typical length scale of the system. This implies that $\phi^{\rm mem}$ varies linearly as one traverses the membrane from $\Omega^{(k)}$ to $\Omega^{(l)}$. Thus,

$$\frac{\partial \phi^{\text{(mem)}}}{\partial \mathbf{n}} = \frac{\phi^{(k)} - \phi^{(l)}}{d_{\text{m}}}.$$
 (6)

We obtain the following boundary condition,

$$C_{\mathbf{m}}^* \phi^{(kl)} = \epsilon \frac{\partial \phi^{(k)}}{\partial \mathbf{n}^{(kl)}} \tag{7}$$

where $\phi^{(kl)} = \phi^{(k)} - \phi^{(l)}$, $C_{\rm m}^* = \frac{\epsilon_{\rm m}}{d_{\rm m}}$ and ${\bf n}^{(kl)}$ is the unit normal on the membrane pointing from $\Omega^{(k)}$ to $\Omega^{(l)}$. $C_{\rm m}^*$ may be considered the intrinsic capacitance of the membrane, which is to be distinguished from the effective membrane capacitance

 $C_{\rm m}$ to appear later. The jump in the electrostatic potential $\phi^{(kl)}$ is termed the membrane potential and is one of the primary biophysical quantities of interest.

The boundary conditions for the drift diffusion equations are simple:

$$qz_i \mathbf{f}_i \cdot \mathbf{n}^{(kl)} = j_i^{(kl)} \tag{8}$$

where $j_i^{(kl)}$ are ion channel currents carried by the *i*-th species of ion. note that $j_i^{(kl)} = -j_i^{(lk)}$. These currents can in general be functions of the ionic concentrations of arbitrary species on either side of the membrane, the membrane potential $\phi^{(kl)}$ and gating variables which describe the internal states of a given ionic channel [11, 15].

We shall refer to equations (1)-(3) supplemented with boundary conditions (7) and (8), as the Poisson model.

Non-Dimensionalization and Multiple Spatiotem-3 poral Scales

We non-dimensionalize the Poisson model. We first rescale the ionic concentrations c_i and the electrostatic potential ϕ as follows.

$$\phi = \frac{k_B T}{q} \Phi, \qquad c_i = c_0 C_i$$

$$\rho_0 = q c_0 \tilde{\rho_0}, \qquad \mathbf{f}_i = c_0 \tilde{\mathbf{f}}_i, \qquad j_i = \gamma q c_0 \tilde{j}_i$$
(9)

$$\rho_0 = qc_0\tilde{\rho_0}, \qquad \qquad \mathbf{f}_i = c_0\tilde{\mathbf{f}}_i, \qquad \qquad j_i = \gamma qc_0\tilde{j}_i \tag{10}$$

where $c_0 \approx 100 mmol/l$ is the characteristic concentration and $\gamma q c_0$ is the characteristic magnitude of the transmembrane current per unit area. $k_BT/q\approx 25mV$ is the natural unit for the membrane potential. The constant γ has units of velocity=length/time and its typical physiological range is:

$$\gamma \approx 10^{-5} \sim 10^{-3} \mu \text{m/msec} \tag{11}$$

We determine a typical length scale of the system. We take equation (8) and integrate over the membrane surface $\partial \Omega^{(k)}$.

$$\int_{\partial\Omega^{(k)}} \gamma \tilde{j}_i dA = \int_{\partial\Omega^{(k)}} z_i \tilde{\mathbf{f}}_i \cdot \mathbf{n}^{(kl)} dA = \int_{\Omega^{(k)}} z_i \nabla \cdot \tilde{\mathbf{f}}_i dV
= -\int_{\Omega^{(k)}} z_i \nabla \cdot D_i C_i(\nabla \mu_i) dV$$
(12)

where we have used dimensionless variables for ionic concentration and the electrostatic potential. In the above, dV and dA denote volume and surface integrals respectively and μ_i is the chemical potential $\ln C_i + z_i \Phi$. We have used the divergence theorem in the second equality and the flux expression (2) in the third. Let L_0 be the typical length over which the flux and the chemical potential vary. Balancing the order of magnitude of the surface and volume integrals above,

$$\gamma |\partial \Omega^{(k)}| = \frac{D_i |\Omega^{(k)}|}{L_0^2}.$$
 (13)

where $|\partial\Omega^{(k)}|$ is the surface area of the region $\Omega^{(k)}$ and $|\Omega^{(k)}|$ is the volume of $\Omega^{(k)}$. We therefore set:

$$L_0 = \sqrt{\frac{lD_0}{\gamma}}, \text{ where } l = \frac{|\Omega^{(k)}|}{|\partial\Omega^{(k)}|}.$$
 (14)

The constant $D_0 \approx 1 \mu m/msec^2$ is the typical diffusion coefficient for ions. The quantity l is a measure of the volume per unit surface area, and is a representative length scale of the distance between membranes. For a cylindrical axon, l corresponds roughly to the diameter of the axon. As we shall see in Section 8.3, L_0 is what is termed the electrotonic length in cable theory. Notice that L_0 is proportional to \sqrt{l} . This is in agreement with the observation in cable theory that the electrotonic length scales with the square root the diameter of a cylindrical cable [11].

Given L_0 , we can define a typical time scale T_0 as $T_0 = L_0^2/D_0 = l/\gamma$. This expression tells us that T_0 is equivalently the time scale in which the dimensionless ionic concentration experiences changes of $\mathcal{O}(1)$. We shall call T_0 the diffusion time scale or the slow diffusion time scale.

Using L_0 and T_0 as the representative spatiotemporal scales, we introduce the following dimensionless variables.

$$\mathbf{x} = L_0 \mathbf{X}, \qquad t = T_0 \tau_D, \qquad D_i = D_0 \tilde{D}_i \qquad (15)$$

$$\tilde{\mathbf{f}}_i = \frac{D_0}{L_0} \mathbf{F}_i \qquad \qquad \alpha = \frac{l}{L_0} \tag{16}$$

We can now write the Poisson model (1)-(3) and (7)-(8) in dimensionless form:

$$\frac{\partial C_i}{\partial \tau_D} = -\nabla_{\mathbf{X}} \cdot \mathbf{F}_i \tag{17}$$

$$\mathbf{F}_{i} = -\tilde{D}_{i}(\nabla_{\mathbf{X}}C_{i} + z_{i}C_{i}\nabla_{\mathbf{X}}\Phi) \tag{18}$$

$$\beta^2 \Delta_{\mathbf{X}} \Phi = -(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i)$$
(19)

The boundary conditions are,

$$\theta^* \Phi^{(kl)} = \beta \frac{\partial \Phi}{\partial \mathbf{n}^{(kl)}} \tag{20}$$

$$z_i \mathbf{F}_i \cdot \mathbf{n}^{(kl)} = \alpha \tilde{j}_i \tag{21}$$

Note that α is the dimensionless magnitude of the transmembrane currents as well as the dimensionless volume to surface ratio. We have introduced the

dimensionless parameters β and θ^* . The parameter β is the ratio between the Debye length r_d [23] and L_0 :

$$\beta = \frac{r_d}{L_0}, \quad r_d \equiv \sqrt{\frac{\epsilon k_B T}{q^2 c_0}} \tag{22}$$

The Debye length is typically $r_d \approx 1nm$, and is considerably smaller than the typical length scale L_0 . The parameter θ^* is defined as follows:

$$\theta^* = \frac{C_{\rm m}^*}{\epsilon/r_d} = \frac{C_{\rm m}^* k_B T/q}{q c_0 r_d} \approx 10^{-2}$$
 (23)

We have, thus, three constants β , α and θ^* that characterize the system.

Given typical values of l and γ , we can find typical physiological values of the parameters β and α (the magnitude of θ^* is given in (23).). Recall that l is the (dimensional) volume to surface ratio, and thus, roughly measures the separation distance of membranes. Values typical in the central nervous system can range from 100nm to 10 μ m. Combining this with the radius of γ (11), we obtain the following physiological ranges for the above parameters.

$$L_0 = \sqrt{\frac{lD_0}{\gamma}} = 10\mu \text{m} \sim 1 \text{mm}$$
 (24)

$$\beta = r_d \sqrt{\frac{\gamma}{lD_0}} = 10^{-6} \sim 10^{-4}, \qquad \alpha = \sqrt{\frac{l\gamma}{D_0}} = 10^{-3} \sim 10^{-1}$$
 (25)

We note that while the magnitude of β and α depend on the geometry (l) and electrophysiological properties (γ) of the physiological system under consideration, θ^* defined in (23) is a constant that varies little between physiological systems.

We shall exploit the smallness of the parameter β to reduce the Poisson model. Note that β^2 multiplies the Laplacian in (18). By formally taking $\beta \to 0$ in (18), we see that the electroneutrality condition:

$$\tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i = 0 \tag{26}$$

should be approximately satisfied in the bulk of the region of interest. The electroneutrality condition above is in general not compatible with the mixed (Robin) boundary condition of (20), and thus, we have a singular perturbation problem which gives rise to a boundary layer at the membrane. Given that β^2 multiplies a second spatial derivative in (18), a layer of $\mathcal{O}(\beta)$ develops at the membrane, where electric charge may accumulate. In dimensional terms, this layer has thickness $r_d \sim 1nm$ near the membrane. We shall refer to this layer as the space charge layer or Debye layer. This is a layer that we have no need to resolve as long as we are interested in electrophysiology at the cellular or subcellular level and not at the molecular level. The biophysical equivalent

of this layer in the cable model is the charge associated with the membrane modeled as a capacitor, and accordingly, has no spatial extent. Starting with Section 5, we shall perform a matched asymptotic calculation that addresses the presence of this layer.

We can now interpret the dimensionless parameter θ^* in (23) as follows. The constant k_BT/q is the typical magnitude of the membrane potential, whereas qc_0r_d is a natural unit of surface charge density since r_d gives the surface charge thickness. Thus, $qc_0r_d/(k_BT/q)$ is a natural unit of capacitance per unit area. The constant θ^* expresses the membrane capacitance per unit area in these natural units.

Before we can perform asymptotics on the model, we would like to identify other spatiotemporal scales that the Poisson model possesses. Differentiate both sides of equation (19) in τ_D and take the integral over $\Omega^{(k)}$. The left hand side yields:

$$\int_{\Omega^{(k)}} \frac{\partial}{\partial \tau_D} (\beta^2 \Delta \Phi) dV = \int_{\partial \Omega^{(k)}} \frac{\partial}{\partial \tau_D} \left(\beta^2 \frac{\partial \Phi}{\partial \mathbf{n}^{kl}} \right) dA$$

$$= \int_{\partial \Omega^{(k)}} \beta \theta^* \frac{\partial \Phi^{(kl)}}{\partial \tau_D} dA. \tag{27}$$

We used the boundary condition (20) in the second inequality. The right hand side yields:

$$-\int_{\Omega^{(k)}} \frac{\partial}{\partial \tau_D} \left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i \right) dV = \int_{\partial \Omega^{(k)}} \alpha \sum_{i=1}^N \tilde{j_i}^{(kl)} dA.$$
 (28)

where we have used (17), (20) and the divergence theorem. The above says that the change in total charge within $\Omega^{(k)}$ comes from transmembrane currents. Balancing the quantities in (27) and (28), we see that the membrane potential and hence the electrostatic potential can vary on the time scale of $\beta \frac{\theta^*}{\alpha} T_0$. It is an interesting coincidence that θ^* and α are roughly of the same order of magnitude, as can be seen from (23) and (25). Thus, this time scale is roughly equal to βT_0 , which we shall call the membrane potential time scale. Given the smallness of β , the membrane potential time scale is considerably smaller than the slow diffusion time scale T_0 . We shall see in Section 8.3 that the membrane potential time scale βT_0 corresponds to the "diffusion" time scale of the membrane potential in the traditional cable model.

There is yet another time scale, which corresponds to charge relaxation:

$$\frac{\partial}{\partial \tau_D} \left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i \right) = \sum_{i=1}^N (z_i \nabla \cdot \tilde{D}_i \nabla C_i + z_i^2 \nabla (\tilde{D}_i C_i) \cdot \nabla \Phi + z_i^2 C_i \Delta \Phi)$$

$$= -\left(\sum_{i=1}^N z_i^2 C_i \right) \frac{1}{\beta^2} \left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i \right) + \text{other terms}$$
(29)

where we have used the Poisson equation (19) in the last equality to replace $\Delta\Phi$. We see that charge density decays exponentially with a time constant of $\beta^2 T_0 = r_d^2/D_0 = 1$ nsec. We can infer that this time scale is only important where the electrolyte solution may deviate significantly from electroneutrality, i.e., within the space charge layer.

We thus see that there are three time scales present in the Poisson model, T_0 , βT_0 and $\beta^2 T_0$. We list the physiological values for these time scales.

$$T_0 = 10^{-1} \sim 10^3 \text{ sec}, \quad \beta T_0 = 10^{-2} \sim 1 \text{ msec}, \quad \beta^2 T_0 = 1 \text{ nsec}$$
 (30)

The time scale of greatest interest is the βT_0 time scale, in which the membrane potential varies. This is also roughly equal to the time scale in which the most rapid physiological processes take place, such as channel gating, chemical neurotransmission and calcium concentration changes [4]. We shall thus focus our attention on this time scale and rescale the time variable τ_D to a newly rescaled time variable $\tau_V \equiv \tau_D/\beta$. We write C_i , Φ as functions of τ_V rather than τ_D . Equation (17) is rescaled to:

$$\frac{\partial C_i}{\partial \tau_V} = -\beta \nabla_{\mathbf{X}} \cdot \mathbf{F}_i \tag{31}$$

The $\beta^2 T_0$ time scale and the space charge layer within which this time scale is relevant are spatiotemporal details that we have no need to resolve. The T_0 time scale is important with regard to long term changes in ionic concentrations. We shall make some brief remarks about this time scale in the final section.

An overarching goal is to computationally investigate the three dimensional electrical activity of complex physiological systems. A great difficulty with the Poisson model is that one inevitably needs to resolve spatiotemporal scales associated with the space charge layer in a numerical simulation, making such computations prohibitively expensive. It would therefore be computationally desirable to have a model that resolves the membrane potential time scale but does not resolve the Debye spatiotemporal scales.

4 Electroneutral Model

We propose the following as a computationally efficient alternative to the Poisson Model:

$$0 = \frac{\partial C_i}{\partial \tau_V} + \beta \nabla_{\mathbf{X}} \cdot \mathbf{F}_i \tag{32}$$

$$\mathbf{F}_{i} = -\tilde{D}_{i}(\nabla_{\mathbf{X}}C_{i} + z_{i}C_{i}\nabla_{\mathbf{X}}\Phi)$$
(33)

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i \tag{34}$$

$$z_i \mathbf{F}_i \cdot \mathbf{n}^{(kl)} = \frac{\partial \sigma_i^{(k)}}{\partial \tau_V} + \alpha \tilde{j}_i$$
 (35)

The Poisson equation in the Poisson model has been replaced by the electroneutrality condition (34). Since this is an algebraic condition, it does not require a boundary condition at the membrane. The boundary conditions for the drift-diffusion equations (32) and (33) are given by (35). In comparison to (21), we have an additional term:

$$\frac{\partial \sigma_i}{\partial \tau_V}$$
. (36)

 σ_i is the amount of electric charge at the membrane face contributed by the *i*-th species of ion. In the electroneutral model, the electric charge within the Debye layer is represented as a surface charge density of zero thickness. In this picture, the amount of ionic current $qz_i\mathbf{f}_i \cdot \mathbf{n}$ either contributes to the change in surface charge density σ_i or flows across the membrane through ion channels. This picture is better aligned with the biophysical view of the membrane in the cable model, in which the membrane is a capacitor within an ohmic medium. One important advantage of the boundary condition (35) compared with (21) is that the parameter values in (35) are directly observable experimentally. Since the Debye layers are too thin to be explored experimentally, the parameter values in (21) can only be inferred, as argued in detail in [15].

The surface charge contributions σ_i must be related to the dynamic variables C_i and/or $\Phi^{(kl)}$ to close the system of equations. First we let

$$\sum_{i=1}^{N} \sigma_i \equiv \sigma = \theta \Phi^{(kl)}. \tag{37}$$

This relation says that the total amount of surface charge σ is linearly proportional to the membrane potential $\Phi^{(kl)}$, where θ is the effective dimensionless membrane capacitance. Note that θ is different from θ^* , the *intrinsic* membrane capacitance, used in (20). The lipid bilayer sandwiched by the two boundary layers considered as a whole gives rise to a capacitor with the effective capacitance θ . This is the capacitance that is measured experimentally, given that it is impossible to to distinguish the contributions to the capacitance from the Debye layers and the lipid bilayer. The relation between these two quantities will be clarified in Appendix 11. Now, define λ_i as the fraction of the total charge σ that is contributed by the *i*-th species of ion:

$$\sigma_i = \lambda_i \sigma. \tag{38}$$

We let λ_i evolve according to the following:

$$\frac{\partial \lambda_i}{\partial \tau_V} = \frac{\tilde{\lambda}_i - \lambda_i}{\beta}, \quad \tilde{\lambda}_i = \frac{z_i^2 C_i}{\sum_{i'=1}^N z_{i'}^2 C_{i'}}$$
(39)

The charge fraction λ_i relaxes to $\tilde{\lambda}_i$ in the charge relaxation time scale. The specific form of $\tilde{\lambda}_i$ was derived in [15], but is also given in Appendix 11. Note that:

$$\beta \frac{\partial}{\partial t} \left(\sum_{i=1}^{N} \lambda_i \right) = \sum_{i=1}^{N} (\tilde{\lambda}_i - \lambda_i) = 1 - \left(\sum_{i=1}^{N} \lambda_i \right)$$
 (40)

and therefore, $\sum_{i=1}^{N} \lambda_i \equiv 1$ provided that $\sum_{i=1}^{N} \lambda_i = 1$ at the initial time, as required by the definition of λ_i as the charge fraction. In [15], $\tilde{\lambda}_i$ was used in place of λ_i in (38), in which case the charge fraction relaxation equation in (39) is not needed. This original system, however, leads to ill-posed behavior which we examine in Appendix 12.

We shall call the system (32)-(35) and (39) the electroneutral model. There is no longer a space charge layer to be resolved at the membrane, since the presence of the surface charge has been taken care of in the boundary condition (35). The charge relaxation time scale only appears in a simple ODE (39), and does not pose serious difficulties in the construction of a numerical scheme [16]. We propose the electroneutral model as a computationally tractable model that addresses the shortcomings of the cable model pointed out in Section 1.

An important difference between the electroneutral model and the Poisson model is what the state variables are. In the Poisson model, specifying the ionic concentrations at every point in space is enough to describe the state of the system. The electrostatic potential can be found from the ionic concentration profile by solving the Poisson equation (19) with the boundary conditions (20). The difficulty, though, is that we must specify the ionic concentrations up to the boundary to within the space charge layer. The electroneutral model, on the other hand, does not require the ionic concentration profiles in the space charge layer. The spatiotemporal details of the space charge layer are represented by the the membrane potential $\Phi^{(kl)}$ and the charge fractions λ_i . The state variables for the electroneutral model thus include the ionic concentration profile as well as the membrane potential $\Phi^{(kl)}$ and the membrane charge fractions λ_i . This means in particular that we need to specify the values of these quantities as initial conditions.

In the electroneutral model we have ion conservation in the following sense:

$$\frac{\partial}{\partial \tau_V} \left(\int_{\Omega^{(k)}} z_i C_i dV + \int_{\Gamma^{(kl)}} \beta \theta \lambda_i^{(k)} \Phi^{(kl)} dA \right) = - \int_{\Gamma^{(kl)}} \beta \alpha \tilde{j}_i dA. \tag{41}$$

This equation says that for each ionic species the change in the sum of the ionic content of the region $\Omega^{(k)}$ and of the space charge layer is equal to the transmembrane current that flows out of this region. This is an important property not only from a physical point of view, but also from a practical point of view if we are to perform long-time calculations of ionic concentration dynamics.

The natural question that arises is whether the electroneutral model is in any way an approximation to the Poisson model. We investigate this question using both asymptotic and numerical computations. Beginning with the next section, we present a matched asymptotic study to show that the electroneutral model gives an approximation to the Poisson model. In Section 9, we shall computationally investigate how well the electroneutral model approximates the Poisson model.

5 Matched Asymptotics

We recall the Poisson Model:

$$\frac{\partial C_i}{\partial \tau_V} = -\beta \nabla_{\mathbf{X}} \cdot \mathbf{F}_i \tag{42}$$

$$\mathbf{F}_{i} = -\tilde{D}_{i}(\nabla_{\mathbf{X}}C_{i} + z_{i}C_{i}\nabla_{\mathbf{X}}\Phi) \tag{43}$$

$$\beta^2 \Delta_{\mathbf{X}} \Phi = -\left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i\right) \tag{44}$$

Recall from (31) that we rescaled time to τ_V to capture the dynamics in the membrane potential time scale. We now perform matched asymptotics on the above to clarify the relation between the electroneutral and Poisson models.

As noted earlier, a boundary layer of thickness $\mathcal{O}(\beta)$ develops at the membrane when $\beta \ll 1$. We therefore introduce an *inner layer* of thickness $\mathcal{O}(\beta)$ at the membrane. We shall continue to use the terms space charge layer or Debye layer to denote this layer.

We need to introduce another spatial scale of order $\mathcal{O}(\sqrt{\beta})$ at the membrane. This need arises as the result of introducing a newly rescaled time variable τ_V . The spatial scale of order $\mathcal{O}(\sqrt{\beta})$ corresponds to the length over which ions can diffuse in the membrane potential time scale, βT_0 . Formally, the necessity for this layer can be seen by noting that β multiplies a second order spatial derivative in (31) since \mathbf{F}_i is itself written in terms of spatial derivatives (c.f. 18). We shall refer to this layer as the intermediate layer or the fast diffusion layer. It is interesting to note that the presence of such layers have been postulated to account for \mathbf{K}^+ ion accumulation in the extracellular space of the squid giant axon [3]. We thus have three regions to consider in the asymptotic calculations to follow: the inner and intermediate layers located adjacent to the membrane, and the region away from the membrane, which we shall call the outer layer. We perform two matching procedures, at the inner-intermediate layer interface and at the intermediate-outer layer interface. We have summarized the relevant spatial scales in Figure 2.

The above discussion prompts us to expand the physical variables in powers of $\sqrt{\beta}$ instead of β :

$$C_i(\mathbf{X}, \tau_V) = C_i^0(\mathbf{X}, \tau_V) + \sqrt{\beta} C_i^1(\mathbf{X}, \tau_V) + \beta C_i^2(\mathbf{X}, \tau_V) \cdots$$
 (45)

$$\Phi(\mathbf{X}, \tau_V) = \Phi^0(\mathbf{X}, \tau_V) + \sqrt{\beta} \Phi^1(\mathbf{X}, \tau_V) + \beta \Phi^2(\mathbf{X}, \tau_V) \cdots$$
 (46)

The other two parameters of the system, α and θ^* are also small (c.f. (25),(23)), but we shall treat them as being $\mathcal{O}(1)$ with respect to β . We note that β is typically a few orders of magnitude smaller than α or θ^* . The smallness of α and θ^* will be later exploited, in sections 8.3 and 6 respectively.

In performing matched asymptotics at the membrane, we introduce a coordinate system at the membrane $\boldsymbol{\xi} = (\xi_1, \xi_2, \xi_3)$, where the ξ_1 axis is taken to be perpendicular to the membrane, while ξ_2 and ξ_3 are curvilinear coordinates

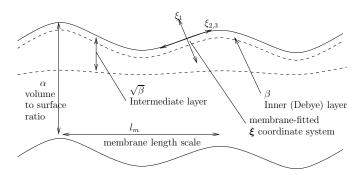


Figure 2: A schematic of the relevant spatial scales used in the asymptotic calculations. The solid lines denote the membrane and the dotted lines are the interfaces between the boundary layers. The inner-most layer has width β , the intermediate layer $\sqrt{\beta}$. The typical membrane separation is α and the typical length scale associated with the membrane is l_m . ξ is the membrane-fitted coordinate used in the matched asymptotics calculations.

that run "parallel" to the membrane. The ξ_1 axis will be rescaled to yield coordinates in the intermediate layer $\boldsymbol{\xi}^a$ such that $\xi_1 = \sqrt{\beta}\xi_1^a$ and in the inner layer $\boldsymbol{\xi}^b$ such that $\xi_1 = \beta \xi_1^b$.

We must now ask how we are to rescale ξ_2 and ξ_3 . There are at least two spatial scales that are relevant: ρ_{κ} the dimensionless curvature radius of the membrane and l_j the dimensionless length scale on which one may see $\mathcal{O}(1)$ changes in ion channel current density. Let l_m be the smaller of the two spatial scales l_j and ρ_{κ} . We shall call l_m the membrane length scale. The question raised at the beginning of this paragraph can be answered by comparing the relative magnitude of this length scale to the $\mathcal{O}(\sqrt{\beta})$ length scale.

If l_m is considerably larger than $\sqrt{\beta}$, there is no need to rescale ξ_2 and ξ_3 . If l_m is order $\mathcal{O}(\sqrt{\beta})$, we must scale ξ_2, ξ_3 to $\xi_2 = \sqrt{\beta} \xi_2^{a,b}, \xi_3 = \sqrt{\beta} \xi_3^{a,b}$ so that the curvature correction and the ionic fluxes parallel to the membrane are $\mathcal{O}(1)$ quantities when measured in the intermediate layer coordinate $\boldsymbol{\xi}^a$. We shall mainly be concerned with the case $l_m > \sqrt{\beta}$ but we shall quote results of calculations when $l_m \sim \sqrt{\beta}$.

We point out that there could be situations in which l_m is small only along a certain coordinate direction. For example, if we take a cylindrical axon with diameter $\mathcal{O}(\sqrt{\beta})$, and take ξ_2 to be the angular coordinate, and ξ_3 to be the axial coordinate, the curvature radius along the ξ_2 coordinate is $\mathcal{O}(\sqrt{\beta})$ whereas the curvature radius along the ξ_3 coordinate is large (curvature is negligible). In such cases (and if the cylindrical axon is endowed with near uniform ion channel density so that l_j is large), we need only rescale ξ_2 but not ξ_3 . We shall not deal with such cases, since such an analysis will follow along similar lines as the case in which $l_m \sim \sqrt{\beta}$.

6 Inner-Intermediate Matching

We first consider inner-intermediate matching when $l_m > \sqrt{\beta}$.

Consider the membrane surface facing $\Omega^{(\vec{k})}$. We now introduce a coordinate system $\boldsymbol{\xi}$ so that the ξ_1 coordinate direction is perpendicular to the membrane. We let $\xi_1=0$ coincide with the membrane face, and let the positive ξ_1 axis point into the region $\Omega^{(k)}$. For simplicity, we shall assume that the membrane is flat, i.e., that it has no curvature. Therefore, we can take the coordinate system to $\boldsymbol{\xi}$ to be orthonormal. When $l_m > \sqrt{\beta}$, it turns out that curvature corrections produce only higher order terms that we can ignore.

In the inner layer, we rescale ξ as:

$$\boldsymbol{\xi}^b = (\xi_1^b, \xi_2^b, \xi_3^b), \quad \xi_1 = \beta \xi_1^b, \quad \xi_2 = \xi_2^b, \quad \xi_3 = \xi_3^b.$$
 (47)

The equations are:

$$\beta \frac{\partial C_i^b}{\partial \tau_V} = -\left(\frac{\partial F_{i1}^b}{\partial \xi_1^b} + \beta^2 \left(\frac{\partial F_{i2}^b}{\partial \xi_2^b} + \frac{\partial F_{i3}^b}{\partial \xi_3^b}\right)\right) \tag{48}$$

$$F_{ip}^{b} = -\tilde{D}_{i} \left(\frac{\partial C_{i}^{b}}{\partial \xi_{p}^{b}} + z_{i} C_{i}^{b} \frac{\partial \Phi^{b}}{\partial \xi_{p}^{b}} \right), \quad p = 1, 2, 3 \quad (49)$$

$$\frac{\partial^2 \Phi^b}{\partial \xi_1^{b^2}} + \beta^2 \left(\frac{\partial^2 \Phi^b}{\partial \xi_2^{b^2}} + \frac{\partial^2 \Phi^b}{\partial \xi_3^{b^2}} \right) = -\left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i^b \right). \tag{50}$$

Since the inner layer is adjacent to the membrane, we must supplement the above with boundary conditions, suitably rescaled:

$$\theta^*(\Phi|_{\xi_1^b=0} - \Phi^{(l)}) = -\frac{\partial \Phi^b}{\partial \xi_1^b}\Big|_{\xi_2^b=0}$$
(51)

$$-z_i F_{i1}^b \big|_{\mathcal{E}_{=0}^b} = \beta \alpha \tilde{j}_i. \tag{52}$$

We shall make the simplifying assumption that the transmembrane ionic current densities j_i are given functions of position (on the membrane) and time instead of being functions of C_i , $\Phi^{(kl)}$ and the gating variables.

In the intermediate layer we rescale ξ as:

$$\boldsymbol{\xi}^a = (\xi_1^a, \xi_2^a, \xi_3^a), \quad \xi_1 = \sqrt{\beta} \xi_1^a, \quad \xi_2 = \xi_2^a, \quad \xi_3 = \xi_3^a.$$
 (53)

The equations are:

$$\frac{\partial C_i^a}{\partial \tau_V} = -\left(\frac{\partial F_{i1}^a}{\partial \xi_1^a} + \beta \left(\frac{\partial F_{i2}^a}{\partial \xi_2^a} + \frac{\partial F_{i3}^a}{\partial \xi_3^a}\right)\right) \tag{54}$$

$$F_{ip} = -\tilde{D}_i \left(\frac{\partial C_i^a}{\partial \xi_p^a} + z_i C_i^a \frac{\partial \Phi^a}{\partial \xi_p^a} \right), \quad p = 1, 2, 3 \quad (55)$$

$$\beta \frac{\partial^2 \Phi^a}{\partial \xi_1^{a^2}} + \beta^2 \left(\frac{\partial^2 \Phi^a}{\partial \xi_2^{a^2}} + \frac{\partial^2 \Phi^a}{\partial \xi_3^{a^2}} \right) = -\left(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i^a \right). \tag{56}$$

Substitute (45) and (46) in the inner layer equations (48)-(50), and collect like terms in order β . The expansions of C_i and Φ in $\sqrt{\beta}$ induce expansions of \mathbf{F}_i in terms of $\sqrt{\beta}$. We shall denote the $\mathcal{O}(\sqrt{\beta}^k)$ term as \mathbf{F}_i^k . For example,

$$F_{i1}^{b0} = -\tilde{D}_i \left(\frac{\partial C_i^{b0}}{\partial \xi_1^b} + z_i C_i^{b0} \frac{\partial \Phi^{b0}}{\partial \xi_1^b} \right)$$
 (57)

$$F_{i1}^{b1} = -\tilde{D}_i \left(\frac{\partial C_i^{b1}}{\partial \xi_1^b} + z_i C_i^{b1} \frac{\partial \Phi^{b0}}{\partial \xi_1^b} + z_i C_i^{b0} \frac{\partial \Phi^{b1}}{\partial \xi_1^b} \right)$$
 (58)

By applying the same procedure to the equations (54)-(56), we may obtain analogous expressions in the intermediate layer.

We derive matching conditions at the inner-intermediate layer interface in terms of the ionic fluxes. Note from (48) and (52) that:

$$\frac{\partial F_{i1}^{b0}}{\partial \xi_1^b} = 0, \quad F_{i1}^{b0} \Big|_{\xi_1^b = 0} = 0 \tag{59}$$

$$\frac{\partial F_{i1}^{b1}}{\partial \xi_1^b} = 0, \quad F_{i1}^{b1} \big|_{\xi_1^b = 0} = 0 \tag{60}$$

From this, we find that

$$F_{i1}^{b0} = F_{i1}^{b1} \equiv 0 \tag{61}$$

within the inner layer.

Now, consider the p=1 component of (49) and (55), F_{i1}^b and F_{i1}^a . We introduce a matching coordinate system ξ^{η} in between the inner and intermediate layers such that,

$$\xi_1^a = \eta(\beta)\xi^{\eta}, \quad \lim_{\beta \to 0} \frac{\sqrt{\beta}}{\eta} = \lim_{\beta \to 0} \eta = 0$$
 (62)

Applying Kaplun's matching condition [6, 10] to F^b_{i1} and F^a_{i1} , we obtain:

$$\lim_{\beta \to 0} F_{i1}^{b0} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) = 0 \tag{63}$$

$$\lim_{\beta \to 0} \left(\frac{1}{\sqrt{\beta}} F_{i1}^{b0} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) + F_{i1}^{b1} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) - F_{i1}^{a0} (\eta \xi^{\eta}) \right) = 0 \tag{64}$$

$$\lim_{\beta \to 0} \left(\frac{1}{\beta} F_{i1}^{b0} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) + \frac{1}{\sqrt{\beta}} F_{i1}^{b1} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) + F_{i1}^{b2} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) - \frac{1}{\sqrt{\beta}} F_{i1}^{a0} (\eta \xi^{\eta}) - F_{i1}^{a1} (\eta \xi^{\eta}) \right) = 0$$

$$(65)$$

Condition (63) is automatically satisfied by (61). Condition (64), taken together with (61), yields:

$$\lim_{\beta \to 0} F_{i1}^{a0}(\eta \xi^{\eta}) = F_{i1}^{a0} \Big|_{\xi_1^a = 0} = 0.$$
 (66)

We thus have the matching condition for the leading order ionic flux in the intermediate layer. The last matching condition (65), combined with (61), yields

the following.

$$\lim_{\beta \to 0} \left(F_{i1}^{b2} \left(\frac{\eta}{\sqrt{\beta}} \xi^{\eta} \right) - \frac{1}{\sqrt{\beta}} F_{i1}^{a0} (\eta \xi^{\eta}) - F_{i1}^{a1} (\eta \xi^{\eta}) \right) = 0.$$
 (67)

To evaluate (67), we need to calculate C_i and Φ to leading order in the inner layer. From (61), (50) and (51) we see that the leading order terms satisfy the following one dimensional boundary value problem in ξ_1^a in the inner layer:

$$0 = \frac{\partial C_i^{b0}}{\partial \xi_1^b} + z_i C_i^{b0} \frac{\partial \Phi^{b0}}{\partial \xi_1^b}$$
 (68)

$$\frac{\partial^2 \Phi^{b0}}{\partial \xi_1^{b^2}} = -(\tilde{\rho_0} + \sum_{i=1}^N z_i C_i^{b0})$$
 (69)

$$\theta^* \left(\Phi^{b0}(\xi_1^b = 0) - \Phi^{(l),b0}(\xi_1^{b,(l)} = 0) \right) = -\left. \frac{\partial \Phi^{b0}}{\partial \xi_1^b} \right|_{\xi_1^b = 0}$$
(70)

$$C_i^{b0}(\xi_1^b = \infty) = C_i^{a0}(\xi_1^a = 0) \tag{71}$$

$$\Phi^{b0}(\xi_1^b = \infty) = \Phi^{a0}(\xi_1^a = 0). \tag{72}$$

The last two conditions come from matching conditions at the inner-intermediate layer interface. Here, $\xi_1^{b,(l)}$ refers to the inner layer coordinate system on the $\Omega^{(l)}$ side of the membrane $\Gamma^{(kl)}$ (note that we are now working on the $\Omega^{(k)}$ side). Equations (68), (69) with boundary conditions (70)-(72) can be solved explicitly under the approximation that θ^* is small, a reasonable approximation since $\theta^* \approx 10^{-2}$ (cf. (23)). We quote the results below, and relegate the calculations to Appendix 11.

$$\Phi^{b0}(\xi_1^b) = \Phi^{a0}(0) - \frac{\tilde{\sigma}}{\Gamma} \exp(-\Gamma \xi_1^b)$$
 (73)

$$C_i^{b0}(\xi_1^b) = C_i^{a0}(0) \left(1 + \frac{z_i \tilde{\sigma}}{\Gamma} \exp(-\Gamma \xi_1^b) \right)$$
 (74)

$$\Gamma^2 = \sum_{i=1}^{N} z_i^2 C_i^{a0}(0), \quad \Gamma > 0$$
 (75)

$$\tilde{\sigma}_i \equiv \frac{z_i^2 C_i^{a0}(0)}{\Gamma^2} \tilde{\sigma} \equiv \tilde{\lambda}_i \tilde{\sigma} \tag{76}$$

$$\tilde{\sigma} = \theta \Phi^{(kl),a0}, \quad \frac{1}{\theta} = \frac{1}{\theta^*} + \frac{1}{\Gamma^{(k)}} + \frac{1}{\Gamma^{(l)}}$$

$$(77)$$

In the above, $\tilde{\sigma}$ denotes the total charge in the Debye layer, and $\tilde{\sigma}_i$ is the charge contributed by the *i*-th species of ion. Thus, $\tilde{\sigma}_i/\tilde{\sigma} = \tilde{\lambda}_i$ is the charge fraction contributed by the *i*-th species of ion. Note by design that $\sum_{i=1}^N \tilde{\lambda}_i = 1$. The variable θ is the dimensionless effective membrane capacitance to be distinguished from the dimensionless *intrinsic* membrane capacitance θ^* . We refer the reader to Appendix 11 for further elaboration.

Now, consider (48) and (52) at the first non-trivial order:

$$\frac{\partial C_i^{b0}}{\partial \tau_V} = -\frac{\partial F_{i1}^{b2}}{\partial \mathcal{E}_i^b}, \quad -z_i F_{i1}^{b2} \Big|_{\xi_1^b = 0} = \alpha \tilde{j}_i \tag{78}$$

Since our goal is to evaluate (67), we would like to obtain an expression for F_{i1}^{b2} . We integrate the above in ξ_1^b to obtain:

$$-z_{i}F_{i1}^{b2} = \alpha \tilde{j}_{i} + z_{i} \int_{0}^{\xi_{1}^{b}} \frac{\partial C_{i}^{b0}}{\partial \tau_{V}} d\xi_{1}^{b}$$

$$= \alpha \tilde{j}_{i} + z_{i} \frac{\partial C_{i}^{a0}(0)}{\partial \tau_{V}} \xi_{1}^{b} + \int_{0}^{\xi_{1}^{b}} \frac{\partial}{\partial \tau_{V}} \frac{z_{i}C_{i}^{a0}(0)\tilde{\sigma}}{\Gamma} \exp(-\Gamma \xi_{1}^{b}) d\xi_{1}^{b}$$

$$\equiv \alpha \tilde{j}_{i} + z_{i} \frac{\partial C_{i}^{a0}(0)}{\partial \tau_{V}} \xi_{1}^{b} + I^{\text{charge}}$$

$$(79)$$

where we used (74) for C_i^{b0} . We can finally consider condition (67). We would like (67) be satisfied regardless of the value of ξ^{η} . For the F_{i2}^{b2} term, taking $\beta \to 0$ in (67) amounts to studying the behavior of (79) in the limit $\xi_1^b \to \infty$. Take $\xi_1^b \to \infty$ in I^{charge} .

$$\lim_{\xi_i^b \to \infty} z_i I^{\text{charge}} = \frac{\partial \tilde{\sigma}_i}{\partial \tau_V}.$$
 (80)

where we have used (76). We thus conclude using (79) and the above that:

$$-z_i F_{i1}^{b2} = \left(\frac{\partial \tilde{\sigma}_i}{\partial \tau_V} + \alpha \tilde{j}_i\right) + z_i \frac{\partial C_i^{a0}(0)}{\partial \tau_V} \xi_1^b + \mathcal{O}(\exp(-\Gamma \xi_1^b))$$
(81)

Note that F_{i1}^{b2} thus consists of a constant and a linear component in ξ_1^b as well as a residual term that decays exponentially. We now expand the intermediate layer expressions of (67) at $\xi^{\eta} = 0$.

$$\frac{1}{\sqrt{\beta}}F_{i1}^{a0}(\eta\xi^{\eta}) + F_{i1}^{a1}(\eta\xi^{\eta}) = \frac{1}{\sqrt{\beta}}F_{i1}^{a0}(0) + \frac{\eta\xi^{\eta}}{\sqrt{\beta}}\frac{\partial F_{i1}^{a0}(0)}{\partial \xi_{1}^{a}} + F_{i1}^{a1}(0) + \cdots
= \frac{\eta\xi^{\eta}}{\sqrt{\beta}}\frac{\partial F_{i1}^{a0}(0)}{\partial \xi_{1}^{a}} + F_{i1}^{a1}(0) + \cdots$$
(82)

where we have used (66) to eliminate $F_{i1}^{a0}(0)$. Substituting the above as well as (81) into (67),

$$\lim_{\beta \to 0} \left(F_{i1}^{a1}(0) + \frac{1}{z_i} \left(\frac{\partial \tilde{\sigma}_i}{\partial \tau_V} + \alpha \tilde{j}_i \right) \right) + \frac{\eta \xi^{\eta}}{\sqrt{\beta}} \left(\frac{\partial F_{i1}^{a0}(0)}{\partial \xi_1^a} + \frac{\partial C_i^{a0}(0)}{\partial \tau_V} \right) + \mathcal{O}(\exp(-\Gamma \xi_1^b)) + \cdots$$

$$= 0$$
(83)

The necessary conditions for the above to be satisfied are:

$$-z_i F_{i1}^{a1}(0) = \frac{\partial \tilde{\sigma}_i}{\partial \tau_V} + \alpha \tilde{j}_i \tag{84}$$

$$\frac{\partial C_i^{a0}(0)}{\partial \tau_V} = -\frac{\partial F_{i1}^{a0}(0)}{\partial \xi_1^a} \tag{85}$$

The second expression (85) is automatically satisfied as can be seen by taking (55) to leading order. Equation (84) together with (66) are the matching condition we set out to obtain.

When $l_m \sim \sqrt{\beta}$, as discussed at the end of the previous section, we must rescale the coordinates so that $\xi_p = \sqrt{\beta} \xi_p^{a,b}$, p = 2,3. We can obtain the matching conditions for this case in a manner similar to the $l_m > \sqrt{\beta}$ case, although the calculations are more involved. The matching conditions corresponding to (84) and (85) are respectively [16]:

$$-z_i F_{i1}^{a1}(0) = \frac{\partial \tilde{\sigma}_i}{\partial \tau_V} + \alpha \tilde{j}_i - \nabla_{S^a} \cdot \left(\tilde{D}_i \tilde{\sigma}_i \nabla_{S^a} \left(\ln C_i^{a0}(0) + z_i \Phi^{a0}(0) \right) \right)$$
(86)

$$\frac{\partial C_i^{a0}(0)}{\partial \tau_V} = -\left(\frac{\partial F_{i1}^{a0}(0)}{\partial \xi_1^a} + \nabla_{S^a} \cdot \mathbf{F}_{iS^a}^{a0}(0)\right)$$
(87)

Here, the operators ∇_{S^a} and ∇_{S^a} denote respectively the gradient and divergence operators on the membrane, where the length is measured in terms of $\sqrt{\beta}L_0$.

Compared with (84), equation (86) has an additional membrane drift diffusion term. The surface gradient of the chemical potential potential $\mu_i = \ln C_i^{a0} + z_i \Phi^{a0}$, scaled by the diffusion coefficient, gives the drift velocity of $\tilde{\sigma}_i$ along the membrane.

We shall henceforth limit our attention to the case $l_m > \beta$.

7 Electroneutral Model as Approximation to Poisson Model

We now examine the relationship between the Poisson and electroneutral models. Consider two pairs of ionic concentrations and electrostatic potential $C_i^{\rm EN}, \Phi^{\rm EN}$ and $C_i^{\rm Po}, \Phi^{\rm Po}$, which evolve according to the electroneutral and Poisson models respectively. We postulate an expansion of $C_i^{\rm EN}, C_i^{\rm Po}$ and $\Phi^{\rm EN}, \Phi^{\rm Po}$ in $\sqrt{\beta}$ of the form (45) and (46) respectively and see if the electroneutral and Poisson models produce the same leading order equations.

First consider the intermediate layer. We write equations (32)-(35) and (39) of the electroneutral model in the ξ^a coordinate and write out the leading order

equations. The $\mathcal{O}(1)$ equations are:

$$\frac{\partial C_i^{a0,\text{EN}}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a0,\text{EN}}}{\partial \xi_1^a} \tag{88}$$

$$F_{i1}^{a0,\text{EN}} = -\tilde{D}_i \left(\frac{\partial C_i^{a0,\text{EN}}}{\partial \xi_1^a} + z_i C_i^{a0,\text{EN}} \frac{\partial \Phi^{a0,\text{EN}}}{\partial \xi_1^a} \right)$$
(89)

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i^{a0, \text{EN}}$$
 (90)

$$F_{i1}^{a0,\text{EN}}(\xi_1^a = 0) = 0 \tag{91}$$

The $\mathcal{O}(\sqrt{\beta})$ equations are:

$$\frac{\partial C_i^{a1,\text{EN}}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a1,\text{EN}}}{\partial \xi_1^a} \tag{92}$$

$$F_{i1}^{a1,\text{EN}} = -\tilde{D}_i \left(\frac{\partial C_i^{a1,\text{EN}}}{\partial \xi_1^a} + z_i C_i^{a1,\text{EN}} \frac{\partial \Phi^{a0,\text{EN}}}{\partial \xi_1^a} + z_i C_i^{a0,\text{EN}} \frac{\partial \Phi^{a1,\text{EN}}}{\partial \xi_1^a} \right)$$
(93)

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i^{a1, \text{EN}}$$
(94)

$$F_{i1}^{a1,\text{EN}}(\xi_1^a = 0) = \theta \frac{\partial \lambda_i \Phi^{(kl)a0,\text{EN}}}{\partial \tau_V} + \alpha \tilde{j}_i$$
(95)

$$\frac{\partial \lambda_i}{\partial \tau_V} = \frac{\tilde{\lambda}_i^{\text{EN}} - \lambda_i}{\beta}, \tilde{\lambda}_i^{\text{EN}} = \frac{z_i^2 C_i^{a0,\text{EN}}}{\sum_{i'=1}^N z_{i'}^2 C_{i'}^{a0,\text{EN}}}$$
(96)

The same procedure on the Poisson model yields the following. The $\mathcal{O}(1)$ equations are:

$$\frac{\partial C_i^{a0,\text{Po}}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a0,\text{Po}}}{\partial \xi_1^a} \tag{97}$$

$$F_{i1}^{a0,\text{Po}} = -\tilde{D}_i \left(\frac{\partial C_i^{a0,\text{Po}}}{\partial \xi_1^a} + z_i C_i^{a0,\text{Po}} \frac{\partial \Phi^{a0,\text{Po}}}{\partial \xi_1^a} \right)$$
(98)

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i^{a0, \text{Po}}$$
(99)

$$F_{i1}^{a0,\text{Po}}(\xi_1^a = 0) = 0 \tag{100}$$

Equation (100) comes from the matching condition (66). The $\mathcal{O}(\sqrt{\beta})$ equations

are:

$$\frac{\partial C_i^{a1,\text{Po}}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a1,\text{Po}}}{\partial \xi_1^a} \tag{101}$$

$$F_{i1}^{a1,\text{Po}} = -\tilde{D}_i \left(\frac{\partial C_i^{a1,\text{Po}}}{\partial \xi_1^a} + z_i C_i^{a1,\text{Po}} \frac{\partial \Phi^{a0,\text{Po}}}{\partial \xi_1^a} + z_i C_i^{a0,\text{Po}} \frac{\partial \Phi^{a1,\text{Po}}}{\partial \xi_1^a} \right)$$

$$(102)$$

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i^{a1, \text{Po}}$$
 (103)

$$F_{i1}^{a1,\text{Po}}(\xi_1^a = 0) = \theta \frac{\partial \tilde{\lambda}_i^{\text{Po}} \Phi^{(kl)a0,\text{Po}}}{\partial \tau_V} + \alpha \tilde{j}_i$$

$$\tilde{\lambda}_i^{\text{Po}} = \frac{z_i^2 C_i^{a0,\text{Po}}}{\sum_{i'=1}^N z_{i'}^2 C_{i'}^{a0,\text{Po}}}$$
(104)

$$\tilde{\lambda}_i^{\text{Po}} = \frac{z_i^2 C_i^{a0,\text{Po}}}{\sum_{i'=1}^{N} z_{i'}^2 C_{i'}^{a0,\text{Po}}}$$
(105)

where equations (104) and (105) come from the matching condition (84).

We see that (88)-(91), (92)-(95) are identical to (97)-(100), (101)-(104), except for the difference between λ_i and λ_i in equation (95) and (104). In Appendix 12 we show that in fact (Eq. (205)):

$$\frac{\partial \lambda_i^{\text{EN}}}{\partial \tau_V} = \frac{\partial \tilde{\lambda}_i^{\text{EN}}}{\partial \tau_V} + \mathcal{O}(\beta)$$
 (106)

Therefore, $\lambda_i^{\rm EN}$ may be replaced by $\tilde{\lambda}_i^{\rm EN}$ without affecting the order of the approximation. This shows that $C_i^{\rm EN}$, $\Phi^{\rm EN}$ and $C_i^{\rm Po}$, $\Phi^{\rm Po}$ satisfy identical equations in the intermediate layer to order $\mathcal{O}(\sqrt{\beta})$.

The same procedure in the outer layer shows that the two models agree up to equations of order $\mathcal{O}(\beta^{3/2})$. We thus see that the electroneutral model formally approximates the Poisson model in the intermediate layer and outer layers, where the biophysical processes of interest take place. In Section 9, we shall show computationally that the electroneutral model indeed provides an excellent approximation to the Poisson model.

8 Equations in the Outer Layer

We continue with the asymptotic calculations with the goal of obtaining the cable model under certain conditions to be set forth below.

8.1 3D Cable Model

We now consider intermediate-outer matching. We first turn to the equations satisfied in the outer layer, which can be obtained by substituting (46) and (45) into (31), (18) and (19).

$$\frac{\partial C_i^0}{\partial \tau_V} = 0, \qquad \frac{\partial C_i^1}{\partial \tau_V} = 0 \qquad (107)$$

$$\frac{\partial C_i^2}{\partial \tau_V} = -\nabla_{\mathbf{X}} \cdot \mathbf{F}_i^0 \tag{108}$$

$$0 = \tilde{\rho_0} + \sum_{i=1}^{N} z_i C_i^0 \qquad 0 = \sum_{i=1}^{N} z_i C_i^2 \qquad (109)$$

Equation (107) tells us that C_i to leading order does not change in the τ_V time variable. We still need to know the evolution of Φ^0 . This can be obtained by summing (108) in i and and using (109) to conclude:

$$\nabla \cdot \left(\sum_{i=1}^{N} z_i \mathbf{F}_i^0\right) = 0 \tag{110}$$

This is the equation satisfied by Φ^0 in the outer layer. In order to obtain the boundary condition for this equation, all we need is $(\sum_{i=1}^N z_i \mathbf{F}_i^0) \cdot \mathbf{n}^{(kl)}$.

Let $\mathcal{J} = \sum_{i=1}^{N} z_i \mathbf{F}_i$. We shall use the usual subscripts and superscripts on \mathcal{J} to denote terms of the expansion of \mathcal{J} in β in the different layers, induced by the expansion of \mathbf{F}_i . We find from (54) and (56) that:

$$\sum_{i=1}^{N} z_i C_i^{a0} = 0, \qquad \sum_{i=1}^{N} z_i C_i^{a1} = 0$$
 (111)

$$\frac{\partial C_i^{a0}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a0}}{\partial \xi_1^a}, \qquad \frac{\partial C_i^{a1}}{\partial \tau_V} = -\frac{\partial F_{i1}^{a1}}{\partial \xi_1^a} \qquad (112)$$

Using the above relations we see that:

$$\frac{\partial \mathcal{J}_1^{a0}}{\partial \xi_1^a} = \frac{\partial \mathcal{J}_1^{a1}}{\partial \xi_1^a} = 0 \tag{113}$$

The value of \mathcal{J}_1^{a0} and \mathcal{J}_1^{a1} at $\xi_1^a=0$ can be computed from (66) and (84), and we see from (113) that:

$$\mathcal{J}_1^{a0} = 0, \quad -\mathcal{J}_1^{a1} = \theta \frac{\partial \Phi^{(kl),a0}}{\partial \tau_V} + \sum_{i=1}^N \alpha \tilde{j}_i$$
 (114)

where we have used $\sum_{i=1}^{N} \tilde{\lambda}_i = 1$. Following the same matching procedure as for the inner-intermediate layer matching, we conclude:

$$\theta \frac{\partial \Phi^{(kl),a0}}{\partial \tau_V} + \alpha \sum_{i=1}^{N} \tilde{j}_i = -\mathcal{J}^0$$
 (115)

We can now use the above as the boundary condition for (110) and explicitly write down the equations satisfied in the outer layer.

$$\nabla \cdot (A \nabla \Phi^0 + \nabla B) = 0 \tag{116}$$

$$-(A\nabla\Phi^{0} + \nabla B) \cdot \mathbf{n}^{(kl)} = \theta \frac{\partial \Phi^{(kl),0}}{\partial \tau_{V}} + \alpha I_{\text{ion}}$$
(117)

$$A = \sum_{i=1}^{N} z_i^2 C_i^0, \quad B = \sum_{i=1}^{N} z_i C_i^0, \quad I_{\text{ion}} = \sum_{i=1}^{N} \tilde{j}_i$$
 (118)

Note here that A and B are functions of **X** only, and do not depend on time, since C_i^0 does not change in the τ_V time scale.

There is one difficulty here that needs to be pointed out. Equation (115) and (117) are not exactly the same. In (115), $\Phi^{(kl)}$ is evaluated just outside the inner layer, whereas in (117), $\Phi^{(kl)}$ is evaluated just outside the intermediate layer. There is a similar concern for the transmembrane current terms \tilde{j}_i if they are functions of C_i or $\Phi^{(kl)}$.

From (111) and (66), and the fact that C_i^{a0} and Φ^{a0} must match to leading order at $\xi_1^a = \infty$ to the outer layer solution, we see that C_i^{a0} and Φ^{a0} decay to a uniform state after an initial transient (note C_i^{a0} decays to a constant where as Φ^{a0} decays to a time-varying uniform state, whose value is equal to $\Phi^0(\xi_1^b = 0)$). Therefore, after an initial transient, the discrepancy between $\Phi^{(kl),0}$, $\Phi^{(kl),a0}$ and C_i^{a0} , C_i^0 will decay to 0.

This model is valid to leading order outside the intermediate layer of thickness $\mathcal{O}(\sqrt{\beta})$. We shall call this the 3D-cable model.

The the 3D-cable model may be derived very easily from the electroneutral model. Consider equations (32)-(35) of the electroneutral model. We can take the time derivative of the electroneutrality condition (34) and substitute (32) to obtain the elliptic equation satisfied by the electrostatic potential, (116). Sum (35) in i and we find the boundary condition (117). The coefficients A and B in equation (116) are now time dependent, but we can see from (32), that to leading order, the ionic concentrations do not change in the membrane potential time scale. Thus, A and B are constant to leading order. The ease with which one can see the correspondence between the electroneutral model and the cable model is an appealing feature of the electroneutral approach.

8.2 Simplified 3D-Cable Model

We reach a further simplification by considering the following situation. Suppose the long time average of the transmembrane currents \tilde{j}_i is equal to 0. That is to say, if we average over a sufficient long time, there is no net current flowing through the membrane. An electrically active cell whose ion channel currents are quickly counter-balanced by ionic pumps may fit this category. Then, the ionic concentrations should relax to a stationary value in the slow diffusion time scale. If there are no fixed charges $\tilde{\rho}$, or if the fixed charges are spatially uniform, the resulting ion concentration profile will be spatially uniform within each region.

We apply the above 3-D cable model to this situation. From (116)-(118), we obtain:

$$\Delta \Phi^0 = 0 \tag{119}$$

$$-A^{(k)}\nabla\Phi^{0}\cdot\mathbf{n}^{(kl)} = \theta \frac{\partial\Phi^{(kl),0}}{\partial\tau_{V}} + \alpha I_{\text{ion}}$$
(120)

The gradient of B vanishes because of the spatial uniformity of C_i^0 . Note that $A^{(k)}$ is a constant that depends only on the region number (k), and expresses the ohmic conductivity of the electrolyte medium. We shall call this the *simplified 3-D cable model*. We note that this system, when homogenized in a quasiperiodic domain, gives rise to the bidomain equations, which are widely used in simulations of organ-level cardiac electrophysiology [17, 11].

8.3 Derivation of Standard Cable Model

We now derive the traditional cable model by considering the above simplified 3D-cable model under specialized geometry. We note of an analysis of a similar situation for a passive cable in which a different approach is used to address this issue [21].

Consider an infinitely long cylinder of radius $r^{\rm int}$. The dimensionless radius will therefore be $\eta \equiv r^{\rm int}/L_0$. This infinite cylinder is surrounded by an extracellular space which lies between this cylinder and a concentric cylinder of radius $r^{\rm ext}(>r^{\rm int})$. This extracellular region is insulated at the outer boundary. We shall let $\xi = r^{\rm ext}/r^{\rm int}$. Equations of the simplified 3D-cable model (119) and (120) specialized to this situation are:

$$\frac{\partial^2 \Phi}{\partial Z^2} + \Delta_D \Phi = 0 \text{ in } \Omega^{\text{int}}, \Omega^{\text{ext}}$$
(121)

$$-A^{(k)}\frac{\partial\Phi}{\partial R} = \theta \frac{\partial[\Phi]}{\partial \tau_V} + \alpha I_{\text{ion}}, \quad [\Phi] \equiv \Phi^{\text{int}} - \Phi^{\text{ext}} \text{ at } R = \eta^{\pm}$$
 (122)

$$-A^{\text{ext}}\frac{\partial\Phi}{\partial R} = 0 \text{ at } R = \eta\xi \tag{123}$$

To avoid cluttered notation, we have eliminated the superscript 0. In the above, R is the radial, Z the axial coordinate and Δ_D denotes the Laplacian on the plane Z = const. Equation (122) is satisfied at $R = \eta$ from both the intracellular (η^-) and extracellular (η^+) sides. The superscript k denotes either the intra or extracellular region.

We shall now take η to be the small parameter in our system. What follows is a thin-domain asymptotics calculation used for example in lubrication theory [7]. We rescale the the radial coordinate to $R = \eta \rho$ in (121)-(123) so that the

cell membrane corresponds to $\rho = 1$.

$$\eta^2 \frac{\partial^2 \Phi}{\partial Z^2} + \Delta_{\tilde{D}} \Phi = 0 \text{ in } \Omega^{\text{int}}, \Omega^{\text{ext}}$$
(124)

$$-\frac{A^{(k)}}{\eta} \frac{\partial \Phi}{\partial \rho} = \theta \frac{\partial [\Phi]}{\partial \tau_V} + \alpha I_{\text{ion}}, \quad [\Phi] \equiv \Phi^{\text{int}} - \Phi^{\text{ext}} \text{ at } \rho = 1^{\pm}$$
 (125)

$$-A^{\text{ext}}\frac{\partial\Phi}{\partial\rho} = 0 \text{ at } \rho = \xi \tag{126}$$

where $\Delta_{\tilde{D}}$ denotes the rescaled Laplacian on $Z={\rm const.}$ We now expand Φ in powers of η^p in the following fashion:

$$\Phi = \Phi^0 + \eta^p \Phi^1 + \cdots \tag{127}$$

We let p=2 so that we obtain nontrivial expressions when the above substituted into (124):

$$\Delta_{\tilde{D}}\Phi^0 = 0 \tag{128}$$

$$\Delta_{\tilde{D}}\Phi^{0} = 0 \tag{128}$$

$$\frac{\partial^{2}\Phi^{0}}{\partial Z^{2}} + \Delta_{\tilde{D}}\Phi^{1} = 0 \tag{129}$$

Consider the boundary condition (125). Upon substitution of (127), we see that a distinguished limit can be obtained by taking $\alpha \sim \eta$. This is in fact, hardly surprising. In Section 3, we introduced α as the volume to surface ratio of the domain of interest. The dimensionless radius η is exactly equal to this ratio (up to a factor of order 1). We shall thus take $\eta = \alpha$. Therefore,

$$\frac{\partial \Phi^{0,(k)}}{\partial \rho} = 0 \text{ at } \rho = 1^{\pm}, \rho = \xi \tag{130}$$

$$-A^{(k)}\frac{\partial\Phi^{1}}{\partial\rho} = \frac{\theta}{\alpha}\frac{\partial[\Phi^{0}]}{\partial\tau_{V}} + I_{\text{ion at }\rho = 1^{\pm}, \quad \frac{\partial\Phi^{1}}{\partial\rho} = 0 \text{ at } \rho = \xi$$
 (131)

First of all, (128) with (130) tells us that Φ^0 is constant for fixed Z. In order to find the Z dependence of Φ^0 , we need to look at the next order, (129). The solvability of this equation with respect to Φ^1 requires that the following identities between an area and a line integral hold for each $Z = Z_0$.

$$\int_{\rho<1,Z=Z_0} \Delta_{\tilde{D}} \Phi^1 dA = \int_{\rho=1^-,Z=Z_0} \frac{\partial \Phi^1}{\partial \rho} ds$$
 (132)

$$\int_{1<\rho<\xi,Z=Z_0} \Delta_{\tilde{D}} \Phi^1 dA = -\int_{\rho=1^+,Z=Z_0} \frac{\partial \Phi^1}{\partial \rho} ds + \int_{\rho=\xi,Z=Z_0} \frac{\partial \Phi^1}{\partial \rho} ds \qquad (133)$$

where dA denotes an area integral and ds denotes a line integral. Applying the above to (129) and (131) we find that:

$$\pi A^{\text{int}} \frac{\partial^2 \Phi^{0,\text{int}}}{\partial Z^2} = 2\pi \frac{\theta}{\alpha} \frac{\partial [\Phi^0]}{\partial \tau_V} + \int_0^{2\pi} I_{\text{ion}} d\psi$$
 (134)

$$-\pi(\xi^2 - 1)A^{\text{ext}}\frac{\partial^2 \Phi^{0,\text{ext}}}{\partial Z^2} = 2\pi \frac{\theta}{\alpha} \frac{\partial [\Phi^0]}{\partial \tau_V} + \int_0^{2\pi} I_{\text{ion}} d\psi$$
 (135)

Dividing by the prefactors and adding the two expressions, we immediately obtain the cable equations:

$$G^{\text{eff}} \frac{\partial^2 [\Phi^0]}{\partial Z^2} = 2\pi \left(\frac{\theta}{\alpha} \frac{\partial [\Phi^0]}{\partial \tau_V} + I_{\text{ion}}(Z) \right)$$
(136)

$$\frac{1}{G^{\text{eff}}} = \frac{1}{\pi A^{\text{int}}} + \frac{1}{\pi (\xi^2 - 1) A^{\text{ext}}}, \quad I_{\text{ion}}(Z) = \frac{1}{2\pi} \int_0^{2\pi} I_{\text{ion}} d\psi$$
 (137)

We have thus succeeded in deriving the cable model. We note in particular that Z is measured with respect to the length scale L_0 , which we can now identify as the electrotonic length. The time variable τ_V is measured with respect to βT_0 which tells us that βT_0 is "diffusion" time scale for the membrane potential.

If $1 \ll \xi \ll \alpha^{-1} (r^{\text{int}} \ll r^{\text{ext}} \ll L_0)$, we can take the extracellular space to be an isopotential compartment and set $G^{\text{eff}} = \pi A^{\text{int}}$ without sacrificing the validity of the above cable equations. In dimensional terms, the above equations take the following familiar form:

$$\frac{1}{R} \frac{\partial^2 \phi_{\rm m}}{\partial z^2} = p_{\rm m} \left(C_{\rm m} \frac{\partial \phi_{\rm m}}{\partial t} + i_{\rm ion} \right), \quad p_{\rm m} = 2\pi r^{\rm int}$$
 (138)

$$R = R^{\text{int}} + R^{\text{ext}} \tag{139}$$

$$\frac{1}{R^{\text{int}}} = S^{\text{int}} \sum_{i=1}^{N} \frac{(qz_i)^2 D_i}{k_B T} c_i^{\text{int}}, \quad S^{\text{int}} = \pi (r^{\text{int}})^2$$
 (140)

$$\frac{1}{R^{\text{ext}}} = S^{\text{ext}} \sum_{i=1}^{N} \frac{(qz_i)^2 D_i}{k_B T} c_i^{\text{ext}}, \quad S^{\text{ext}} = \pi ((r^{\text{ext}})^2 - (r^{\text{int}})^2)$$
(141)

Here, $\phi_{\rm m}$ is the membrane potential and $i_{\rm ion}$ is the dimensional transmembrane current, averaged over the Z =const cross-section of the membrane.

We note that the above derivation of the cable model did not assume an axisymmetric solution to the equations. The axisymmetry, or more strongly, the constancy of the electrostatic potential for each Z cross-section is a consequence purely of the scaling relations. Related to this is the observation that the above can be generalized to arbitrary cross-sectional geometry. All we have used is the divergence theorem as applied to each cross section; we have made essentially no use of the fact that the cross-section was a disc.

9 Numerical Validation of Asymptotics

In this section we shall test the behavior of the electroneutral model against that of the Poisson model by way of numerical simulations. We confine numerical validation to test cases which reduce to one dimensional computations. This is because the Poisson model requires extremely small time steps and spatial resolution, which makes it computationally overwhelming to compare the two models in a full two or three dimensional setting. We have considered two geometrical situations, one spherical and one planar, but we shall only discuss

the spherical case, since results for the planar calculations are very similar to the spherical [16].

We take a spherical cell of radius l. Let the center of the cell be the origin, and let r be the radial coordinate. We seek solutions to the equations (electroneutral or Poisson) which depend only on the radial coordinate r. We have thus a one dimensional problem. The region characterized by r < l is the intracellular space. We confine our simulation domain to r < 2l and impose noflux boundary conditions at r=2l. Thus, our extracellular space is the region l < r < 2l. The l we use here as the radius of the cell is to be identified with the l we introduced as the volume to surface ratio in Section 3.

We now rescale length so that L_0 , (14), is the representative length scale. The dimensionless cell radius is now $\alpha = \frac{l}{L_0}$. We shall continue to use r as our dimensionless coordinate. Thus, $r < \alpha$ is the intracellular region and $\alpha < 1$ $r < 2\alpha$ is the extracellular region. We use the finite volume method to perform the simulations. We subdivide the computational region into spherical shells indexed by k. The thickness of the spherical shells is made to be smaller near the membranes so as to resolve the space charge layer and the fast diffusion layer. The details of the numerical scheme as explained in [16] will be reported elsewhere.

We consider four ionic species with the following dimensionless diffusion coefficient and valence.

$$\tilde{D}_1 = 2,$$
 $\tilde{D}_2 = 1/2,$ $\tilde{D}_3 = 1,$ $\tilde{D}_4 = 1/2$ (142)
 $z_1 = 1,$ $z_2 = 1,$ $z_3 = -1,$ $z_4 = 2$ (143)

$$z_1 = 1,$$
 $z_2 = 1,$ $z_3 = -1,$ $z_4 = 2$ (143)

Recall from Section 3 that β, α and θ^* are the dimensionless parameters that characterize the system of equations. The parameter $\theta^* = 10^{-2} (\text{cf } (23) \text{ has a})$ fixed value. We consider three pairs of parameter values:

$$(\beta, \alpha) = (10^{-3}, 10^{-2}), (10^{-3.5}, 10^{-1.5}), (10^{-4}, 10^{-1})$$
 (144)

We expect the electroneutral model to be a good approximation to the Poisson model for small values of β . We thus take β to be slightly larger than the typical values $\beta = 10^{-4} \sim 10^{-6}$ to perform a more stringent test of validity of the electroneutral model.

We shall start our simulation at time $\tau_V = -T_r$ where T_r is positive. The reason for this will become clear shortly. For the electroneutral model, we set the initial conditions at $\tau_V = -T_r$ for C_i to be:

$$C_1(r, -T_r) = 1 + C_g(2|\alpha - r| - \alpha)$$
 $C_2(r, -T_r) = 2 - C_1(r, -T_r)$ (145)

$$C_3(r, -T_r) = 2 (146)$$

$$C_4(r, -T_r) = 10^{-6} \text{ for } r < \alpha$$
 $C_4(r, -T_r) = 10^{-3} \text{ for } r > \alpha$ (147)

$$\tilde{\rho}_0(r) = -\sum_{i=1}^4 z_i C_i(r, -T_r)$$
(148)

We let $C_g = 0.9$ so that there is a steep initial gradient of the ionic concentrations. The very small initial values of C_4 are motivated by calcium concentration profiles in physiological systems. At the membrane boundary, we must specify $\Phi_{\rm m}(\tau_V)$ and $\lambda_i(\alpha\pm,\tau_V)$ at $\tau_V = -T_r$.

$$\Phi_{\rm m}(-T_r) = \Phi(\alpha -) - \Phi(\alpha +) = -\frac{\theta^*}{\theta}$$
(149)

$$\lambda_i(\alpha \pm, -T_r) = \frac{z_i^2 C_i(\alpha \pm, -T_r)}{\sum_{k=1}^4 z_k^2 C_k(\alpha \pm, -T_r)}$$
(150)

where $\alpha+$ and $\alpha-$ denote the $r>\alpha$ and the $r<\alpha$ faces of the membrane respectively.

For the Poisson model, we need to specify the initial ionic concentrations. Given initial conditions for the electroneutral model, we set the corresponding initial conditions for the Poisson model to be:

$$C_i(r, -T_r) = C_i^{\text{electroneutral}}(r, -T_r) - \frac{4\pi\alpha^2 \lambda_i(\alpha - T_r)\theta^*}{z_i(4\pi/3)\alpha^3} \text{ if } r < \alpha$$
 (151)

$$C_i(r, -T_r) = C_i^{\text{electroneutral}}(r, -T_r) + \frac{4\pi\alpha^2 \lambda_i(\alpha + -T_r)\theta^*}{z_i(4\pi/3)((2\alpha)^3 - \alpha^3)} \text{ if } r > \alpha$$
 (152)

The rationale for setting C_i as above is the following. The initial conditions for the electroneutral model says that each ionic species contributes a surface charge amount $\lambda_i \theta^*$ times the membrane area $4\pi\alpha^2$. To set the initial conditions for the Poisson model, we need to take into account this contribution. We spread this surface charge contribution uniformly throughout the intracellular and extracellular spaces.

The problem with this initialization is that the excess charge should not be uniformly distributed but should be distributed so that the concentration profile shows a space charge layer near the membrane. Since we do not know the exact details of this concentration profile a priori, we let the Poisson system relax between $-T_r < \tau_V < 0$ to a state where the bulk is approximately electroneutral and the excess charge accumulates near the membrane. During this period, we set the membrane current equal to zero and the dimensionless diffusion coefficients to be equal to $\tilde{D}_i = 1$. We let $T_r = 10\beta$, 10 times the charge relaxation time.

At time t=0 we turn on a current of constant strength α carried by ionic species i=4 flowing from the extracellular space $(r>\alpha)$ into the intracellular space $(r<\alpha)$. We let our simulations last until $\tau_V=T_e=2\frac{\theta^*}{\alpha}$, which is approximately the time it takes to depolarize the dimensionless membrane potential from -1 to 1. We place $N_r=200$ computational voxels in both the extracellular and intracellular regions (a total of $2N_r=400$ voxels), and we take the time step $\Delta\tau_V=\frac{\beta}{5}$. Using a larger time step led to numerical instabilities with the Poisson model. A snapshot from a sample run of this simulation is shown in Figure 3.

Raw data produced by the electroneutral model do not capture the ionic concentration or electrostatic potential profiles in the Debye layer. But it is

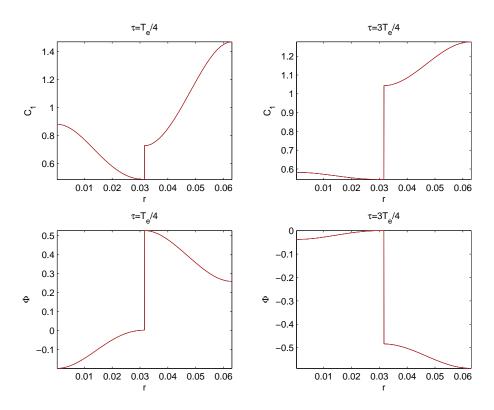


Figure 3: Snapshots of simulation when $(\beta, \alpha) = (10^{-3.5}, 10^{-1.5})$. Three curves, the Poisson computation, the raw data and modified data from the electroneutral models are plotted. The three curves are virtually indistinguishable.

possible to produce an approximate profile in the Debye layer based on the asymptotic calculations we performed. We can see from (73) and (74) that the Debye layer has the effect of adding a correction term to C_i and Φ that decays exponentially with distance from the membrane. The decay length and the magnitude of the correction term can be approximated by the values of Φ , C_i evaluated at the membrane and λ_i . For Φ , we modify the raw data from the electroneutral model as follows:

$$\Phi^{\text{modified}} = \Phi + \delta \Phi \tag{153}$$

$$\delta\Phi = -\frac{\theta\Phi_{\rm m}}{\Gamma^{+}} \exp\left(-\Gamma^{+} \frac{|r-\alpha|}{\beta}\right) \text{ if } r > \alpha \tag{154}$$

$$= -\frac{\theta \Phi_{\rm m}}{\Gamma^{-}} \exp\left(-\Gamma^{-} \frac{|r - \alpha|}{\beta}\right) \text{ if } r < \alpha \tag{155}$$

$$\Gamma^{\pm} = \sqrt{z_i^2 C_i(r = \alpha \pm)} \tag{156}$$

where the double signs correspond in the last line. For the ionic concentrations C_i ,

$$C_i^{\text{modified}} = C_i + \delta C_i \tag{157}$$

$$\delta C_i = -\frac{\lambda_i(\alpha^+)\theta\Phi_{\rm m}\Gamma^+}{z_i}\exp\left(-\Gamma^+\frac{|r-\alpha|}{\beta}\right) \text{ if } r > \alpha \qquad (158)$$

$$= -\frac{\lambda_i(\alpha^-)\theta\Phi_{\rm m}\Gamma^-}{z_i}\exp\left(-\Gamma^-\frac{|r-\alpha|}{\beta}\right) \text{ if } r < \alpha$$
 (159)

We note that δC_i and $\delta \Phi$ are expressed entirely in terms of raw data computed with the electroneutral model. When comparing the electroneutral model with the Poisson model, we shall use the above modified profile.

In order to quantify the difference between the electroneutral and Poisson calculations, we introduce the following norm on the computational domain. Suppose the quantity u is defined at each voxel indexed by k. We define the discrete p-norm as:

$$||u||_{L^p} = \left(\frac{\sum_{k=1}^{2N_r} |V_k| |u_k|^p}{\sum_{k=1}^{2N_r} |V_k|}\right)^{1/p}, \quad 1 \le p < \infty$$
 (160)

$$||u||_{L^{\infty}} = \max_{k} |u_k| \tag{161}$$

where u_k is the value of u at the k-th voxel and V_k is the volume of the k-th voxel. In defining the L^p norm in (160), we have divided by a normalizing factor so that $||u||_{L^p}$ gives an average measure of the " L^p deviation". In particular, $\lim_{p\to\infty}||u||_{L^p}=||u||_{L^\infty}$. For ionic concentrations C_i , we use the relative error:

$$\mathcal{E}_{p}(C_{i}) = \frac{\left\| C_{i}^{\text{electroneutral}} - C_{i}^{\text{Poisson}} \right\|_{L^{p}}}{\left\| C_{i}^{\text{Poisson}} \right\|_{L^{p}}}$$
(162)

(β, α)	L^p	$\mathcal{M}_p(C_1)$	$\mathcal{M}_p(C_2)$	$\mathcal{M}_p(C_3)$	$\mathcal{M}_p(C_4)$	$\mathcal{M}_p(\Phi)$
(β_1, α_1)	L^1	3.79×10^{-5}	6.98×10^{-5}	6.56×10^{-5}	1.55×10^{-4}	2.73×10^{-5}
	L^2	4.67×10^{-5}	8.43×10^{-5}	7.71×10^{-5}	1.74×10^{-4}	5.95×10^{-5}
	L^{∞}	2.87×10^{-4}	2.35×10^{-4}	2.86×10^{-4}	5.85×10^{-4}	1.40×10^{-4}
(β_2, α_2)	L^1	7.20×10^{-5}	2.76×10^{-5}	3.25×10^{-5}	2.99×10^{-5}	4.70×10^{-5}
	L^2	8.46×10^{-5}	4.40×10^{-5}	5.47×10^{-5}	5.15×10^{-5}	1.03×10^{-4}
	L^{∞}	2.32×10^{-4}	1.57×10^{-4}	1.89×10^{-4}	2.06×10^{-4}	1.71×10^{-4}
(β_3, α_3)	L^1	1.74×10^{-6}	1.79×10^{-6}	4.25×10^{-7}	3.31×10^{-7}	1.62×10^{-5}
	L^2	2.58×10^{-6}	2.98×10^{-6}	1.97×10^{-6}	1.71×10^{-6}	4.16×10^{-5}
	L^{∞}	1.19×10^{-5}	8.59×10^{-5}	7.53×10^{-5}	1.57×10^{-4}	6.95×10^{-5}

Table 1: \mathcal{M}_p values for spherical geometry for three computational experiments with different values of β and α . Here, $(\beta_1, \alpha_1) = (10^{-3}, 10^{-2}), (\beta_2, \alpha_2) = (10^{-3.5}, 10^{-1.5}), (\beta_3, \alpha_3) = (10^{-4}, 10^{-1}).$

This is a more stringent criteria than using the absolute error (without the denominator in the above) especially for C_4 whose initial concentration is very small.

For the electrostatic potential Φ , it does not make sense to use the relative error since an arbitrary constant constant may be added to Φ . We thus, measure the error in Φ as:

$$\mathcal{E}_{p}(\Phi) = \min_{c_{p} \in \mathbb{R}} \left\| \Phi^{\text{electroneutral}} - \Phi^{\text{Poisson}} + c_{p} \right\|_{L^{p}}$$
 (163)

Note that it is reasonable to consider the absolute error in Φ , since Φ is dimensionless, and its typical magnitude is 1. Though $\mathcal{E}_p(\Phi)$ may in general be difficult to compute in closed form, this is possible when $p=1,2,\infty$, values of p for which we shall compute $\mathcal{E}_p(\Phi)$ in the following.

In table (1), we list the $\mathcal{M}_p(u)$, $u = \Phi$ or C_i where:

$$\mathcal{M}_p(u) = \max_{0 \le \tau_V \le T_e} \mathcal{E}_p(u)$$
 (164)

We see that for all parameter ranges tested here, the error falls within order 10^{-4} . This translates to a 0.01% error in C_i and an error of about 0.025mV in the dimensional electrostatic potential ϕ . In cases $(\beta, \alpha) = (10^{-3}, 10^{-2})$ or $(10^{-3.5}, 10^{-1.5})$, α is comparable in magnitude to $\sqrt{\beta}$. The degree of correspondence exhibited for these two cases is remarkable since the asymptotic calculations were performed under the assumption that $\alpha = \mathcal{O}(1)$ with respect to $\sqrt{\beta}$. It is notable that the relative error is order 10^{-4} even for C_4 which has a vanishing small concentration. This tells us that we may include ions of very small concentration into our model framework, which is significant if we are to include calcium dynamics [1].

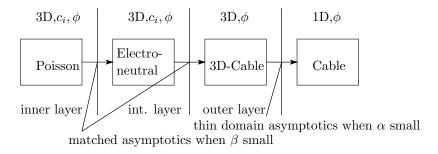


Figure 4: Hierarchy of Electrophysiology Models

We see that $\mathcal{M}_{\infty}(C_i)$ is significantly larger than $\mathcal{M}_1(C_i)$ or $\mathcal{M}_2(C_i)$. Despite the modification we performed on the raw data for the electroneutral model, the deviation between the electroneutral and Poisson models are still concentrated at the Debye layer. Since this layer is very small in volume, the L^1 and L^2 errors are not significantly affected.

10 Conclusion

The Poisson model, a candidate model for three dimensional cellular electrical activity, is computationally difficult to deal with, because of the presence of the Debye layer which develops at membrane interfaces. We introduced the electroneutral model as a computationally amenable and biophysically natural model of cellular electrical activity. We use asymptotic calculations to demonstrate the validity of the electroneutral model. The matched asymptotic calculations required the introduction of two boundary layers at the membrane, the inner Debye layer and the intermediate fast diffusion layer. We show that the electroneutral model gives an approximation to the Poisson model in the intermediate and outer layers as the small parameter β , the ratio between the Debye length and the electroneutral model gives an excellent approximation to the Poisson model.

We have also succeeded in systematically deriving the standard cable model from the Poisson model or the electroneutral model. The above derivation can be viewed as a significant step toward a full study of the validity of the cable model, an issue of fundamental importance to computational neuroscience [24]. In the course of this derivation, we have seen that there are models of intermediate complexity in between the Poisson or electroneutral model and the cable model (Figure 4). The 3D-cable model and the simplified 3D-cable model describe the dynamics of the electrostatic potential in a three dimensional setting, but ignores the dynamics of ionic concentrations. We believe that each of these models will be suitable in certain situations, the Poisson or electroneutral models being the most detailed.

When $l_m \sim \sqrt{\beta}$ matching at the inner-intermediate layer interface resulted

in an additional surface drift-diffusion term along the membrane (cf. 86). It would be interesting to incorporate this into the electroneutral model and see whether this term leads to a significant difference in the behavior of the model. When $l_m \sim \sqrt{\beta}$, matching between the intermediate and outer layers is probably challenging, since ionic fluxes parallel to the membrane will be comparable in magnitude to fluxes perpendicular to the membrane. The intermediate layer will lose its one-dimensional structure. We believe that the electroneutral model correctly captures the dynamics of ionic concentrations in the slow diffusion time scale (time scale T_0). This claim is supported in part by the fact that the conservation relation, equation (41) is satisfied. We plan to investigate these points in future work.

11 Appendix

The calculations presented below are identical to the one that appears in [15], except for notational differences and some additions. We would like to solve (68), (69) under the boundary conditions (70)-(72). Since this is a one dimensional boundary value problem, we shall think of Φ^{b0} and C_i^{b0} as functions only of ξ_1^b and do not explicitly write their dependence on ξ_2^b or ξ_3^b .

Equation (68) can be integrated easily to obtain

$$C_i^{b0}(\xi_1^b) = C_i^{b0}(\infty) \exp\left(-z_i(\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty))\right). \tag{165}$$

This equation can be substituted into (69) to yield:

$$-\frac{\partial^2 \Phi^{b0}}{\partial \xi_1^{b^2}} = \left(\tilde{\rho}_0 + \sum_{i=1}^N z_i C_i^{b0}(\infty) \exp\left(-z_i (\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty))\right)\right).$$
 (166)

Here we use an approximation to linearize the above Poisson-Boltzmann equation. We suppose

$$|z_i(\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty))| \ll 1.$$
 (167)

This can be justified if θ^* is small, as was shown in [15]. The smallness of θ^* states that the amount of charge that may accumulate at the membrane is small. The smallness of this charge accumulation guarantees that the deviation of Φ in the inner layer from its value in the intermediate layer is small. Given that (167) is a valid assumption, we linearize (166) to find:

$$C_i^{b0}(\xi_1^b) = C_i^{b0}(\infty) \left(1 - z_i(\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty))\right)$$
 (168)

$$\frac{\partial^2}{\partial \xi_1^{b^2}} (\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty)) = \Gamma^2(\Phi^{b0}(\xi_1^b) - \Phi^{b0}(\infty))$$
 (169)

$$\Gamma^2 = \sum_{i=1}^{N} z_i^2 C_i^{b0}(\infty) = \sum_{i=1}^{N} z_i^2 C_i^{a0}(0), \quad \Gamma > 0.$$
 (170)

Here $C_i^{a0}(0)$ is shorthand for $C_i^{a0}(\xi_1^a=0)$. To derive (168) and (169), we have used

$$\tilde{\rho}_0 + \sum_{i=1}^N z_i C_i^{b0}(\infty) = \tilde{\rho}_0 + \sum_{i=1}^N z_i C_i^{a0}(0) = 0$$
(171)

which follows as a consequence of (56) and the matching condition (71). Solving (169) with (69) and (72),

$$\Phi^{b0}(\xi_1^b) = \Phi^{a0}(0) - \frac{\tilde{\sigma}}{\Gamma} \exp(-\Gamma \xi_1^b)$$
 (172)

where $\Phi^{a0}(0)$ is shorthand for $\Phi^{a0}(\xi_1^a=0)$ and $\tilde{\sigma}$ is equal to

$$\tilde{\sigma} = \theta^*(\Phi^{b0}(0) - \Phi^{(l),b0}(0)). \tag{173}$$

Hence, according to (168) and the matching condition (71),

$$C_i^{b0}(\xi_1^b) = C_i^{a0}(0) \left(1 + \frac{z_i \tilde{\sigma}}{\Gamma} \exp(-\Gamma \xi_1^b) \right)$$
 (174)

We note that $\tilde{\sigma}$ is the total excess charge found in the inner layer, as can be seen as follows. The excess charge contributed by the *i*-th species of ion $\tilde{\sigma}_i$ can be computed using expression (174) as:

$$\tilde{\sigma}_{i} \equiv \int_{0}^{\infty} z_{i} (C_{i}^{b0}(\xi_{1}^{b}) - C_{i}^{a0}(0)) d\xi_{1}^{b} = \frac{z_{i}^{2} C_{i}^{a0}(0)}{\Gamma^{2}} \tilde{\sigma} \equiv \tilde{\lambda}_{i} \tilde{\sigma}$$
 (175)

From (75), we see that $\tilde{\lambda}_i$ is given by:

$$\tilde{\lambda}_i = \frac{z_i^2 C_i^{a0}(0)}{\Gamma^2} = \frac{z_i^2 C_i^{a0}(0)}{\sum_{i'=1}^N z_{i'}^2 C_{i'}^{a0}(0)}$$
(176)

We immediately conclude that $\sum_{i=1}^{N} \tilde{\lambda}_i = 1$. The total excess charge is given by summing $\tilde{\sigma}_i$ in i.

$$\sum_{i=1}^{N} \tilde{\sigma}_{i} = \left(\sum_{i=1}^{N} \tilde{\lambda}_{i}\right) \tilde{\sigma} = \tilde{\sigma}.$$
(177)

The factor $\tilde{\lambda}_i$ thus represents the fraction of excess charge contributed by the *i*-th species of ion.

We now have the solutions C_i^{b0} and Φ^{b0} except that $\tilde{\sigma}$ is expressed in terms of Φ^{b0} . We shall now express $\tilde{\sigma}$ in terms of $C_i^{a0}(0)$ and $\Phi^{a0}(0)$. First, we observe by substituting $\xi_1^b = 0$ in (172) that

$$\tilde{\sigma} = \Gamma(\Phi^{a0}(0) - \Phi^{b0}(0)). \tag{178}$$

We next rewrite $\Phi^{a0}(0) = \Phi^{(k),a0}(0), \Phi^{b0}(0) = \Phi^{(k),b0}(0), \tilde{\sigma} = \tilde{\sigma}^{(k)}, \Gamma = \Gamma^{(k)}$ and consider (173) and (178) as well as the corresponding expressions on the other

side of the membrane (the $\Omega^{(l)}$ side).

$$\tilde{\sigma}^{(k)} = \theta^*(\Phi^{(k),b0}(0) - \Phi^{(l),b0}(0)) \tag{179}$$

$$\tilde{\sigma}^{(k)} = \Gamma^{(k)}(\Phi^{(k),a0}(0) - \Phi^{(k),b0}(0)) \tag{180}$$

$$\tilde{\sigma}^{(l)} = \theta^* (\Phi^{(l),b0}(0) - \Phi^{(k),b0}(0)) \tag{181}$$

$$\tilde{\sigma}^{(l)} = \Gamma^{(l)}(\Phi^{(l),a0}(0) - \Phi^{(l),b0}(0)) \tag{182}$$

After some algebra, we find,

$$\tilde{\sigma}^{(k)} = -\tilde{\sigma}^{(l)} = \theta(\Phi^{(k),a0}(0) - \Phi^{(l),a0}(0)) \tag{183}$$

$$\frac{1}{\theta} = \frac{1}{\theta^*} + \frac{1}{\Gamma^{(k)}} + \frac{1}{\Gamma^{(l)}}.$$
(184)

The meaning of relation (184) becomes clear once this is written in dimensional terms:

$$\frac{1}{C_{\rm m}} = \frac{1}{C_{\rm m}^*} + \frac{1}{\epsilon \gamma^{(k)}} + \frac{1}{\epsilon \gamma^{(l)}}.$$
 (185)

where $\Gamma = \gamma r_d$. This relation states that the effective membrane capacitance $C_{\rm m}$ can be computed as the intrinsic membrane capacitance $C_{\rm m}^*$ and the capacitance of the space charge layers $\epsilon \gamma^{(k)}, \epsilon \gamma^{(l)}$ in series. We note that in (184), θ^* is small in magnitude whereas $\Gamma^{(k)}$ and $\Gamma^{(l)}$ are order 1. Therefore, $\theta \approx \theta^*$, and $C_{\rm m} \approx C_{\rm m}^*$.

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In [15], $\tilde{\lambda}_i$ was used in place of λ_i in (38). This expression substituted into the boundary condition (35) yields:

$$z_{i}\mathbf{F}_{i}\cdot\mathbf{n}^{(kl)} = \theta \frac{\partial \tilde{\lambda}_{i}\Phi^{(kl)}}{\partial \tau_{V}} + \alpha \tilde{j}_{i}$$
(186)

By following the same procedure as in Section 7, it can be easily seen that (32)-(34) together with (186) has the desired approximation properties. Unfortunately, this system is ill-posed.

We shall exhibit the ill-posed behavior in a simple situation. Assume we have two regions, one intracellular and one extracellular. Let there be no transmembrane currents. Suppose that there are two positive ionic species with identical physical properties: the valence and diffusion coefficient are equal and scaled to 1. Assume moreover that the positive ionic charges are counterbalanced completely by a spatially uniform immobile charge of magnitude -1. Equations (32)-(34) and (186) become:

$$0 = \frac{\partial C_i}{\partial \tau_V} + \beta \nabla_{\mathbf{X}} \cdot \mathbf{F}_i \tag{187}$$

$$\mathbf{F}_i = -\left(\nabla_{\mathbf{X}} C_i + C_i \nabla_{\mathbf{X}} \phi\right) \tag{188}$$

$$1 = C_1 + C_2 \tag{189}$$

Let **n** be the outward normal pointing from intracellular to extracellular and the membrane potential $[\Phi] = \Phi^{i} - \Phi^{e}$. The boundary conditions on the intracellular and extracellular sides of the membrane are respectively:

$$\frac{\partial \tilde{\sigma}_{i}^{(i)}}{\partial \tau_{V}} = \mathbf{F}_{i}^{i} \cdot \mathbf{n} \qquad \qquad \tilde{\sigma}_{i}^{(i)} = C_{i}^{i} \theta[\Phi]$$
 (190)

$$\frac{\partial \tilde{\sigma}_{i}^{(e)}}{\partial \tau_{V}} = -\mathbf{F}_{i}^{e} \cdot \mathbf{n} \qquad \qquad \tilde{\sigma}_{i}^{(e)} = -C_{i}^{e} \theta[\Phi]$$
 (191)

We solve the above with the following initial condition:

$$[\Phi](\mathbf{X},0) = \Phi_0 \neq 0 \tag{192}$$

$$C_i(\mathbf{X}, 0) = C_{i,0}(\mathbf{X}), C_{1,0}(\mathbf{X}) + C_{2,0}(\mathbf{X}) = 1$$
 (193)

We thus assume that the membrane potential is initially constant (= Φ_0) throughout, whereas the ionic concentration may be nonuniform. From a physical standpoint, the system should relax to an equilibrium state in which the ionic concentration gradients have disappeared.

We now show that this initial value problem is ill-posed. Summing equation (187) in i and using (189) one immediately concludes:

$$\Delta_{\mathbf{X}}\Phi = 0 \tag{194}$$

To obtain boundary conditions for the above Laplace equation, we take the summation of both (190) and (191) in i to obtain:

$$\theta \frac{\partial [\Phi]}{\partial \tau_V} = -\frac{\partial \Phi^{i}}{\partial \mathbf{n}} = \frac{\partial \Phi^{e}}{\partial \mathbf{n}}$$
 (195)

The equations (194), (195), (192) together form an initial value problem for Φ and this has a unique solution: Φ does not change, and is constant within each spatial region.

We now turn to C_i . From equation (187) we obtain:

$$\frac{\partial C}{\partial \tau_V} = \beta \Delta_{\mathbf{X}} C, \quad C = C_1, \quad C_2 = 1 - C_1 \tag{196}$$

where we used $\Phi = \text{const}$ within each region. The boundary conditions are:

$$\theta \Phi_0 \frac{\partial C^{i}}{\partial \tau_V} = -\frac{\partial C^{i}}{\partial \mathbf{n}} \tag{197}$$

$$\theta \Phi_0 \frac{\partial \dot{C}^{e}}{\partial \tau_V} = -\frac{\partial \dot{C}^{e}}{\partial \mathbf{n}} = \frac{\partial \dot{C}_1^{e}}{\partial \mathbf{n}^{e}}$$
(198)

where $\mathbf{n}^{\mathrm{e}} = -\mathbf{n}$ is the normal pointing from the extracellular to intracellular space. The evolution equations for the concentrations completely decouple into two separate diffusion problems for which the boundary conditions have the form $k\frac{\partial C}{\partial t} + \frac{\partial C}{\partial \mathbf{n}} = 0$. When k is negative, this problem is ill-posed, as was

formally established recently in [25]. We see from (197) and (198) that one of the diffusion problems is bound to be ill-posed unless $\Phi_0 = 0$ identically. Here, we shall illustrate this by way of a simple example.

Consider the above in $\mathbf{X} = (X,Y) \in \mathbb{R}^2$ and let the upper and lower half planes correspond to the intracellular and extracellular spaces respectively. We let $\Phi_0 = -1$, and seek solutions to (196) and (197) in the upper half plane subject to the condition that C decays to 0 as $Y \to \infty$. We obtain a family of solutions parametrized by l > 1:

$$C_l(\mathbf{X}, \tau_V) = \exp\left(\frac{l}{\beta\theta^2}\tau_V - \frac{l}{\beta\theta}Y\right)\sin\left(\frac{X}{\beta\theta}\sqrt{l^2 - l}\right)$$
 (199)

If the initial data contain any non-zero frequency component along the membrane, this component will grow exponentially, the exponent being roughly proportional to the wave number. Thus, the problem is ill-posed.

This instability is most probably a generic feature of the equations not confined to the simple situation above. The instability is caused by the $\frac{\partial C}{\partial \tau_V}$ term in the boundary conditions, which came from the $\frac{\partial \tilde{\lambda}_i}{\partial \tau_V}$ term. In general, the boundary conditions are complicated functions of the ionic concentrations, but the leading order terms $\frac{\partial C}{\partial \tau_V}$ and $\frac{\partial C}{\partial \mathbf{n}}$ will dominate in stability considerations. Since the membrane potential $[\Phi]$ is multiplying the $\frac{\partial \tilde{\lambda}_i}{\partial \tau_V}$ term, the diffusion problem is bound to be ill-posed at least on one side of the membrane.

We now take a closer look at the above situation in an attempt to obtain a well-posed system of equations. Equation (199) tells us that the time constant associated with exponential growth in the ill-posed solution is at most $\beta\theta^2$, since l>1. This time duration belongs to the charge relaxation regime (actually even faster, by a factor of θ^2). The spatial scale that appears in (199) is on the order of the Debye length or shorter. The instabilities that develop are thus inconsistent with our ansatz that the evolution of C_i and Φ do not possess spatiotemporal scales associated with charge relaxation in the space charge layer.

We would like to remove the explosive behavior caused by $\frac{\partial \tilde{\lambda}_i}{\partial \tau_V}$. We propose the following fix. Let λ_i be a quantity that evolves according to the following differential equation.

$$\frac{\partial \lambda_i}{\partial \tau_V} = \frac{\tilde{\lambda}_i - \lambda_i}{\tau_\lambda}, \quad \tau_\lambda = \beta, \qquad \tilde{\lambda}_i = \frac{z_i^2 C_i}{\sum_{i'=1}^N z_{i'}^2 C_{i'}}$$
(200)

Thus λ_i tracks $\tilde{\lambda}_i$ with a time lag $\tau_{\lambda} = \beta$, the charge relaxation time. This has the effect of filtering out any temporal structure that exists on a time scale smaller than $\mathcal{O}(\beta)$. Instead of $\tilde{\lambda}_i$, we shall use λ_i in (186). We note that since the relaxation time constant $(=\beta)$ is taken equal for all ionic species, the important relation $\sum_i \lambda_i = 1$ holds true as long as this relation is satisfied at the initial time (see equation (40)).

It is important to demonstrate that this replacement does not change the formal approximation properties of the original system of equations. We can

find the discrepancy between λ_i and $\tilde{\lambda}_i$ as follows. We can solve (200) so that:

$$\lambda_i(\tau_V) = \lambda_i(0) \exp\left(-\tau_V/\beta\right) + \frac{1}{\beta} \int_0^{\tau_V} \tilde{\lambda}_i(s) \exp\left(\frac{s - \tau_V}{\beta}\right) ds \tag{201}$$

If τ_V is order 1, expanding $\lambda_i(s)$ around τ_V , one can easily see that:

$$\lambda_{i}(\tau_{V}) = \tilde{\lambda}_{i}(0) \exp\left(-\tau_{V}/\beta\right) + \tilde{\lambda}_{i}(\tau_{V}) \left(1 - \exp\left(-\tau_{V}/\beta\right)\right) + \beta \frac{\partial \tilde{\lambda}_{i}}{\partial \tau_{V}}(\tau_{V}) \left(1 - \exp\left(-\tau_{V}/\beta\right)\right) + \cdots$$
(202)

We see that

$$\lambda_i(\tau_V) = \tilde{\lambda}_i(\tau_V) + \mathcal{O}(\beta) \tag{203}$$

as long as $\frac{\partial \tilde{\lambda}_i}{\partial \tau_V}$ is $\mathcal{O}(1)$. Likewise,

$$\frac{\partial \lambda_{i}}{\partial \tau_{V}}(\tau_{V}) = -\frac{1}{\beta} \tilde{\lambda}_{i}(0) \exp\left(-\tau_{V}/\beta\right) + \frac{\partial \tilde{\lambda}_{i}}{\partial \tau_{V}} \left(1 - \exp\left(-\tau_{V}/\beta\right)\right)
+ \beta \frac{\partial^{2} \tilde{\lambda}_{i}}{\partial \tau_{V}^{2}}(\tau_{V}) \left(1 - \exp\left(-\tau_{V}/\beta\right)\right) + \cdots$$
(204)

from which we find that

$$\frac{\partial \lambda_i}{\partial \tau_V}(\tau_V) = \frac{\partial \tilde{\lambda}_i}{\partial \tau_V}(\tau_V) + \mathcal{O}(\beta)$$
 (205)

as long as $\frac{\partial^2 \tilde{\lambda}_i}{\partial \tau_V^2}$ is $\mathcal{O}(1)$. It is also possible to show that the error is $\mathcal{O}(\beta)$ when $\tau_V = \mathcal{O}(\beta)$ provided $\lambda_i(0) = \tilde{\lambda}_i(0)$. Since λ_i and $\frac{\partial \lambda_i}{\partial \tau_V}$ follow $\tilde{\lambda}_i$ and $\frac{\partial \tilde{\lambda}_i}{\partial \tau_V}$ to order $\mathcal{O}(\beta)$, replacing (186) with (200) will not alter the formal approximation properties of the ill-posed model.

Now we perform the same half plane analysis for the model we just proposed as was done for the ill-posed system. We take τ_{λ} in (200) as a parameter for now, and see what values of τ_{λ} will remove the instability. The expression corresponding to (199) is:

$$C_l(\mathbf{X}_V, \tau_V) = \exp(l\tau_V - mY^a)\sin(kX^a)$$
(206)

$$k^2 = m^2 - l, \quad m = \frac{\sqrt{\beta}\theta l}{\tau_{\lambda}l + 1} \tag{207}$$

Exponential growth corresponds to l > 0. We would therefore like to make sure that the following equation for l does not have a positive solution for any real k.

$$\left(\frac{\sqrt{\beta}\theta l}{\tau_{\lambda}l+1}\right)^2 - l = k^2 \tag{208}$$

This is equivalent to showing that the left hand side of the above is non positive when $l \ge 0$. Note that $l \ge 0$ implies:

$$\left(\frac{\sqrt{\beta}\theta l}{\tau_{\lambda}l+1}\right)^{2} - l = \frac{\beta\theta^{2}l^{2}}{(\tau_{\lambda}l+1)^{2}} - l \le \left(\frac{\beta\theta^{2}}{4\tau_{\lambda}} - 1\right)l \tag{209}$$

Therefore, $\tau_{\lambda} = \beta$ is more than adequate to make the above expression non positive, since θ is a small number much less than 1. We thus see that for the above situation in which model the system (32)-(34), (186) fails, the new model is stable.

What we have done is to add a stabilizing term to an asymptotically correct but ill-posed system. The situation here is analogous to having a consistent but unstable numerical discretization for an evolution equation. In such cases, one often adds to the numerical scheme a stabilizing term (e.g. small diffusive correction) whose order is small so that it does not alter the consistency of the scheme [14].

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