

$$1- \quad Y = K \cdot 5 \quad (R-Y) \Rightarrow Y \left( 1 + \frac{5K}{(s+2)(s+3)(s+4)} \right) = \frac{5K}{(s+2)(s+3)(s+4)} R$$

$$\frac{Y}{R} = \frac{\left( \frac{5K}{(s+2)(s+3)(s+4)} \right)}{\left( \frac{s^3 + 9s^2 + 26s + 24 + 5K}{(s+2)(s+3)(s+4)} \right)} = \frac{5K}{s^3 + 9s^2 + 26s + 24 + 5K} = G_p(s)$$

$$\frac{26 \cdot 9 - 24 - 5K}{9} > 0 \Rightarrow 260 - 24 - 26 - 5K > 0 \Rightarrow 5K < 210$$

$$K < 42$$

$$s^3: 1 \quad 26$$

$$s^2: 9 \quad 24 + 5K$$

$$s^1: \frac{26 \cdot 9 - 24 - 5K}{9}$$

$$s^0: 24 + 5K$$

$$24 + 5K > 0 \Rightarrow K > -\frac{24}{5} = -4.8$$

$$a = -4.8 \quad \text{e} \quad b = 42 \quad K \in ]-4.8, 42[$$

$$2- \quad Y(s) = \left( Y(s) \frac{K_p \cdot s + K_i}{s} + D(s) \right) \cdot \frac{1}{ms+b}$$

$$(ms+b)Y(s) = \frac{K_p \cdot s + K_i}{s} Y(s) + D(s)$$

$$(ms+b - \frac{K_p \cdot s + K_i}{s}) Y(s) = D(s)$$

$$\frac{Y(s)}{D(s)} = G_{fp}(s) = \frac{s}{ms^2 + (b - K_p)s - K_i}$$

$$e_{\infty} = \lim_{s \rightarrow 0} s E(s) = \lim_{s \rightarrow 0} s \cdot G_{fp}(s) \cdot D(s) = \lim_{s \rightarrow 0} \frac{s^2}{ms^2 + (b - K_p)s - K_i} \cdot \frac{1}{s^2} = -\frac{1}{K_i}$$

$$3- \quad \begin{cases} \ddot{y} = v \\ \dot{v} = \frac{K_f}{m} \frac{\mu^2}{(y_{max} - y)^2} - \frac{b}{m} v - g \end{cases} \Rightarrow \frac{d}{dt} \left[ \frac{y}{b} \right] = \left[ \frac{K_f}{m} \frac{\mu^2}{(y_{max} - y)^2} - \frac{b}{m} v - g \right] = 0$$

$$v_0 = 0$$

$$\Rightarrow \frac{K_f}{m} \frac{\mu_0^2}{(y_{max} - y_0)^2} - \frac{b}{m} v_0 - g = 0 \Rightarrow \mu_0^2 = \frac{mg}{K_f} (y_{max} - y_0)^2 \Rightarrow \mu_0 = \sqrt{\frac{mg}{K_f}} (y_{max} - y_0)$$

$$\frac{d}{dt} \begin{bmatrix} y \\ v \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial y}(v) \big|_{y_0, v_0, \mu_0} & \frac{\partial}{\partial v}(v) \big|_{y_0, v_0, \mu_0} \\ \frac{\partial}{\partial y} \left( \frac{k}{m} \frac{u^2}{(y_{max}-y)^2} - \frac{bv}{m} - g \right) \big|_{y_0, v_0, \mu_0} & \frac{\partial}{\partial v} \left( \frac{k}{m} \frac{u^2}{(y_{max}-y)^2} - \frac{bv}{m} - g \right) \big|_{y_0, v_0, \mu_0} \end{bmatrix} \begin{bmatrix} y - y_0 \\ v - v_0 \end{bmatrix} + \begin{bmatrix} \frac{\partial}{\partial \mu}(v) \big|_{y_0, v_0, \mu_0} \\ \frac{\partial}{\partial \mu} \left( \frac{k}{m} \frac{u^2}{(y_{max}-y)^2} - \frac{bv}{m} - g \right) \big|_{y_0, v_0, \mu_0} \end{bmatrix} (\mu - \mu_0)$$

$$\frac{d}{dt} \begin{bmatrix} y \\ v \end{bmatrix} = \frac{d}{dt} \begin{bmatrix} \delta y \\ \delta v \end{bmatrix} = \begin{bmatrix} 0 \\ -\frac{2k\mu_0}{m(y_{max}-y_0)^3} \end{bmatrix} \begin{bmatrix} \delta y \\ \delta v \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{2k\mu_0}{m(y_{max}-y_0)^2} \end{bmatrix} \delta \mu$$

$$\frac{d}{dt} \begin{bmatrix} \delta y \\ \delta v \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 1 \\ -\frac{2k\mu_0}{m(y_{max}-y_0)^3} & -\frac{b}{m} \end{bmatrix}}_A \begin{bmatrix} \delta y \\ \delta v \end{bmatrix} + \underbrace{\begin{bmatrix} 0 \\ \frac{\sqrt{k\mu_0}}{m} \cdot \frac{2}{y_{max}-y_0} \end{bmatrix}}_B \delta \mu$$

$$4 - G(s) = \frac{600}{(s+10)(s+20)(s^2+2s+4)} = \frac{10}{s+10} \cdot \frac{20}{s+20} \cdot \frac{3}{s^2+2s+4}$$

$$G(s) \approx \frac{3}{s^2+2s+4} \quad e_{\infty} = \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} sE(s) = \lim_{s \rightarrow 0} s(R - G(s)R) = \lim_{s \rightarrow 0} sR(1 - G(s))$$

$$e_{\infty} = \lim_{s \rightarrow 0} s \cdot \frac{1}{2} \left( 1 - \frac{3}{s^2+2s+4} \right) = \frac{1}{4}$$

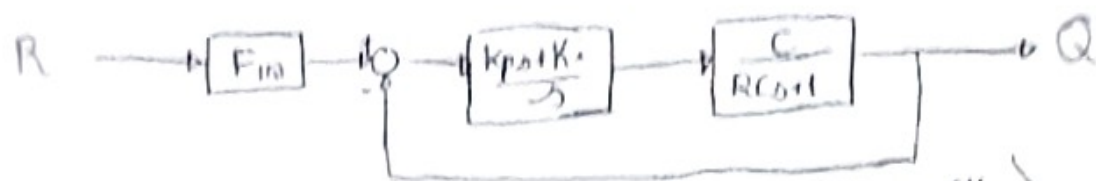
$$\lambda_{1,2} = \frac{2.16 \pm 0.6}{\omega_n}$$

$$\lambda_{1,2} = -\frac{\ln\left(\frac{1}{60}\right)}{\xi \omega_n} = \frac{\ln 50}{\xi \omega_n}$$

$$\begin{cases} 2\xi\omega_n = 2 \Rightarrow \xi = \frac{1}{2} \\ \omega_n^2 = 4 \Rightarrow \omega_n = 2 \end{cases}$$

$$V = R i + \frac{q}{C} = R \dot{q} + \frac{q}{C} \Rightarrow V = R \frac{Q}{s} + \frac{Q}{C}$$

$$\frac{Q(s)}{V(s)} = \frac{C}{RCs+1}$$



$$G_f = F \cdot \frac{\frac{K_p s + K_i}{s} \cdot \frac{C}{RCs+1}}{1 + \frac{K_p s + K_i}{s} \cdot \frac{C}{RCs+1}} = F \cdot \frac{\frac{(CK_p s + CK_i)}{s(RCs+1)}}{\frac{(RCs^2 + (CK_p + 1)s + CK_i)}{s(RCs+1)}} = F \cdot \frac{K_p s + K_i}{R}$$

$$= \frac{\omega_m^2}{s^2 + 2\xi\omega_m s + \omega_m^2} \Rightarrow \begin{cases} \frac{F \cdot (K_p s + K_i)}{R} = \frac{K_i}{R} \Rightarrow F = \frac{1}{\frac{K_p}{K_i} s + 1} \\ \frac{K_i}{R} = \omega_m^2 \Rightarrow K_i = R\omega_m^2 \\ 2\xi\omega_m = \frac{K_p + \frac{1}{C}}{R} \Rightarrow K_p = R(2\xi\omega_m - \frac{1}{C}) \end{cases}$$

$$F = \frac{1}{\frac{2\xi\omega_m - \frac{1}{C}}{\omega_m} s + 1}$$

$$M_p = \exp\left(-\frac{\pi \xi}{\sqrt{1-\xi^2}}\right) \Rightarrow \ln^2 M_p = \frac{\pi^2 \xi^2}{1-\xi^2}$$

$$\xi = \sqrt{\frac{1}{1 + \left(\frac{\pi}{\ln^2 M_p}\right)^2}}$$

$$\tan^{-1} \omega_m = \frac{\pi - \arccos \xi}{\omega_m \sqrt{1-\xi^2}} \Rightarrow \omega_m = \frac{\pi - \arccos \xi}{\tan^{-1} \omega_m \sqrt{1-\xi^2}}$$

$$K_p = R(2\xi\omega_m - \frac{1}{C})$$

$$K_i = R\omega_m^2$$