

1-

$$F(s) = \frac{3s+5}{s^3+4s^2+5s+2} = \frac{3s+5}{(s+2)(s+1)^2}$$

$$\begin{array}{c|ccc|c} -1 & 1 & 4 & 5 & 2 \\ -1 & 1 & 3 & 2 & 0 \\ -2 & 1 & 2 & 0 & \\ \hline & 1 & 0 & & \end{array}$$

$$F(s) = \frac{C_1}{s+2} + \frac{C_2}{s+1} + \frac{C_3}{(s+1)^2} = \frac{C_1(s+1)^2 + C_2(s+2)(s+1) + C_3(s+2)}{(s+2)(s+1)^2}$$

$$F(s) = \frac{(C_1+C_2)s^2 + (2C_1+3C_2+C_3)s + (C_1+2C_2+2C_3)}{(s+2)(s+1)^2} = \frac{3s+5}{(s+2)(s+1)^2}$$

$$\begin{cases} C_1+C_2=0 \Rightarrow C_1=-C_2 \\ 2C_1+3C_2+C_3=3 \\ C_1+2C_2+2C_3=5 \end{cases} \Rightarrow \begin{cases} C_2+C_3=3 \\ C_2+2C_3=5 \end{cases} \Rightarrow C_3=2, C_2=1, C_1=-1$$

$$\therefore F(s) = -\frac{1}{s+2} + \frac{1}{s+1} + \frac{2}{(s+1)^2} \Rightarrow f(t) = -e^{-2t} + e^{-t} + 2te^{-t}$$

2-  $\ddot{x} + 6\dot{x} + 18x = 18, x(0)=1, \dot{x}(0)=3$

$$s^2 X - s x(0) - \dot{x}(0) + 6sX - 6x(0) + 18X = \frac{18}{s}$$

$$(s^2 + 6s + 18)X = s + 9 + \frac{18}{s} = \frac{s^2 + 9s + 18}{s}$$

$$\Rightarrow X = \frac{s^2 + 9s + 18}{s(s^2 + 6s + 18)} = \frac{C_1}{s} + \frac{C_2 s + C_3}{s^2 + 6s + 18} = \frac{(C_1+C_2)s^2 + (6C_1+C_3)s + 18C_1}{s(s^2 + 6s + 18)}$$

$$\begin{cases} C_1+C_2=1 \Rightarrow C_2=0 \\ 6C_1+C_3=9 \Rightarrow C_3=3 \\ 18C_1=18 \Rightarrow C_1=1 \end{cases} \Rightarrow X = \frac{1}{s} + \frac{3}{(s+3)^2 + 3^2}$$

$$\Rightarrow x(t) = 1 + e^{-3t} \sin(3t)$$

3-  $\begin{cases} V = R\dot{i} + L\ddot{i} + V_b \\ J\ddot{\theta} = \tau_m - b\dot{\theta} \end{cases}$

$$\tau_m = K_t i \quad \tau_m \omega = V_b \cdot i \Rightarrow V_b = K_t \omega$$

$$\begin{cases} V = R\dot{i} + L\ddot{i} + K_t \dot{\theta} \\ J\ddot{\theta} + b\dot{\theta} = K_t i \Rightarrow i = \frac{J\ddot{\theta} + b\dot{\theta}}{K_t} \Rightarrow \dot{i} = \frac{J\ddot{\theta} + b\dot{\theta}}{K_t} \end{cases}$$

$$\frac{L}{K_t} J \ddot{\theta} + \frac{bL + RJ}{K_t} \dot{\theta} - \frac{bR + K_t^2}{K_t} \dot{\theta} = V$$

$$\Delta^3 \frac{LJ}{K_t} \Theta(\Delta) + \Delta^2 \frac{bL+RJ}{K_t} \Theta(\Delta) + \Delta \frac{bR+K_t^2}{K_t} \Theta(\Delta) = V(\Delta)$$

$$\frac{\Theta(\Delta)}{V(\Delta)} = G(\Delta) = \frac{K_t}{\Delta (LJ \Delta^2 + (bL+RJ)\Delta + (bR+K_t^2))}$$

$$4- \quad m\ddot{x} + (b+K_v)\dot{x} + K_p K_v x = K_p K_v u(t)$$

$$\Delta^2 m X + \Delta(b+K_v)X + K_p K_v X = K_p K_v U$$

$$\Rightarrow (m\Delta^2 + (b+K_v)\Delta + K_p K_v) X = K_p K_v U$$

$$\frac{X(\Delta)}{U(\Delta)} = G(\Delta) = \frac{K_p K_v}{m\Delta^2 + (b+K_v)\Delta + K_p K_v}$$