Stochastic Process - Fall 2024

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Problem 1. X(t): Markov stochastic process

t, 5 t2 5 ... 5 tn

Prove that: $f_{x_1}(x_1; t, | X(t_2) = x_2, ..., X(t_n) = x_n) = f_{x_1}(x_1, t, | X(t_2) = x_2)$

$$f_{X_1}(\alpha_1;t_1|X(t_2)=\alpha_2,\ldots,X(t_n)=x_n)=\frac{f_{X_1\cdots X_n}(X(t_r)=\alpha_1,\ldots,X(t_n)=\alpha_n)}{f_{X_1\cdots X_n}(X(t_2)=\alpha_2,\ldots,X(t_n)=\alpha_n)}$$

Also we know:
$$f_{x_1 \cdots x_n}(X(t_1) = x_1, \dots, X(t_n) = x_n) = f_{x_1}(x_1; t_1) f_{x_2}(x_2, t_2 \mid X(t_1) = x_1) \cdots f_{x_n}(x_n, t_n \mid X(t_1) = x_1, \dots, X(t_{n-1}) = x_{n-1})$$

$$f_{x_{2}...x_{n}}(X(t_{2})=x_{2},...,X(t_{n})=x_{n})=f_{x_{2}}(x_{2};t_{2})f_{x_{3}}(x_{3},t_{3}|X(t_{2})=x_{2})...$$

$$f_{x_{n}}(x_{n},t_{n}|X(t_{2})=x_{2},...,X(t_{n-1})=x_{n-1})$$

$$\text{Markov SP Property } \begin{cases} f_{x_{1},...,x_{n}}(X(t_{1})=x_{1},...,X(t_{n})=x_{n}) = f_{x_{1}}(x_{1};t_{1}) f_{x_{2}}(x_{2};t_{2} \mid X(t_{1})=x_{1}) \dots \\ f_{x_{n}}(x_{n},t_{n} \mid X(t_{n-1})=x_{n-1}) \end{cases}$$

$$f_{x_{1},...,x_{n}}(X(t_{2})=x_{2},...,X(t_{n})=x_{n}) = f_{x_{2}}(x_{2};t_{2}) f_{x_{3}}(x_{3};t_{3} \mid X(t_{2})=x_{2}) \dots$$

$$f_{x_{n}}(x_{n},t_{n} \mid X(t_{n-1})=x_{n-1})$$

According to (1) and (11) we can write:

$$\frac{f_{X_{1}}(x_{1};t_{1}|X(t_{2})=x_{2}...,X(t_{n})=x_{n})}{f_{X_{2}}(x_{2};t_{2})} = \frac{f_{X_{1}}(x_{1};t_{1})f_{X_{2}}(x_{2};t_{2}|X(t_{1})=x_{1})}{f_{X_{2}}(x_{2};t_{2})}$$

$$= \frac{f_{X_{1}X_{2}}(X(t_{1})=x_{1},X(t_{2})=x_{2})}{f_{X_{1}}(X(t_{1})=x_{2})} = f_{X_{1}}(x_{1};t_{1}|X(t_{2})=x_{2})$$

Problem 2. X(t): Poisson process with uniform density &

Lyjumps at Poisson points
$$ti \geqslant 0$$
 $(i=1,2,...)$; $T_n = t_{i+n} - t_i$ $(n \geqslant 1)$

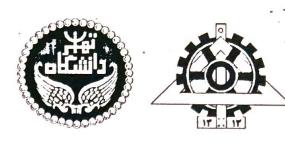
Poisson process
$$\Rightarrow P(X(t) = k) = e^{-\lambda t} \frac{(\lambda t)^k}{k!}$$

$$F_{T_n}(t) = P(T_n \leqslant t) = 1 - P(T_n > t) = 1 - P\left\{\begin{array}{l} zero & points \\ in & period \\ (t_1, t_{in}) \end{array}\right\} = 1 - P(X(t) = k-1)$$

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$$\frac{\partial}{\partial t} = 1 - \rho \left\{ X(t) = k - 1 \right\} = 1 - e^{-\lambda t} \frac{(\lambda t)^{k-1}}{(k-1)!}$$

$$\frac{\partial}{\partial t} = \frac{\partial}{\partial t} = \lambda e^{-\lambda t} \frac{(\lambda t)^{k-1}}{(k-1)!} - (k-1) e^{-\lambda t} \frac{\lambda^{k-1} t^{k-2}}{(k-1)!}$$

$$= e^{-\lambda t} \frac{(\lambda t)^{k-1}}{(k-1)!} \left[\lambda - \frac{k-1}{t} \right].$$

Problem 4. W(t): Wiener process; $W(t) = \int_0^t X(\alpha) d\alpha \rightarrow \begin{cases} X(t): zero-mean stationary \\ white Gaussian process \end{cases}$ $Y(t) = W^2(t)$ $R_X(z) = N_0 S(z)$

$$f_{w(t)}(\omega;t) = \frac{1}{\sqrt{2\pi N_{\circ}t}} \exp\left(\frac{-\omega^{2}}{2N_{\circ}t}\right) \quad ; \quad Y = W^{2} \rightarrow \begin{cases} W_{1} = -\sqrt{y} \\ W_{2} = \sqrt{y} \end{cases} \quad ; \quad f_{y}(y;t) = \frac{\sum_{i} f_{y}(\omega_{i};t)}{IJI}$$

$$|J| = |2w| = 2\sqrt{y} \implies f_{\gamma}(y;t) = \frac{f_{\omega}(\sqrt{y};t)}{2\sqrt{y}} + \frac{f_{\omega}(-\sqrt{y};t)}{2\sqrt{y}}$$

$$\rightarrow f_{\gamma}(y;t) = \frac{1}{\sqrt{2\pi N_{o}ty}} \exp\left(\frac{-y}{2N_{o}t}\right) ; \quad \gamma>0 , \quad t>0$$

b. Is Y(t) an IIP? IIP Def. t, \(t_1 \langle \cdots \langle t_1 \langle t_2 \langle \cdots \langle t_2 \langle \cdot Y(t_1) \Langle Y(t_1) \Langle \cdots \cdot Y(t_n) - Y(t_n) - Y(t_n) \langle \cdot Y(t_n) - Y(t_n) \langle Y(t_n) - Y(t_n) \langl

$$\begin{split} f_{y_{(e,)}y_{(e_{2})}}(Y_{1},Y_{2};t_{1},t_{2}) &= \frac{1}{4\sqrt{y_{1}y_{2}}} \left[f_{w}(\sqrt{y_{1}},\sqrt{y_{2}};t_{1},t_{2}) + f_{w}(\sqrt{y_{1}},\sqrt{y_{2}};t_{1},t_{2}) + f_{w}(-\sqrt{y_{1}},-\sqrt{y_{2}};t_{1},t_{2}) \right] \\ &= \frac{1}{4\sqrt{y_{1}y_{2}}} \left[f_{w_{1}}(\sqrt{y_{1}}) f_{w_{2}}(\sqrt{y_{2}}+\sqrt{y_{1}}) + f_{w_{1}}(\sqrt{y_{1}}) f_{w_{2},w_{1}}(\sqrt{y_{1}}-\sqrt{y_{2}}) + f_{w_{1}}(-\sqrt{y_{1}}) f_{w_{2},w_{1}}(\sqrt{y_{1}}-\sqrt{y_{2}}) + f_{w_{1}}(-\sqrt{y_{1}}) f_{w_{2},w_{1}}(\sqrt{y_{1}}-\sqrt{y_{2}}) + f_{w_{1}}(-\sqrt{y_{1}}) f_{w_{2},w_{1}}(\sqrt{y_{1}}-\sqrt{y_{2}}) \right] \\ &= \frac{exp\left(\frac{-y_{1}}{2N_{0}t_{1}}\right)}{4\pi N_{0}\sqrt{y_{1}y_{2}t_{1}(t_{2}-t_{1})}} \left[exp\left(-\frac{(\sqrt{y_{1}}+\sqrt{y_{2}})^{2}}{2N_{0}(t_{2}-t_{1})}\right) + exp\left(-\frac{(\sqrt{y_{1}}-\sqrt{y_{2}})^{2}}{2N_{0}(t_{2}-t_{1})}\right) \right] \end{split}$$

 $\Rightarrow f_{y}(y_{1},y_{2};t_{1},t_{2}) \neq f_{y}(y_{2}-y_{1};t_{1})t_{2}) f_{y}(y_{1},t_{1}) \Rightarrow \underline{Y(t)} \text{ is NOT IIP}$

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Problem 5. $X(t) = A\cos(2\pi F t + \theta)$ A: constant; $F \sim UC2,43$; $\theta \sim U[0,2\pi]$; $F \sqcup \theta$

$$\begin{split} E\{X(t)^2\} &= E\{A\cos(2\pi F t + \theta)^2\} = AE\{\cos(2\pi F t)\cos(\theta) - \sin(2\pi F t)\sin(\theta)^2\} \\ &= AE\{\cos(2\pi F t)^2\} E\{\cos(\theta)^2\} - AE\{\sin(2\pi F t)^2\} E\{\sin(\theta)^2\} = 0 \end{split}$$

· Autocorrelation function of X(t):

$$R_{x}(t_{1}, t_{2}) = E \left\{ X(t_{1}) X(t_{2}) \right\} = E \left\{ A^{2} \cos \left(2\pi F t_{1} + \theta \right) \cos \left(2\pi F t_{2} + \theta \right) \right\}$$

$$= \frac{A^{2}}{2} E \left\{ \cos \left(2\pi F (t_{1} + t_{2}) + 2\theta \right) \right\} + \frac{A^{2}}{2} E \left\{ \cos \left(2\pi F (t_{1} - t_{2}) \right) \right\}$$

$$= \frac{A^{2}}{2} E \left\{ \cos \left(2\pi F (t_{1} + t_{2}) \right) \right\} E \left\{ \cos \left(2\theta \right) \right\} - \frac{A^{2}}{2} E \left\{ \cos \left(2\pi F (t_{1} + t_{2}) \right) \right\} E \left\{ \sin \left(2\theta \right) \right\}$$

$$+ \frac{A^{2}}{2} E \left\{ \cos \left(2\pi F (t_{1} - t_{2}) \right) \right\} = \frac{A^{2}}{2} \int_{2}^{4} \frac{1}{2} \cos \left(2\pi F (t_{1} - t_{2}) \right) df$$

$$= \frac{A^{2}}{8\pi (t_{1} - t_{2})} \left[\sin \left(8\pi (t_{1} - t_{2}) \right) - \sin \left(4\pi (t_{1} - t_{2}) \right) \right]$$

$$\Rightarrow R_{x}(z) = \frac{A^{2}}{8\pi\tau} \left[\sin(8\pi\tau) - \sin(4\pi\tau) \right] \quad \boxed{B}$$

Problem 6. X(t): zero-mean stationary Gaussian process (Rx(z))

· Mean of Y(t):

$$E\{Y(t)\}=E\{Ae^{jX(t)}\}=E\{A\}E\{e^{jX(t)}\}=aE\{e^{jX(t)}\}=aE_{X(t)}$$

• Normal RV
$$\longrightarrow \Phi_{x}(\omega) = e^{j\omega m_{x}} e^{-\frac{1}{2}\delta_{x}^{2}\omega^{2}} \longrightarrow m_{x} = 0$$
, $\delta_{x}^{2} = \mathcal{R}_{x}(0)$

$$\Rightarrow E \mid Y(t) \mid Y = \alpha e^{-\frac{R_{\pi}(0)}{2}} \quad \text{(I)}$$

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• Autocorrelation function of Y(t):

$$R_{y}(t_{1},t_{2}) = E \left\{ Y(t_{1}) Y(t_{2}) \right\} = E \left\{ A e^{jX(t_{1})} \cdot A e^{-jX(t_{2})} \right\} = E \left\{ A^{2} \right\} \left\{ E \left\{ e^{j(X(t_{1})-X(t_{2}))} \right\} \right\}$$

$$= (a+a^{2}) E \left\{ e^{jU} \right\} = (a+a^{2}) \oint_{U} (1)$$

$$U \sim N \left(m_{U}, \Delta_{V}^{2} \right) \quad ; \quad \oint_{U} (\omega) = e^{j\omega m_{U}} \cdot e^{-\frac{1}{2}\Delta_{0}^{2}\omega^{2}} \longrightarrow \oint_{U} (1) = e^{jm_{U}} e^{-\frac{1}{2}\Delta_{0}^{2}}$$

$$m_{U} = E \left\{ U^{2} \right\} = E \left\{ X(t_{1}) - X(t_{2}) \right\} = E \left\{ X(t_{1}) \right\} - E \left\{ X(t_{1}) \right\} - 2X(t_{1})X(t_{2}) + X^{2}(t_{2}) \right\}$$

$$= E \left\{ X^{2}(t_{1}) \right\} - 2E \left\{ X(t_{1}) \cdot X(t_{2}) \right\} + E \left\{ X^{2}(t_{1}) \cdot X(t_{2}) + X^{2}(t_{2}) \right\}$$

$$\Rightarrow R_{y}(t_{1}, t_{2}) = (a+a^{2}) e^{-(R_{x}(0) - R_{x}(t_{1} - t_{2}))}$$

$$\Rightarrow R_{y}(\tau) = (a+a^{2}) e^{-(R_{x}(0) - R_{x}(t_{1} - t_{2}))}$$

$$\Rightarrow Y(t) \text{ is a WSS process}$$

Problem 3. W(t) = $\int_0^t X(\alpha) d\alpha$; X(t): WSS Gaussian process; $R_x(z) = N_s \delta(z)$

We want to estimate W(2) given W(1) by MMSE criterion.

$$f_{W(t)}(\omega;t) = \frac{1}{\sqrt{2\pi N_{\circ}t}} e^{-\frac{\omega^{2}}{2N_{\circ}t}} \Rightarrow \frac{\omega(1): f_{\omega(1)}(\omega) = \frac{1}{\sqrt{2\pi N_{\circ}}} \exp\left(-\frac{\omega^{2}}{2N_{\circ}}\right)}{\omega(2): f_{\omega(2)}(\omega) = \frac{1}{\sqrt{2\pi 12N_{\circ}}} \exp\left(\frac{-\omega^{2}}{4N_{\circ}}\right)}$$

W(1), $W(2) \Rightarrow Jointly Normal (<math>\mu_{W(1)} = \mu_{W(2)} = 0$, $\delta_{(W_1)}^2 = N_0$, $\delta_{(W_2)}^2 = 2N_0$, $f_{W_1W_2}$)

$$P_{\omega_1 \omega_2} = \frac{\text{cov}(\omega_1, \omega_2)}{\delta_{\omega_1, \delta_{\omega_2}}} = \frac{E_1^5 \omega_{(1)} \omega_{(2)}^2}{\delta_{\omega_2, \delta_{\omega_2}}} = \frac{R_{\omega}(1, 2)}{1 \times \sqrt{2}} = \frac{\sqrt{2}}{2} N_0$$

according to the property of Jointly Normal dist. $\Rightarrow E \left[w_2 \mid w_1 \right] = m_{w_2} + m_{w_2} \frac{\delta w_2}{\delta w_1} \left[w_1 - m_{w_1} \right]$

$$\Rightarrow \hat{W(2)}_{MMSE} = E \{ W(2) | W(1) \} = \frac{2}{2} N. \frac{\sqrt{2}N.}{\sqrt{N.}} W(1) = W(1)$$

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$$MSE = E \left\{ \left(\omega(2) - \hat{\omega}(2) \right)^{2} \right\} = E \left\{ \left(\omega(2) - \omega(1) \right)^{2} \right\} = E \left\{ \hat{\omega}(2) - 2 \omega(1) \omega(2) + \hat{\omega}(1) \right\}$$

$$= E \left\{ \hat{\omega}^{2}(2) \right\} - 2 E \left\{ \hat{\omega}(1) \omega(2) \right\} + E \left\{ \hat{\omega}^{2}(1) \right\} = 2 N_{\circ} - 2 N_{\circ} + N_{\circ} = N_{\circ}$$

$$= \frac{2 N_{\circ} = \delta_{\omega(2)}^{2}}{2 N_{\circ} = \delta_{\omega(2)}^{2}} \frac{N_{\circ} = K_{\omega}(1,2)}{N_{\circ} = \delta_{\omega(1)}^{2}}$$

Estimation $\Rightarrow W(2)_{MMSE} = W(1)$; $MSE = N_0$

Problem 8. U(n): iid sequence of Gaussian RVs __ N(0,1)

 $X(t) \Rightarrow$ obtained by linearly interpolating between U'S $\rightarrow X(t) = U(t)$ for t = neZ

 $X(t) = (1-\alpha) U(t) + \alpha U(t+1)$; t=n Part a. fx (x;t) _

$$\rightarrow f_{x}(x;t) = f_{u,(u,)} * f_{u,(u,2)}$$

fu, (ui) and fuz (uz) both have



$$t = n + a \longrightarrow a = t - n \longrightarrow d_x^2 = 2(n+1-t)^2 + 2t - 2n - 1 = (n-t)^2$$

$$\Rightarrow f_{\chi}(\chi;t,h) = \frac{1}{\sqrt{2\pi(t-n)}} exp\left(\frac{-\chi^{2}}{2(n-t)^{2}}\right)$$

Part b. Is the K(t) wide sense stationary?

• Mean:
$$E \{X(t)\} = 0$$

$$(1-\alpha_1)U(n_1) + \alpha_1U(n_1+1)$$
$$(1-\alpha_2)U(n_1) + \alpha_2U(n_1+1)$$

$$\begin{array}{c} \alpha_1 = t_1 - n_1 \\ \alpha_2 = t_2 - n_2 \end{array} \Longrightarrow \mathcal{R}_{\mathbf{x}}(t_1, t_2) = (n_1 + 1 - t_1)(n_1 + 1 - t_2) + (t_1 - n_1)(t_2 - n_1) \\ = 2n_1^2 - 2n_1t_1 - 2n_1t_2 + 2t_1t_2 - t_1 - t_2 + 2n_1 + 1 \end{array}$$

$$\longrightarrow R_{x}(t_{1},t_{2}) \neq R_{x}(t_{1}-t_{2}) \longrightarrow X(t) \text{ is not WSSI}$$