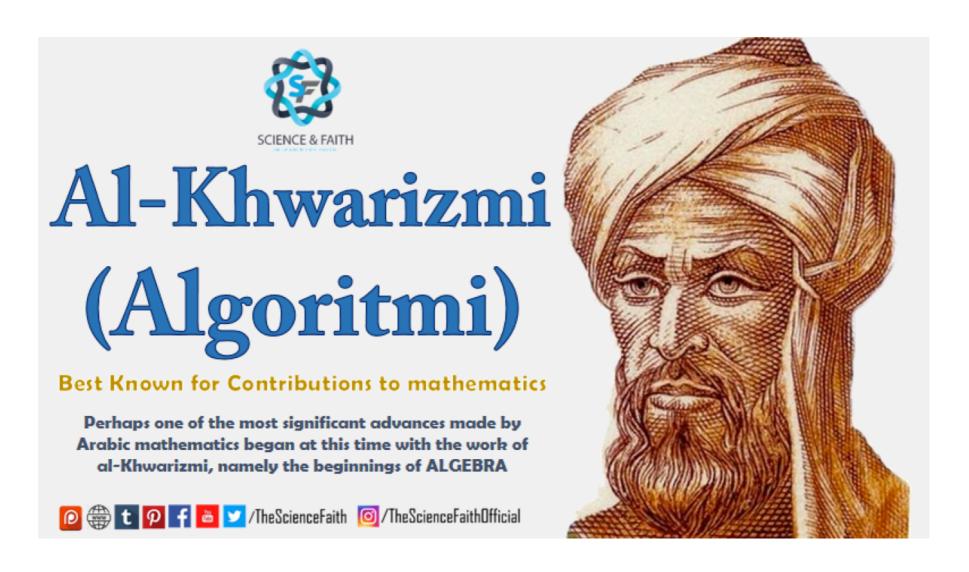
04 Complexity of Algorithms

CS201 Discrete Mathematics

Instructor: Shan Chen

Algorithms

 An algorithm is a finite sequence of precise instructions for performing a computation or for solving a problem.



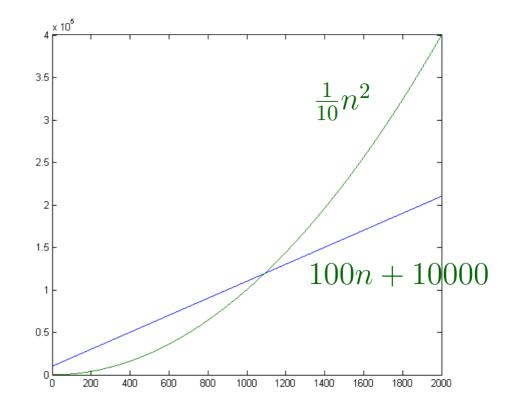
Al-Khwarizmi, Persian polymath



The Growth of Functions

Which Function is Larger?

- \circ **Q:** Which function is "larger"? $n^2/10$ vs 100n + 10000
- A: It depends on the value of n.
- In computer science, usually we are interested in what happens when the problem input size n gets big.
- Note that when n is "large enough",
 n²/10 gets bigger than 100n + 10000
 and stays bigger for larger n.



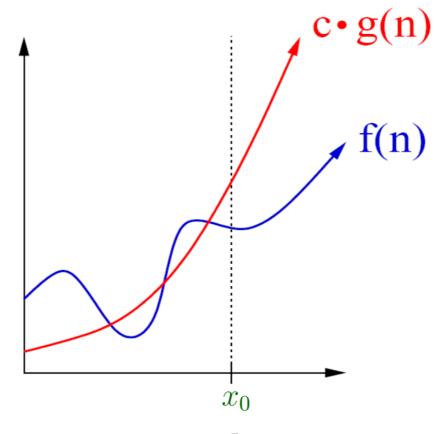


Big-O Notation

• **Definition:** Let f and g be functions from Z (or R) to R. We say that f(x) = O(g(x)) (read as f(x) is big-oh of g(x)), if there exist some positive constants c and x_0 such that

 $|f(x)| \le c|g(x)|$, whenever $x > x_0$.

Big-O gives an upper bound on the growth of a function. It tells
us that a function grows at most as fast as the other function.





Big-O Notation

- \circ Example: $100n + 10000 = O(n^2/10)$
 - Let k = 2000, we can verify that $\forall n > k$, $100n + 10000 < n^2/10$
 - By definition, the opposite is not true, i.e., $n^2/10 \neq O(100n + 10000)$
- \circ Some other $O(n^2)$ functions:
 - 4n²
 - $8n^2 + 2n 3$
 - $n^2/5 + n^{1/2} 10 \log n$
 - n(n 3)



Big-O Estimates for Polynomials

- **Theorem:** Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$, where a_0 , a_1, \ldots, a_n are real numbers. Then, $f(x) = O(x^n)$.
 - The leading term $a_n x^n$ of a polynomial dominates its growth.
- Proof:
 - Assuming x > 1, we have

$$|f(x)| = |a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0|$$

$$\leq |a_n| x^n + |a_{n-1}| x^{n-1} + \dots + |a_1| x + |a_0|$$

$$= x^n (|a_n| + |a_{n-1}|/x + \dots + |a_1|/x^{n-1} + |a_0|/x^n)$$

$$\leq x^n (|a_n| + |a_{n-1}| + \dots + |a_1| + |a_0|)$$

• Choose $x_0 = 1$ and $c = |a_n| + |a_{n-1}| + \dots + |a_1| + |a_0|$, then $|f(x)| \le cx^n$ whenever $x > x_0$.



Some Big-O Estimates

$$0 1 + 2 + \cdots + n = O(n^2)$$

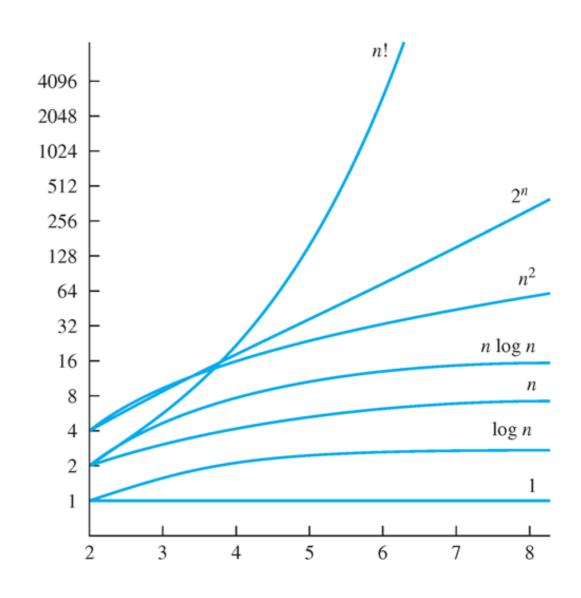
$$\circ$$
 $n! = O(n^n)$

$$\circ$$
 log $n! = O(n \log n)$

o
$$log_a n = O(n)$$
 for $a > 0$

$$\circ n^a = O(n^b)$$
 for $0 \le a \le b$

o
$$n^a = O(2^n)$$





Combination of Functions

• **Theorem:** If $f_1(x)$ is $O(g_1(x))$ and $f_2(x)$ is $O(g_2(x))$, then $(f_1 + f_2)(x) = O(\max(|g_1(x)|, |g_2(x)|))$

Proof:

- By definition, there exist constants C_1 , C_2 , k_1 , k_2 such that $|f_1(x)| \le C_1 |g_1(x)|$ when $x > k_1$ $|f_2(x)| \le C_2 |g_2(x)|$ when $x > k_2$
- Let $g(x) = max(|g_1(x)|, |g_2(x)|)$, when $x > max(k_1, k_2)$ we have $|(f_1 + f_2)(x)| = |f_1(x) + f_2(x)| \le |f_1(x)| + |f_2(x)|$ $\le C_1|g_1(x)| + C_2|g_2(x)| \le C_1|g(x)| + C_2|g(x)|$ $= (C_1 + C_2)|g(x)|$
- The proof is concluded with $C = C_1 + C_2$ and $k = max(k_1, k_2)$.



Combination of Functions

- **Theorem:** If $f_1(x)$ is $O(g_1(x))$ and $f_2(x)$ is $O(g_2(x))$, then $(f_1f_2)(x) = O(g_1g_2(x))$
- Proof: very similar to the previous theorem
 - By definition, there exist constants C_1 , C_2 , k_1 , k_2 such that $|f_1(x)| \le C_1 |g_1(x)|$ when $x > k_1$ $|f_2(x)| \le C_2 |g_2(x)|$ when $x > k_2$
 - Let $g(x) = g_1g_2(x)$, when $x > max(k_1, k_2)$ we have $|(f_1f_2)(x)| = |f_1(x)f_2(x)| = |f_1(x)||f_2(x)|$ $\leq C_1|g_1(x)|C_2|g_2(x)| = C_1C_2|g_1(x)g_2(x)|$ $= C_1C_2|g(x)|$
 - The proof is concluded with $C = C_1C_2$ and $k = max(k_1, k_2)$.



Exercise (3 mins)

Order the following functions by order of growth:

•
$$f_1(n) = (1.5)^n$$

•
$$f_2(n) = 8n^3 + 17n^2 + 111$$

•
$$f_3(n) = (\log n)^2$$

•
$$f_4(n) = 2^n$$

•
$$f_5(n) = log(log n)$$

•
$$f_6(n) = n^2(\log n)^3$$

•
$$f_7(n) = 2^n(n^2 + 1)$$

•
$$f_8(n) = 8n^3 + n(\log n)^2$$

•
$$fg(n) = 100000$$

•
$$f_{10}(n) = n!$$



Exercise (3 mins)

Order the following functions by order of growth:

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$$f_7(n) = 2^n(n^2 + 1)$$

•
$$f_8(n) = 8n^3 + n(\log n)^2$$

•
$$fg(n) = 100000$$

•
$$f_{10}(n) = n!$$

- Solution:
 - f9 < f5 < f3 < f6 < f8 < f2 < f1 < f4 < f7 < f10



Big-Ω Notation

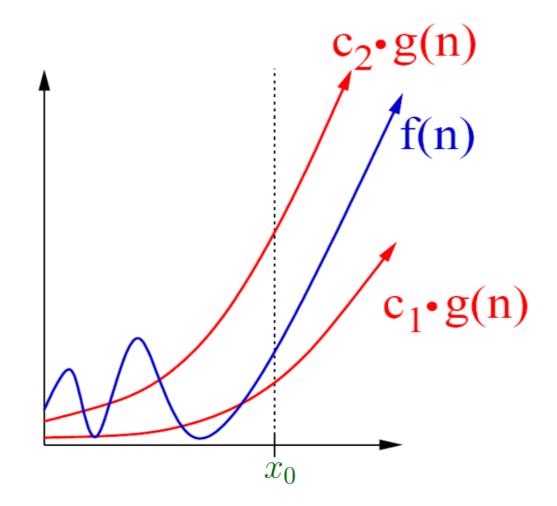
• **Definition:** Let f and g be functions from Z (or R) to R. We say that $f(x) = \Omega(g(x))$ (read as f(x) is big-omega of g(x)), if there exist some positive constants c and x_0 such that $|f(x)| \ge c|g(x)|$, whenever $x > x_0$.

- \circ Big- Ω gives a lower bound on the growth of a function. It tells us that a function grows at least as fast as the other function.
- Note: $f(x) = \Omega(g(x))$ if and only if g(x) = O(f(x))



Big-O Notation

- **Definition:** Let f and g be functions from Z (or R) to R. We say that $f(x) = \Theta(g(x))$ (read as f(x) is big-theta of g(x)), if they have the same order of growth: f(x) = O(g(x)) and $f(x) = \Omega(g(x))$.
- Note: $f(x) = \Theta(g(x))$ is equivalent to $g(x) = \Theta(f(x))$





Exercise (3 mins)

• True or false?

•
$$3n^2 + 4n = \Theta(n)$$
?

•
$$3n^2 + 4n = \Theta(n^2)$$
?

•
$$3n^2 + 4n = \Theta(n^3)$$
?

•
$$n/5 + 10n \log n = \Theta(n^2)$$
?

•
$$n^2/5 + 10n \log n = \Theta(n \log n)$$
?

•
$$n^2/5 + 10n \log n = \Theta(n^2)$$
?



Exercise (3 mins)

True or false?

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?

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$$n/5 + 10n \log n = \Theta(n^2)$$
?

•
$$n^2/5 + 10n \log n = \Theta(n \log n)$$
?

•
$$n^2/5 + 10n \log n = \Theta(n^2)$$
?

No, but
$$\Omega(n)$$

Yes

No, but
$$O(n^3)$$

No, but
$$O(n^2)$$

No, but
$$\Omega(n \log n)$$

Yes



Complexity of Algorithms

Computational Problems and Algorithms

- Computational problem: a task solved by a computer, which formally is a set of instances (i.e., problem input, with size n) together with a (perhaps empty) set of solutions (problem output) for every instance.
 - An instance is just a specific problem input, not the problem itself.
- Algorithm: a finite sequence of precise instructions for performing a computation or for solving a problem.
- We say an algorithm solves the problem if it halts (ends) with the correct output for every input instance.



Computational Problems and Algorithms

- Computational problem: a task solved by a computer.
- Algorithm: a finite sequence of precise instructions for performing a computation or for solving a problem.
- We say an algorithm solves the problem if it halts with the correct output for every input instance
- Example: algorithm for calculating the sum of a₁, a₂, ..., a_n
 - Step 1: set S = 0
 - Step 2: for i = 1 to n, $S := S + a_i$ (i.e., assign S the value $S + a_i$)
 - Step 3: output S



^{*} problem instance example: < 8, 3, 6, 7, 1, 2, 9 > (here n = 7)

Time and Space Complexity

- Time complexity: the number of machine operations (addition, multiplication, comparison, assignment, etc.) in an algorithm
- Space complexity: the amount of memory in an algorithm
- Example: algorithm for calculating the sum of a₁, a₂, ..., a_n
 - Step 1: set S = 0
 - Step 2: for i = 1 to n, $S := S + a_i$ (i.e., assign S the value $S + a_i$)
 - Step 3: output S
 - **time complexity:** O(n) * usually we ignore operations on iterator i Step 2 takes n operations (in-place additions). Step 1 and 3 each take 1 operation. Altogether this algorithm takes n + 2 operations.
 - space complexity: O(n)
 The input numbers take O(n) memory and S, i take O(1) memory.



Example: Horner's Method

- Example: consider the evaluation of $f(x) = 1 + 2x + 3x^2 + 4x^3$
 - direct computation: 3 additions and 6 multiplications
 - **better solution:** evaluate f(x) = 1 + x(2 + x(3 + 4x)) instead, which takes 3 additions and 3 multiplications
- Polynomial evaluation: $f(x) = a_0 + a_1x + \cdots + a_nx^n$
- Horner's method: $f(x) = a_0 + x(a_1 + x(a_2 + \cdots + x(a_{n-1} + xa_n) \cdots))$
 - Step 1: set $S = a_n$
 - Step 2: for i = 1 to n, $S := a_{n-i} + xS$
 - Step 3: output S
 - time complexity: O(n)

Step 1 and 3 each take *one* operation. Step 2 takes *3n* operations: *n* multiplications, *n* additions, *n* assignments.



Another Example

Determine the time complexity of the following algorithm:

```
for i := 1 to n

for j := 1 to n

a := 2 * n + i * j;

end for

end for
```

- Computing the value of a in each iteration takes 4 operations (two multiplications, one addition and one assignment). There are n^2 iterations in two loops. So it takes $n^2 \times 4 = 4n^2$ operations. The time complexity of this algorithm is $O(n^2)$.
 - Note that we can compute 2 * n only once but still $O(n^2)$ complexity.



Exercise (3 mins)

Determine the time complexity of the following algorithm:

```
S := 0
for i := 1 to n
for j := 1 to i
S := S + i * j;
end for
end for
```



Exercise (3 mins)

Determine the time complexity of the following algorithm:

```
S := 0
for i := 1 to n
for j := 1 to i
S := S + i * j;
end for
```

• The first S assignment takes 1 operation. Computing the value of S in each iteration takes 2 operations (one multiplication and one in-place addition). There are 1 + 2 + ... + n = n(n + 1)/2 iterations in two loops, so it takes $1 + n(n + 1)/2 \times 2 = n^2 + n + 1$ operations. The time complexity of this algorithm is $O(n^2)$.

Types of Complexity Analysis

Example: (Insertion Sort)

```
Input: A[1...n] is an array of numbers
                                             Insertion Sort Execution Example
for j := 2 to n
  key = A[j];
  i = j - 1;
  while i \ge 1 and A[i] > key do
     A[i+1] = A[i];
     i--;
  end while
  A[i+1] = key;
end for
```

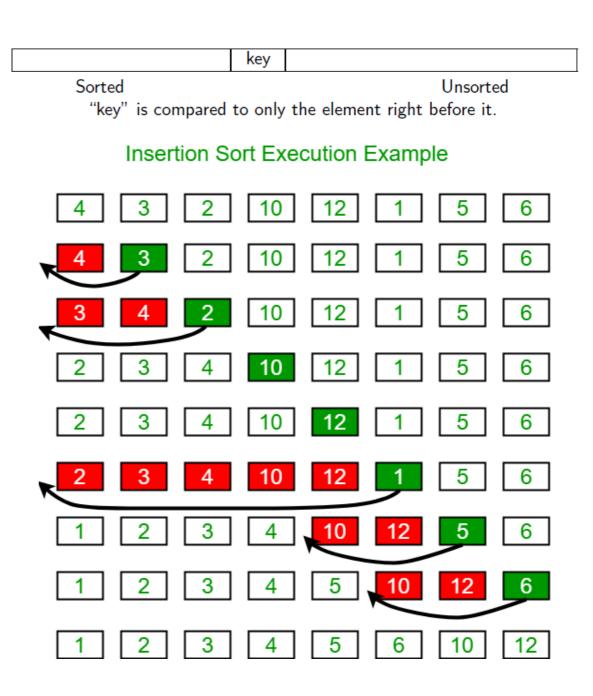


Complexity Analysis: Type I

Best-case complexity:

- constraints on the input rather than size
- resulting in the fastest possible running time for the given size.
- Example: (Insertion Sort)
 - $A[1] \le A[2] \le A[3] \le \cdots \le A[n]$
 - time complexity: ⊖(n)

n - 1 comparisons





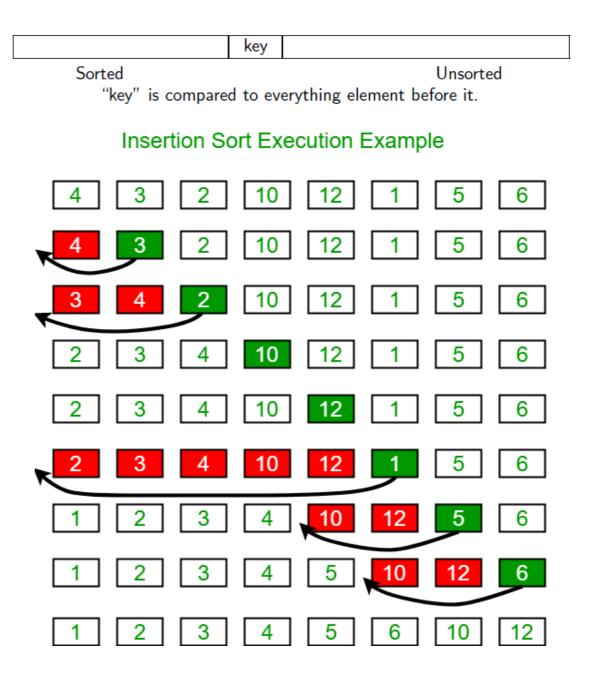
Complexity Analysis: Type II

Worst-case complexity:

- constraints on the input rather than size
- resulting in the slowest possible running time for the given size.
- Example: (Insertion Sort)
 - $A[1] \ge A[2] \ge A[3] \ge \cdots \ge A[n]$
 - time complexity: ⊖(n²)

$$\sum_{j=2}^{n} j - 1 = \frac{n(n-1)}{2}$$

comparisons & swaps





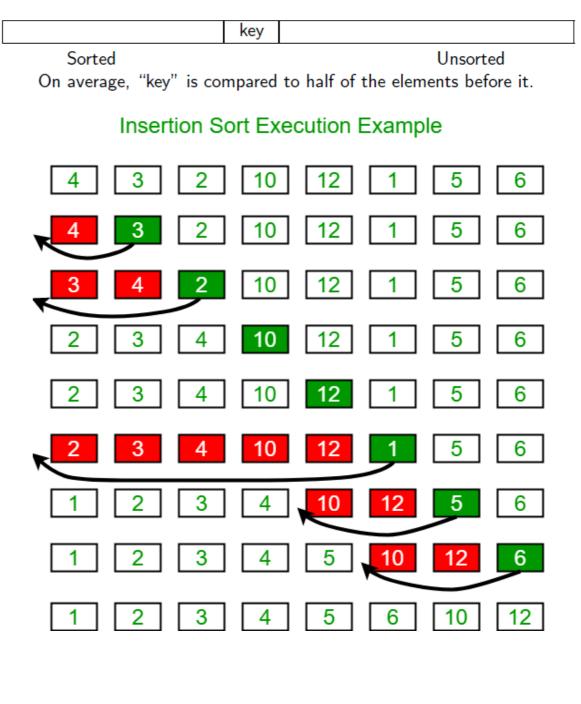
Complexity Analysis: Type III

Average-case complexity:

- constraints on the input rather than size
- average running time over all possible inputs for the given size (usually involving probability distribution on input instances)
- Example: (Insertion Sort)
 - if *n!* instances are equally likely
 - time complexity: $\Theta(n^2)$

$$\sum_{j=2}^{n} \frac{j-1}{2} = \frac{n(n-1)}{4}$$

comparisons & swaps





Some Thoughts on Algorithm Design

- Algorithm design is mainly about designing algorithms that have small Big-O running time.
- Being able to design good algorithms lets you identify the hard parts of your problem and handle them effectively.
- Too often, programmers try to solve problems using brute force techniques and end up with slow and complicated code!
- A few hours of abstract thought devoted to algorithm design could have speeded up and simplified the solution substantially!



Complexity of Problems

Dealing with Hard Problems

• What would you do if you cannot find an efficient algorithm for a given problem?



Blame yourself

Prove that no such algorithm exists



Dealing with Hard Problems

- Showing that a problem has efficient algorithms is relatively easy:
 - All we have to do is to demonstrate an algorithm.
- Proving that no efficient algorithm exists for a particular problem is difficult:
 - How can we prove the non-existence of something?
- We will now learn about NP-complete problems, which provide us with a way to approach this question.



Introduction to NP-Complete

- NP-complete problems: a very large class of problems (> 3000 are known) which is not known to have any "efficient" solutions.
- It is known that if any one of the NP-complete problems has an efficient solution then all of the NP-complete problems have efficient solutions.
- Researchers have spent innumerable man-years trying to find efficient solutions to *NP*-complete problems but failed.
- So, NP-complete problems are very likely to be hard.
- What we can do: prove that a hard problem is NP-complete.
 - This shows no one can find an efficient solution so far.
- Next, we show how to define such complexity classes formally.



Example Problem: COMPOSITE

- **COMPOSITE:** given a positive integer n, are there integers d, $k \ge 2$ such that n = dk?
- The naive algorithm for determining whether *n* is composite is to enumerate *d* from 2 to *n* 1 to see if any of them divides *n*.
 - This takes *Θ(n)* division operations, which might look like linear time and very efficient. However, it is problematic to treat the value of *n* as the input size of the algorithm, because integer *n* is usually processed as a binary string of length *Θ(log₂ n)* rather than *Θ(n)*. An efficient algorithm should have time complexity "close" to its input size *Θ(log₂ n)* rather than the input value *n*.
 - e.g., $n \times n$ requires only $O((\log_2 n)^2)$ bit operations (show later)
 - Therefore, the input size of COMPOSITE is $L = log_2 n$. Then, the time complexity is $\Theta(n) = \Theta(2^L)$, i.e., exponential in the input size L and hence very impractical. (Note that integer division n/d also takes $O((log_2 n)^2)$ bit operations, which we ignore for simplicity.)
- Takeaway: we should use the input size to measure complexity.



The Input Size of Problems

- Complexity of a problem is measured in terms of its input size.
 - The input size of a problem is the number of bits needed to encode the input of the problem.
- The optimal input size, determined by an optimal encoding method, is hard to compute in most cases.
- For most problems, it is sufficient to choose some natural, and (usually) simple, encoding method and use its encoded input size.
- Example 1: COMPOSITE
 - What is the input size of this problem?
 Any integer n ≥ 1 can be represented as a binary string a₀a₁····a_L of length [log₂ (n + 1)]. Therefore, a natural measure of the input size is [log₂ (n + 1)] (or Θ(log₂ n) for simplicity)



The Input Size of Problems

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- For most problems, it is sufficient to choose some natural, and (usually) simple, encoding method and use its encoded input size.
- Example 2: Sort n integers a₁, ..., a_n
 - What is the input size of this problem?

Fixed-length encoding: all input numbers share the same length. We write every input integer a_i as a binary string of the same length $m = \lceil \log_2 \max(|a_i| + 1) \rceil + 1$ (one extra bit for the +/- sign).

This natural encoding gives an input size *nm*.



Decision and Optimization Problems

- Decision problem: a problem that has a yes or no answer.
 - E.g., "Given n > 0, is integer m such that $m^m < n$?"
- Optimization problem: a problem that asks for some answer that maximizes or minimizes a particular objective function.
 - E.g., "Given n > 0, what is the largest integer m such that $m^m < n$?"
- Given an algorithm for solving the optimization problem, solving the corresponding decision problem is usually trivial.
 - Contrapositive: if we prove that a given decision problem is hard to solve efficiently, then the corresponding optimization problem must be (at least as) hard.
- The other direction (decision → optimization) also often works.
 - E.g., use binary search to find m in the above examples.



Complexity Classes

- Computational complexity theory is a field that deals with:
 - classification of certain "decision problems" into several classes:
 the class of "easy" problems
 the class of "hard" problems
 the class of "hardest" problems
 - relations among the above classes
 - properties of problems in the above classes
- Our How to classify decision problems?
 - use polynomial-time algorithms (often called efficient algorithms)



Polynomial-Time Algorithms

- Polynomial-time algorithm: an algorithm that runs in time O(nc), where c > 0 is a constant number independent of n, and n is the input size of the problem that the algorithm solves.
 - E.g., popular sorting algorithms are polynomial-time algorithms.
- Our expectations:
 - When the input size of the algorithm is n^a (for any constant a > 0), the algorithm should still be polynomial-time.
 - Also, an algorithm that is composed by several polynomial-time algorithms should still be polynomial-time.
- The above somehow shows why people choose polynomial-time to define efficient algorithms, because the common operations (e.g., addition, subtraction, multiplication, composition, etc.) are closed for polynomials.



Non-Polynomial-Time Algorithms

- Non-polynomial-time algorithm: an algorithm of which the running time is not $O(n^c)$ for any constant c > 0.
 - E.g., naive algorithm for solving the composite number problem
- Non-polynomial-time algorithms are usually impractical.
 - E.g., exponential-time 2^n for n = 100 takes billions of years!!!
- Caveat: even polynomial-time algorithms could be impractical.
 - E.g., a $\Theta(n^{20})$ algorithm may not be very practical bb for n = 100.



Tractable Problems and Class P

- Tractable problem: a problem that is solvable in polynomial time (or the problem is in polynomial time). That is, there exists a polynomial-time algorithm that solves the problem.
- Class P consists of all decision problems that are solvable in polynomial time. That is, there exists a polynomial-time algorithm that decides if any given input is a yes-input or a no-input.
 - E.g., PRIMES (determining whether a number is prime) is in P.
- How to prove that a decision problem is in P?
 - find a polynomial-time algorithm (relatively easy)
- How to prove that a decision problem is not in P?
 - prove that there is no polynomial-time algorithm for solving this problem (much much harder)



Certificates and Class NP

- A decision problem is usually formulated as: "Is there an object satisfying some conditions?"
- A proof/certificate/witness for a yes-input is a specific object that
 is used to verify/prove/show that this input is indeed a yes-input.
 - E.g., the COMPOSITE problem can be formulated as: "Is there an integer d (1 < d < n) such that d divides n?". So, a certificate for a composite number n (i.e., n is a yes-input of COMPOSITE) can be one of such integer factors d.
- Class NP (nondeterministic polynomial-time) consists of all decision problems that: there exists a polynomial-time algorithm V such that, for each yes-input, there is a proof/certificate/witness with which V can verify the input is indeed a yes-input.
 - E.g., COMPOSITE is in NP because the certificate can be verified in polynomial time (in the input size): the input size is Θ(log₂ n) and checking if d divides n takes O((log₂ n)²) bit operations.



P = NP?

- \circ Whether P = NP is one of the most important problems in CS.
- O It is not hard to see that P ⊆ NP. * why?
- Intuitively, NP ⊆ P is doubtful.
 - Just being able to verify a certificate in polynomial time does not necessarily mean we can tell whether an input is a yes-input or a no-input in polynomial time, e.g., certificates may be hard to find.
 - So far, we are still far from solving it and do not know the answer.
 However, the search for such a solution has provided us with deep insights into what distinguishes "easy" problems from "hard" ones.



NP-Complete and NP-Hard

- NP-complete: consists of the hardest problems in NP.
 - NP-complete problems are reducible to each other, i.e., they are equivalently hard
 - If solving problem A can be transformed into solving problem B, we say A reduces to B. This also means B is at least as hard as A.
- NP-hard: consists of problems at least as hard as NP-complete.
 - Some NP-hard problems may not belong to NP.



05 Number Theory and Cryptography

To be continued...

Announcements

- Please submit your Undergraduate Students Declaration Form with your handwritten signature in Assignment 0 if you have not yet done so.
- Assignment 2 was already released and is due on Oct 23:
 - 100 points maximum but 110 in total
 - DO NOT CHEAT!

