Eric Crosson

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Bachelor of Science in Computer Engineering at University of Texas 2016

Recent classes include embedded & real time operating systems, computer architecture, neural networks Interested in immutable pipelines, GNU/Linux, free software, logic, artificial intelligence & computer vision

Extra Curricular Activities

- Self-study of functional programming, infrastructure as code, formal verification
- o Founding mentor to FIRST Robotics Competition (FRC) team 3529; mentor FTC, FLL, Jr. FLL teams

Hobbyist programmer, GNU/Linux aficionado, Emacs appreciator

- Expertise with LISP, git, Ruby, C/C++, Python, Java, Perl, Bash, asm, LATEX, documentation, CMake, Ansible
- o Familiar with Node.js, DevOps, CI, Docker, Octave, Haskell, Tcl, VHDL, S. Verilog, ACL2, Promela, FPGAs

Work Experience

ShoreTel- Software Engineer (2012 - 2013)

Created IP Phone VNC client and unit test architecture/DSL for firmware regression

Intel- Post Silicon Validation (2013 - 2014)

- Managed tests to determine quality of hardware
- Wrote, executed tests to stress hardware components

Intel- Pre Silicon Validation (2014 - 2015)

- \circ Created analysis engine for internal signals of $3^{\rm rd}$ party RTL
- Integrated DHCP model tests against project RTL

ShoreTel (2015 - Today)

- Architect of dev build system, work infrastructure
- o Create custom Linux distro for custom hardware

Centaur Technology- Design Verification (2013)

- Integrated processor model with bochs to allow OSlevel emulation and testing of presilicon hardware
- Profiled, optimized, debugged, and documented presilicon hardware

Centaur Technology- Design Verification (2014)

- Created multicore PSE36/PAE x86 bytecode generator
- o Designed, implemented true LRU in System Verilog

IBM- Cloud Infrastructure Services (2015)

- Community work with OpenStack
- $\circ\,$ DevOps management of public cloud
- Created API to manage production accounts
- Fostered habit of working with patent teams

Self-motivated projects

- o http://www.github.com/EricCrosson
- Autonomous objective-based drone operation
- Programming contests in Java, C++ and z80 asm
- $\circ\,$ Founded competitive UIL computer science team
- Cell-tracking image processing
- Eye-gaze projection software
- 4 degree of freedom robotic arm articulation
- $\circ\,$ Static image background extraction

Autodidactic

- Seeking knowledge from OpenCourseware, Coursera, edx, and other manuscripts
- o Classes taken: machine learning, neural networks, big data, algorithms II, cryptography II, hardware security