One view print: The determinant provides an explicit formla" for each entry of A-1 and A-16 (recall MM- of linear eg "s.). Mes for diterminants!

(1) Test for invertibility: If det (A) = 0 then A is Ringular. If det (A) +0 then A is investible.

(In the next chapter we want to understand let (A-DI) hetter which is a polynomial of degre n in I and has a nots-)

(2) Geometry: The det (A) is the volume of a hox in an W-dimensional space. The edge are the character sows. The columns give a different box with the same volume.

(991,912,913) (a21, 922, a23)

volume = det (A)

(3) Formula for each pivot: determinat = ± (product of the pivoh)

(4) Independence Dependence of A-16 on each clement of 6: If we change just one parameter then in an expt/eq. then the ent referents in A-1 is a radio of determinants.

- There are more than one way to define a determinate.
- what matters for us are the algebraic properties that a determinant forces.

The three most basic properties are:

- (a) det I = 1 (think of an unit cabe)
- (6) Exchanging a sun reverses the sign
- (c) It is linear in each son reparately.

Propostics of the Determinant:

Consider the Rystem
$$a_{11}x_1 + a_{12}x_2 = b_1$$

$$a_{21}x_1 + a_{22}x_2 = b_2$$

$$\Rightarrow x_1 = \frac{b_1 a_{22} - b_2 a_{12}}{a_{11}a_{22} - a_{12}a_{22}}$$

9/2 = b29/1 - b1921

Common denominator is then defined as the determinant of the co-eff. matrix.

Similarly for a 3x3 system A = b, we again get ed=s Mi= Numeratri, of i=1,2,3.

There is actually another definition of determinants: Def": Let A be a 3x3 motorx, let Aju be the 2x2 motorx obtained from A by deleting the jth was and the kth win The cofactor of a ju is then defined as eje = (-1) it dot A ju. The determinant is then dot A = 911 C11 + 912 C12 + 913 C13.

expansion along the 1st son.

· we can extend this def immediately. Thrn: Let A be an nxn matrix, then dot A may be obtained by refactor exp along any now/rd m of A: det A = aj, Cj, + aj, Cj, + ... + aj, Cjn.

Cosollary: If A has a 0 sow col then dot A = 0.

Corollary: For any eq. matrix A, det A = det AT.

Theorem: The det. of a LT/UT matrix is the product of its diagonal entries.

Theorem: det In = 1.

Theorem: The determinant changes sign when this srows are reversed.

Corollary: If two news of A are equal then dot A = 0.

Theorem: Let & B be the matrix obtained by multiplying a row of A by B. Then det B = B det A.

Proof: Let the jth now of B be is obtained from A by multiplying we have, B. $B_{jk} = A_{jk}$, k = 1, 2, ..., n.

In particular the (j,k) respectives of A and B are equal.

Expanding along the jth new now gives the result.

Theorem: Let B be the matrix obtained from A by adding B times the Know to the jth Row. Then det B = ded A.

Prost: For any motoix A and now vector $r = (r_1 \tau_2 ... \tau_n)$, $\tau_1(j_1 + \tau_2(j_2 + ... + \tau_n C_{j_n})$ is the det. of the matrix obtained from A by replacing the jth now with σ .

The jh how of B is bj = aj+Bak. Now, expanding along the jh how, det B = $(aj+Bak) \cdot c_j^T$ where $c_j = (c_j, c_{j2} \dots c_{jn}) \cdot c_j^T + \beta(a_k, c_j^T)$

= det A " since here the htm mo and the jtm no are equal. for k + j.

Mrs! det B = (3a1+7a3).c3T = 3a1.c3T + 7a3.c3T = 7(a3.c3T) = 71/1.

Theorem: A eq. matrix A is invertible iff det A = 0.

Proof: Strating with A, we perform elementary how operations to get a matrix in the sow scholar from and thus triangular:

A~A,~A2~...~Au.

there if det Ai-1 = 0 then det Ai = 0.

In particular, det A == 0 iff for det Ap=0.

If all diagnal entries of Ap are non-zero then deptap \$0. SIn this care Ap is investible since me have n pivots in Ap.

If at least one diagnal only of Ap is O then let Ap = O and in This care Ap is not investible bleame ne have < n pivoto. //.

Theorem: Let B = BA, them det B = B" det A.

troof: le induction.

Thurrem: det AB = det A. det B.

Corollary: For any so-matrix, det (AK) = (lot A)K.

Corollary: If A is invertible, then det (A-1) = 1 det A

Proof of Theorem: Let d(A) = det AB he show that d(f) has

the following properties: (i) d(I) = 1.

(Ti) d (4) change sign when two sows are

(iii) d(A) depends linearly on the 1st ros.

Then d(A) must equal det (A).

(i) is easy to verify.

(Ii) If two rows of A are exchanged then two rows of AB are also exchanged.

Thus the sign of d changes since sign of det AB changes.

(ii) A linear combination in the 1st sow of A gives the same linear combination in the 1st sow of AB. 11.

Formula for the inverse of a matrix:

Recall, $A \in \mathbb{R}^{n \times n}$, $\det A = a_{j_1}C_{j_1} + a_{j_2}C_{j_2} + \dots + a_{j_n}C_{j_n}$. then $C_{j_k} = (-1)^{j+k} \det A_{j_k}$ is the $(j_{j_n}k)$ - coference of A and, $a_{j_n} = (a_{j_1}a_{j_2}\dots a_{j_n})$ is the j^{j_n} sum of A. If $C_j = (C_{j_1}C_{j_2}\dots C_{j_n})$ then, $\det A = a_{j_n}C_{j_n}$.

In fact, aj. $C_{k}^{T} = \begin{cases} det A & ij = k \\ 0 & ij \neq k \text{ (as this gives det of a matrix with the rows equal).} \end{cases}$

We now form the cofactor matrix Cof(A) as, $Cof(A) = \begin{pmatrix} C_{11} & C_{12} & \dots & C_{1n} \\ C_{21} & C_{12} & \dots & C_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ C_{n_1} & C_{n_2} & \dots & C_{n_n} \end{pmatrix} = \begin{pmatrix} C_1 \\ C_2 \\ \vdots \\ C_n \end{pmatrix}$

Then, $A(Cof(A))^T = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \begin{pmatrix} c_1^T & c_2^T & \dots & c_n^T \end{pmatrix}$

 $= \begin{pmatrix} a_1 C_1^T & a_1 C_2^T & \cdots & a_1 C_n^T \\ a_2 C_1^T & a_2 C_2^T & \cdots & a_2 C_n^T \end{pmatrix}$ \vdots $a_n C_1^T & a_n C_2^T & \cdots & a_n C_n^T \end{pmatrix}$

 $= \begin{pmatrix} \det A & O \\ \det A & O \\ O & \det A \end{pmatrix} = \det A \cdot I_{n}.$

So, we have obtained,

$$A(\operatorname{Cof}(A))^{T} = \operatorname{dut}(A) \operatorname{In}.$$

$$= A\left(\frac{1}{\operatorname{dut}A}\right) \left(\operatorname{Cof}(A)\right)^{T} = \operatorname{In} \quad \text{if } \operatorname{dut}A \neq 0.$$

$$= A \left(\frac{1}{\operatorname{dut}A}\right) \left(\operatorname{Cof}(A)\right)^{T}. \quad \text{if } \operatorname{dut}A \neq 0.$$

$$=) A^{-1} = \frac{1}{\text{det } A} \left(\text{cof}(A) \right)^{T}. \quad \text{if } \text{det } A \neq 0.$$

(This is very computationally intensive!!)

eg:
$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
, $Cof(A) = \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix} = \begin{pmatrix} d & -c \\ -b & a \end{pmatrix}$

$$A^{-1} = \frac{1}{dt} \left(\operatorname{Cof}(A) \right)^{T} = \frac{1}{ad-bc} \left(\frac{d}{-c} - \frac{b}{a} \right) \cdot 1.$$

Q. When does an integer matrix have an integer inverse?

4 way entry of the matrix is an integer.

Therrem: An invertible integer metrix $A \in \mathbb{R}^{n \times n}$ has an integer inverse A-1 if det A = ±1.

Prof: Suppose A E RMXn is an invertible integer matrx. Co det A +0,. and det det A \in \mathbb{Z}, (Cof(A))^T is an integer matrix.

If A-1 is also an integer motorix then det (+1) EZ.

Now, det (A) det (A-1) = let (A A-1) = 1. =) det A = ±1.

Let on the other hand, let A = ±1 then A-1 = ± (lof(A)) T. A.

* We can generalt integer matrices with an integer inverse.

- Start with Uo on upper frighlar matrix with integer enfores and diagonal entries either 1 or - 1. Then det Uo = ±1.

- Perform any rept of elementary now operations . (interchange Ino rim or multiply a son add a multiple of one now to another) U0 ~ U1 ~ ... ~ Uk.

Recall, if A is invertible then a Roll of AM= b in N= A-16.

Thus,
$$\chi = \frac{1}{\det A} \begin{pmatrix} c_{11} & c_{21} & \dots & c_{n1} \\ c_{12} & c_{22} & \dots & c_{n2} \\ \vdots & \vdots & \vdots & \vdots \\ c_{1n} & c_{2n} & \dots & c_{nn} \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

This gives us, $\gamma_1 = \frac{1}{dut A} \left(b_1 c_{11} + b_2 c_{21} + \dots + b_n c_{n A} \right)$

Similarly, $n_2 = \frac{1}{\det A} \left(b_1 c_{12} + b_2 c_{22} + \cdots + b_n c_{n2} \right)$

In general we get the following:

Clamer's Rule: Ret A ER MAN he an invertible matrix. Let b EIR h and let A; be-the matrix obtained from A by neplocing the its ellumn with of A by b. Then the 201 to An=b is,

$$x = \frac{1}{\det A} \begin{pmatrix} \det A_1 \\ \det A_2 \\ \vdots \\ \det A_n \end{pmatrix}$$

(this is computationally very intensive!!)

mother formula for determinants:

when want to derive there formulas from the defining properties of the det: (i) det th = 1.

(ii) Exchange rowe changes high.

Cet's Look at 2x2 can, Ren (a b) = (a 0) + (0 b)

$$= dit \begin{pmatrix} a & 0 \\ c & 0 \end{pmatrix} + dit \begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix} + dit \begin{pmatrix} 0 & b \\ c & 0 \end{pmatrix} + dit \begin{pmatrix} 0 & b \\ 0 & d \end{pmatrix}$$

- · Each how explits into a co-ordinate direction.
- · So, the expr has no terms.
- . Most of the terms equal o.
- o When kno rows point in the Rame co-ordinate direction, one is a multiple of another. In dd = dd = dd = 0.
- the non-zero terms have to some in different abune. That is, they are a reordering or a permutation of .1,2,..., n. Thus they produce n! determinants.

eg. For n=3 can me have the following:

 $dit \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{32} \end{pmatrix} = dd \begin{pmatrix} a_{11} \\ a_{22} \\ a_{33} \end{pmatrix} + dut \begin{pmatrix} a_{12} \\ a_{31} \end{pmatrix}$ $+ det \begin{pmatrix} a_{13} \\ a_{21} \\ a_{32} \end{pmatrix} + dut \begin{pmatrix} a_{11} \\ a_{22} \\ a_{32} \end{pmatrix} + dut \begin{pmatrix} a_{21} \\ a_{22} \\ a_{32} \end{pmatrix}$ $+ dut \begin{pmatrix} a_{21} \\ a_{22} \\ a_{31} \end{pmatrix}$ $+ dut \begin{pmatrix} a_{12} \\ a_{21} \\ a_{22} \\ a_{31} \end{pmatrix}$

Only the are non-zero, otherwise a colum is repeated and have they are zero as one est heromer 0.

\$\, \text{det } A = \quad \qu

This suggests the following formula for $A \in \mathbb{R}^{n \times n}$:

det A = \(\left(a_{1\times} a_{2\beta} \ldots a_{n\times} \right) \det P

all P's

Shee Pir a permetation matrix and.